

# Day 01-3

## *Assignment:*

- Homework 01, Due Thursday
- 

## *Today's Topics:*

- Python GPIO
- /sys/

# 01-3 – Blink an LED the Easy Way

Much of this is from  
BeagleBone Cookbook

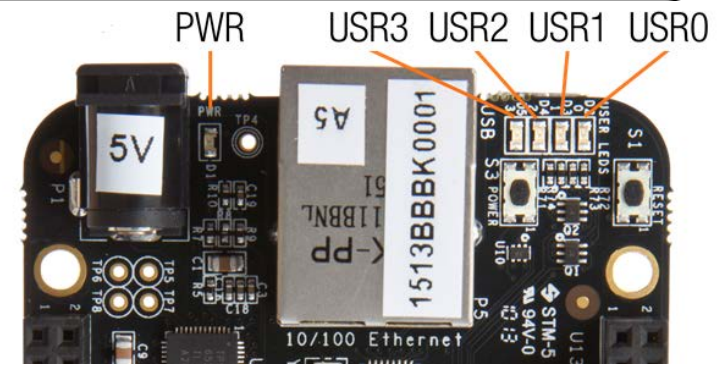
# Adafruit BBIO Python Library

- <https://learn.adafruit.com/setting-up-io-python-library-on-beaglebone-black/overview>

# Blink an LED

```
#!/usr/bin/env python3
import Adafruit_BBIO.GPIO as GPIO
import time
LED = "USR0"
delay = 0.25
GPIO.setup(LED, GPIO.OUT)

while True:
    GPIO.output(LED, 1)
    time.sleep(delay)
    GPIO.output(LED, 0)
    time.sleep(delay)
```



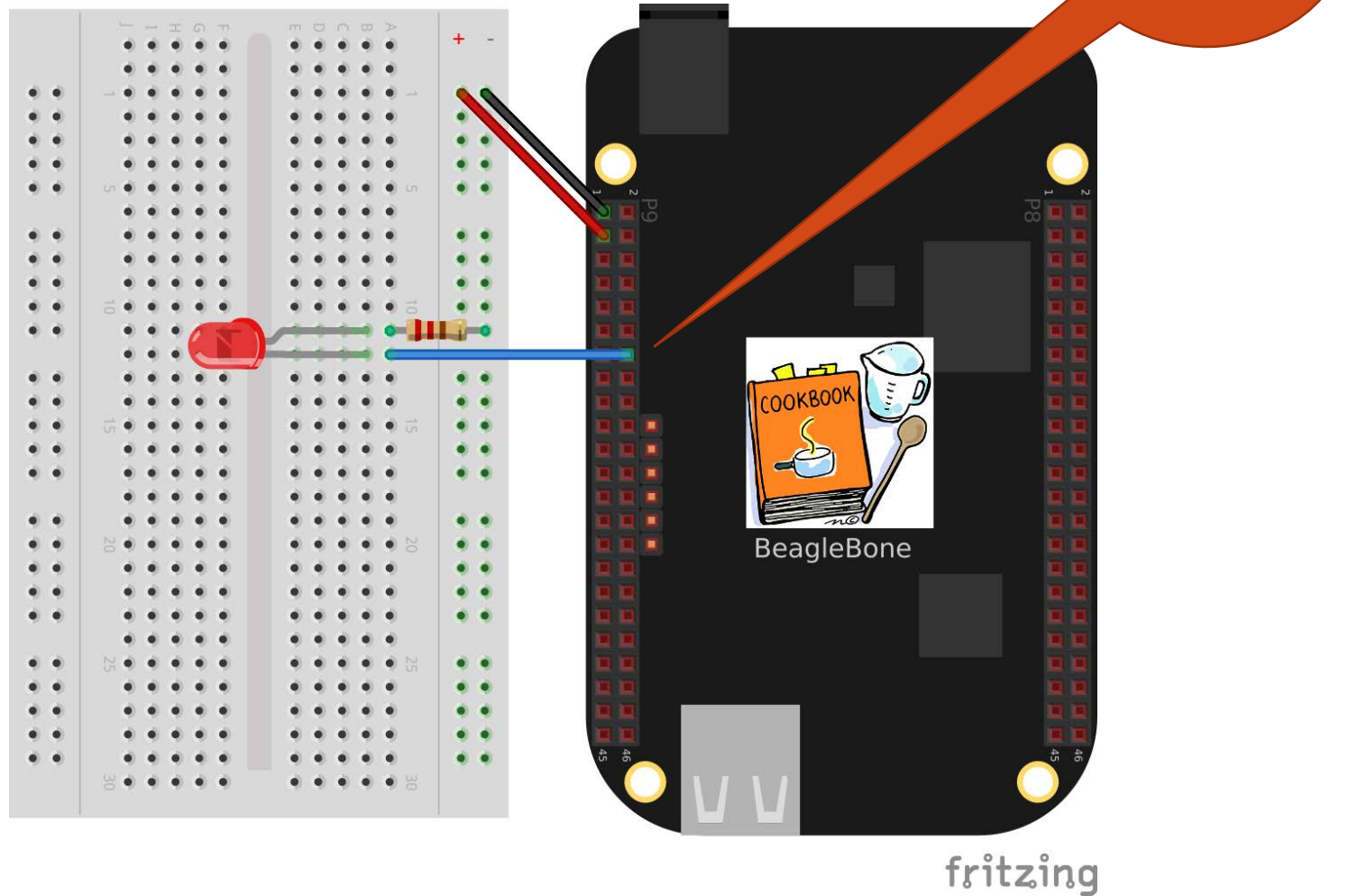
# Running python

- Use Cloud9 debugger
- From command line
- If the first line is: **#!/usr/bin/env python3**

```
bone$ chmod +x ./blink1led.py
```

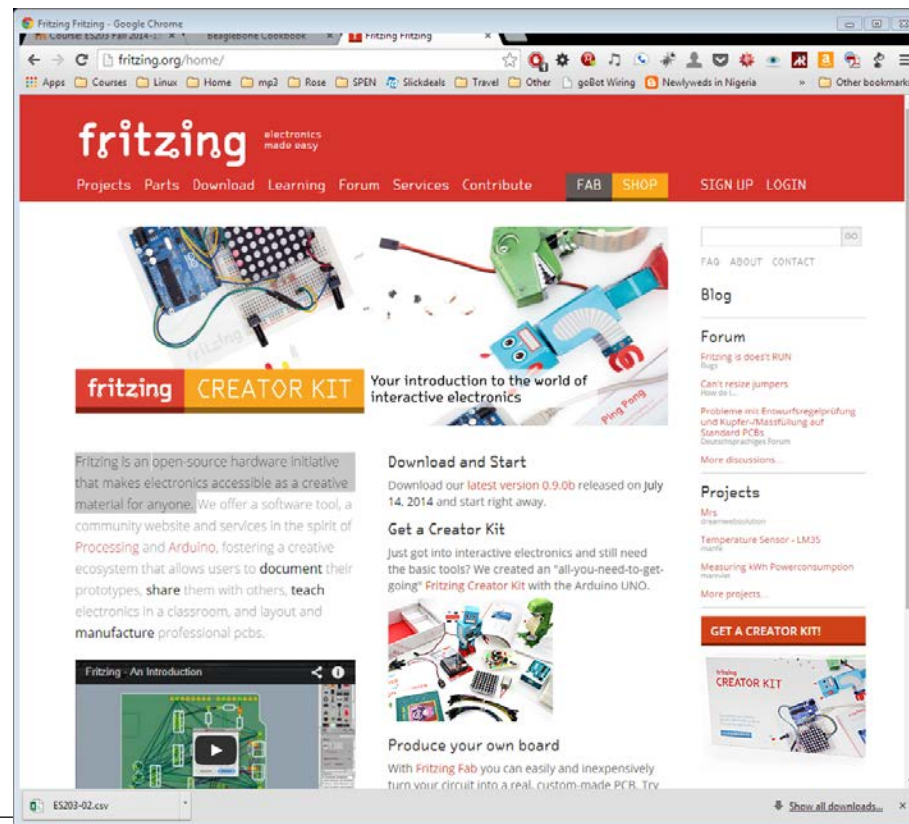
```
bone$ ./blink1led.py
```

# External LED



# Fritzing

- <http://fritzing.org/home/>
- Fritzing is an *open-source hardware initiative* that makes electronics accessible as a creative material for anyone.



# Blink an LED

## External

```
#!/usr/bin/env python3
import Adafruit_BBIO.GPIO as GPIO
import time
```

```
LED = "GP9_14"
delay = 0.25
```

```
GPIO.setup(LED, GPIO.OUT)
```

```
while True:
```

```
    GPIO.output(LED, 1)
    time.sleep(delay)
    GPIO.output(LED, 0)
    time.sleep(delay)
```

## Internal

```
#!/usr/bin/env python3
import Adafruit_BBIO.GPIO as GPIO
import time
```

```
LED = "USR0"
delay = 0.25
```

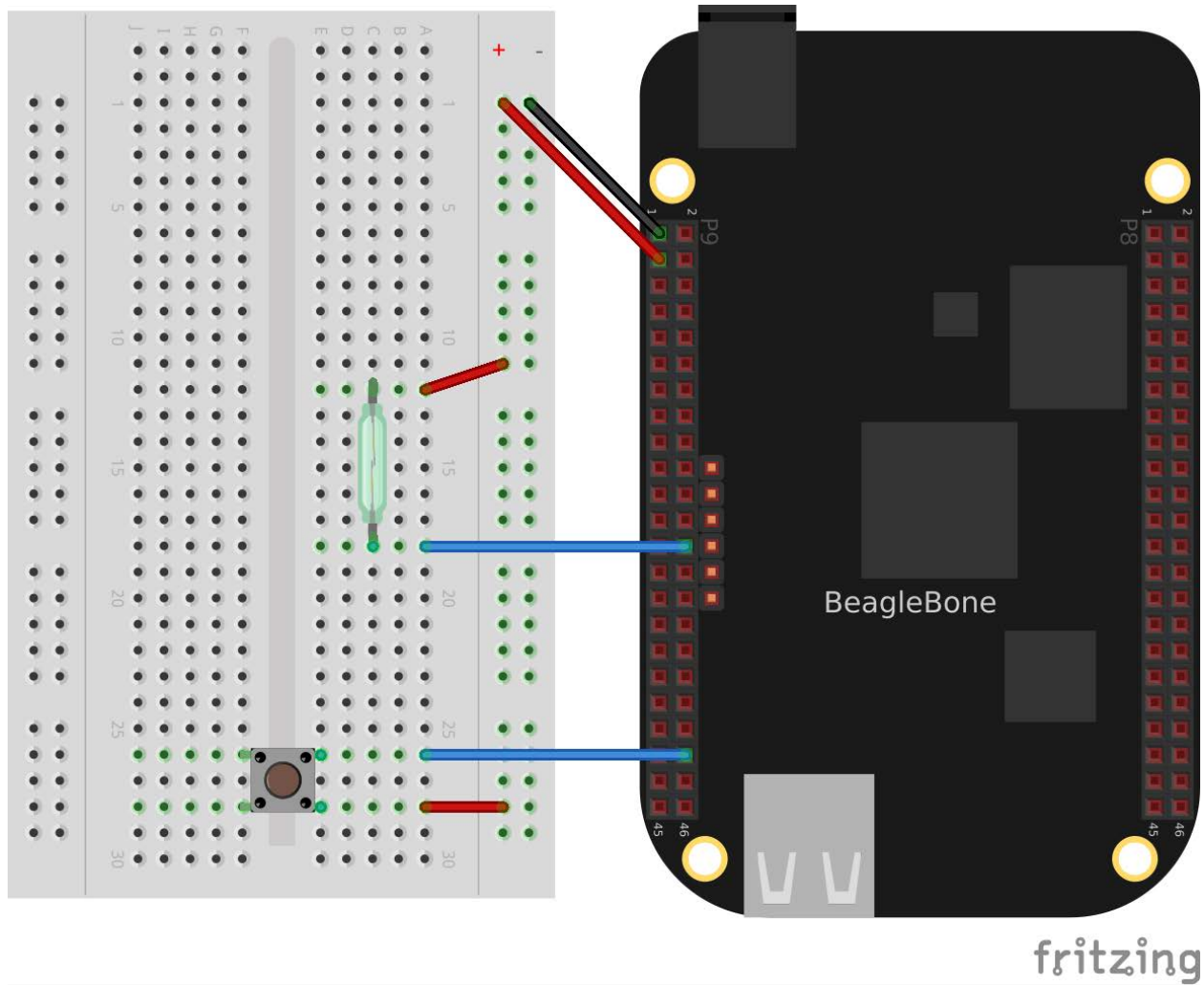
```
GPIO.setup(LED, GPIO.OUT)
```

```
while True:
```

```
    GPIO.output(LED, 1)
    time.sleep(delay)
    GPIO.output(LED, 0)
    time.sleep(delay)
```



# Read a button

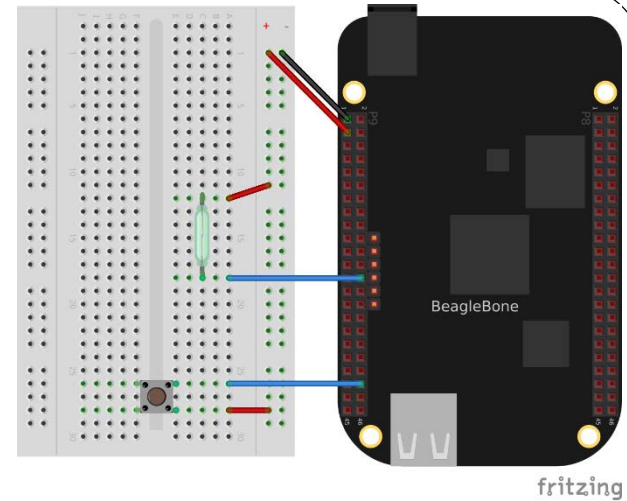


# Button

```
#!/usr/bin/env python3
import Adafruit_BBIO.GPIO as GPIO
import time
button="P9_42"
LED    ="USR3"
# Set the GPIO pins:
GPIO.setup(LED,      GPIO.OUT)
GPIO.setup(button, GPIO.IN)

while True:
    state = GPIO.input(button)
    GPIO.output(LED, state)

    GPIO.wait_for_edge(button, GPIO.BOTH)
    print("Pressed")
```



Careful when pasting code

`exercises/displays/blue/button.py`

# Button - Events

```
#!/usr/bin/env python3
import Adafruit_BBIO.GPIO as GPIO
import time
```

```
buttonP="P9_26"  # PAUSE or MODE
buttonM="P9_42"
```

```
LEDp    ="USR0"
LEDm    ="USR1"
```

```
# Set the GPIO pins:
```

```
GPIO.setup(LEDp,    GPIO.OUT)
GPIO.setup(LEDm,    GPIO.OUT)
GPIO.setup(buttonP, GPIO.IN)
GPIO.setup(buttonM, GPIO.IN)
```

```
# Turn on both LEDs
```

```
GPIO.output(LEDp, 1)
GPIO.output(LEDm, 1)
```

```
# Map buttons to LEDs
```

```
map = {buttonP: LEDp, buttonM: LEDm}
```

```
def updateLED(channel):
```

```
    print("channel = " + channel)
```

```
    state = GPIO.input(channel)
```

```
    GPIO.output(map[channel], state)
```

```
    print(map[channel] + " Toggled")
```

```
print("Running...")
```

```
GPIO.add_event_detect(buttonP, GPIO.BOTH, callback=updateLED)
```

```
# RISING, FALLING or BOTH
```

```
GPIO.add_event_detect(buttonM, GPIO.BOTH, callback=updateLED)
```

```
try:
```

```
    while True:
```

```
        time.sleep(100)    # Let other processes run
```

```
except KeyboardInterrupt:
```

```
    print("Cleaning Up")
```

```
    GPIO.cleanup()
```

```
GPIO.cleanup()
```

**exercises/displays/blue/buttonEvent.py**

# 65 possible digital I/Os

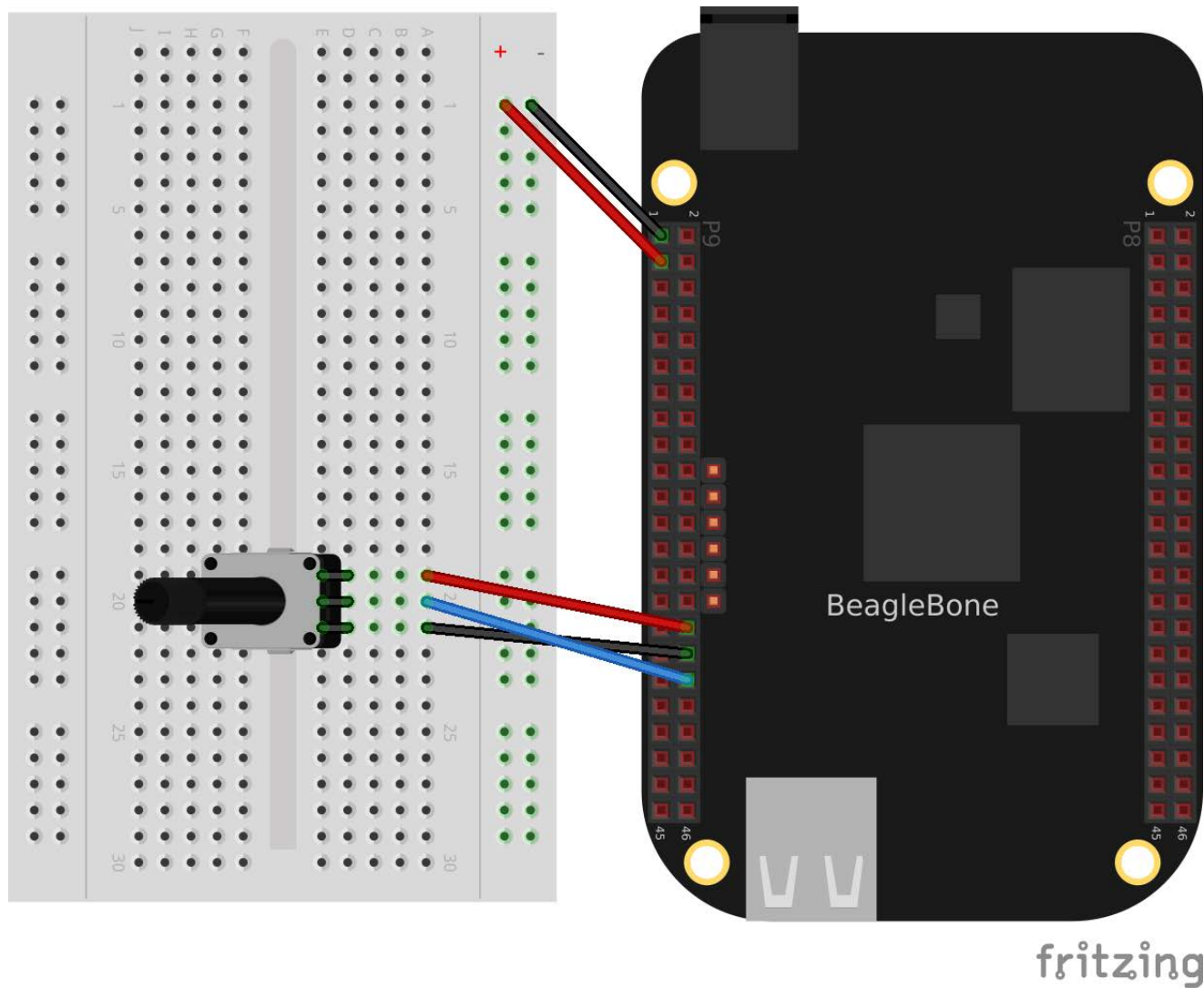
P9

DGND	1	2	DGND
VDD_3V3	3	4	VDD_3V3
VDD_5V	5	6	VDD_5V
SYS_5V	7	8	SYS_5V
PWR_BUT	9	10	SYS_RESETN
GPIO_30	11	12	GPIO_60
GPIO_31	13	14	GPIO_50
GPIO_48	15	16	GPIO_51
GPIO_5	17	18	GPIO_4
I2C2_SCL	19	20	I2C2_SDA
GPIO_3	21	22	GPIO_2
GPIO_49	23	24	GPIO_15
GPIO_117	25	26	GPIO_14
GPIO_115	27	28	GPIO_123
GPIO_121	29	30	GPIO_122
GPIO_120	31	32	VDD_ADC
AIN4	33	34	GNDA_ADC
AIN6	35	36	AIN5
AIN2	37	38	AIN3
AIN0	39	40	AIN1
GPIO_20	41	42	GPIO_7
DGND	43	44	DGND
DGND	45	46	DGND

P8

DGND	1	2	DGND
GPIO_38	3	4	GPIO_39
GPIO_34	5	6	GPIO_35
GPIO_66	7	8	GPIO_67
GPIO_69	9	10	GPIO_68
GPIO_45	11	12	GPIO_44
GPIO_23	13	14	GPIO_26
GPIO_47	15	16	GPIO_46
GPIO_27	17	18	GPIO_65
GPIO_22	19	20	GPIO_63
GPIO_62	21	22	GPIO_37
GPIO_36	23	24	GPIO_33
GPIO_32	25	26	GPIO_61
GPIO_86	27	28	GPIO_88
GPIO_87	29	30	GPIO_89
GPIO_10	31	32	GPIO_11
GPIO_9	33	34	GPIO_81
GPIO_8	35	36	GPIO_80
GPIO_78	37	38	GPIO_79
GPIO_76	39	40	GPIO_77
GPIO_74	41	42	GPIO_75
GPIO_72	43	44	GPIO_73
GPIO_70	45	46	GPIO_71

# Analog in



# Analog Code

```
#!/usr/bin/env python3
# From: https://learn.adafruit.com/setting-up-io-python-library-on-beaglebone-black/adc
import Adafruit_BBIO.ADC as ADC
ADC.setup()
value = ADC.read("P9_40")
voltage = value * 1.8 #1.8V
```

# 7 analog inputs (1.8V)

P9

DGND	1	2	DGND
VDD_3V3	3	4	VDD_3V3
VDD_5V	5	6	VDD_5V
SYS_5V	7	8	SYS_5V
PWR_BUTTON	9	10	SYS_RESETN
GPIO_30	11	12	GPIO_60
GPIO_31	13	14	GPIO_50
GPIO_48	15	16	GPIO_51
GPIO_5	17	18	GPIO_4
I2C2_SCL	19	20	I2C2_SDA
GPIO_3	21	22	GPIO_2
GPIO_49	23	24	GPIO_15
GPIO_117	25	26	GPIO_14
GPIO_115	27	28	GPIO_123
GPIO_121	29	30	GPIO_122
GPIO_120	31	32	VDD_ADC
AIN4	33	34	GNDA_ADC
AIN6	35	36	AIN5
AIN2	37	38	AIN3
AIN0	39	40	AIN1
GPIO_20	41	42	GPIO_7
DGND	43	44	DGND
DGND	45	46	DGND

P8

DGND	1	2	DGND
GPIO_38	3	4	GPIO_39
GPIO_34	5	6	GPIO_35
GPIO_66	7	8	GPIO_67
GPIO_69	9	10	GPIO_68
GPIO_45	11	12	GPIO_44
GPIO_23	13	14	GPIO_26
GPIO_47	15	16	GPIO_46
GPIO_27	17	18	GPIO_65
GPIO_22	19	20	GPIO_63
GPIO_62	21	22	GPIO_37
GPIO_36	23	24	GPIO_33
GPIO_32	25	26	GPIO_61
GPIO_86	27	28	GPIO_88
GPIO_87	29	30	GPIO_89
GPIO_10	31	32	GPIO_11
GPIO_9	33	34	GPIO_81
GPIO_8	35	36	GPIO_80
GPIO_78	37	38	GPIO_79
GPIO_76	39	40	GPIO_77
GPIO_74	41	42	GPIO_75
GPIO_72	43	44	GPIO_73
GPIO_70	45	46	GPIO_71



# Pulse Width Modulation (PWM)

```
#!/usr/bin/env python3
```

```
# From: https://learn.adafruit.com/setting-up-io-python-library-on-beaglebone-black/pwm
```

```
import Adafruit_BBIO.PWM as PWM
```

```
#PWM.start(channel, duty, freq=2000, polarity=0)
```

```
PWM.start("P9_14", 50)
```

#optionally, you can set the frequency as well as the polarity from their defaults:

```
PWM.start("P9_14", 50, 1000, 1)
```

```
PWM.set_duty_cycle("P9_14", 50)
```

```
PWM.set_frequency("P9_14", 100)
```

```
exercises/displays/blue/pwm.py
```



# External LED

