

MATH20410 (W25): Analysis in \mathbb{R}^n II (accelerated)

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1 Single-Variable Differential Calculus

In this chapter, we consider mainly functions of the form $f : I \rightarrow \mathbb{R}$, where I is an interval, e.g., (a, b) , $[a, b]$, (a, ∞) , \mathbb{R} . This is the function we have in mind unless otherwise stated.

Definition 1.1 (Differentiability). We say f is **differentiable** at $x \in I$ if the limit

$$f'(x) := \lim_{t \rightarrow x} \frac{f(t) - f(x)}{t - x} = \lim_{h \rightarrow 0} \frac{f(x + h) - f(x)}{h}$$

exists. In this case, we call $f'(x)$ the derivative of f at x . Moreover:

- We say that f is **differentiable** if $f'(x)$ exists for each $x \in I$.
- We say f is **continuously differentiable** ($f \in C^1$) if $f' : I \rightarrow \mathbb{R}$ is continuous.

Example 1.2.

- $f(x) = |x|$. Differentiable on $\mathbb{R} \setminus \{0\}$.
- $f(x) = \begin{cases} x \sin \frac{1}{x}, & x \neq 0 \\ 0, & x = 0 \end{cases}$. Continuous but not differentiable at 0.
- $f(x) = \begin{cases} x^2 \sin \frac{1}{x}, & x \neq 0 \\ 0, & x = 0 \end{cases}$. Differentiable everywhere (in particular at 0), but $f \notin C^1$.

Proposition 1.3 (Rules for computing derivatives).

- Linearity.* $(af + bg)' = af' + bg'$ (if f' and g' exist, such requirements are hereafter omitted).
- Product rule.* $(fg)' = f'g + fg'$.
- Quotient rule.* $(f/g)' = (f'g - fg')/g^2$.¹
- Chain rule.* $(f \circ g)' = (f' \circ g) \cdot g'$.

¹Low dhigh minus high dlow. Not Haidilao...

Proof. We prove the quotient rule; the remaining are left as exercises. Starting from the definition

$$\begin{aligned}\left(\frac{f}{g}\right)'(x) &= \lim_{t \rightarrow x} \frac{\frac{f}{g}(t) - \frac{f}{g}(x)}{t - x} \\ &= \lim_{t \rightarrow x} \frac{\frac{f(t)}{g(t)} + \frac{f(x)}{g(t)} - \frac{f(x)}{g(t)} + \frac{f(x)}{g(x)}}{t - x}.\end{aligned}$$

Note that

$$\frac{\frac{f(x)}{g(t)} + \frac{f(x)}{g(x)}}{t - x} = \frac{f(x)}{g(x)g(t)} \frac{g(x) - g(t)}{t - x}$$

and we have

$$\left(\frac{f}{g}\right)'(x) = \frac{f'(x)}{g(x)} - \frac{f(x)g'(x)}{g^2(x)}$$

□

Theorem 1.4. *If f is differentiable at x then f is continuous at x .*

Proof. Note that

$$\lim_{t \rightarrow x} f(t) - f(x) = \lim_{t \rightarrow x} \frac{f(t) - f(x)}{t - x} (t - x) = f'(x) \cdot 0 = 0.$$

□

1.1 The Mean Value Theorem

Lemma 1.5. *Suppose $f : [a, b] \rightarrow \mathbb{R}$ has a local maximum or minimum at $x \in (a, b)$. If $f'(x)$ exists, then $f'(x) = 0$.*

Proof. From the definition of the derivative, consider the limits from the left and right; one is non-positive and the other is non-negative. □

Theorem 1.6 (Rolle's Theorem). *Suppose $f : [a, b] \rightarrow \mathbb{R}$ is continuous on $[a, b]$, differentiable on (a, b) , and such that $f(a) = f(b)$. Then there exists $x \in (a, b)$ such that $f'(x) = 0$.*

Proof. Consider the global maximum or minimum (exist since f is a continuous function defined on a compact set) and apply the previous lemma. (If both the maximum and minimum is at a or b , f is constant.) □

Theorem 1.7 (Mean Value Theorem). *Let $f : [a, b] \rightarrow \mathbb{R}$ be such that f is continuous on $[a, b]$ and differentiable on (a, b) . Then there exists $x \in (a, b)$ such that $f(b) - f(a) = f'(x)(b - a)$.*

Proof. Apply Rolle's to $\tilde{f} = f - [f(b) - f(a)] \cdot \frac{x-a}{b-a}$. □

Theorem 1.8. *Let $f : (a, b) \rightarrow \mathbb{R}$ be differentiable.*

(a) *if $f' = 0$, then f is constant.*

(b) *if $f' \geq 0$, then f is increasing.*

(c) *if $f' \leq 0$, then f is decreasing.*

Proof. Apply the mean value theorem. □

Theorem 1.9 (The Intermediate Value Property of Derivatives). *Let $f : [a, b] \rightarrow \mathbb{R}$ be differentiable² and suppose $f'(a) < \lambda < f'(b)$. Then there exists $x \in (a, b)$ such that $f'(x) = \lambda$.* ² f need not be C^1 !

Proof (*à la Pugh*). Slide a small secant of length so small that the slope around a and b is separated also by λ . By continuity of the slope, there exists a secant between a and b with slope λ . Apply the mean value theorem to this slope. □

Proof (*à la Joe/Rudin*). We start with $\lambda = 0$. Then $f'(a), f'(b) \neq 0$ and the global min/max of f cannot be at the endpoints. At the global extrema we have the desired result. When $\lambda \neq 0$, consider $\tilde{f} := f - \lambda x$. □

Example 1.10. Consider

$$f(x) = \begin{cases} x^2 \sin(1/x), & x \neq 0 \\ 0, & x = 0 \end{cases}.$$

We have

$$f(x) = \begin{cases} 2x \sin(1/x) = \cos(1/x), & x \neq 0 \\ 0, & x = 0 \end{cases},$$

which has the intermediate value property.

Theorem 1.11 (Generalized Mean Value Theorem). *Let $f, g : [a, b] \rightarrow \mathbb{R}$ be continuous on $[a, b]$ and differentiable on (a, b) . Then there exists $x \in (a, b)$ such that*

$$(f(a) - f(b))g'(x) = (g(a) - g(b))f'(x).$$

Remark 1.12. When the above is not zero,

$$\frac{f(a) - f(b)}{g(a) - g(b)} = \frac{f'(x)}{g'(x)}.$$

Proof. Define

$$h(t) := (f(b) - f(a))g(t) - (g(b) - g(a))f(t).$$

Note that

$$h(a) = f(b)g(a) - f(a)g(b) = h(b)$$

and apply Rolle's. □

1.2 L'Hôpital's Rule

Theorem 1.13 (L'Hôpital's Rule, a particular case). *Let $f, g : [a, b] \rightarrow \mathbb{R}$ be continuous on $[a, b]$ and differentiable on (a, b) . If $g(x) \neq 0$ in a neighborhood of a and $f(x) = g(x) = 0$, then*

$$\lim_{x \rightarrow a} \frac{f(x)}{g(x)} = \lim_{x \rightarrow a} \frac{f'(x)}{g'(x)},$$

if the last limit exists.

Proof. Consider some small $\delta > 0$. The generalized MVT gives some $x \in (a, a+\delta)$ such that

$$\frac{f(a+\delta)}{g(a+\delta)} = \frac{f'(x)}{g'(x)} \approx \lim_{t \rightarrow a} \frac{f'(t)}{g'(t)},$$

where the last approximation follows from the existence of the limit. Note that as $\delta \rightarrow 0$, $x \rightarrow a$, and the approximation error shrinks to 0. □

Refer to Rudin or something for the general case.

1.3 Higher Derivatives

If $f : I \rightarrow \mathbb{R}$ is differentiable, then we can define the second derivative $f'' := (f')'$ if f' is differentiable. Higher derivatives can be defined similarly. We usually write $f^{(n)}$ for the n -th derivative of f .

Example 1.14. $L(x) = f(x_0) + f'(x_0)(x - x_0)$ is a (first order) linear approximation of f at x_0 . How good is this approximation? A first answer is

$$f(x) = L(x) + o(|x - x_0|),$$

since we have as $x \rightarrow x_0$ that

$$\frac{f(x) - L(x)}{x - x_0} = \frac{f(x) - f(x_0)}{x - x_0} - f'(x_0) \rightarrow 0.$$

But can we say even more about the quality of the approximation? – Yes, if f is twice differentiable.

Proposition 1.15 (First-order Taylor's Theorem). *Suppose f' exists and is continuous on $[a, b]$ and f'' exists on (a, b) . Let $x_0, x \in [a, b]$ with $x_0 \neq x$. Then*

$$f(x) = f(x_0) + f'(x_0)(x - x_0) + \frac{1}{2}f''(y)(x - x_0)^2,$$

where y is between x_0 and x . In particular, we have

$$|f(x) - f(x_0) - f'(x_0)(x - x_0)| \leq \frac{1}{2} \sup_{y \in (a, b)} |f''(y)| \cdot |x - x_0|^2.$$

Proof. Find M such that we have

$$f(x) = f(x_0) + f'(x_0)(x - x_0) + \frac{M}{2}(x - x_0)^2.$$

We need only find y such that $M = f''(y)$. Define

$$g(t) := f(t) - f(x_0) - f'(x_0)(t - x_0) - \frac{M}{2}(t - x_0)^2.$$

Note that $g''(t) = f''(t) - M$, so we need only find a point at which g'' vanishes. Since $g(x_0) = g(x) = 0$, by the MVT there exists y' between x_0 and x such that $g'(y') = 0$. Observe that $g'(x_0) = 0$, and so by the MVT again, there exists y between x_0 and y' (and by extension between x_0 and x) such that $g''(y) = 0$. \square

The more general story: given $f : [a, b] \rightarrow \mathbb{R}$ and $x_0 \in [a, b]$, we may define

$$P_0(x) := f(x_0),$$

$$P_1(x) := f(x_0) + f'(x_0)(x - x_0),$$

$$P_2(x) := f(x_0) + f'(x_0)(x - x_0) + \frac{1}{2}f''(x_0)(x - x_0)^2,$$

\vdots

$$P_n(x) := \sum_{k=0}^n \frac{f^{(k)}(x_0)}{k!} (x - x_0)^k,$$

when the corresponding derivatives exist. Note that $P_n(x)$ is the unique degree n polynomial such that $P_n^{(k)}(x_0) = f^{(k)}(x_0)$ for $k = 1, \dots, n$.

Theorem 1.16 (Taylor's Theorem). *Let $f : [a, b] \rightarrow \mathbb{R}$ be such that*

- $f^{(k)}$ exists on $[a, b]$ for $k = 1, \dots, n$; and
- $f^{(n+1)}$ exists on (a, b) .

Then, for any $x_0, x \in [a, b]$ with $x_0 \neq x$, there exists y between x_0 and x such that

$$f(x) = P_n(x) + \frac{f^{(n+1)}(y)}{(n+1)!} (x - x_0)^{n+1}.$$

for some y between x_0 and x .

We proof the case $n = 2$, the same idea can be used to prove the general case.

Proof. Define

$$g(t) = f(t) - P_2(t) - \frac{M}{6} (t - x_0)^3.$$

Since $g''' = f''' - M$, we need only find y such that $g'''(y) = 0$. Note that $g(x_0) = g(x) = 0$, and so by the MVT there exists y' between x_0 and x such that $g'(y') = 0$. Next, note that $g'(x_0) = 0$, and so by the MVT there exists y'' between x_0 and y' such that $g''(y'') = 0$. Finally, note that $g''(x_0) = 0$, and so by the MVT there exists y between x_0 and y'' such that $g'''(y) = 0$. \square

2 Multivariable Differential Calculus

Some remainders about \mathbb{R}^n :

- $\mathbb{R}^n = \{x = (x_1, \dots, x_n) : x_i \in \mathbb{R}\}.$
- \mathbb{R}^n is a vector space, with canonical basis $\{e_1, \dots, e_n\}.$
- \mathbb{R}^n comes with an inner product $\langle x, y \rangle = x \cdot y = \sum x_i y_i$, a norm $|x| = \sqrt{x \cdot x} = (\sum x_i y_i)^{1/2}$, and a metric $d(x, y) = |x - y|.$

2.1 Higher Dimensional Codomains

Consider a function $f : \mathbb{R} \supset I \rightarrow \mathbb{R}^n$.

Definition 2.1. f is differentiable at x if the limit

$$f'(x) := \lim_{t \rightarrow x} \frac{f(t) - f(x)}{t - x}$$

exists.

Remark 2.2. We may write $f(t) = (f_1(t), \dots, f_n(t))$, and $f'(x) = (f'_1(x), \dots, f'_n(x))$, since a sequence $x \in \mathbb{R}^n$ converges if and only if each of its components converges.

Theorem 2.3. *We have the following analog of the MVT:*

$$|f(b) - f(a)| \leq |f'(t)| \cdot |b - a|.$$

for some t between a and b .

Proof. Assume $a < b$. Define

$$h(t) := \langle f(b) - f(a), f(t) \rangle.$$

The MVT gives

$$\begin{aligned} h(b) - h(a) &= h'(t)(b - a) = \langle f(b) - f(a), f'(t) \rangle (b - a) \\ &\leq (b - a) |f(b) - f(a)| |f'(t)|, \end{aligned}$$

where the last inequality follows from the Cauchy-Schwarz inequality. Noting that

$$h(b) - h(a) = |f(b) - f(a)|^2,$$

we have the desired result. □

2.2 Higher Dimensional Domain

We next consider functions $f : U \rightarrow \mathbb{R}$, where $U \subset \mathbb{R}^n$ is open.

Definition 2.4 (Partial Derivatives).

$$\frac{\partial f}{\partial x_i}(x) = D_i f(x) := \lim_{h \rightarrow 0} \frac{f(x + h e_i) - f(x)}{h}.$$

Definition 2.5 (Directional Derivatives). Fix $u \in \mathbb{R}^n$.

$$= D_u f(x) := \lim_{h \rightarrow 0} \frac{f(x + hu) - f(x)}{h}.$$

2.2.1 The Derivative

Intuition: A function is differentiable if a first-order Taylor expansion holds. That is, if f is “well-approximated” by a linear function.

Definition 2.6. We denote the set of all linear maps from \mathbb{R}^n to \mathbb{R} as $L(\mathbb{R}^n, \mathbb{R})$.

Definition 2.7 (The Derivative). A function f is differentiable at x if there exists a linear map $T \in L(\mathbb{R}^n, \mathbb{R})$ such that

$$\lim_{h \rightarrow 0} \frac{f(x + h) - f(x) - T(h)}{|h|} = 0.$$

In this case we write $Df(x) = T$. In other words, $f(x + h) = f(x) + Df(x)(h) + o(|h|)$.

Remark 2.8.

- If f is differentiable, then

$$Df : U \longrightarrow L(\mathbb{R}^n, \mathbb{R}).$$

- It is easy to check that Df is well defined, that is, there is at most one T such that the limit holds.

We may think of the linear map $T : \mathbb{R}^n \rightarrow \mathbb{R}$ as

$$T(u) = \langle u, v \rangle, \tag{1}$$

where $v := (Te_1, \dots, Te_n)$.

Definition 2.9 (The Gradient). If f is differentiable at x , we define $\nabla f(x) = v$, where v satisfies (1). In other words,

$$\lim_{h \rightarrow 0} \frac{f(x+h) - f(x) - \langle \nabla f(x), h \rangle}{|h|} = 0.$$

Theorem 2.10. If f is differentiable at x , then $D_u f(x)$ exists for all $u \in \mathbb{R}^n$ and $D_u f(x) = Df(x)u = \langle \nabla f(x), u \rangle$.

Proof. Note that as $t \rightarrow 0$, we have

$$\begin{aligned} \left| \frac{f(x+tu) - f(x)}{t} - Df(x)u \right| &= \left| \frac{f(x+tu) - f(x) - Df(x)(tu)}{t} \right| \\ &= \left| \frac{f(x+tu) - f(x) - Df(x)(tu)}{|tu|} \right| \cdot |u| \rightarrow 0. \end{aligned}$$

□

Remark 2.11. In particular we have $D_i f(x) = D_{e_i} f(x) = Df(x)e_i = \langle \nabla f(x), e_i \rangle$. In other words, if f is differentiable, then $\nabla f(x) = (D_1 f, \dots, D_n f)$.

Remark 2.12.

- Differentiability holds if and only if the gradient exists.
- Differentiability implies the existence of directional derivatives, which then implies the existence of partial derivatives. The converse implications are not true.

Example 2.13. Consider

$$f(x_1, x_2) := \begin{cases} \frac{x_1 x_2}{x_1^2 + x_2^2}, & x \neq 0 \\ 0, & x = 0 \end{cases}.$$

It is easy to see that $D_1 f(0) = D_2 f(0) = 0$ but $D_{(1,1)} f(0)$ does not exist. Indeed, f is not even continuous on the line $t(1, 1)$.

Example 2.14. Consider

$$f(x_1, x_2) := \begin{cases} \frac{x_1^3}{x_1^2 + x_2^2}, & x \neq 0 \\ 0, & x = 0 \end{cases}.$$

Note that

$$D_u f(0) = \lim_{t \rightarrow 0} \frac{t^3 u_1^3}{t^2(u_1^2 + u_2^2)} \cdot \frac{1}{t} = \frac{u_1^3}{u_1^2 + u_2^2}.$$

However, $Df(0)$ cannot exist, since the above mapping is not linear.

Question 2.15. If $D_u f$ exists for all u , is f continuous?