

ASSET PRICING: MATHEMATICAL FOUNDATIONS

ADEN CHEN

CONTENTS

1. Derivatives: A One-Dimensional Recap	1
2. Derivatives: Partial and Total	1
3. The Lagrangian	2
4. Lagrangian: An Example	2
4.1. The Utility Maximization Problem	2
4.2. Interpretation	2
5. Taylor Expansion	3
6. Probability	4

1. DERIVATIVES: A ONE-DIMENSIONAL RECAP

Definition 1.1. Let $f : \mathbb{R} \supset \Omega \rightarrow \mathbb{R}$. The derivative of f at $x \in \Omega$ is defined as

$$f'(x) = \lim_{h \rightarrow 0} \frac{f(x+h) - f(x)}{h},$$

if the limit exists.

Remark 1.2.

- Think “first order approximation.”
- Note that f' is also a function, with the same domain as f (when f is enough regular).

2. DERIVATIVES: PARTIAL AND TOTAL

Definition 2.1. Let $f : \mathbb{R}^n \supset \Omega \rightarrow \mathbb{R}$. The partial derivative of f at $\mathbf{x} \in \Omega$ with respect to the i th variable is defined as

$$\frac{\partial f}{\partial x_i} = f_{x_i} = f_i(x) = \lim_{h \rightarrow 0} \frac{f(\mathbf{x} + h\mathbf{e}_i) - f(\mathbf{x})}{h},$$

if the limit exists.

Remark 2.2.

- [Desmos 3d Demo](#).
- Think derivative with respect to the i th position, not to x_i .
- “First order approximation in the i th direction.”

Date: Wednesday 23rd October, 2024

The most recent version of this document can be found [here](#).

- With enough regularity imposed on f , we can write

$$df = \sum_{k=1}^n \frac{\partial f}{\partial x_k} dx_k.$$

“Think first order approximation.”

3. THE LAGRANGIAN

Example 3.1.

$$\max_{\{x,y\}} U(x,y), \quad \text{s.t.} \quad \begin{cases} p_x x + p_y y \leq m \\ x, y \geq 0 \end{cases}$$

- For ease of mathematics, we often consider the constraint $p_x x + p_y y = m$.
- For a more general case, see [Karush–Kuhn–Tucker conditions](#).

Theorem 3.2. *More abstractly, the above problem can be thought of as*

$$\max f(x_1, x_2) \quad \text{s.t.} \quad g(x_1, x_2) = c$$

for a constant c . With enough regularity, the optima occurs at the critical points of the Lagrangian, defined as

$$\mathcal{L}(x_1, x_2, \lambda) := f(x_1, x_2) + \lambda[c - g(x_1, x_2)].$$

That is, the optima subject to given constraint satisfies

$$\begin{aligned} [x_1] : & \quad f_1(x_1^*, x_2^*) = \lambda g_1(x_1^*, x_2^*) \\ [x_2] : & \quad f_2(x_1^*, x_2^*) = \lambda g_2(x_1^*, x_2^*) \\ [\lambda] : & \quad g(x_1^*, x_2^*) = c. \end{aligned}$$

4. LAGRANGIAN: AN EXAMPLE

4.1. The Utility Maximization Problem. The problem:

$$v(p_x, p_y, m) := \max_{x,y} U(x,y) \quad \text{s.t.} \quad p_x x + p_y y = m.$$

4.2. Interpretation. We want to maximize

$$dU = U_x dx + U_y dy$$

such that

$$p_x dx + p_y dy = 0 \implies dy = -\frac{p_x}{p_y} dx.$$

This gives

$$dU = \left[U_x - U_y \cdot \frac{p_x}{p_y} \right] dx.$$

We can rewrite these two expressions in the following forms:

- Set $dx > 0$ if $U_x/U_y > p_x/p_y$.

$$\left[\frac{U_x}{U_y} - \frac{p_x}{p_y} \right] U_y dx$$

“Take advantage of all trading opportunities.”

- Set $dx > 0$ if $U_x/p_x > U_y/p_y$. Note that U_x/p_y is marginal utility of money *spent* on x .

$$\left[\frac{U_x}{p_x} - \frac{U_y}{p_y} \right] p_x dx$$

“Bang for your buck.”

- Set $dx > 0$ if $U_x > U_y \cdot p_x/p_y$. Note that U_x is the marginal benefit of buying x and $U_y \cdot p_x/p_y$ is the marginal cost of buying x .

$$\left[U_x - U_y \cdot \frac{p_x}{p_y} \right] dx$$

“Trade until marginal cost equals marginal benefit.”

In the last expression, if we write

$$\lambda = \frac{U_y}{p_y},$$

(think marginal utility of income) we have that at optimum,

$$(U_x - \lambda p_x) dx = 0,$$

$$\lambda = \frac{U_y}{p_y} \iff U_y - \lambda p_y = 0,$$

$$p_x x + p_y y = m.$$

These three equalities describe precisely the critical points of the following

$$\mathcal{L}(p_x, p_y, \lambda) := U(x, y) + \lambda [m - p_x x - p_y y],$$

called the **Lagrangian**. That is, setting

$$\frac{\partial \mathcal{L}}{\partial x} = \frac{\partial \mathcal{L}}{\partial y} = \frac{\partial \mathcal{L}}{\partial \lambda} = 0$$

recovers the above three equations.

Remark 4.1.

- We are not maximizing the Lagrangian but utility level (subject to given constraint).
- λ might be negative or zero. Think bliss point.

5. TAYLOR EXPANSION

Definition 5.1. The Taylor polynomial of degree n of the function f around point a is given by

$$P(a+x) = \sum_{k=1}^n \frac{f^{(k)}(a)}{k!} \cdot x^k.$$

It has the same k derivatives as f . Think “ k th order approximation.”

Remark 5.2. We will often use the first or second order approximation starting from a given point a :

$$f(a+h) \approx f(a) + f'(a)h,$$

$$f(a+h) \approx f(a) + f'(a)h + f''(a)\frac{h^2}{2}.$$

6. PROBABILITY

Definition 6.1. A discrete random variable X can be described by the (at most countable) values it can attain and the probability of attaining them.

- The expectation of X is defined as

$$\mathbb{E}(X) = \sum x \cdot \mathbb{P}(X = x).$$

Think weighted average.

- The variance of X is defined as

$$\text{Var}(X) = \mathbb{E}[(X - \mathbb{E}(X))^2].$$

- For discrete random variables X and Y , the covariance is defined by

$$\text{Cov}(X, Y) = \mathbb{E}[(X - \mathbb{E}(X)) \cdot (Y - \mathbb{E}(Y))].$$

Proposition 6.2.

- \mathbb{E} is linear. That is, $\mathbb{E}[a + bX] = a + b \mathbb{E}[X]$ for $a, b \in \mathbb{R}$.
- $\text{Var}(X) = \mathbb{E}(X^2) - \mathbb{E}(X)^2$ and $\text{Var}(a + bX) = b^2 \text{Var}(X)$.
- $\text{Cov}(X, Y) = \mathbb{E}(XY) - \mathbb{E}(X) \mathbb{E}(Y)$.