

## Day 02-2

### Assignment:

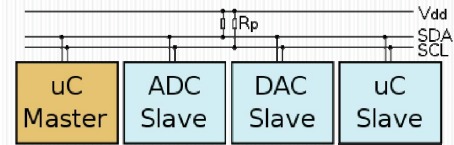
- Hw 02, Due Tuesday
- Hw 03, Due Next Tuesday
- 

### Today's Topics:

- Project Ideas
- I2C
- LED Matrix

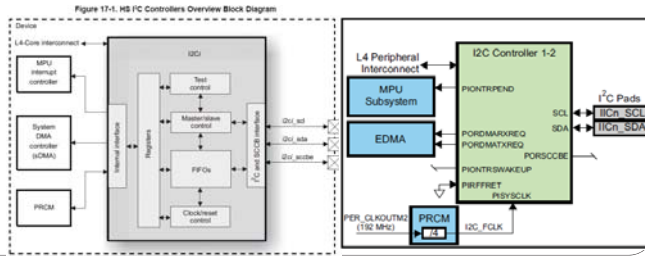
## 02-2 I2C

Interfacing with sensors over a serial bus



## I<sup>2</sup>C

- “two-wire interface” standard
- Used to attach low-speed peripherals to embedded systems
- The Bone has three I<sup>2</sup>C controllers (Section 21 of TRM)



## Hardware - Bone

Display Kernel Log Messages

- You can see which ones are configured at boot time

```
bone$ dmesg | grep i2c
[ 1.577027] omap_i2c 44e0b000.i2c: could not find pctldev for node
/ocp/14_wkup@44c00000/scm@210000/pinmux@800/pinmux_i2c0_pins, deferring
probe
[ 1.577893] omap_i2c 4802a000.i2c: bus 1 rev0.11 at 400 kHz
[ 1.578556] omap_i2c 4819c000.i2c: bus 2 rev0.11 at 400 kHz
[ 2.200784] i2c /dev entries driver
[ 2.438435] input: tps65217_pwr_but as
/devices/platform/ocp/44e0b000.i2c/i2c-0/0-0024/input/input0
[ 2.464756] omap_i2c 44e0b000.i2c: bus 0 rev0.11 at 400 kHz
```

Three buses each running at same speeds

## dmesg -Hw

Human readable

Wait for more input

```
[ +0.147158] IPv6: ADDRCONF(NETDEV_CHANGE): SoftAp0: link becomes ready
[Sep 8 08:20] fbttft: module is from the staging directory, the quality is unknown,
you have been warned.
[ +0.016886] fbttft_device: module is from the staging directory, the quality is
unknown, you have been warned.
[ +0.001700] spidev spi1.0: spidev spi1.0 24000kHz 8 bits mode=0x00
[ +0.000026] spidev spi1.1: spidev spi1.1 24000kHz 8 bits mode=0x00
[ +0.000188] spidev spi1.0: Deleting spi1.0
[ +0.009426] fbttft_device: GPIOs used by 'adafruit28':
[ +0.000026] fbttft_device: 'reset' = GPIO113
[ +0.000008] fbttft_device: 'dc' = GPIO116
[ +0.000022] spidev spi1.1: spidev spi1.1 24000kHz 8 bits mode=0x00
[ +0.000014] spi spi1.0: fb_ili9341 32000kHz 8 bits mode=0x00
[ +0.043846] fb_ili9341: module is from the staging directory, the quality is
unknown, you have been warned.
[ +0.344838] Console: switching to colour frame buffer device 40x30
[ +0.000694] graphics fb0: fb_ili9341 frame buffer, 320x240, 150 KiB video
memory, 16 KiB DMA buffer memory, fps=20, spi1.0 at 32 MHz
[Sep 8 08:22] usb 1-1.4: USB disconnect, device number 8
[Sep 8 08:34] usb 1-1.1: USB disconnect, device number 3
[ +0.000030] usb 1-1.1.1: USB disconnect, device number 9
```

## Hardware - Bone

- You can see which ones are configured at boot time

```
bone$ dmesg | grep i2c
[ 1.577027] omap_i2c 44e0b000.i2c: could not find pctldev for node
/ocp/14_wkup@44c00000/scm@210000/pinmux@800/pinmux_i2c0_pins, deferring
probe
[ 1.577893] omap_i2c 4802a000.i2c: bus 1 rev0.11 at 400 kHz
[ 1.578556] omap_i2c 4819c000.i2c: bus 2 rev0.11 at 400 kHz
[ 2.200784] i2c /dev entries driver
[ 2.438435] input: tps65217_pwr_but as
/devices/platform/ocp/44e0b000.i2c/i2c-0/0-0024/input/input0
[ 2.464756] omap_i2c 44e0b000.i2c: bus 0 rev0.11 at 400 kHz
```

Three buses each running at same speeds

Time in seconds

Sept-2016

```
[ 2.105100] i2c /dev entries driver
[ 2.228438] input: tps65217_pwr_but as
/devices/platform/ocp/44e0b000.i2c/i2c-0/0-0024/input/input0
[ 2.258422] omap_i2c 44e0b000.i2c: bus 0 rev0.11 at 400 kHz
[ 2.262395] omap_i2c 4819c000.i2c: bus 2 rev0.11 at 100 kHz
[ 94.721560] omap_i2c 4802a000.i2c: bus 1 rev0.11 at 100 kHz
```

The diagram shows a BeagleBone Black board with various components labeled. A red box highlights the I2C bus pins and a note says "No pullup resistors needed".

The 0<sup>th</sup> I2C bus can't be used for other digital I/O operations without interfering with that function, but you can still use it to add other I2C devices at available addresses.  
The 1<sup>st</sup> I2C bus is available for you to configure and use.

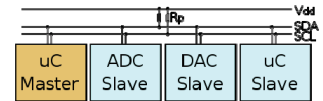
## Hardware – TMP101

- Goal: Interface to a TMP101 temp sensor

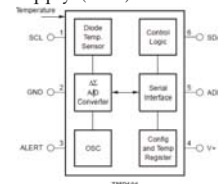
Parameter Name	Value
Typical Accuracy (°)	±2.0°C from -25°C to +85°C (max) ±3.0°C from -55°C to +125°C (max)
Supply Current (µA)	45µA, 0.1µA Standby
Resolution	9- to 12-bits,
Operating Voltage Range (V)	2.7V to 5.5V
Device Description	Serial Output Temp Sensor

<http://www.ti.com/lit/gpn/tmp101>

## 2-wire bus



- The two wires are
  - Serial Clock (SCL), is an input to the TMP101 and is used to clock data into and out of the TMP101.
  - Serial Data (SDA), is bidirectional and carries the data to and from the TMP101.
- The only other two pins on the TMP101 that you need to use are the Power Supply (Vdd) and Ground.



## Software - bone

- See what's on a bus with **i2cdetect**

```
bone$ i2cdetect -y -r 1
    0  1  2  3  4  5  6  7  8  9  a  b  c  d  e  f
00:  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --
10:  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --
20:  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --
30:  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --
40:  --  --  --  --  --  --  --  --  --  --  48 49  --  --  --  --
50:  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --
60:  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --
70: 70  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --
```

I have 2, TMP101's and an LED matrix.

- The TMP101's are at **1001 000** and **1001 001**
- Convert to hex **0x48** and **0x49**

## Registers

- Each TMP101 has four registers

Table 2. Pointer Addresses of the TMP100 and TMP101 Registers

P1	P0	REGISTER
0	0	Temperature Register (READ Only)
0	1	Configuration Register (READ/WRITE)
1	0	TLOW Register (READ/WRITE)
1	1	THIGH Register (READ/WRITE)

- Read with **\$ i2cget -y 1 0x48 00**
- 0x18** which is 24C or 75.2F

Table 6. Configuration Register Format

BYTE	D7	D6	D5	D4	D3	D2	D1	D0
1	OS/ALERT	R1	R0	F1	F0	POL	TM	SD

Table 2. Pointer Addresses of the TMP100 and TMP101 Registers

P1	P0	REGISTER
0	0	Temperature Register (READ Only)
0	1	Configuration Register (READ/WRITE)
1	0	T <sub>LOW</sub> Register (READ/WRITE)
1	1	T <sub>HIGH</sub> Register (READ/WRITE)

- Read with `$ i2cget -y 1 0x48 01`
- `0x80` which is `1000 0000`

Table 6. Configuration Register Format

BYTE	D7	D6	D5	D4	D3	D2	D1	D0
1	OS/ALERT	R1	R0	F1	F0	POL	TM	SD

SD – Shutdown Mode  
 TM – Thermostat Mode  
 POL – Polarity  
 F1/F0 – Fault Queue  
 R1/R0 – Converter Resolution  
 OS – OS/Alert

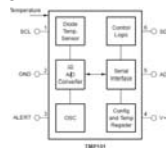


Table 8. Resolution of the TMP100 and TMP101

R1	R0	RESOLUTION	CONVERSION TIME (typical)
0	0	9 Bits (0.5°C)	40ms
0	1	10 Bits (0.25°C)	80ms
1	0	11 Bits (0.125°C)	160ms
1	1	12 Bits (0.0625°C)	320ms

## Read TMP101

```
#!/usr/bin/env python3
# Read a TMP101 sensor
# sudo apt install python3-smbus
```

Must install

```
import smbus
import time
```

Bus Number

```
bus = smbus.SMBus(1)
address = 0x49
```

Address of device

```
while True:
    temp = bus.read_byte_data(address, 0)
    print (temp, end="\r")
    time.sleep(0.25)
```

Register to read

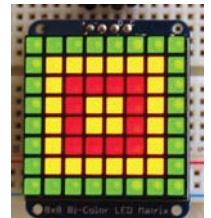
- smbus commands

```
read_byte_data(int addr,char cmd)
write_byte_data(int addr,char cmd, char val)
write_byte_data(int addr,char cmd, char val)
write_i2c_block_data(int addr, char cmd, long vals[])
```

<http://www.raspberry-projects.com/pi/programming-in-python/i2c-programming-in-python/using-the-i2c-interface-2>

## LED Matrix

- In the lab you will be interfacing an I2C LED matrix
- Some are bicolor (red and green)
- Some are single color
- Both interface the same way: i2c
- How many wires to you need to control 128 LEDs?



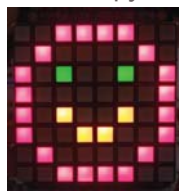
<https://www.adafruit.com/products/902>

<https://www.adafruit.com/products/871>

## exercises/displays/matrix8x8/i2cmatrix.py

```
#!/usr/bin/env python3
import smbus
import time
bus = smbus.SMBus(1) # Use i2c bus 1
matrix = 0x70 # Use address

# The first byte is GREEN, the second is RED.
smile = [0x00, 0x3c, 0x00, 0x42, 0x28, 0x89, 0x04, 0x85,
0x04, 0x85, 0x28, 0x89, 0x00, 0x42, 0x00, 0x3c]
]
frown = [0x3c, 0x00, 0x42, 0x00, 0x85, 0x20, 0x89, 0x00,
0x89, 0x00, 0x85, 0x20, 0x42, 0x00, 0x3c, 0x00]
]
neutral = [0x3c, 0x3c, 0x42, 0x42, 0xa9, 0xa9, 0x89, 0x89,
0x89, 0x89, 0xa9, 0xa9, 0x42, 0x42, 0x3c, 0x3c]
]
```



## exercises/displays/matrix8x8/i2cmatrix.py

```
# Start oscillator (p10)
bus.write_byte_data(matrix, 0x21, 0)
# Disp on, blink off (p11)
bus.write_byte_data(matrix, 0x81, 0)
# Full brightness (page 15)
bus.write_byte_data(matrix, 0xe7, 0)
```



exercises/displays/matrix8x8/i2c



```
bus.write_i2c_block_data(matrix, 0, frown)
time.sleep(delay)

bus.write_i2c_block_data(matrix, 0, neutral)

for fade in range(0xe0, 0xef, 1):
    bus.write_byte_data(matrix, fade, 0)
    time.sleep(delay/10)

bus.write_i2c_block_data(matrix, 0, smile)
```

## Writing one column

```
bus.write_i2c_block_data(matrix,
                          0x04, [0xff]);
```

- Turns on the third column of *green* LEDs, without writing the other columns
- Try it!

## LED Matrix

- Goal: Etch-a-Sketch on the LED Matrix!