

Day 3 Lecture 12 Saliency

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Organizers



Dublin City University







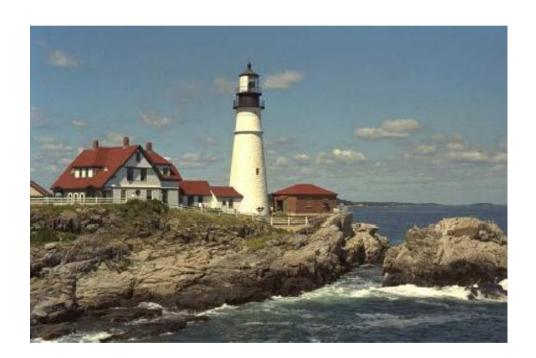


+ info: TelecomBCN.DeepLearning.Barcelona



Elisa Sayrol





What have you seen?

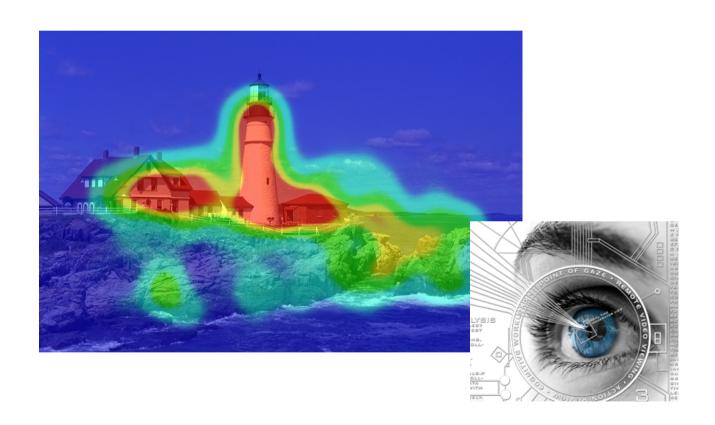
Lighthouse

LighthouseHouse

Lighthouse

House

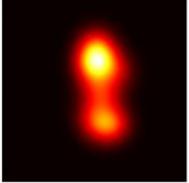
Rocks



Saliency Map

The Goal is to obtain the Saliency Map of an Image. Regression problem, not Classification





Original Image

Ground Truth
Saliency Map
(Eye-Fixation Map)

Data Bases: Groundtruth generation





Eye Tracker

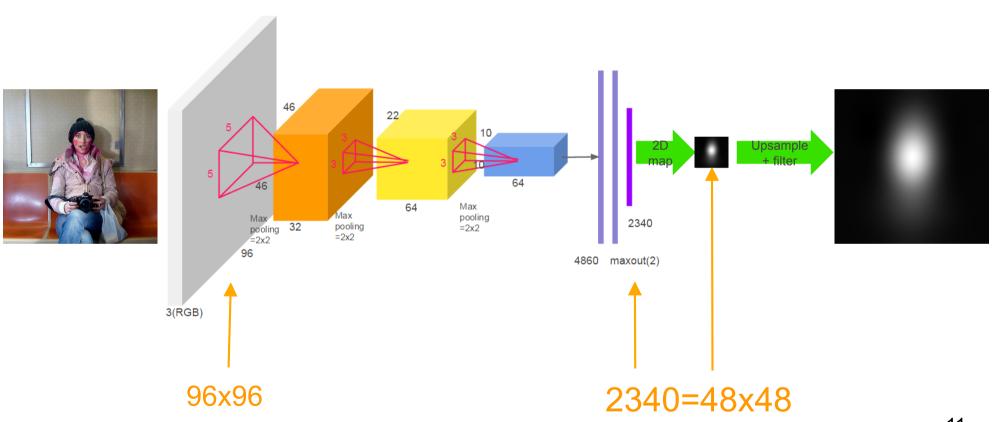
Mouse Click

DataBases

	TRAIN	VALIDATION	TEST
SALICON [Jiang'15]	10,000	5,000	5,000
<u>iSun [Xu'15]</u>	6,000	926	2,000
<u>CAT2000</u> [Borji'15]	2,000	-	2,000
MIT300 [Judd'12]	300	-	-
Pascal-S	850		

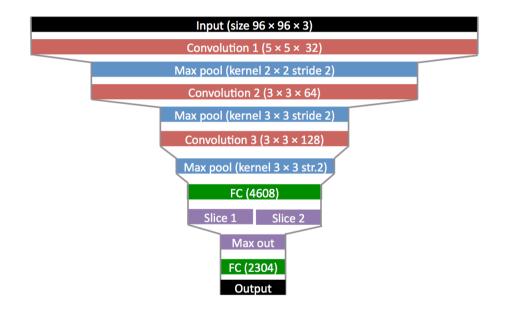
Other databases: http://saliency.mit.edu/datasets.html

Architectures: Junting Net (Shallow Network)



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Winner of the LSUN Challenge 2015!!

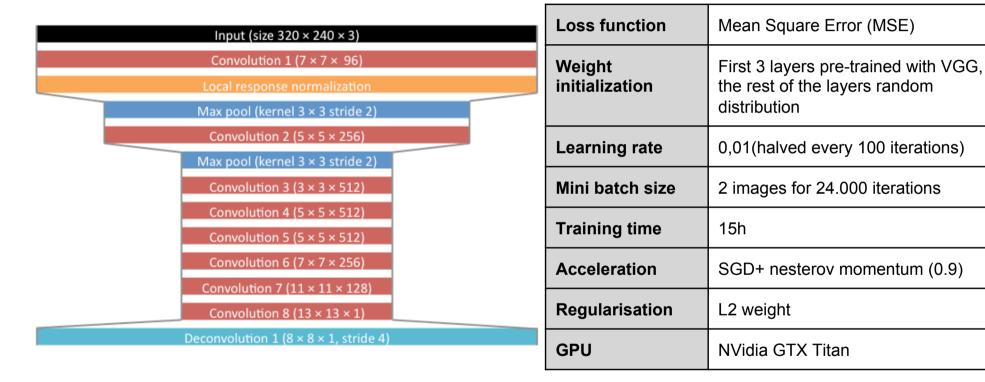


Loss function	Mean Square Error (MSE)			
Weight initialization	Gaussian distribution			
Learning rate	0.03 to 0.0001			
Mini batch size	128			
Training time	7h (SALICON) / 4h (iSUN)			
Acceleration	SGD+ nesterov momentum (0.9)			
Regularisation	Maxout norm			
GPU	NVidia GTX 980			

Shallow and Deep Convolutional Networks for Saliency Prediction

Junting Pan, Kevin McGuinness, Elisa Sayrol, Noel O'Connor, Xavier Giro-i-Nieto, CVPR 2016

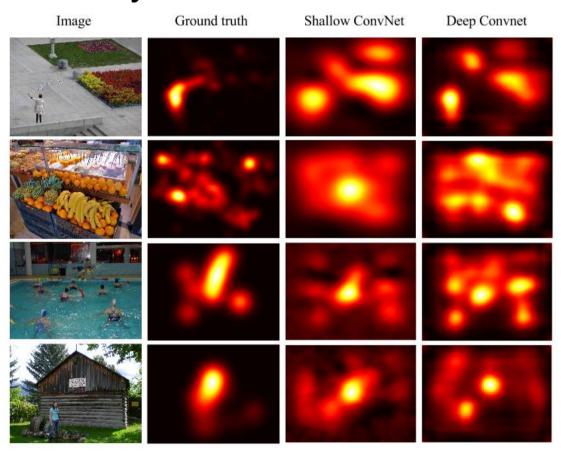
Architectures: SalNet (Deep Network)



Shallow and Deep Convolutional Networks for Saliency Prediction

Junting Pan, Kevin McGuinness, Elisa Sayrol, Noel O'Connor, Xavier Giro-i-Nieto, CVPR 2016

Quality Results



Architectures: Junting Net (Shallow Network) Winner of the LSUN Challenge 2015!!

Results from CVPR LSUN Challenge 2015 (iSUN Database)

Method	Similarity	\$	СС	‡	AUC_shuffled +	AUC_Borji +	AUC_Judd +
UPC	0.6833		0.8230		0.6650	0.8463	0.8693
Xidian	0.5713		0.6167		0.6484	0.7949	0.8207
WHU_IIP	0.5593		0.6263		0.6307	0.7960	0.8197
LCYLab	0.5474		0.5699		0.6259	0.7921	0.8133
Rare 2012 Improved	0.5199		0.5199		0.6283	0.7582	0.7846
Baseline: BMS ^[1]	0.5026		0.3465		0.5885	0.6560	0.6914
Baseline: GBVS ^[2]	0.4798		0.5087		0.6208	0.7913	0.8115
Baseline: Itti ^[3]	0.4251		0.3728		0.6024	0.7262	0.7489

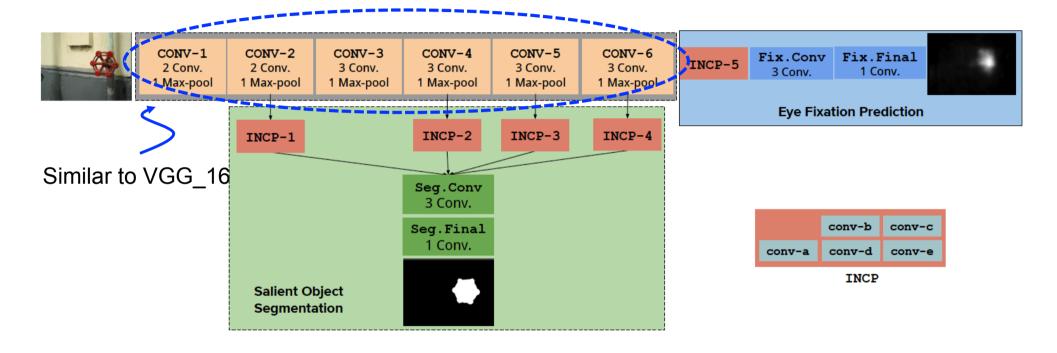
Quantitative Results

	Similarity	CC	AUC shuffled	AUC Borji	AUC Judd
Baseline: Infinite Humans	1.00	1.00	0.80	0.87	0.91
SALICON [11]	0.60	0.74	0.74	0.85	0.87
DeepFix	0.67	0.78	0.71	0.80	0.87
Deep Gaze 1 [17]	0.39	0.48	0.66	0.83	0.84
Deep Convnet	0.52	0.58	0.69	0.82	0.83
BMS [31]	0.51	0.55	0.65	0.82	0.83
eDN [27]	0.41	0.45	0.62	0.81	0.82
GBVS [9]	0.48	0.48	0.63	0.80	0.81
Judd [15]	0.42	0.47	0.60	0.80	0.81
Shallow Convnet	0.46	0.53	0.64	0.78	0.80
Mr-CNN [20]	0.48	0.48	0.69	0.75	0.79
Rare 2012 Improved [22]	0.46	0.42	0.67	0.75	0.77
Baseline: One human	0.38 - 0.46	0.52 - 0.65	0.63 - 0.67	0.66 - 0.71	0.80 - 0.83

Table 6. Results of the MIT300 dataset.

Metrics: Saliency and Human Fixations: State-of-the-art and Study of Comparison Metrics
Nicolas Riche, Matthieu Duvinage, Matei Mancas, Bernard Gosselin and Thierry Dutoit, iccv 2013

Architectures: Saliency Unified (Very Deep Network)



Saliency Unified: A Deep Architecture for simultaneous Eye Fixation Prediction and Salient Object Segmentation Srinivas S S Kruthiventi, Vennela Gudisa, Jaley H Dholakiya and R. Venkatesh Babu, CVPR 2016

Quantitative Results

Dataset	Metric	ITTI	GBVS	AWS	BMS	eDN	MrCNN	untingNet	Proposed
		[2]	[13]	[46]	[47]	[48]	[26]	[49]	
PASCAL-S [9]	s-AUC ↑	0.64	0.65	0.67	0.67	0.65	_	0.69	0.72
	EMD ↓	1.21	1.16	1.38	1.32	1.29	_	1.03	0.73
	NSS ↑	1.30	1.36	1.12	1.28	1.42	_	1.90	2.22
DUT-OMRON [40]	s-AUC ↑	0.78	0.81	0.78	0.79	0.80	_	0.83	0.83
	EMD ↓	1.47	1.32	1.62	1.58	1.56	_	1.37	1.03
	NSS ↑	1.54	1.71	1.51	1.66	1.33	_	2.03	3.02
MIT1003 [14]	s-AUC ↑	0.66	0.66	0.69	0.69	0.66	0.71	0.68	0.73
	EMD ↓	2.33	2.19	2.54	2.40	2.39	2.30	1.91	1.49
	NSS ↑	1.06	1.17	1.07	1.19	1.24	1.28	1.60	2.08
IS [43]	s-AUC ↑	0.66	0.67	0.72	0.71	0.61	_	0.65	0.70
	EMD ↓	1.30	1.22	1.49	1.43	1.49	_	1.11	0.77
	NSS ↑	1.50	1.58	1.58	1.74	1.27	_	1.72	2.30

Table 3. Quantitative results of our approach on eye fixation prediction compared against other state-of-the art methods on PASCAL-S, DUT-OMRON, MIT1003 and IS datasets. The best results are shown in red and the second best in blue.

<u>Saliency Unified: A Deep Architecture for simultaneous Eye Fixation Prediction and Salient Object Segmentation</u> Srinivas S S Kruthiventi, Vennela Gudisa, Jaley H Dholakiya and R. Venkatesh Babu, *CVPR 2016*