

# Notes: MATH235 (F25) Markov Chains, Martingales, and Brownian Motion

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# 1 Preliminaries

**Definition 1.1** (Stochastic Process). A **stochastic process** is a collection of random variables  $\{X_t\}_{t \in T}$ , where each  $X_t$  takes values in a **state space**  $S$ .

*Remark 1.2.* Alternatively, one may think of a random function  $X : T \rightarrow S$ . ☕

*Remark 1.3.* We think of  $T$  as representing time. In this course,  $T$  will either be discrete ( $T = \mathbb{N}_0$ ) or continuous ( $T = [0, \infty)$ ). ☕

*Example 1.4.*

- $\{X_n\}_{n \geq 0}$  is a sequence of independent random variables.
- Let  $\{Y_n\}_{n \geq 0}$  are iid RVs in  $\mathbb{R}$ . We can consider  $X_0 = 0$  and  $X_n = \sum_{i=1}^n Y_i$  for  $n \geq 1$ .



Now recall that if  $Y$  is a RV in a countable set, the **distribution** of  $Y$  is the function  $y \mapsto \mathbb{P}(Y = y)$ . What is the analogue for a stochastic process? How to describe the distribution of  $\{X_n\}_{n \geq 0}$ . It suffices to describe

$$\mathbb{P}[X_0 = s_0, \dots, X_n = s_n], \quad \forall n \in \mathbb{N}, \quad \forall s_0, \dots, s_n \in S.$$

**Definition 1.5** (Conditional Probability). Let  $E$  and  $F$  be events such that  $\mathbb{P}(F) > 0$ . Then the **conditional probability** of  $E$  given  $F$  is

$$\mathbb{P}(E | F) = \frac{\mathbb{P}(E \cap F)}{\mathbb{P}(F)}.$$

By definition, for each  $n$  and each  $s_0, \dots, s_n \in S$ , we may write

$$\begin{aligned} \mathbb{P}[X_0 = s_0, \dots, X_n = s_n] &= \mathbb{P}[X_n = s_n | X_0 = s_0, \dots, X_{n-1} = s_{n-1}] \mathbb{P}[X_0 = s_0, \dots, X_{n-1} = s_{n-1}] \\ &= \left( \prod_{i=1}^n \mathbb{P}[X_i = s_i | X_0 = s_0, \dots, X_{i-1} = s_{i-1}] \right) \mathbb{P}[X_0 = s_0], \end{aligned}$$

assuming the conditional probabilities are well-defined. Thus it suffices to specify the initial distribution  $\mathbb{P}(X_0 = s_0)$  and the conditional probabilities to describe the distribution of the stochastic process.

Without imposing any restrictions, there is little more we can say about the distribution of a stochastic process. The first restriction we will impose is the Markov property.

## 2 Markov Chains on Finite State Space

**Definition 2.1** (Markov). We say that a stochastic process  $\{X_n\}_{n \geq 0}$  is a **Markov process (chain)** if for each  $n$  and each  $s_0, \dots, s_n, s_{n+1} \in S$ , we have

$$\mathbb{P}[X_n = s_n | X_0 = s_0, \dots, X_{n-1} = s_{n-1}] = \mathbb{P}[X_n = s_n | X_{n-1} = s_{n-1}].$$

We say  $\{X_n\}_{n \geq 0}$  is **time-homogeneous** if for each  $n$  and each  $s, s' \in S$ , we have

$$\mathbb{P}[X_n = y | X_{n-1} = x] = \mathbb{P}[X_1 = y | X_0 = x], \quad \forall n \geq 1, \quad \forall x, y \in S.$$

In this class, we will assume all Markov processes are time-homogeneous.

To describe the distribution of a Markov process, we need only describe the distribution of  $X_0$  together with the **transition probabilities**

$$P(x, y) := \mathbb{P}(X_1 = y | X_0 = x), \quad \forall x, y \in S.$$

*Example 2.2.*

- Let  $\{Y_j\}_{j \geq 0}$  be iid RV in  $\mathbb{Z}$ . Let  $X_0 = 0$  and  $X_n = \sum_{j=1}^n Y_j$  for all  $n \geq 1$ . Then  $\{X_n\}_{n \geq 0}$  is a Markov process:  $X_n = X_{n-1} + Y_n$ . The transition probabilities are given by  $p(x, y) = \mathbb{P}(Y_1 = y - x)$ .
- Let  $S = \{0, 1\}$ . We have the restrictions

$$P(0, 0) + P(0, 1) = P(1, 0) + P(1, 1) = 1.$$

The Markov chain is thus completely characterized by the values of  $P(0, 0)$  and  $P(1, 0)$ . The transition probabilities can be represented by a graph with nodes  $S$ .



*Example 2.3* (Random Walk on a Graph). A **graph**  $G$  is a collections of **vertices**  $V(G)$  and **edges**  $E(G)$  joining pairs of vertices. We assume each vertex is incident to finitely many edges, though we allow infinitely many vertices.

A random walk on  $G$  is the Markov chain with transition probabilities given by

$$P(x, y) = \begin{cases} 1/\deg(x), & \text{if } x \text{ and } y \text{ are joined by an edge,} \\ 0, & \text{otherwise,} \end{cases} \quad \forall x, y \in V(G).$$

Here  $\deg(x)$  is the **degree** of vertex  $x$ , i.e. the number of neighbors of  $x$ .



*Example 2.4* (Simple Random Walk on  $\mathbb{Z}$ ). Let  $G = \mathbb{Z}$  with edges joining  $n$  and  $n + 1$  for each  $n \in \mathbb{Z}$ . We can equivalently describe the simple random walk on  $\mathbb{Z}$  as follows: Let  $\{Y_j\}_{j \geq 0}$  be iid RVs with  $\mathbb{P}(Y_1 = 1) = \mathbb{P}(Y_1 = -1) = 1/2$ . Let  $X_0 = 0$  and  $X_n = \sum_{j=1}^n Y_j$  for  $n \geq 1$ . Then  $\{X_n\}_{n \geq 1}$  is a simple random walk on  $\mathbb{Z}$ .



*Example 2.5* (Non-example). Let  $S = \mathbb{Z}$ . Consider  $X_0 = X_1 = X_2 = 0$ , and for each  $n \geq 3$ ,

$$X_n = \begin{cases} X_{n-1} + 1, & \text{wp } \frac{1}{3}, \\ X_{n-1} - 1, & \text{wp } \frac{1}{3}, \\ X_{n-3}, & \text{wp } \frac{1}{3}. \end{cases}$$

Then  $\{X_n\}_{n \geq 0}$  is not a Markov process.



**Definition 2.6.** The  $n$ -step transition probabilities are

$$P^n(x, y) := \mathbb{P}(X_n = y | X_0 = x), \quad \forall x, y \in S.$$

**Proposition 2.7.** For each  $n, m \in \mathbb{N}$ ,  $x, y \in S$ , we have

$$P^{n+m}(x, y) = \sum_{z \in S} P^n(x, z) P^m(z, y).$$

**Proof.**

$$\begin{aligned} P^n(x, z) P^m(z, y) &= \mathbb{P}(X_n = z | X_0 = x) \mathbb{P}(X_m = y | X_0 = z) \\ &= \mathbb{P}(X_n = z | X_0 = x) \mathbb{P}(X_{n+m} = y | X_n = z, X_0 = x) \\ &= \mathbb{P}(X_n = z, X_{n+m} = y | X_0 = x). \end{aligned}$$

The second equality follows from time-homogeneity, the third from the Markov property. Thus,

$$\begin{aligned} \sum_{z \in S} P^n(x, z) P^m(z, y) &= \sum_{z \in S} \mathbb{P}(X_n = z, X_{n+m} = y | X_0 = x) \\ &= \mathbb{P}(X_{n+m} = y | X_0 = x) = P^{n+m}(x, y). \end{aligned}$$

□

### 2.0.1 Transition Matrix

Assume now that  $S$  is finite. Without loss of generality, let  $S = \{1, 2, \dots, N\}$ .

**Definition 2.8.** The **transition matrix** of a Markov chain  $\{X_n\}_{n \geq 1}$  is the  $N \times N$  matrix  $P$  such that  $P_{i,j} = P(i, j)$ :

$$P := \begin{pmatrix} P(1, 1) & P(1, 2) & \cdots & P(1, N) \\ P(2, 1) & P(2, 2) & \cdots & P(2, N) \\ \vdots & \vdots & \ddots & \vdots \\ P(N, 1) & P(N, 2) & \cdots & P(N, N) \end{pmatrix}.$$

We write  $\pi_j = \mathbb{P}(X_0 = j)$  and define the row vector  $\pi = (\pi_1, \dots, \pi_N)$ .

**Remark 2.9.** Note that each row of  $P$  sums to 1. A matrix with this property is called a **stochastic matrix**. ☕

**Proposition 2.10.** For each  $i = 1, \dots, N$ , the  $i^{\text{th}}$  entry of the vector  $\pi P$  is  $\mathbb{P}(X_1 = i)$ .

**Proof.**

$$\begin{aligned} (\pi P)_i &= \sum_{j=1}^N \pi_j P(j, i) = \sum_{j=1}^N \mathbb{P}(X_0 = j) \mathbb{P}(X_1 = i | X_0 = j) \\ &= \sum_j \mathbb{P}(X_0 = j, X_1 = i) = \mathbb{P}(X_1 = i). \end{aligned}$$

□

**Proposition 2.11.** For each  $n \geq 1$ , the  $(P^n)_{i,j}$  is  $P^n(i, j)$ .

**Proof.** We induct on  $n$ . The base case  $n = 1$  is true by definition. Now assume  $n \geq 2$  and  $(P^{n-1})_{i,j} = P^{n-1}(i, j)$ . We have

$$\begin{aligned} (P^n)_{i,j} &= (P^{n-1}P)_{i,j} = \sum_{k=1}^N (P^{n-1})_{i,k} P_{k,j} \\ &= \sum_{k=1}^N P^{n-1}(i, k) P(k, j) = P^n(i, j). \end{aligned}$$

In the second line, the first equality comes from the induction hypothesis, the second from a previous proposition.  $\square$

*Example 2.12.* Let  $S = \{0, 1\}$ ,  $P(0, 1) = 1/3$ , and  $P(1, 0) = 1/2$ . This information completely determines the transition matrix:

$$P = \begin{pmatrix} \frac{2}{3} & \frac{1}{3} \\ \frac{1}{2} & \frac{1}{2} \end{pmatrix}.$$

Suppose we want to find the conditional distribution of  $X_3$  given  $X_0 = 0$ .

$$P^3 = \begin{pmatrix} \frac{65}{108} & \frac{43}{108} \\ \frac{43}{72} & \frac{29}{72} \end{pmatrix}.$$

We have

$$\mathbb{P}(X_3 = 0 | X_0 = 0) = (P^3)_{1,1} = \frac{65}{108}, \quad \mathbb{P}(X_3 = 1 | X_0 = 0) = (P^3)_{1,2} = \frac{43}{108}.$$



## 2.0.2 Recurrent and Transient States

**Definition 2.13.** We say states  $x, y \in S$  **communicate** (denoted  $x \leftrightarrow y$ ) if there exist  $m, n \geq 1$  such that  $P^m(x, y) > 0$  and  $P^n(y, x) > 0$ . That is, if it is possible to reach  $y$  from  $x$  and  $x$  from  $y$ .

**Proposition 2.14.** Communication is an equivalence relation on  $S$ .

**Proof.**

- (i) Reflexivity is clear since  $P^0(x, x) = 1 \geq 0$ .
- (ii) Symmetry is clear from definition.
- (iii) Transitivity: Choose  $n, m, l, k$  such that

$$P^n(x, y), P^m(y, x), P^l(y, z), P^k(z, y) > 0.$$

Then

$$P^{n+l}(x, z) = \sum_{w \in S} P^n(x, w) P^l(w, z) \geq P^n(x, y) P^l(y, z) > 0,$$

and similarly  $P^{m+k}(z, x) > 0$ .

□

**Definition 2.15** (Communication Classes, Recurrent and Transient for Finite State Space). The equivalence classes induced by communication are called **communication classes**. That is,  $x, y \in S$  belong to the same communication class if and only if  $x \leftrightarrow y$ .

A communication class  $C \subset S$  is said to be **recurrent** if  $P(x, y) = 0$  for each  $x \in C$  and each  $y \notin C$ . Otherwise,  $C$  is said to be **transient**.

*Remark 2.16.* Intuitively, a recurrent class is one that the Markov chain cannot leave. Note that this definition only works for finite state spaces. ☕

**Definition 2.17.** We say  $\{X_n\}$  is **irreducible** if there is only one communication class.

*Remark 2.18.* An irreducible Markov chain has only one recurrent class. ☕

*Example 2.19.* Fix graph  $G$  and consider the random walk  $\{X_n\}$  on  $G$ . Then two vertices  $x, y$  are in the same communication class if and only if there exists a path from  $x$  to  $y$ . Thus the communication classes are exactly the connected components of  $G$ . 📖

*Example 2.20.* Let  $S = \{1, 2, 3, 4, 5\}$  and

$$P := \begin{pmatrix} \frac{1}{5} & \frac{1}{5} & 0 & 0 & \frac{3}{5} \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & \frac{1}{2} & \frac{1}{2} & 0 \\ 0 & 0 & \frac{1}{4} & \frac{3}{4} & 0 \\ \frac{1}{2} & \frac{1}{4} & \frac{1}{4} & 0 & 0 \end{pmatrix}.$$

The matrix  $P$  can be described by a directed graph. 📖

*Example 2.21.* Consider the random walk on  $\{0, 1, \dots, N\}$  with **absorbing boundary**. That is,

$$P(x, x+1) = P(x, x-1) = \frac{1}{2}, \quad \forall x = 1, \dots, N-1,$$

and

$$P(0, 0) = P(N, N) = 1.$$

The random walk has the communication classes  $\{0\}, \{N\}, \{1, 2, \dots, N-1\}$ . The classes  $\{0\}$  and  $\{N\}$  are recurrent, while  $\{1, 2, \dots, N-1\}$  is transient. 📖

**Proposition 2.22.** Assume  $S$  is finite. Let  $C$  be a recurrent communication class. Then for each  $x, y \in C$ , we have

$$\mathbb{P}[\exists \text{ infinitely many } n \text{ such that } X_n = y | X_0 = x] = 1.$$

**Proof.** Fix  $x, y \in C$  and assume  $X_0 = x$ . Since  $C$  is a communication class, for each  $z \in C$ , there exists  $n_z \geq 0$  such that  $P^{n_z}(z, y) > 0$ . Define

$$n := \max_z n_z < \infty, \quad q := \min_z P^{n_z}(z, y) > 0.$$

For  $k \in \mathbb{N}$ , let

$$E_k = \{\exists j \in [n(k-1) + 1, nk] \text{ s.t. } X_j = y\}$$

be the event that  $X_j = y$  for some  $j$  in the  $k^{\text{th}}$  block of length  $n$ . Note that for  $s_0, \dots, s_{nk} \in C$ , we have

$$\begin{aligned}\mathbb{P}[E_{k+1}|X_0 = s_0, \dots, X_{nk} = s_{nk}] &= \mathbb{P}[E_{k+1}|X_{nk} = s_{nk}] \\ &= \mathbb{P}[E_1|X_0 = s_{nk}] \geq P^{n_{s_{nk}}}(s_{nk}, y) \geq q.\end{aligned}$$

Let  $M, N \in \mathbb{N}$  be such that  $M > N$ . Note that

$$\begin{aligned}\mathbb{P}[E_k \text{ does not occur } \forall k \in \{N, \dots, M\}] &= \mathbb{P}\left[\bigcap_{k=N}^M E_k^c\right] = \mathbb{P}\left[E_M^c \bigcap_{k=N}^{M-1} E_k^c\right] \mathbb{P}\left[\bigcap_{k=N}^{M-1} E_k^c\right] \\ &\leq (1-q) \mathbb{P}\left[\bigcap_{k=N}^{M-1} E_k^c\right] \\ &\vdots \\ &\leq (1-q)^{M-N},\end{aligned}$$

which converges to 0 as  $M \rightarrow \infty$ , with  $N$  fixed. Thus

$$\mathbb{P}[E_k \text{ does not occur for all } k \geq N] = 0.$$

from which

$$\mathbb{P}[\exists j \geq nN \text{ s.t. } X_j = y] = 1,$$

and so

$$\begin{aligned}\mathbb{P}[\exists \text{ infinitely many } n \text{ such that } X_n = y|X_0 = x] \\ = \mathbb{P}\left[\bigcap_n \{\exists j \geq nN : X_j = y\}\right] = 1,\end{aligned}$$

where the last line follows from continuity of probability measures and the fact that events  $\{\exists j \geq nN : X_j = y\}$  are decreasing in  $n$ .  $\square$

*Remark 2.23.* We showed that there exists a  $q \in (0, 1)$  and  $n \geq 1$  such that for each  $k \in \mathbb{N}$ , and each  $x, y \in C$ , we have


$$\mathbb{P}[X \text{ hits } y \text{ before time } nk|X_0 = x] \geq 1 - (1-q)^k.$$

This can be written in the following form: given  $j \geq 1$ , choose  $k$  such that  $j \in [nk, n(k+1)]$  and set

$$c := -\frac{\log(1-q)}{n}.$$

Then,

$$\mathbb{P}[X \text{ hits } y \text{ before time } j|X_0 = x] \geq 1 - (1-q)^{j/n} = 1 - e^{-cj}$$

decays exponentially fast in time. 

**Proposition 2.24.** Assume  $S$  is finite and let  $C$  be a transient communication class. Then, with probability 1,  $\{X_n\}$  eventually leaves  $C$  and never returns.



**Proof.** Similar to the previous proof; see lecture notes for details.  $\square$

*Remark 2.25.* There exists a positive  $c > 0$  such that for each  $x \in C$  and each  $j \in \mathbb{N}$ , we have

$$\mathbb{P}[\{X_n\} \text{ exits } C \text{ before time } j \mid X_0 = x] \geq 1 - e^{-cj}.$$



[Q: can have two transient classes?]

## 2.1 Stopping Times and the Strong Markov Property

**Definition 2.26** (Stopping Time). A random time  $\tau \in \mathbb{N}_0 \cup \{+\infty\}$  is a **stopping time** if for each  $n \in \mathbb{N}$ , the event  $\{\tau = n\}$  is determined by  $X_0, \dots, X_n$ .

*Remark 2.27.* Equivalent definitions of stopping time:

- For each  $n$ , the event  $\{\tau \leq n\}$  is determined by  $X_0, \dots, X_n$ . Equivalent to above since  $\{\tau \leq n\} = \cup_{j=0}^n \{\tau = j\}$  and  $\{\tau = n\} = \{\tau \leq n\} \setminus \{\tau \leq n-1\}$ .
- For each  $n$ , the event  $\{\tau > n\}$  is determined by  $X_0, \dots, X_n$ . Equivalent to above since  $\{\tau > n\} = \{\tau \leq n\}^c$ .



*Example 2.28.*


- $\tau = n$  is a non-random stopping time.
- $\tau = \min\{n \geq 0 : X_n = x\}$  for some  $x \in S$  is a stopping time, since  $\{\tau \leq n\} = \{\exists j \leq n \text{ s.t. } X_j = x\}$  is determined by  $X_0, \dots, X_n$ .
- $\tau :=$  the  $k^{\text{th}}$  time such that  $X_j \in A$  for fixed  $k \in \mathbb{N}$  and  $A \subset S$  is a stopping time.
- The minimum of two stopping times is a stopping time, since

$$\{\min\{\tau_1, \tau_2\} \leq n\} = \{\tau_1 \leq n\} \cup \{\tau_2 \leq n\}.$$



*Example 2.29* (Non Example). Let  $N \in \mathbb{N}$  and  $x \in S$ . Let

$$\tau := \text{last } n \leq N \text{ such that } X_n = x.$$

This is not a stopping time since if we see only  $X_0, \dots, X_n$  for some  $n \leq N-1$ , we cannot tell whether we visit  $x$  between time  $n$  and  $N$ . 

Let  $\{X_n\}$  be a Markov chain with a countable state space  $S$ . For each  $x_0, \dots, x_n \in S$  and  $y_1, \dots, y_m \in S$ , we have

$$\begin{aligned} & \mathbb{P}[X_{n+1} = y_1, \dots, X_{n+m} = y_m \mid X_0 = x_0, \dots, X_n = x_n] \\ &= \mathbb{P}[X_{n+1} = y_1, \dots, X_{n+m} = y_m \mid X_n = x_n] \\ &= \mathbb{P}(x_n, y_1) \prod_i P(y_{i-1}, y_i). \end{aligned}$$

It turns out that this property works also for random stopping times.

**Theorem 2.30** (The Strong Markov Property). *Let  $\tau$  be a stopping time. Let  $n \geq 0$ ,  $m \geq 1$ ,  $x_0, \dots, x_n \in S$  be such that  $\mathbb{P}[X_0 = x_0, \dots, X_\tau = x_n] > 0$ . Then,*

$$\begin{aligned} & \mathbb{P}[X_{\tau+1} = y_1, \dots, X_{\tau+m} = y_m | X_0 = x_0, \dots, X_\tau = x_n] \\ &= \mathbb{P}[X_{\tau+1} = y_1, \dots, X_{\tau+m} = y_m | X_\tau = x_n]. \end{aligned}$$

**Proof.** Note that

$$\begin{aligned} \{X_0 = x_0, \dots, X_\tau = x_n\} &= \{\tau = n\} \cap \{X_0 = x_0, \dots, X_n = x_n\} \\ &= \{X_0 = x_0, \dots, X_n = x_n\}, \end{aligned}$$

where the last equality follows since the event  $\{\tau = n\}$  is determined by  $X_0, \dots, X_n$ . Thus,

$$\begin{aligned} & \mathbb{P}[X_{\tau+1} = y_1, \dots, X_{\tau+m} = y_m | X_0 = x_0, \dots, X_\tau = x_n] \\ &= \mathbb{P}[X_{n+1} = y_1, \dots, X_{n+m} = y_m | X_0 = x_0, \dots, X_n = x_n] \\ &= \mathbb{P}[X_{n+1} = y_1, \dots, X_{n+m} = y_m | X_n = x_n], \end{aligned}$$

where the last equality following from the Markov property.  $\square$

*Example 2.31.* Let  $x \in S$  and define  $\tau := \min\{n \geq 0 : X_n = x\}$ . Assume further that  $\mathbb{P}(\tau < \infty) = 1$ . For each  $y_1, \dots, y_m \in S$  and  $x_0, \dots, x_n \in S$  such that  $\mathbb{P}(X_0 = x_0, \dots, X_\tau = x_n) > 0$ . Note that  $x_n = x$  by definition of  $\tau$ . The strong Markov property gives

$$\mathbb{P}(X_{\tau+1} = y_1, \dots, X_{\tau+m} = y_m | X_0 = x_0, \dots, X_\tau = x_n) = \mathbb{P}(X_1 = y_1, \dots, X_m = y_m | X_0 = x).$$



**Proposition 2.32.** *Suppose  $X_0 = x \in S$  and assume*

$$\mathbb{P}[\{X_n\} \text{ visits } x \text{ infinitely often}] = 1.$$

*Let  $\tau_k$  be the  $k^{\text{th}}$  time  $n$  such that  $X_n = x$ , and set  $\tau_0 = 0$ . Then the increments  $\{(X_{\tau_k}, \dots, X_{\tau_{k+1}})\}_{k \in \mathbb{N}_0} \in \cup_{j=1}^\infty S^j$  are iid.*

**Proof.** Observe first that each  $\tau_k$  is a stopping time and  $X_{\tau_k} = x$ . This implies that the conditional distribution of  $\{X_{\tau_k+j}\}_{j \geq 0}$  given everything before time  $\tau_k$  is the same as the distribution of  $\{X_j\}_{j \geq 0}$  given  $X_0 = x$ .

Observe also that  $\tau_{k+1} - \tau_k$  is the first time  $j \geq 1$  such that  $X_{\tau_k+j} = x$ . Thus the conditional distribution of  $(X_{\tau_k}, \dots, X_{\tau_{k+1}})$  given everything before time  $\tau_k$  is the same as the distribution of  $(X_0, \dots, X_{\tau_1})$ , which implies that the increments are iid.  $\square$

**Definition 2.33.** We say a random variable  $M$  in  $\mathbb{N}$  has the **geometric distribution** with **success probability**  $p \in (0, 1)$  if

$$\mathbb{P}(M = m) = p(1-p)^{m-1}, \quad \forall m \geq 1.$$

**Proposition 2.34.** *Suppose  $X_0 = x \in S$  and  $\mathbb{P}(X_n \text{ visits } x \text{ infinitely often}) = 1$ . Let  $y$  be a state such that  $x \leftrightarrow y$ . Let  $M$  be the number of times we visit  $x$  before visiting  $y$ . Then  $M$  has a geometric distribution.*

**Proof.** Let  $\tau_k$  be the  $k^{\text{th}}$  time  $n$  such that  $X_n = x$ , and set  $\tau_0 = 0$ . Then  $\{(X_{\tau_k}, \dots, X_{\tau_{k+1}})\}_{k \geq 0}$  are iid. Now,  $M$  is the smallest  $k$  such that  $(X_{\tau_k}, \dots, X_{\tau_{k+1}})$  visits  $y$  and is hence a geometric random variable.  $\square$


## 2.2 Periodicity


Let  $\{X_n\}$  be a Markov chain and the state space  $S$  be countable.

**Definition 2.35.** For a state  $x \in S$ , the **period** of  $x$  is

$$d(x) := \gcd(J_x), \quad \text{where } J_x := \{n \geq 1 : P^n(x, x) > 0\}.$$

Note that if  $P(x, x) > 0$ , then  $d(x) = 1$ .

*Example 2.36.* A graph  $G$  is said to be **bipartite** if  $V(G) = V_1 \cup V_2$ ,  $V_1 \cap V_2 = \emptyset$ ,  $V_1, V_2$  nonempty, and every edge goes from  $V_1$  to  $V_2$ . 

*Example 2.37.*  $\mathbb{Z}$  is bipartite with  $V_1 = \{\text{odd}\}$  and  $V_2 = \{\text{even}\}$ . 

*Remark 2.38.* For a random walk on a connected graph  $G$ , we always have  $2 \in J_x$ . It turns out that bipartite graphs are precisely those for which any path starting and ending at the same vertex must have even length.

- If  $G$  is connected and bipartite, then  $d(x) = 2$  for the random walk on  $G$  for each  $x \in V(G)$ .
- If  $G$  is connected and not bipartite, then  $d(x) = 1$  for each  $x \in V(G)$ , since  $J_x$  contains both 2 and an odd number.



**Lemma 2.39** ( $J_m$  is closed under addition). *If  $n, m \in J_m$ , then  $n + m \in J_x$ .*

**Proof.** We have  $P^{n+m}(x, x) \geq P^n(x, x)P^m(x, x) > 0$ . □

**Proposition 2.40.** *The set  $J_x$  contains  $kd(x)$  for all sufficiently large  $k$ .*

**Proof.** Via previous lemma and Bezout's identity: if  $d := \gcd(a, b)$ , then there exists integers  $x, y$  such that  $xa + yb = d$ . □

**Proposition 2.41** (The Period is a Class Property). *If  $x \leftrightarrow y$ , then  $d(x) = d(y)$ .*

**Proof.** Choose  $n, m$  such that  $P^n(x, y) > 0$  and  $P^m(y, x) > 0$ . This implies that  $P^{n+m}(x, x) \geq P^n(x, y)P^m(y, x) > 0$ . Similarly  $P^{n+m}(y, y) > 0$ . This gives  $n + m \in J_x \cap J_y$  and so  $d(x)$  and  $d(y)$  both divide  $n + m$ . Assume for contradiction that  $d(x) < d(y)$ . Then there exists  $k \in J_x$  not divisible by  $d(y)$ . Observe that

$$P^{n+m+k}(y, y) \geq P^m(y, x)P^k(x, x)P^n(x, y) > 0,$$

implying  $n + m + k \in J_y$ . Since however that  $n + m \in J_y$ , we know  $d(y)$  divides the difference  $k$ , a contradiction. □

**Definition 2.42.** We say a Markov chain  $\{X_n\}$  is **aperiodic** if  $d(x) = 1$  for all  $x \in S$ .

This is often a “nice” property.

*Remark 2.43.* The propositions above imply the following:

- If  $\{X_n\}$  is irreducible (i.e., any two states communicate), then to check aperiodicity, it suffices to check  $d(x) = 1$  for any  $x \in S$ .
- If  $\{X_n\}$  is aperiodic, then  $P^n(x, x) > 0$  for any large enough  $n$  (depending on  $x$ ).
- For any Markov chain  $\{X_n\}$ , we can construct the following “lazy” Markov chain  $\{\tilde{X}_n\}$  with transition matrix

$$\tilde{P}(x, y) := \begin{cases} \frac{1}{2}P(x, y), & x \neq y \\ \frac{1}{2} + \frac{1}{2}P(x, x), & x = y \end{cases},$$

which is always aperiodic since  $\tilde{P}(x, x) > 0$  for each  $x \in S$ .



## 2.3 Stationary Distribution, Finite State Space

**Definition 2.44.** Let  $\pi : S \rightarrow [0, 1]$  be such that  $\sum_{x \in S} \pi_x = 1$ . We say that  $\pi$  is a **stationary (or invariant) distribution** for the Markov chain  $\{X_n\}$  if  $\pi_y = \sum_{x \in S} \pi_x P(x, y)$  for each  $y \in S$ .

*Remark 2.45* (Equivalent definitions). Suppose  $S = \{1, \dots, N\}$  and  $\pi = (\pi_1, \dots, \pi_N)$  is a row vector.

- Then  $\pi$  is a stationary distribution if and only if  $\sum_j \pi_j = 1$  and  $\pi P = \pi$ . That is,  $\pi$  is a stationary distribution if and only if it is a left eigenvector of  $P$  with eigenvalue 1.
- If  $\mathbb{P}(X_0 = x) = \pi_x$  for each  $x \in S$ , then  $\mathbb{P}(X_1 = y) = \pi_y$ .  
To see the equivalence, note that if  $X_1 \sim \pi$ , then  $\mathbb{P}(X_1 = y) = \sum_x \pi_x P(x, y)$  equals  $\pi_y$  if and only if  $\pi$  is a stationary distribution. Induction gives the following:
- If  $\mathbb{P}(X_0 = x) = \pi_x$  for all  $x \in S$ , then  $X_n \sim \pi$  for each  $n \in \mathbb{N}$ .



Recall the following:


- $\{X_n\}$  is irreducible if  $\forall x, y \in S$  there exists  $n \in \mathbb{N}_0$  such that  $P^n(x, y) > 0$ .
- $\{X_n\}$  is aperiodic if  $\forall x \in S, \gcd(\{n \geq 1; P^n(x, x) > 0\}) = 1$ .
- Period is a class property: if  $x \leftrightarrow y$ , then  $d(x) = d(y)$ .

**Theorem 2.46.** Suppose  $S$  is finite and  $\{X_n\}$  is irreducible and aperiodic. Then there exists a unique stationary distribution  $\pi$ . Moreover, for each  $x, y \in S$ , we have

$$\lim_{n \rightarrow \infty} P^n(x, y) = \pi_y.$$

*Remark 2.47.*


- A probabilistic proof will be given below, though a linear algebra proof (using the Perron-Frobenius theorem) is also possible.
- $\pi_x$  is the long-run proportion of time that the Markov chain spends in state  $x$ . This is useful for sampling algorithms.

*Example 2.48.* Suppose we have a probability distribution  $\pi$  on a large state space  $S$ . We may find a Markov chain  $\{X_n\}$  on  $S$  whose stationary distribution is  $\pi$  and run it for a long time to approximately sample from  $\pi$ . 



*Example 2.49.* Let  $S = \{1, 2, 3\}$  and set

$$P := \begin{pmatrix} \frac{1}{3} & \frac{1}{3} & \frac{1}{3} \\ \frac{1}{2} & 0 & \frac{1}{2} \\ \frac{1}{5} & \frac{1}{5} & \frac{3}{5} \end{pmatrix}.$$

To find the stationary distribution, we need to solve  $\pi P = \pi$  and  $\sum_x \pi_x = 1$ . This gives  $\pi = (3/10, 1/5, 1/2)$ . 

**Proposition 2.50** (The Stationary Distribution Exists). *Suppose  $S$  is finite and  $\{X_n\}$  is irreducible. Assume  $X_0 = z \in S$  and set  $T = \min\{n \geq 1 : X_n = z\}$ . For  $x \in S$ , let  $\tilde{\pi}(x) := \mathbb{E}[\#\{n \in \{0, \dots, T-1\} : X_n = x\}]$ . Let  $\pi_x := \tilde{\pi}_x / \mathbb{E}[T]$ . Then  $\pi$  is a stationary distribution of  $\{X_n\}$ .*

**Proof.** Note first that

$$\sum_{x \in S} \tilde{\pi}_x = \mathbb{E}[\#\{n \in \{0, \dots, T-1\} : X_n \in S\}] = \mathbb{E}[T],$$

which gives  $\sum \pi_x = 1$ . It remains thus to show

$$\tilde{\pi}_y = \sum_x \tilde{\pi}_x P(x, y), \quad \forall y \in S.$$

Note that

$$\tilde{\pi}_x = \mathbb{E}\left[\sum_{n=0}^{T-1} \mathbb{1}_{\{X_n=x\}}\right] = \mathbb{E}\left[\sum_{n=0}^{\infty} \mathbb{1}_{\{X_n=x, T>n\}}\right] = \sum_{n=0}^{\infty} \mathbb{P}[X_n = x, T > n],$$

where the exchange of sum and expectation is justified since the summands are nonrandom. Now note that

$$\begin{aligned} \sum_x \tilde{\pi}_x P(x, y) &= \sum_{x \in S} \sum_{n=0}^{\infty} \mathbb{P}[X_n = x, T > n] P(x, y) \\ &= \sum_{n=0}^{\infty} \sum_{x \in S} \mathbb{P}[X_n = x, T > n] \mathbb{P}[X_{n+1} = y | X_n = x, T > n] \\ &= \sum_{n=0}^{\infty} \sum_{x \in S} \mathbb{P}[X_{n+1} = y, X_n = x, T > n] = \sum_{n=0}^{\infty} \mathbb{P}[X_{n+1} = y, T > n], \end{aligned}$$

where the second equality follows from the fact that  $T$  is a stopping time and depends only on  $X_0, \dots, X_n$ . If  $y \neq z$ , the above can be simplified to

$$\begin{aligned} \sum_{x \in S} \tilde{\pi}_x P(x, y) &= \sum_{n=0}^{\infty} \mathbb{P}[X_{n+1} = y, T > n+1] = \sum_{m=1}^{\infty} \mathbb{P}[X_m = y, T > m] \\ &= \tilde{\pi}_y - \mathbb{P}[T > 0, X_0 = y] = \tilde{\pi}_y, \end{aligned}$$

where the last equality follows since  $X_0 = z \neq y$ . If  $y = z$ , we have

$$\sum_{x \in S} \tilde{\pi}_x P(x, z) = \sum_{n=0}^{\infty} \mathbb{P}[T = n+1] = 1 = \tilde{\pi}_z.$$

□

**Proposition 2.51** (The Stationary Distribution is Unique). *Let  $\{X_n\}$  be irreducible and aperiodic with finite state space  $S$ . If  $\pi$  is a stationary distribution, then for each  $x, y \in S$ , we have  $\lim_{n \rightarrow \infty} P^n(x, y) = \pi_y$ . In particular,  $\pi$  is unique.*

**Proof.** We consider a coupling of the original Markov chain starting at  $x$  and the same Markov chain starting from  $X_0 \sim \pi$ . We will show that with probability 1, the two chains meet at some finite time and then move together forever after.

Specifically, consider the Markov chain  $(X_n, Y_n)$  on  $S \times S$  with transition probability given by

$$\bar{P}((x, y), (x', y')) := \begin{cases} P(x, y)P(x', y'), & x \neq y \\ P(x, x'), & x = y, x' = y' \\ 0, & \text{otherwise} \end{cases}$$

We check that this is indeed a coupling:

$$\begin{aligned} \mathbb{P}[X_1 = x' | X_0 = x, Y_0 = y] &= \mathbb{P}(x, x') \sum_{y' \in S} P(y, y') = P(x, x'), & \text{if } x \neq y \\ \mathbb{P}(X_1 = x' | X_0 = x, Y_0 = y) &= P(x, x'), & \text{if } x = y \end{aligned}$$

A similar calculation holds for  $Y_1$ . Now let  $\tau := \min\{n \geq 0 : X_n = Y_n\}$ . By definition, we know that  $X_n = Y_n$  for each  $n \geq \tau$ .

*Claim 2.52.*  $\mathbb{P}[\tau < \infty | X_0 = x, Y_0 = y] = 1$  for arbitrary  $x, y \in S$ .

Taking this claim as given for now, we consider the initial distribution where  $X_0 = x \in S$  and  $Y_0 \sim \pi$ . Since  $\pi$  is a stationary distribution, we know that  $Y_n \sim \pi$  for each  $n$ . Since also  $X_n = Y_n$  for any large enough  $n$ , we have  $\lim_{n \rightarrow \infty} \mathbb{P}[X_n = Y_n] = 1$ . Now,

$$\lim_{n \rightarrow \infty} (\mathbb{P}[X_n = y | X_0 = x] - \pi_y) = \lim_{n \rightarrow \infty} (\mathbb{P}[X_n = y | X_0 = x] - \mathbb{P}[Y_n = y]) = 0.$$

We now return to the proof of Claim 2.52: We consider  $\{\tilde{X}_n\}$  and  $\{\tilde{Y}_n\}$ , two independent copies of the original Markov chain with  $\tilde{X}_0 = x$  and  $\tilde{Y}_0 = y$ . It suffices to show that

$$\mathbb{P}\{\exists n : \tilde{X}_n = \tilde{Y}_n\} = 1.$$

It suffices to show that  $(\tilde{X}_n, \tilde{Y}_n)$  is an irreducible Markov chain on  $S \times S$ , since in that case it will visit the diagonal  $\{(z, z) : z \in S\}$  infinitely often with probability 1 by irreducibility and finiteness of  $S$ .

Recall that aperiodicity implies that there exists a  $k_0 \in \mathbb{N}$  such that  $P^k(x, x) > 0$  for each  $k \geq k_0$  and  $x \in S$ . Irreducibility implies that for each  $x, x', y, y' \in S$ , there exists  $n$  such that  $P^n(x, x') > 0$ . Furthermore, there exists a  $m \geq n + k_0$  such that  $P^m(y, y') > 0$ . Since  $\tilde{X}_m$  and  $\tilde{Y}_m$  are independent by definition, we see that

$$\begin{aligned} \mathbb{P}\{(\tilde{X}_m, \tilde{Y}_m) = (x', y') | (\tilde{X}_0, \tilde{Y}_0) = (x, y)\} &= P^m(x, x')P^m(y, y') > 0 \\ &\geq P^{m-n}(x, x)P^n(x, x')P^m(y, y') > 0, \end{aligned}$$

where the second line follows from  $m - n \geq k_0$ . This implies that  $(\tilde{X}_n, \tilde{Y}_n)$  is irreducible. Thus with probability 1, there exists  $n$  such that  $(\tilde{X}_n, \tilde{Y}_n) = (x, x)$ .  $\square$

*Example 2.53.* The stationary distribution for the random walk on a finite connected nonbipartite graph  $G$  is given by

$$\pi_x = \frac{\deg(x)}{2\#E}, \quad x \in V(G).$$

We check that  $\pi_x$  is a distribution:

$$\sum_{x \in V} \pi_x = \frac{1}{2\#E} \sum_{x \in V} \deg(x) = 1.$$

And that it is stationary: for  $y \in V$ ,

$$\sum_{x \in V} \pi_x P(x, y) = \sum_{x \sim y} \frac{\deg(x)}{2\#E} \cdot \frac{1}{\deg(x)} = \frac{1}{2\#E} \sum_{x \sim y} 1 = \frac{\deg(y)}{2\#E} = \pi_y.$$



### 3 Markov Chains with Countable State Space

Now consider the case where  $S$  is countably infinite.

#### 3.1 Reducibility and Recurrence

**Definition 3.1.** We say  $\{X_n\}$  is **irreducible** if for each  $x, y \in S$ , there exists  $n \geq 0$  such that  $P^n(x, y) > 0$ .

**Definition 3.2.** We say a state  $x \in S$  is **recurrent** if  $\mathbb{P}[\exists \text{ infinitely many } n : X_n = x | X_0 = x] = 1$ , and **transient** otherwise.

A particular difference of the case of countable state space is that irreducibility no longer imply recurrence, as we will see.

**Proposition 3.3.** *If  $\{X_n\}$  is irreducible, then either all states are recurrent or all states are transient. In particular, it makes sense to say that  $\{X_n\}$  is **recurrent** or **transient**.*

**Proof.** Assume first there exists recurrent state  $x$ . Let  $\tau_0 = 0$  and set

$$\tau_k := k^{\text{th}} \text{ smallest } n \text{ such that } X_n = x.$$

By assumption, we have  $\mathbb{P}(\tau_k < \infty | X_0 = x) = 1$  for each  $k$ . By the strong Markov property, we have

$$(X_{\tau_k}, \dots, X_{\tau_{k+1}}) \in \bigcup_{j \in \mathbb{N}} S^j$$

are iid. Let  $y \in S$ . Since  $\{X_n\}$  is irreducible, there exists  $n$  such that  $P^n(x, y) > 0$ . Thus there exists  $k$  such that  $\mathbb{P}(y \in \{X_{\tau_k}, \dots, X_{\tau_{k+1}}\}) > 0$ . Since the intervals are iid, we have  $q := \mathbb{P}(y \in \{X_{\tau_k}, \dots, X_{\tau_{k+1}}\}) > 0$  for each  $k$ . The events

$$\{y \in \{X_{\tau_k}, \dots, X_{\tau_{k+1}}\}\}$$

are iid, each with probability  $q$ . Thus with probability 1, infinitely many of these events occur, which implies that  $y$  is recurrent. That is,

$$\mathbb{P}[\exists \text{ infinitely many } n \text{ such that } X_n = y | X_0 = x] = 1.$$

Let  $\sigma := \min\{n \geq 0 : X_n = y\}$ . We know  $\mathbb{P}[\sigma < \infty | X_0 = y] = 1$ . By the strong Markov property,  $\{X_{\sigma+j}\}_{j \geq 0}$  has the same distribution as  $\{X_j\}_{j \geq 0}$  given  $X_0 = y$ . This implies that the Markov chain starting at  $y$  visits  $x$  infinitely often with probability 1.  $\square$

**Proposition 3.4.** *A state  $x$  is recurrent if and only if  $\sum_{n=0}^{\infty} P^n(x, x) = \infty$ . Moreover, if  $x$  is transient, then with probability 1, the Markov chain  $\{X_n\}$  visits  $x$  only finitely many times. Thus  $\mathbb{P}(\exists \text{ infinitely many } n : X_n = x | X_0 = x)$  is either 0 or 1.*

**Proof.** Let  $R_x := \sum_{n=0}^{\infty} \mathbb{1}_{\{X_n = x\}}$  be the number of times  $\{X_n\}$  visits  $x$ . Note that

$$\mathbb{E}[R_x | X_0 = x] = \sum_{n=0}^{\infty} \mathbb{P}[X_n = x | X_0 = x] = \sum_{n=0}^{\infty} P^n(x, x).$$



If  $\sum_{n=0}^{\infty} P^n(x, x) < \infty$ , then  $\mathbb{E}[R_x] < \infty$ , which implies that  $R_x < \infty$  with probability 1.

For the converse. Assume  $x$  is a transient state. We will show that  $\sum_{n=0}^{\infty} P^n(x, x) < \infty$ . Let  $\tau_0 = 0$  and set  $\tau_k$  to be the  $k^{\text{th}}$  time such that  $X_n = x$ . Since  $x$  is transient, there exists  $k$  such that  $\mathbb{P}(\tau_k = \infty | X_0 = x) > 0$ . By the strong Markov property, we have for each  $k$  that

$$\mathbb{P}[\tau_{k+1} - \tau_k = \infty | \tau_k < \infty] =: q > 0.$$

Note that the number of visits to  $x$  is  $R_x := \min\{k : \tau_{k+1} = \infty\}$ . Thus  $R_x$  has a geometric distribution with success probability  $q$ . In particular,  $\mathbb{E}[R_x | X_0 = x] = 1/q < \infty$ , which gives  $\sum_{n=0}^{\infty} P^n(x, x) < \infty$ . Note that this also implies that with probability 1, the Markov chain visits  $x$  only finitely many times.  $\square$

Note that in light of the previous two propositions, if  $\{X_n\}$  is irreducible, to check recurrence, it suffices to check if  $\sum_{n=0}^{\infty} P^n(x, x)$  is infinite for some  $x \in S$ .

*Example 3.5.* Let  $S = \mathbb{N}_0$  and set

$$P(x, 0) = \frac{1}{x+2}, \quad P(x, x+1) = 1 - \frac{1}{x+2}, \quad \forall x \geq 0.$$

This Markov chain is irreducible. To check recurrence, we compute  $\sum P^n(0, 0)$ . Assume  $X_0 = 0$  and note that  $X_n \leq n$ . Thus  $P^n(0, 0) = \mathbb{P}[X_n = 0 | X_0 = 0] \geq 1/(n+1)$ , which gives  $\sum P^n(0, 0) = \infty$ . Thus the Markov chain is recurrent.

Alternatively, let  $\tau := \min\{n \geq 1 : X_n = 0\}$ . It suffices to show that  $\mathbb{P}[\tau < \infty] = 1$ . To do this, we need only show  $\lim_{N \rightarrow \infty} \mathbb{P}(\tau > N) = 0$ . Note that  $\tau > N$  if and only if the first  $N$  steps are upward. Thus

$$\mathbb{P}[\tau > N] = \prod_{k=0}^{N-1} \left(1 - \frac{1}{k+2}\right).$$

Taking logs, we have

$$\log \mathbb{P}[\tau > N] = \sum_{k=0}^{N-1} \log \left(1 - \frac{1}{k+2}\right) = - \sum_{k=0}^{N-1} \left( \frac{1}{n+2} + O\left(\frac{1}{(n+2)^2}\right) \right) \rightarrow -\infty.$$

This implies that  $\mathbb{P}[\tau > N] \rightarrow e^{-\infty} = 0$  as  $N \rightarrow \infty$ . 

### 3.2 Biased Random Walk

**Proposition 3.6** (Biased Random Walk). *Consider the biased random walk on  $\mathbb{Z}$  with*

$$P(x, x+1) = p, \quad P(x, x-1) = 1-p, \quad \forall x \in \mathbb{Z},$$

*Let  $N \geq 1$ . For  $x \in \{0, \dots, N\}$ , we have*

$$\mathbb{P}[\{X_n\} \text{ hits } N \text{ before } 0 | X_0 = x] = \begin{cases} \left(\frac{1-p}{p}\right)^x - 1, & p \neq \frac{1}{2}; \\ \frac{x}{N}, & p = \frac{1}{2}. \end{cases}$$

**Proof.** Let  $\alpha(x) := \mathbb{P}[\{X_n\} \text{ hits } N \text{ before } 0 | X_0 = x]$ . Note that  $\alpha(0) = 0$ ,  $\alpha(N) = 1$ , and for each  $x \in \{1, \dots, N-1\}$ , we have

$$\alpha(x) = p\alpha(x+1) + (1-p)\alpha(x-1).$$

This gives a system of  $N+1$  equations in  $N+1$  unknowns.

When  $p = 1/2$ , we have

$$\alpha(x) = \frac{\alpha(x+1) + \alpha(x-1)}{2}, \quad x \in \{1, \dots, N-1\}.$$

Thus  $\alpha(x)$  is affine in  $x$ . Suppose  $\alpha(x) = \alpha + \beta x$  and plugging in the boundary conditions gives  $\alpha = 0$  and  $\beta = 1/N$ , as desired.

When  $p \neq 1/2$ , we use the ansatz  $\alpha(x) = b^x$ . Plugging this in gives

$$b^x = pb^{x+1} + (1-p)b^{x-1} \iff pb^2 - b + (1-p) = 0.$$

Solving this quadratic gives roots  $b = 1$  and  $b = (1-p)/p$ . The general solution is thus

$$\alpha(x) = c_1 + c_2 \left( \frac{1-p}{p} \right)^x.$$

Plugging in the boundary conditions gives

$$c_1 = -c_2 = \left( 1 - \left( \frac{1-p}{p} \right)^N \right)^{-1}.$$

□

**Corollary 3.7.** *For each  $x \geq 1$*

$$\mathbb{P}[\{X_n\} \text{ hits } 0 | X_0 = x] = \begin{cases} 1, & p \leq \frac{1}{2}; \\ \left( \frac{1-p}{p} \right)^x, & p > \frac{1}{2}. \end{cases}$$

**Proof.** Send  $N \rightarrow \infty$  in the previous proposition. □

**Corollary 3.8.** *A biased random walk is recurrent if  $p = 1/2$  and transient otherwise.*

**Proof.** Note first that the biased random walk is irreducible. If  $p > 1/2$ , then  $\{X_n\}$  has a positive chance to never hit 0 and so is transient. If  $p < 1/2$ , then  $\{-X_n\}$  is a biased random walk with parameter  $1-p > 1/2$  and so is transient. If  $p = 1/2$ , then  $\{X_n\}$  has by the previous corollary a probability 1 of hitting 0 no matter where it starts, and so is recurrent. □

### 3.3 A Queuing Model

At each time  $n \geq 1$ , the following events occur independently from each other and from the past, in the following order:

- With probability  $q$ , if there is at least one person, then one person is served and leaves the queue.
- With probability  $p$ , a new person arrives and joins the queue.

Let  $X_n$  denote the number of people in queue at time  $n$ . Note that  $\{X_n\}$  is a Markov chain on  $S := \mathbb{N}_0$  with transition probabilities

$$\begin{aligned} P(0, 1) &= p, & P(0, 0) &= 1 - p, \\ P(x, x - 1) &= q(1 - p), & P(x, x + 1) &= p(1 - q), \quad \forall x \geq 1. \end{aligned}$$

Observe that this Markov chain is irreducible.

**Proposition 3.9.**  $\{X_n\}$  is recurrent if  $q \geq p$ .

**Proof.** We will reduce to the biased random walk. Let  $\tau_k$  be the  $k^{\text{th}}$  time such that  $X_{n-1} \neq X_n$ . Note that  $\tau_k$  is a stopping time, and thus we have

$$\begin{aligned} \mathbb{P}[X_{\tau_k} = x + 1 | X_{\tau_k} = x] &= \mathbb{P}[X_1 = x + 1 | X_0 = x, X_1 \neq X_0] \\ &= \frac{P(x, x + 1)}{1 - P(x, x)} = \frac{p(1 - q)}{p(1 - q) + q(1 - p)}. \end{aligned}$$

Since

$$\mathbb{P}[X_{\tau_k} = x + 1 | X_{\tau_k} = x] = \mathbb{P}[X_{\tau_k} = x + 1 | X_{\tau_{k-1}} = x],$$

and  $\tau_k - 1$  is not a stopping time, we cannot omit the extra conditioning above. Similar to the calculation above, we have

$$\mathbb{P}[X_{\tau_k} = x + 1 | X_{\tau_k} = x] = 1 - \frac{p(1 - q)}{p(1 - q) + q(1 - p)}.$$

Thus  $\{X_{\tau_k}\}_{k \geq 0}$  is a biased random walk with parameter

$$\frac{p(1 - q)}{p(1 - q) + q(1 - p)}$$

until it hits 0. Thus  $\{X_{\tau_k}\}$  eventually hits 0 with probability 1 if and only if

$$\frac{p(1 - q)}{p(1 - q) + q(1 - p)} \leq \frac{1}{2} \iff q \geq p,$$

and so  $\{X_n\}$  has probability 1 of eventually hitting 0 if and only if  $q \geq p$ .  $\square$

### 3.4 Stationary Distribution

**Definition 3.10.** Let  $S$  be countable. We say  $\pi : S \rightarrow [0, 1]$  is a **stationary distribution** for the Markov chain  $\{X_n\}$  if  $\sum_{x \in S} \pi_x = 1$  and for each  $y \in S$ , we have  $\sum_{x \in S} \pi_x P(x, y) = \pi_y$ .

Recall that for a *finite*  $S$ , there exists a unique stationary distribution if  $\{X_n\}$  is irreducible and aperiodic. When  $S$  is countably infinite, we need stronger assumptions.

**Proposition 3.11.** *If  $\{X_n\}$  is irreducible and transient, then there does not exist a stationary distribution.*

**Proof.** Then for each  $x, y \in S$ ,

$$\mathbb{P}[\{X_n\} \text{ visits } y \text{ finitely many times} | X_0 = x] = 1.$$

This implies that  $P^n(x, y) \rightarrow 0$  as  $n \rightarrow \infty$ . Now if  $\pi$  is a stationary distribution, then for each  $n \in \mathbb{N}$ ,

$$\pi_y = \sum_{x \in S} \pi_x P^n(x, y) \rightarrow 0 \text{ as } n \rightarrow \infty,$$

which implies that  $\pi_y = 0$  for each  $y \in S$ , a contradiction.  $\square$

**Definition 3.12.** Assume  $\{X_n\}$  is irreducible and recurrent. We say  $\{X_n\}$  is **null recurrent** if  $\lim_{n \rightarrow \infty} P^n(x, y) = 0$  for each  $x, y \in S$ . We say  $\{X_n\}$  is **positive recurrent** otherwise.

Note that the same argument above shows that null recurrent Markov chains do not have a stationary distribution.

**Proposition 3.13.** *Assume  $\{X_n\}$  is irreducible. Then the following are equivalent:*

- (i)  $\{X_n\}$  is positive recurrent.
- (ii)  $\{X_n\}$  has a stationary distribution.
- (iii)  $\limsup_{n \rightarrow \infty} P^n(x, y) > 0$  for all (or equivalently, some)  $x, y \in S$ .
- (iv) If  $T_x := \min\{n \geq 1 : X_n = x\}$ . Then  $\mathbb{E}[T_x | X_0 = x] < \infty$  for all  $x \in S$ .

Furthermore, if  $\{X_n\}$  is aperiodic and positively recurrent, then the stationary distribution is unique and

$$\pi_y = \lim_{n \rightarrow \infty} P^n(x, y) = \frac{1}{\mathbb{E}[T_y | X_0 = y]}, \quad \forall x, y \in S.$$

**Proof.** Basically the same as the finite case.  $\square$

We summarize the characterization of recurrence in the following proposition: If  $\{X_n\}$  is irreducible, then for any  $x \in S$ , we have

- (i) Transient  $\iff \sum P^n(x, x) < \infty$ .
- (ii) Null recurrent  $\iff \sum P^n(x, x) = \infty$  and  $P^n(x, x) \rightarrow 0$ .
- (iii) Positive recurrent  $\iff \limsup P^n(x, x) > 0 \iff \mathbb{E}[T_x | X_0 = x] < \infty \iff$   
there exists a stationary distribution.

*Example 3.14* (Biased Random Walk with Partially Reflecting Boundary). Consider the based random walk on  $\mathbb{N}_0$  with partially reflected boundary:

$$\begin{aligned} P(0, 0) &= 1 - p, & P(0, 1) &= p, \\ P(x, x-1) &= 1 - p, & P(x, x+1) &= p, & \forall x \geq 1. \end{aligned}$$

It is clear that this Markov chain is irreducible. Since  $P(0,0) = 1 - p$ , it is also aperiodic.

It is positive recurrent, null recurrent, or transient?

- (i) If  $p > 1/2$ , it is transient since it has a positive probability of never hitting 0 if  $X_0 \geq 1$ .
- (ii) If  $p \leq 1/2$ , we know that it is recurrent. To see if it is null or positive recurrent, we try to find a stationary distribution  $\pi$ . Recall that  $\pi$  must satisfy

$$\begin{aligned}\pi_0 &= (1 - p)\pi_0 + p_1\pi_1, \\ \pi_y &= p\pi_{y-1} + (1 - p)\pi_{y+1}, \quad \forall y \geq 1.\end{aligned}$$

If  $p < 1/2$ , it turns out that the general solution to the above is given by

$$\pi_y = c_1 + c_2 \left( \frac{p}{1-p} \right)^y, \quad y \geq 1.$$

Since also  $\sum_y \pi_y = 1$ , we have  $c_1 = 0$  and

$$1 = c_2 \sum \left( \frac{p}{1-p} \right)^y = \frac{c_2}{1 - \frac{p}{1-p}}.$$

Thus  $c_2 = 1 - p/(1 - p)$  and

$$\pi_y = \left( 1 - \frac{p}{1-p} \right) \left( \frac{p}{1-p} \right)^y$$

is the stationary distribution, and so the Markov chain is positive recurrent.

When  $p = 1/2$ , the general solution is given by  $\pi_y = c_1 + c_2 y$ . Since  $\sum_y \pi_y = 1$ , we must have  $c_1 = c_2 = 0$ , which is not a distribution. Thus the Markov chain is null recurrent.



### 3.5 Random Walk on the Integer Lattice

Consider the random walk on  $\mathbb{Z}^d$ . We view  $\mathbb{Z}^d$  as a graph where  $x, y \in \mathbb{Z}^d$  are joined by an edge if and only if  $|x - y| = 1$ .

**Theorem 3.15.** *The random walk on  $\mathbb{Z}^d$  is null recurrent if  $d = 1, 2$  and transient if  $d \geq 3$ .*

**Proof.** Consider first  $d = 1$ . Since  $\{X_n\}$  is irreducible, we need only consider  $X_0 = 0$ . If  $n$  is odd,  $X_n \neq 0$  since  $\mathbb{Z}$  is bipartite. For each  $n$ ,  $X_{2n} = 0$  if and only if there are  $n$  positive steps and  $n$  negative steps in the first  $2n$  steps. Thus

$$\mathbb{P}[X_{2n} = 0] = \binom{2n}{n} \left( \frac{1}{2} \right)^{2n}.$$

To determine whether the expression above is summable, we recall **Stirling's formula**:

$$n! \sim \sqrt{2\pi n} n^{n+\frac{1}{2}} e^{-n},$$

where  $a_n \sim b_n$  means  $a_n/b_n \rightarrow 1$  as  $n \rightarrow \infty$ . This approximation gives

$$\begin{aligned} \mathbb{P}(X_{2n} = 0) &\sim \frac{\sqrt{2\pi}(2n)^{2n+\frac{1}{2}} e^{-2n}}{\left(\sqrt{2\pi} n^{n+\frac{1}{2}} e^{-n}\right)^2} \cdot 2^{-2n} \\ &= \frac{1}{\sqrt{2\pi}} 2^{2n+\frac{1}{2}} n^{-\frac{1}{2}} 2^{-2n} = \frac{1}{\sqrt{\pi n}}. \end{aligned}$$

From this we know that  $P^{2n}(0, 0) \rightarrow 0$  and so  $\{X_n\}$  is not positive recurrent. But since  $\sum_{n \geq 1} \frac{1}{\sqrt{\pi n}} = \infty$ , we know that  $\{X_n\}$  is recurrent. Thus we can conclude that  $\{X_n\}$  is null recurrent.

Now consider the case  $d \geq 2$ . Since there are  $d$  components, by the law of large numbers, in  $2n$  steps, there will be around  $2n/d$  steps in each component. For  $k = 1, \dots, d$ , each step in the  $k^{\text{th}}$  component is  $+1$  with probability  $1/2$  and  $-1$  with probability  $1/2$ . By the  $d = 1$  case,

$$\mathbb{P}[\text{k}^{\text{th}} \text{ component of } X_{2n} \text{ is } 0] = \frac{1}{\sqrt{\pi(2n/d)}}.$$

Thus

$$\mathbb{P}[X_{2n} = 0] = \left(\frac{d}{2\pi n}\right)^{d/2} = \text{constant} \cdot n^{-d/2},$$

which goes to 0 as  $n \rightarrow \infty$  and is summable if  $d \geq 3$  (thus transient) and not summable if  $d = 2$  (thus null recurrent).  $\square$

## 4 Branching (or Galton-Watson) Processes

Given the offspring distribution  $\{p_k\}_{k \geq 0}$  with  $\sum_{k=0}^{\infty} p_k = 1$  (where  $p_k$  models the probability of having  $k$  children), we define the branching process  $\{X_n\}_{n \geq 0}$  (modelling the total number of offspring in each generation) as:

$$X_{n+1} = \sum_{i=1}^{X_n} \xi_j,$$

where  $\xi_j$  are conditional independent given  $X_n$  and for each  $x \geq 0$ ,  $\mathbb{P}[\xi_j = k | X_n = x] = p_k$ .

**Remark 4.1.** In addition to modelling population growth, branching processes can also be used to model the spread of epidemics, nuclear chain reactions, and the propagation of information in networks. ☞

What is the extinction probability  $a := \mathbb{P}[\exists n \geq 1 : X_n = 0 | X_0 = 1]$ ? We define  $\mu := \sum_{k=0}^{\infty} k p_k$  to be the expected number of offspring per individual. Observe that

$$\mathbb{E}[X_{n+1} | X_n = m] = \mathbb{E}\left[\sum_{j=1}^m \xi_j \middle| X_n = m\right] = \mu m.$$

Thus  $\mathbb{E}[X_{n+1}] = \mu \mathbb{E}[X_n]$ , and we have  $\mathbb{E}[X_n] = \mu^n \mathbb{E}[X_0]$ . Thus we have the following

**Proposition 4.2.** *If  $\mu < 1$ , then the extinction probability  $a = 1$ .*

**Proof.** Assume  $X_0 = 1$ . We have as  $n \rightarrow \infty$  that  $\mathbb{P}[X_n \geq 1] \leq \mathbb{E}[X_n] = \mu^n \rightarrow 0$ .  $\square$

What if  $\mu \geq 1$ ? Observe that if  $X_1 = k$ , then the descendants of the  $k$  individuals are  $k$  independent branching processes with the same offspring distribution. From this we see that

$$\mathbb{E}[\text{extinct} | X_1 = k] = a^k.$$

Thus, assuming  $X_0 = 1$ , we have

$$a := \mathbb{P}[\text{extinction}] = \sum_{k=0}^{\infty} \mathbb{P}[X_1 = k] \mathbb{P}[\text{extinction} | X_1 = k] = \sum_{k=0}^{\infty} p_k a^k.$$

Thus  $a = \varphi(a)$ , where  $\varphi$  is the generating function for  $\{p_k\}$ , defined as:

**Definition 4.3.** Let  $Y$  be a random variable in  $\mathbb{N}_0$ . The **generating function** of  $Y$  is defined as

$$\begin{aligned} \varphi &= \varphi_Y : [0, \infty] \longrightarrow [0, \infty] \\ s &\longmapsto \mathbb{E}[s^Y] = \sum_{k=0}^{\infty} \mathbb{P}[Y = k] s^k. \end{aligned}$$

**Proposition 4.4** (Properties of Generating Functions).

- (i) We allow  $\varphi(s) = \infty$ , but note that we have  $\varphi(s) < \infty$  for all  $s \in [0, 1]$ .
- (ii)  $\varphi(1) = \sum \mathbb{P}[Y = k] = 1$ .
- (iii)  $\varphi(0) = \mathbb{P}[Y = 0] \cdot 0^0 = \mathbb{P}[Y = 0]$ .
- (iv)  $\varphi'(s) = \sum_{k=0}^{\infty} k \mathbb{P}[Y = k] s^{k-1}$ . Thus  $\varphi'(1) = \mathbb{E}[Y]$ .
- (v) If  $Y_1, \dots, Y_m$  are independent, then

$$\varphi_{Y_1 + \dots + Y_m}(s) = \mathbb{E} \left[ \prod s^{Y_j} \right] = \prod \mathbb{E} [s^{Y_j}] = \prod_{i=1}^m \varphi_{Y_i}(s).$$

**Proposition 4.5.** Consider the branching process  $\{X_n\}$  with offspring distribution  $\{p_k\}$ . Let  $\varphi$  be the generating function for  $\{p_k\}$  and let  $\varphi^{(n)} := \underbrace{\varphi \circ \dots \circ \varphi}_{n \text{ times}}$ . Then

$$\varphi_{X_n}(s) = \varphi^{(n)}(s).$$

**Proof.** It suffices to show that  $\varphi_{X_{n+1}}(s) = \varphi_{X_n}(\varphi(s))$ . Note that

$$\begin{aligned} \varphi_{X_{n+1}}(s) &= \sum_{k \geq 0} \mathbb{P}[X_{n+1} = k] s^k \\ &= \sum_{k \geq 0} \sum_{j \geq 0} \mathbb{P}[X_{n+1} = k | X_n = j] \mathbb{P}[X_n = j] s^k \\ &= \sum_{j \geq 0} \mathbb{P}[X_n = j] \sum_{k \geq 0} \mathbb{P}[X_{n+1} = k | X_n = j] s^k. \end{aligned}$$

If  $X_n = j$ , we have  $X_{n+1} = \sum_{i=1}^j \xi_i$ , where  $\{\xi_i\}$  are iid with distribution  $\{p_k\}$ . Thus  $\sum_{k \geq 0} \mathbb{P}[X_{n+1} = k | X_n = j] s^k$  is the generating function of  $\sum \xi_i$ , and thus can be written as  $\varphi(s)^j$ . Thus we have

$$\varphi_{X_{n+1}}(s) = \sum_{j \geq 0} \mathbb{P}[X_n = j] \varphi(s)^j = \varphi_{X_n}(\varphi(s)),$$

□

**Proposition 4.6.** Assume  $0 < p_0 < 1$ . Then the extinction probability  $a$  is the smallest positive solution to the equation  $s = \varphi(s)$ .

**Proof.** We know that  $\varphi(a) = a$ . We first check that there exists a smallest positive solution. Note that  $\varphi(s) - s$  as a power series is continuous within its radius of convergence, which in particular includes  $[0, 1]$ . Thus  $\{s \in [0, 1] : \varphi(s) = s\}$  is closed. Since  $\varphi(0) = p_0$ , we have that  $\varphi(0) \neq 0$ . Thus there exists a smallest  $s_0 := \min\{s \in [0, 1] : \varphi(s) = s\}$ .

We claim that  $\varphi_{X_n}(0) < s_0$  for any  $n \geq 0$ . We prove this by induction. Recall that  $\varphi_{X_0}(s) = s$ , so  $\varphi(0) = 0 < s_0$ . Assume now that  $n \geq 0$  and  $\varphi_{X_n}(0) < s_0$ . We have

$$\varphi_{X_{n+1}}(0) = \varphi(\varphi_{X_n}(0)) < \varphi(s_0) = s_0,$$



where the inequality comes from the fact that  $\varphi$  is strictly increasing on  $[0, 1]$  (since it has nonnegative derivative).

Now since  $\varphi_{X_n}(0) = \mathbb{P}[X_n = 0]$ , we have

$$a = \lim_{n \rightarrow \infty} \mathbb{P}[X_n = 0] \leq s_0.$$

Since  $s_0$  is the smallest positive solution for  $\varphi(a) = a$ , we have  $a = s_0$ .  $\square$

**Proposition 4.7.** Assume  $0 < p_0 < 1$ . If  $\mu := \sum k p_k > 1$ , then the extinction probability  $a < 1$ . If  $\mu \leq 1$ , then  $a = 1$ .

**Proof.** We saw that  $a = 1$  if  $\mu < 1$ , so we need only consider the case  $\mu \geq 1$ . Note that

$$\varphi''(s) = \sum_{k=2}^{\infty} k(k-1)p_k s^{k-2} \geq 0,$$

If  $p_0 > 0$ , and  $\mu \geq 1$ ,  $p_k > 0$  for some  $k \geq 2$ . This implies that  $\varphi''(s) > 0$  for all  $s \in (0, 1)$ , so  $\varphi'$  is strictly increasing on  $(0, 1)$ . Recall that  $\varphi(1) = 1$  and  $\varphi'(1) = \mu$ .

If  $\mu = 1$ , we have

$$1 - \varphi(s) = \int_s^1 \varphi'(t) dt < \int_s^1 1 dt = 1 - s,$$

which gives  $\varphi(s) > s$  for all  $s \in [0, 1)$ . Since  $a$  is the smallest positive solution to  $\varphi(s) = s$ , we have  $a = 1$ .

If  $\mu > 1$ , we have  $\varphi'(1) > 1$  and  $\varphi(1) = 1$ . By a Taylor expansion of  $\varphi$  around  $s = 1$ , we have

$$\varphi(1 - \varepsilon) = 1 - \varphi'(1)\varepsilon + O(\varepsilon).$$

Since  $\varphi'(1) > 1$ , we see that there exists  $\varepsilon \in (0, 1)$  such that  $\varphi(1 - \varepsilon) < 1 - \varepsilon$ . But note also that  $\varphi(0) = p_0 > 0$ . Since  $\varphi(s) - s$  is continuous on  $[0, 1]$ , by the intermediate value theorem, there exists  $s_0 \in (0, 1 - \varepsilon)$  such that  $\varphi(s_0) = s_0$ . This gives  $a \leq s_0 < 1 - \varepsilon$ .  $\square$

*Remark 4.8.* The graph of  $\varphi(s)$  can be described as follows:

- $\mu < 1$  It intersects the  $y$ -axis at  $p_0$ , is convex, and intersects the line  $y = s$  at  $s = 1$  (with slope less than 1) and nowhere else in  $(0, 1)$ .
- $\mu > 1$  It intersects the  $y$ -axis at  $p_0$ , is convex, and intersects the line  $y = s$  at  $s = 1$  (at which point it has slope greater than 1) and at some  $s = a < 1$ .



**Definition 4.9.** We say a branching process  $\{X_n\}$  is


1. **supercritical** if  $\mu > 1$ ;
2. **critical** if  $\mu = 1$ ;
3. **subcritical** if  $\mu < 1$ .

Note that in case 1,  $a < 1$ ; in cases (2) and (3),  $a = 1$ .

*Example 4.10.*  $p_0 = 1/10, p_1 = 3/5, p_2 = 3/10$ . Then  $\mu = 0 \cdot \frac{1}{10} + 1 \cdot \frac{3}{5} + 2 \cdot \frac{3}{10} = 1.2 > 1$ . This is a supercritical branching process.

To find the extinction probability  $a$ , we need to solve  $\varphi(s) = s$ .

$$\varphi(s) = \frac{1}{10} + \frac{3}{5}s + \frac{3}{10}s^2 = s \iff 3s^2 - 4s + 1 = 0 \iff s = 1, \frac{1}{3}.$$

Thus  $a = 1/3$ . 

*Remark 4.11.* Consider a supercritical branching process  $\{X_n\}$ . Conditioning on  $E := \{\text{extinction}\}$ , we have the conditional distribution of  $\{X_n\}$  is a branching process with offspring distribution

$$\tilde{p}_k = a^{k-1} m p_k.$$

This is sometimes called the **conjugate branching process**.

Now consider a subcritical branching process  $\{\tilde{X}_n\}$ . Is it the conjugate of a supercritical branching process? The answer is “usually.” The smallest solution to  $\varphi(s) = s$  for a subcritical branching process is  $s = 1$ , but it usually has an extra solution  $A > 1$ , using which we can define the conjugate supercritical branching process with offspring distribution

$$\hat{p}_k = A^{k-1} \tilde{p}_k.$$



## 5 Poisson Processes

Consider a process  $\{X_t\}_{t \geq 0}$  in  $\mathbb{N}_0$  that models the number of phone line calls arrive at same rate at all hours. Let's suppose there are  $\lambda > 0$  calls per hour on average, and that the number of calls during disjoint time intervals are independent. Let  $X_t$  be the number of calls before time  $t$  (hours).

**Definition 5.1.** A random variable  $Y$  in  $\mathbb{N}_0$  has the **Poisson distribution** with mean  $\lambda > 0$  if

$$\mathbb{P}[Y = k] = \frac{\lambda^k e^{-\lambda}}{k!}, \quad k \in \mathbb{N}_0.$$

One can show that  $\mathbb{E}[Y] = \lambda$ .

**Lemma 5.2.** Let  $Y_1, Y_2$  be independent Poisson random variables with means  $\lambda_1, \lambda_2$  respectively. Then  $Y_1 + Y_2 \sim \text{Poisson}(\lambda_1 + \lambda_2)$ .

**Proof.**

$$\begin{aligned} \mathbb{P}[Y_1 + Y_2 = k] &= \sum_{j=0}^k \mathbb{P}[Y_1 = j] \mathbb{P}[Y_2 = k - j] = \sum_{j=0}^k \frac{\lambda_1^j e^{-\lambda_1}}{j!} \cdot \frac{\lambda_2^{k-j} e^{-\lambda_2}}{(k-j)!} \\ &= \frac{e^{-(\lambda_1 + \lambda_2)}}{k!} \sum_{j=0}^k \frac{k!}{j!(k-j)!} \lambda_1^j \lambda_2^{k-j} = \frac{e^{-(\lambda_1 + \lambda_2)}}{k!} (\lambda_1 + \lambda_2)^k, \end{aligned}$$

where the last equality follows from the binomial theorem.  $\square$

**Definition 5.3.** The **Poisson process** with rate  $\lambda > 0$  is the continuous time stochastic process  $\{X_t\}_{t \geq 0}$  such that  $X_0 = 0$  and for each  $0 \leq s_1 \leq t_1 \leq \dots \leq s_k \leq t_k$ , the random variables  $X_{t_1} - X_{s_1}, \dots, X_{t_k} - X_{s_k}$  are independent and each has distribution  $\text{Poisson}(\lambda(t_j - s_j))$ .

A Poisson process models the number of “arrivals” until time  $t$ , when the number of arrivals in disjoint time intervals are independent.

**Proposition 5.4.** The Poisson process of rate  $\lambda$  exists and is unique.

We omit the proof.

An equivalent way to model Process is to consider the inter-arrival times: Let  $\tau_0 = 0$  and for each  $j \geq 1$ , let  $\tau_j := \min\{t \geq 0 : X_t = j\}$  be the  $j^{\text{th}}$  arrival time. Note that  $X_t = \max\{j : \tau_j \leq t\}$ . It turns out that the inter-arrival times  $T_j := \tau_j - \tau_{j-1}$  are iid with exponential distribution with parameter  $\lambda$ :

**Definition 5.5.** A random variable  $T$  in  $[0, \infty)$  has the **exponential distribution** with parameter  $\lambda > 0$  if for each  $t > 0$ ,

$$\mathbb{P}[T \geq t] = e^{-\lambda t}.$$

We compute the mean of the exponential distribution:

$$\mathbb{E}[T] = \mathbb{E}\left[\int_0^\infty \mathbb{1}(t \leq T) dt\right] = \int_0^\infty \mathbb{E}[\mathbb{1}(t \leq T)] dt = \int_0^\infty e^{-\lambda t} dt = \frac{1}{\lambda}.$$

**Proposition 5.6.** *The inter-arrival times  $\tau_j - \tau_{j-1}$  are iid with distribution  $\text{Exponential}(\lambda)$ .*

We will provide the following “hand-waving” proof that captures the main idea, but does not deal with the measure-theoretic details.

**Proof.** Note that

$$\mathbb{P}[\tau_1 > t] = \mathbb{P}[X_t = 0] = e^{-\lambda t}.$$

Thus  $\tau_1 \sim \text{Exponential}(\lambda)$ . By the independent increments property, for each  $t \geq 0$ , we have that  $\{X_{s+t} - X_t\}_{s \geq 0}$  is a Poisson process with rate  $\lambda$  independent from  $\{X_s\}_{s \leq t}$ . Time  $\tau_1$  is a stopping time for  $\{X_s\}_{s \geq 0}$  since  $\{\tau_1 \leq t\}$  is determined by  $\{X_t\}_{s \leq t}$  for each  $t \geq 0$ .

By a version of the strong Markov property for  $\{X_s\}$ ,<sup>1</sup> we have  $\{X_{s+\tau_1} - X_{\tau_1}\}_{s \geq 0}$  is a Poisson process independent from  $\{X_s\}_{s \leq \tau_1}$ . Note that

$$\tau_2 - \tau_1 = \min\{s \geq 0 : X_{s+\tau_1} - X_{\tau_1} = 1\}.$$


By the  $\tau_1$  case,

$$\tau_2 - \tau_1 \sim \text{Exponential}(\lambda)$$

is independent from  $\tau_1$ . We can apply the same argument iteratively to show that  $\tau_j - \tau_{j-1} \sim \text{Exponential}(\lambda)$  and is independent from  $\{\tau_i\}_{i < j}$  for each  $j \geq 1$ .  $\square$

*Remark 5.7* (Some intuition of why the Poisson Process exists). Let  $\{\tau_j\}_{j \geq 1}$  be iid  $\text{Exponential}(\lambda)$ , and for each  $t$ , let

$$X_t := \max \left\{ k \geq 0 : \sum_{j=1}^k T_j \leq t \right\}.$$

It is possible to show that  $\{X_t\}$  is a Poisson process. 

*Example 5.8.* Consider a bus stop at which buses arrive according to a Poisson process. On average, two buses arrive per hour. We arrive at the bus stop at time  $t = 0$ .

- (i) If we wait for 2 hours, what is the probability that we do not see a bus?

Note that  $X_2 \sim \text{Poisson}(4)$ , and so

$$\mathbb{P}[X_2 = 0] = e^{-4} \approx 0.0183.$$

- (ii) Given that no bus arrives in the first two hours, what is the conditional probability that a bus arrives in the next hour?

$$\mathbb{P}[X_3 - X_2 \geq 0 | X_2 = 0] = \mathbb{P}[X_3 - X_2 \geq 0] = 1 - \mathbb{P}[X_3 - X_2 = 0] = 1 - e^{-2} \approx 0.864.$$

- (iii) What is the expected arrival time of the second bus?

$$\mathbb{E}[\tau_2] = \mathbb{E}[T_1 + T_2] = \mathbb{E}[T_1] + \mathbb{E}[T_2] = \frac{1}{2} + \frac{1}{2} = 1.$$

---

<sup>1</sup>This is where the hand-waving happens.



**Proposition 5.9** (Two Properties of the Exponential Distribution).

(i) *The memoryless property: for each  $t, s \geq 0$ ,*

$$\mathbb{P}[T - t \geq s | T \geq t] = e^{-\lambda s}.$$

(ii) *The minimum property: Let  $T_1, \dots, T_n$  be independent random variables with  $T_j \sim \text{Exponential}(\lambda_j)$ . Then  $T := \min_{1 \leq j \leq n} T_j \sim \text{Exponential}(\sum_{j=1}^n \lambda_j)$ . Moreover,*

$$\mathbb{P}[T_j = \min\{T_1, \dots, T_n\}] = \frac{\lambda_j}{\lambda_1 + \dots + \lambda_n}.$$

**Proof.**

(i)

$$\mathbb{P}[T \geq t + s | T \geq t] = \frac{\mathbb{P}[T \geq t + s]}{\mathbb{P}[T \geq t]} = \frac{e^{-\lambda(t+s)}}{e^{-\lambda t}} = e^{-\lambda s}.$$

(ii) We have

$$\begin{aligned} \mathbb{P}[\min\{T_1, \dots, T_n\} \geq t] &= \mathbb{P}[T_1 \geq t, \dots, T_n \geq t] \\ &= \prod_{j=1}^n \mathbb{P}[T_j \geq t] = e^{-(\lambda_1 + \dots + \lambda_n)t}. \end{aligned}$$

For the second statement, assume without loss of generality that  $j = 1$ . Then

$$\begin{aligned} \mathbb{P}[T_1 = \min\{T_1, \dots, T_n\}] &= \mathbb{P}[T_1 \leq T_j, \forall j \geq 2] \\ &= \mathbb{E}[\mathbb{P}[T_j \geq T_1, \forall j \geq 2 | T_1]] = \mathbb{E}[e^{-(\lambda_1 + \dots + \lambda_n)T_1}] \\ &= \int_0^\infty \lambda_1 e^{-\lambda_1 t} e^{-(\lambda_2 + \dots + \lambda_n)t} dt = \frac{\lambda_1}{\lambda_1 + \dots + \lambda_n}. \end{aligned}$$

□

## 6 Continuous Time Markov Chains

Let  $S$  be finite. We will define a **continuous time Markov chain**  $\{X_t\}_{t \geq 0}$  in  $S$ . The **rates**  $\alpha(x, y) \geq 0$  for distinct  $x, y \in S$  will describe the “rate at which we jump from  $x$  to  $y$ .”

Assume  $X_0 = x \in S$ . For  $y \in S$  with  $\alpha(x, y) \neq 0$ , let  $T_j \sim \text{Exponential}(\alpha(x, y))$  be independent for different  $y$ . Think of this intuitively as “alarm clocks” which rings at time  $T_y$ . At time

$$T := \min \{T_y : \alpha(x, y) \neq 0\},$$

we move to state  $y$ , where  $y$  is such that  $T_y = T$ . By the minimum property of the exponential distribution, we have  $T \sim \text{Exponential}(\alpha(x))$ , where  $\alpha(x) := \sum_{y \neq x} \alpha(x, y)$  and  $\mathbb{P}[X_T = y] = \alpha(x, y)/\alpha(x)$ . After time  $T$ , we forget the  $T_j$ ’s and choose the next step using exponential random variables of parameters  $\alpha(X_T, z)$  for  $z \neq X_T$  and  $\alpha(X_T, z)$ . We continue iteratively to define  $X_t$  for  $t \geq 0$ . If  $\alpha(x, y) = 0$  for all  $y \neq x$ , then once we reach  $x$ , we stay there forever.