

# The Beagle Bone

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## Overview

- Me - Out-of-the-box
- You - Out-of-the-box
- Introductions
  - Me
  - Black Bone
- Technical Details
- You - More Labs
- Teaching with the Bone
- Questions and Wrap Up



## Boris

- ...speaks for himself
- Watch carefully



## You - Out-of-the-box

### Getting Started

1. Plug the BeagleBone into your computer via USB.
2. Open the new drive that appears.
3. Open **START.htm** with Chrome or Firefox.
4. Install driver for your OS. (You'll have to click Install several times.)
5. Return to browser window with **START.htm** and scroll down to **Step 3** to find <http://192.168.7.2> and click on it.
6. Explore.
7. Click on the title Cloud9 IDE (<http://192.168.7.2:3000>).
8. Continue with lab handouts.



## What did you see?

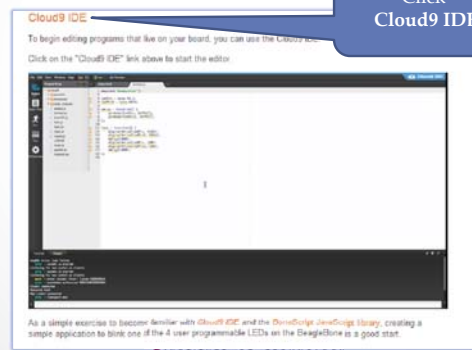
- Small Size
- Powered by USB
- Fast to boot
- Easy to add audio
- Network over USB
- USB drive
- Web server
- Integrated Development Environment
- Speech synthesis
- Linux command line

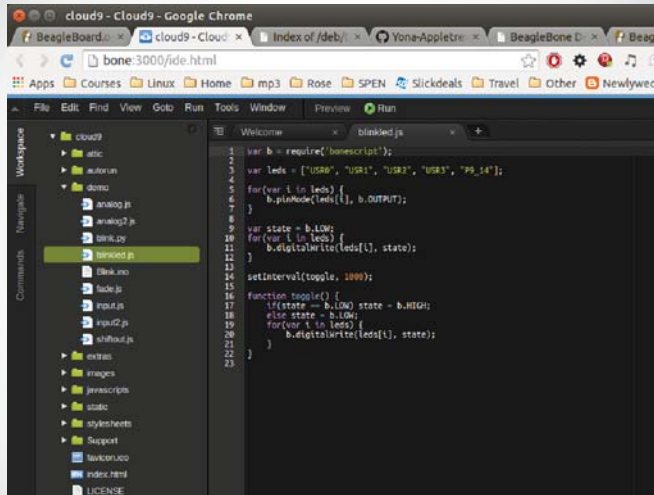


## Cloud 9 IDE

- Zero-install integrated development environment
- Go to <http://192.168.7.2:3000>

Click  
Cloud9 IDE









- [http://www.youtube.com/watch?feature=player\\_embedded&v=blvkerJr5wE](http://www.youtube.com/watch?feature=player_embedded&v=blvkerJr5wE)

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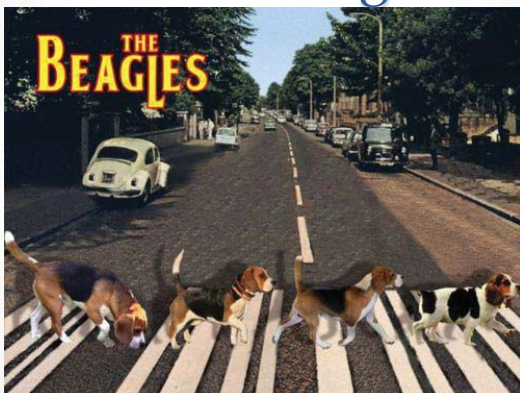
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## BeagleBone Family

	BeagleBoard	BeagleBoard-xM	BeagleBone	BeagleBone Black
Board				
Quick summary	The original open hardware, ARM-based development board	All features of the original BeagleBoard with extra memory	Low-cost, open-source community platform with plug-in board expansion	Next-generation BeagleBone featuring 1-GHz processor
Memory	256KB L2 cache	512MB DDR2	256MB DDR2	512MB DDR3
Special features	2D/3D graphics accelerator, HD video capable, USB powered	1-GHz processing power, Four-port hub with 10/100 Ethernet	USB-powered, 10/100 Ethernet, USB JTAG	2G/4G eMMC, onboard HD, USB, Ethernet and HDMI interfaces
Price (\$U.S.)	\$129	\$149	\$89	\$45/\$55

New

## Introducing...



## Capes expand BeagleBone





# The Community

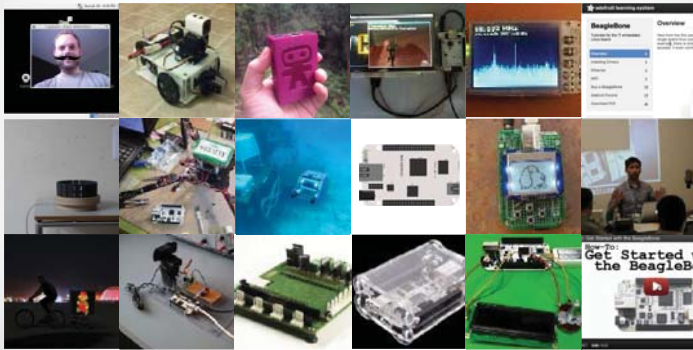
- eLinux.org
- BeagleBoard.org
- Google Group
- IRC



- "OpenROV is a Do It Yourself telorobotics community centered around underwater exploration and education"
- There is an OpenROV Cape  
[http://circuitco.com/support/index.php?title=BeagleBone\\_ROV](http://circuitco.com/support/index.php?title=BeagleBone_ROV)



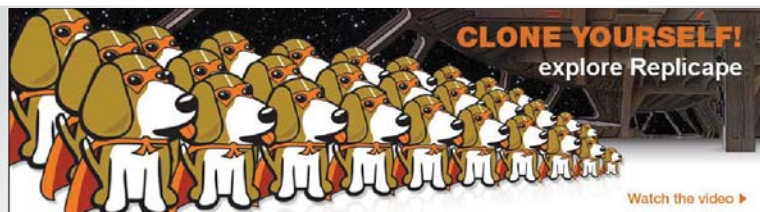
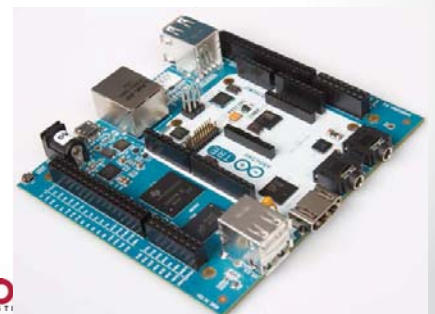
# Projects



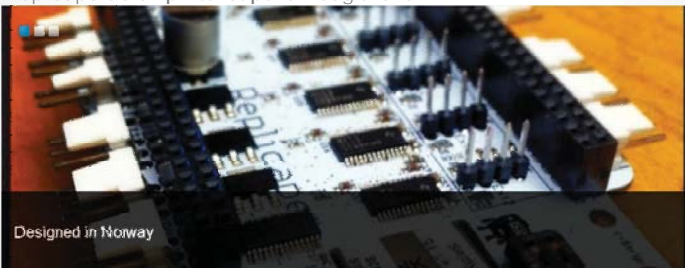
<http://www.youtube.com/watch?v=Nlk81eCuqu0>



- BeagleBoard and Arduino combined



Replacape is a 3D printer cape for BeagleBone



Designed in Norway

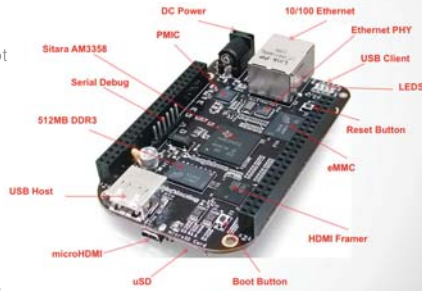
Software written in Python for maintainability and hackability.  
[http://www.youtube.com/watch?feature=player\\_embedded&v=7Sx15geo10w](http://www.youtube.com/watch?feature=player_embedded&v=7Sx15geo10w)

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# Technical Details

- Hardware
  - System on Chip
  - Pin Outs
- Software
  - Quick to learn – BoneScript
  - Easy to use – Shell Scripts
  - Powerful – C

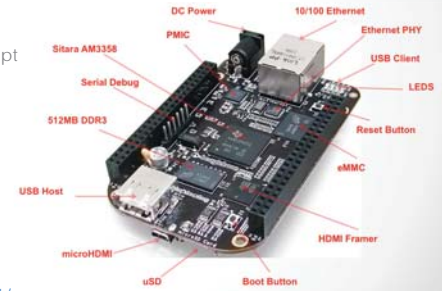


<http://bone/Support/bone101/>

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# Technical Details

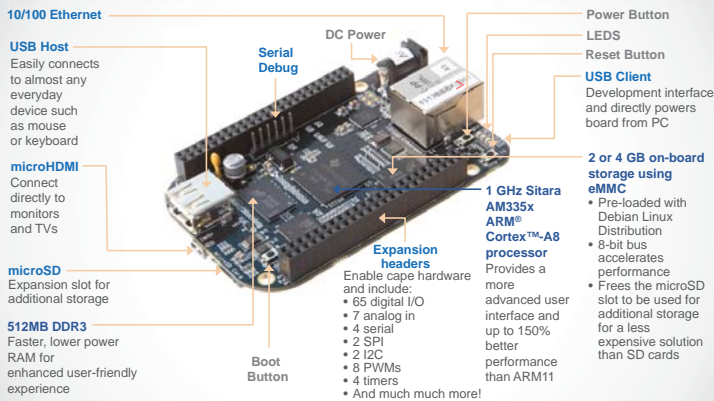
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## BeagleBone Black-ready to use for \$45/\$55



Included in price:
 

- Power supply ~ \$10
- USB network cable ~ \$3
- 2GB on-board storage \$5-\$10
- PRU for real-time tasks typically on FPGA ~ \$20

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## BoneScript

- Familiar Arduino function calls...
  - ...exported to the browser
- Buttons will run code in your browser that will impact the LEDs on your BeagleBone
- The exact code used in the browser is given
  - `digitalWrite()`
  - `digitalRead()`
  - `analogRead()`
  - `attachInterrupt()`
  - `readTextFile()`
  - `writeTextFile()`

<http://bone/Support/bone101/>

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## Cape Expansion Headers

P9				P8			
DSND	1	2	DSND	DSND	1	2	DSND
VDD_3V3	3	4	VDD_3V3	MMC1_DAT6	3	4	MMC1_DAT7
VDD_5V	5	6	VDD_5V	MMC1_DAT2	5	6	MMC1_DAT3
SVS_5V	7	8	SVS_5V	GPIO_66	7	8	GPIO_67
PWR_BTN	9	10	SVS_RESETN	GPIO_69	9	10	GPIO_68
UART4_RXD	11	12	GPIO_60	GPIO_45	11	12	GPIO_44
UART4_TXD	13	14	EHRPWM1A	EHRPWM2B	13	14	GPIO_26
GPIO_48	15	16	EHRPWM1B	GPIO_47	15	16	GPIO_46
SPI0_CS0	17	18	SPI0_D1	GPIO_27	17	18	GPIO_65
I2C2_SCL	19	20	I2C2_SDA	EHRPWM3A	19	20	MMC1_CMD
GPIO_26	21	22	GPIO_60A	MMC1_CLK	21	22	MMC1_DAT5
GPIO_49	23	24	UART1_TXD	MMC1_DAT4	23	24	MMC1_DAT1
GPIO_117	25	26	UART1_RXD	MMC1_DAT0	25	26	GPIO_61
GPIO_115	27	28	SPI1_CS0	LCD_VSYNC	27	28	LCD_PCLK
SPI1_D0	29	30	GPIO_122	LCD_HSYNC	29	30	LCD_AC_BIAS
SPI1_SCLK	31	32	VDD_ADC	LCD_DATA14	31	32	LCD_DATA15
AIN4	33	34	GPIO_ADC	LCD_DATA13	33	34	LCD_DATA11
AIN5	35	36	AIN5	LCD_DATA12	35	36	LCD_DATA10
AIN2	37	38	AIN3	LCD_DATA8	37	38	LCD_DATA9
AIN0	39	40	AIN1	LCD_DATA6	39	40	LCD_DATA7
GPIO_20	41	42	ECAPWM0	LCD_DATA4	41	42	LCD_DATA5
DSND	43	44	DSND	LCD_DATA2	43	44	LCD_DATA3
DSND	45	46	DSND	LCD_DATA0	45	46	LCD_DATA1

LEGEND  
 POWER/GROUND/RESET  
 AVAILABLE DIGITAL  
 AVAILABLE PWM  
 SHARED I2C BUS  
 RECONFIGURABLE DIGITAL  
 ANALOG INPUTS (1.8V)

## Other Languages

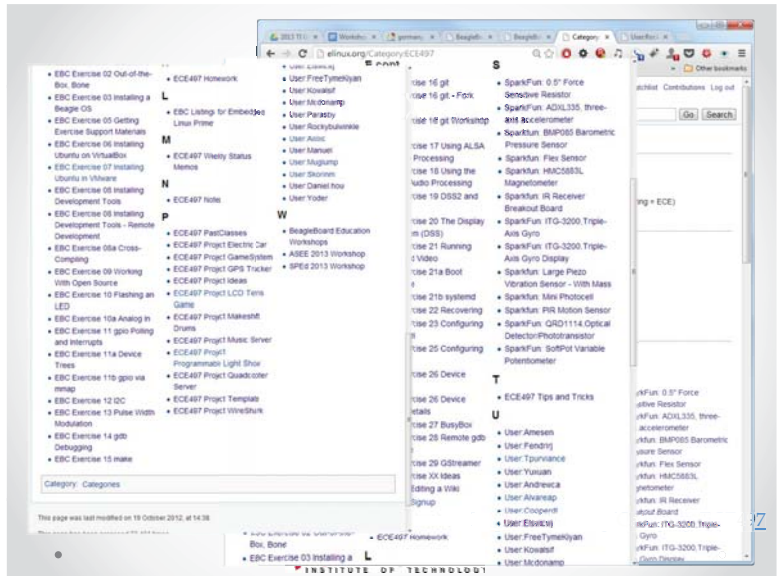
- Out-of-the-box the bone can run
  - C
  - C++
  - bash
  - perl
  - Python
  - JavaScript
- Go, Java, Ruby, Erlang and many, many, many more are very easy to install

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# Teaching with the Bone

- How do you get going?
- Attend a tutorial
- Derek Molloy (<http://derekmolloy.ie/beaglebone/>)
- Yoder's wiki (<http://elinux.org/Category:ECE497>)
- Texts
- Community



# Supporting Texts



# Derek Molloy



<http://derekmolloy.ie/beaglebone/>



# Questions?

- Small
- Inexpensive
- Standard interfaces
- Expandable
- Big support community
- Powerful
- Easy to use
- Low power

