



PANTECH SOLUTIONS
Technology Beyond the Dreams

BRAIN CONTROLLED ROBOT DESIGN

Organized by
Pantech Solutions
&

National Institute of Technology
Karnataka, Surathkal
[STEP]





All Participants, Please fill the Attendance form, Link will be given in the description after 11:10 A.M

ABOUT NITK

01

PROFILE

Founded in 1960 | Well known as
Karnataka Regional Engineering
College (KREC)

02

VISION

To facilitate transformation of students into
good human beings, responsible citizens &
competent professionals, focusing on the
assimilation, generation and dissemination of
knowledge.

ABOUT PANTECH

01

PROFILE

Founded in 2004 | 7 Branches |
100+ Team

03

R & D

Manufacturer of Lab equipment's & Development
boards | Industrial & Funded projects | Online
retail store of engineering products and projects

02

OUR SERVICES

Lab equipment, Engineering Kits,
Components, Sensors and All level
Projects

04

TRAINING

1500+ Workshops | 250+ FDP |
100+ Seminars

PANTECH TECHNOLOGY

Manufacturer of Embedded development Boards | FPGA Boards | Sensors | Interface Modules | E- Vehicle | Renewable energy systems | Motors and Drivers | Power electronics | Power Systems

ELECTRONICS & ELECTRICAL



ROBOTICS & MECHANICAL

Robotics | Mechanical components | 3D design and printing | Autonomous Robot design



Machine Learning | Deep Learning | NLP | Chatbot | Block chain | Data science and AI boards | AR & VR products | Android development | Cyber security | Cloud & Mobile computing | IoT

AI & Software










BRAIN COMPUTER INTERFACE

Brain wave analysis | Brain controlled applications | Manufacturer of EEG headband



AGENDA | BRAIN COMPUTER INTERFACE[BCI]

-  Overview on Brain computer Interface
-  Live Demo on BCI using EEG Headband | Brainsense
-  Robot Design Arduino | Motor Driver
-  Bluetooth Configuration
-  Assembly and Connections
-  Working principle
-  Video Demo on BCI Application using Matlab | Arduino | Raspberry Pi & OpenBCI

BCI (Brain Computer Interface)

- Communication using Thoughts of Brain (EEG) without using any Muscle control, Especially for Severely Paralyzed people

BRAIN COMPUTER INTERFACE

OVERVIEW

Application of BCI

Neuralink

Brainsense

Electrode Placement &
Signal Detection

Anatomy & Function mapping

BCI Devices

Types of Electrodes

Bio Signal

EEG & its Bands



BRAINSENSE FEATURES

Specification

- Direct connect to dry electrode
- One EEG channel + Reference + Ground
- RAW EEG at 512Hz
- Operating voltage 2.97 -3.63V
- 3-100Hz frequency range

Data Outputs

RAW EEG Signal | Attention | Meditation
Delta, Theta, alpha, beta and gamma waves



THINKGEAR MODULE

Specification

- TGAM MODULE offers e-Sense technology
- Outputs Attention, Meditation and Physical eye blinks from raw EEG data
- 2.79cm x 1.52cm x 0.25cm, weighs 130mg
- Communicates through UART interface at Baudrate 1200, 9600 or 57600



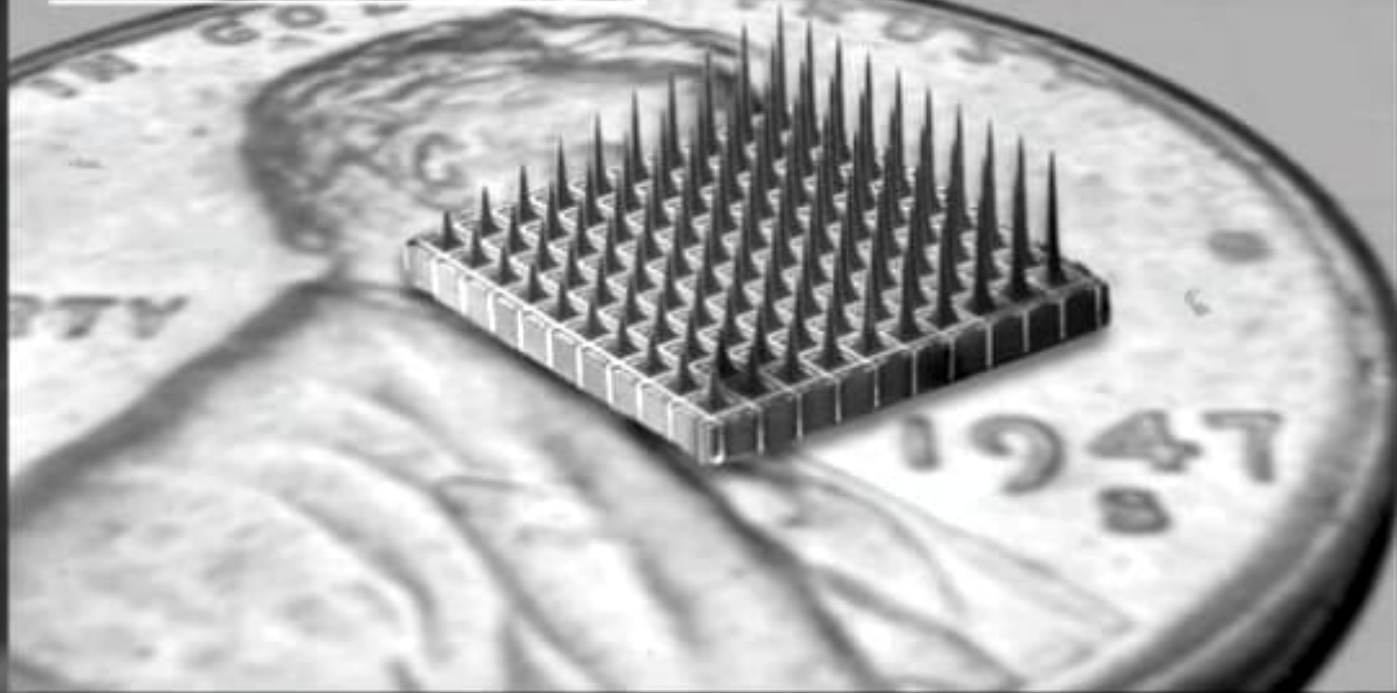
```

1: 01: 0xAA // [SYNC]
2: 02: 0xAA // [SYNC]
3: 03: 0x20 // [LENGTH] (payload length) of 32 bytes
4: 04: 0x02 // [POOR_SIGNAL] Quality
5: 05: 0x00 // No poor signal detected (0/200)
6: 06: 0x83 // [ASIC_REG_POWER_INT]
7: 07: 0x18 // [VLENGTH] 24 bytes
8: 08: 0x00 // (1/3) Begin Delta bytes
9: 09: 0x00 // (2/3)
10: 10: 0x94 // (3/3) End Delta bytes
11: 11: 0x00 // (1/3) Begin Theta bytes
12: 12: 0x00 // (2/3)
13: 13: 0x82 // (3/3) End Theta bytes
14: 14: 0x00 // (1/3) Begin Low-alpha bytes
15: 15: 0x00 // (2/3)
16: 16: 0x0B // (3/3) End Low-alpha bytes
17: 17: 0x00 // (1/3) Begin High-alpha bytes
18: 18: 0x00 // (2/3)
19: 19: 0x64 // (3/3) End High-alpha bytes
20: 20: 0x00 // (1/3) Begin Low-beta bytes
21: 21: 0x00 // (2/3)
22: 22: 0x4D // (3/3) End Low-beta bytes
23: 23: 0x00 // (1/3) Begin High-beta bytes
24: 24: 0x00 // (2/3)
25: 25: 0x3D // (3/3) End High-beta bytes
26: 26: 0x00 // (1/3) Begin Low-gamma bytes
27: 27: 0x00 // (2/3)
28: 28: 0x07 // (3/3) End Low-gamma bytes
29: 29: 0x00 // (1/3) Begin Mid-gamma bytes
30: 30: 0x00 // (2/3)
31: 31: 0x05 // (3/3) End Mid-gamma bytes
32: 32: 0x04 // [ATTENTION] eSense
33: 33: 0x0D // eSense Attention level of 13
34: 34: 0x05 // [MEDITATION] eSense
35: 35: 0x3D // eSense Meditation level of 61
36: 36: 0x34 // [CHECKSUM] 1's comp. inverse of 3-bit payload sum of 0x35

```

TGAM PACKET FORMAT

Utah Slant Electrode Array



ARDUINO UNO

Specification

- Power : Vin, 3.3V, 5V, GND
- Analog Pins: A0 - A5
- IO Pins: D0 - D13
- Serial - 0 (Rx) & 1 (Tx)
- External Interrupt: 2 & 3
- PWM : 3, 5, 6, 9 & 11
- Inbuilt LED: D13



MOTOR DRIVER - L293D

Specification

- Voltage Range: 4.5 to 36 V
- Separate Input-Logic Supply
- Output Current 1A per channel
- H- Bridge



BLUETOOTH CONFIGURATION

Specification

- Finding Serial Unique number of Brainsense
- Connection using Arduino/NodeMCU
- Set Bluetooth in Configurable Mode
- Configure AT Commands using Terminal software.
- While configuring each AT commands verify is it returning OK.



BLUETOOTH CONFIGURATION

AT Commands

`AT+NAME="PANTECH"`

`AT+UART="57600,0,0"`

`AT+ROLE="1"`

`AT+PSWD="1234"`

`AT+CMODE="0"`

`AT+BIND="XXXX,YY,ZZZZZ"(Brainsense UniqueNumber)`

`AT+IAC="9E8B33"`

`AT+CLASS="0"`

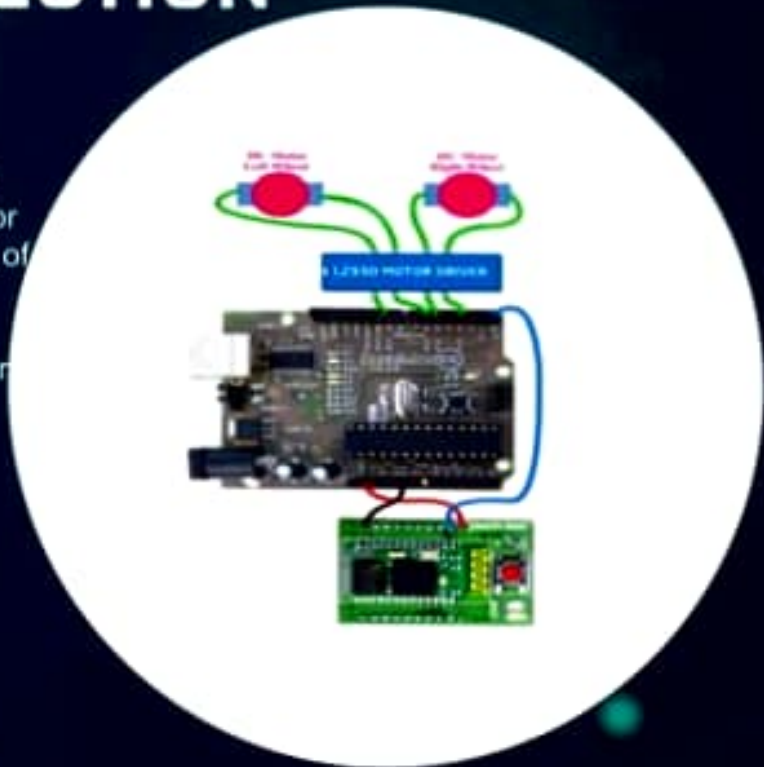
`AT+INQM="1,9,48"`



ASSEMBLY & CONNECTION

Connection

- Then Arduino data line (GPIO) is given to motor driver (L2930) and then it is given to pins of motor driver. After that output of driver is given to input of the motor
- The Transmitter and Receiver of the Arduino is connected to Bluetooth Receiver and Transmitter



WORKING OF BCI APPLICATION



ARDUINO | BRAINSENSE



SIGNAL
ACQUISITION

HARDWARE
APPLICATIONS



WHEEL
CHAIR

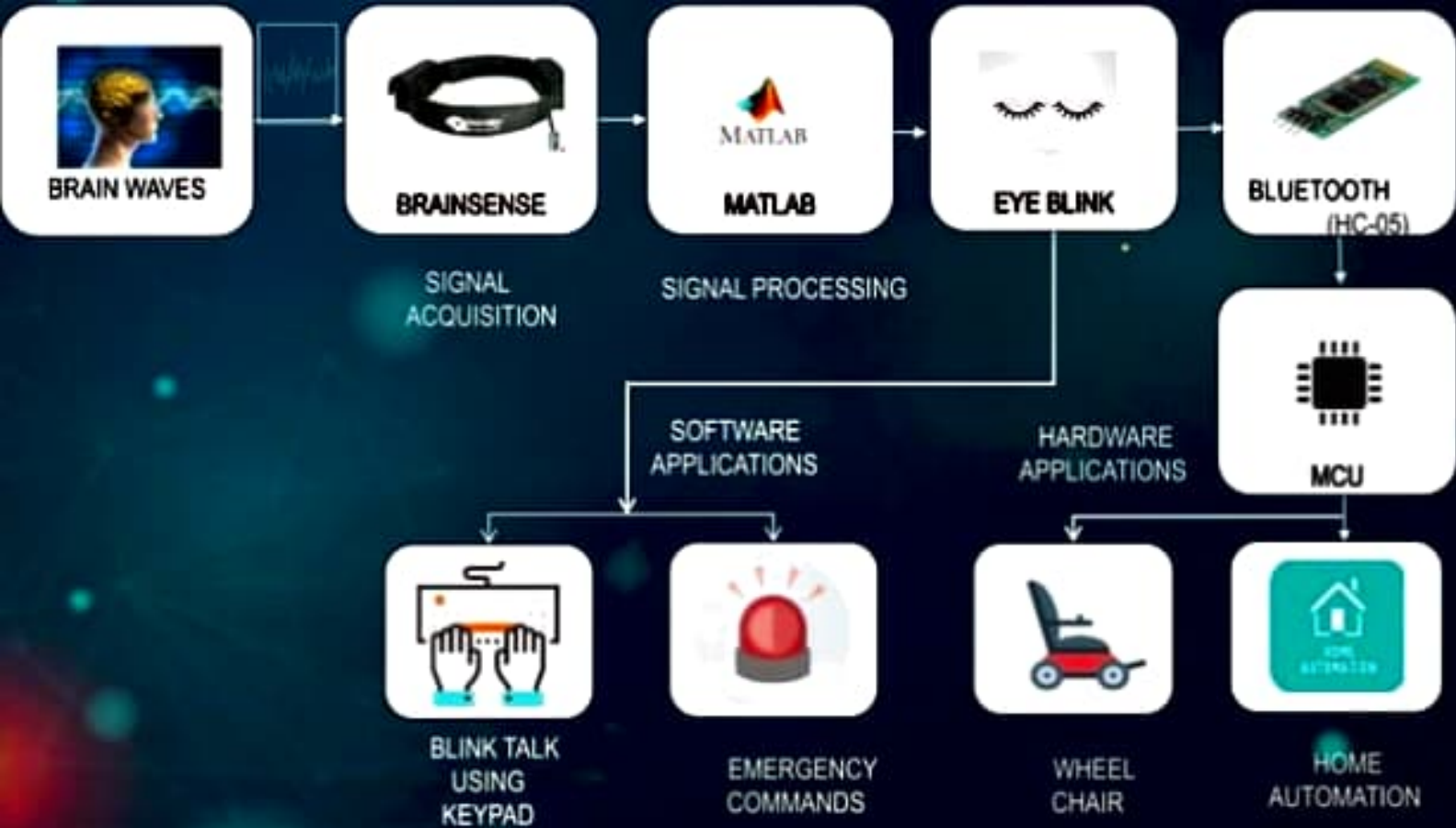


HOME
AUTOMATION

WORKING OF BCI APPLICATION



MATLAB | BRAINSENSE | ARDUINO



APPLICATIONS OF



BRAIN COMPUTER INTERFACE