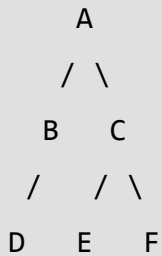


Difference between BFS and DFS

Breadth First Search

BFS stands for **Breadth First Search** is a vertex based technique for finding a shortest path in graph. It uses a Queue data structure which follows first in first out. In BFS, one vertex is selected at a time when it is visited and marked then its adjacent are visited and stored in the queue. It is slower than DFS.

Ex-



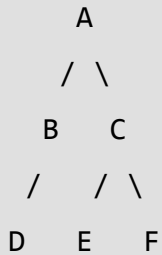
Output is:

A, B, C, D, E, F

Depth First Search

DFS stands for **Depth First Search** is a edge based technique. It uses the Stack data structure, performs two stages, first visited vertices are pushed into stack and second if there is no vertices then visited vertices are popped.

Ex-



Output is:

A, B, D, C, E, F

BFS vs DFS

S.NO	BFS	DFS
	BFS stands for Breadth	DFS stands for Depth
1.	First Search.	First Search.

<p>2. BFS(Breadth First Search) uses Queue data structure for finding the shortest path.</p>	<p>DFS(Depth First Search) uses Stack data structure.</p>
<p>3. BFS can be used to find single source shortest path in an unweighted graph, because in BFS, we reach a vertex with minimum number of edges from a source vertex.</p>	<p>In DFS, we might traverse through more edges to reach a destination vertex from a source.</p>
<p>3. BFS is more suitable for searching vertices which are closer to the given source.</p>	<p>DFS is more suitable when there are solutions away from source.</p>
<p>4. BFS considers all neighbors first and therefore not suitable for decision making trees used in games or puzzles.</p>	<p>DFS is more suitable for game or puzzle problems. We make a decision, then explore all paths through this</p>

decision. And if this
decision leads to win
situation, we stop.

The Time complexity of
BFS is $O(V + E)$ when
Adjacency List is used
and $O(V^2)$ when
Adjacency Matrix is used,
where V stands for
vertices and E stands for

5. edges.

The Time complexity of
DFS is also $O(V + E)$
when Adjacency List is
used and $O(V^2)$ when
Adjacency Matrix is
used, where V stands for
vertices and E stands for
edges.

// The real time example you can take for water jug problem also