

Advanced concepts in deep learning 2

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sonography.ai

XAI (Explainable AI)

- Classify different dog breeds (e.g. the Stanford database with 120 breeds) or hotdogs. Generate cute cat pictures!
- Healthcare, self-driving cars
- Black-box nature of DL hinders its adoption in critical applications
- XAI provides interpretable and understandable explanations
- XAI can also partially address some issues regarding ethics and bias



Click on a word below and Imagen!

A photo of a **An oil painting of a**
fuzzy panda British Shorthair cat **Persian cat** Shiba Inu dog raccoon
wearing a **cowboy hat** and wearing a sunglasses and
red shirt **black leather jacket**
playing a **guitar** riding a bike skateboarding
in a **garden**. on a beach. on top of a mountain.

From <https://imagen.research.google>



From:
www.theverge.com/tldr/2017/5/14/15639784/hbo-silicon-valley-not-hotdog-app-download

XAI Approaches

- **Perturbation:** Changes to features in the input data (e.g. masking, conditional sampling).
- **BackProb:** Back-propagated gradients from output prediction layer back to input layer, e.g. saliency maps, saliency relevance maps, and class activation maps

Perturbation XAI, RISE

- Randomized Input Sampling for Explanation (RISE). 2018:

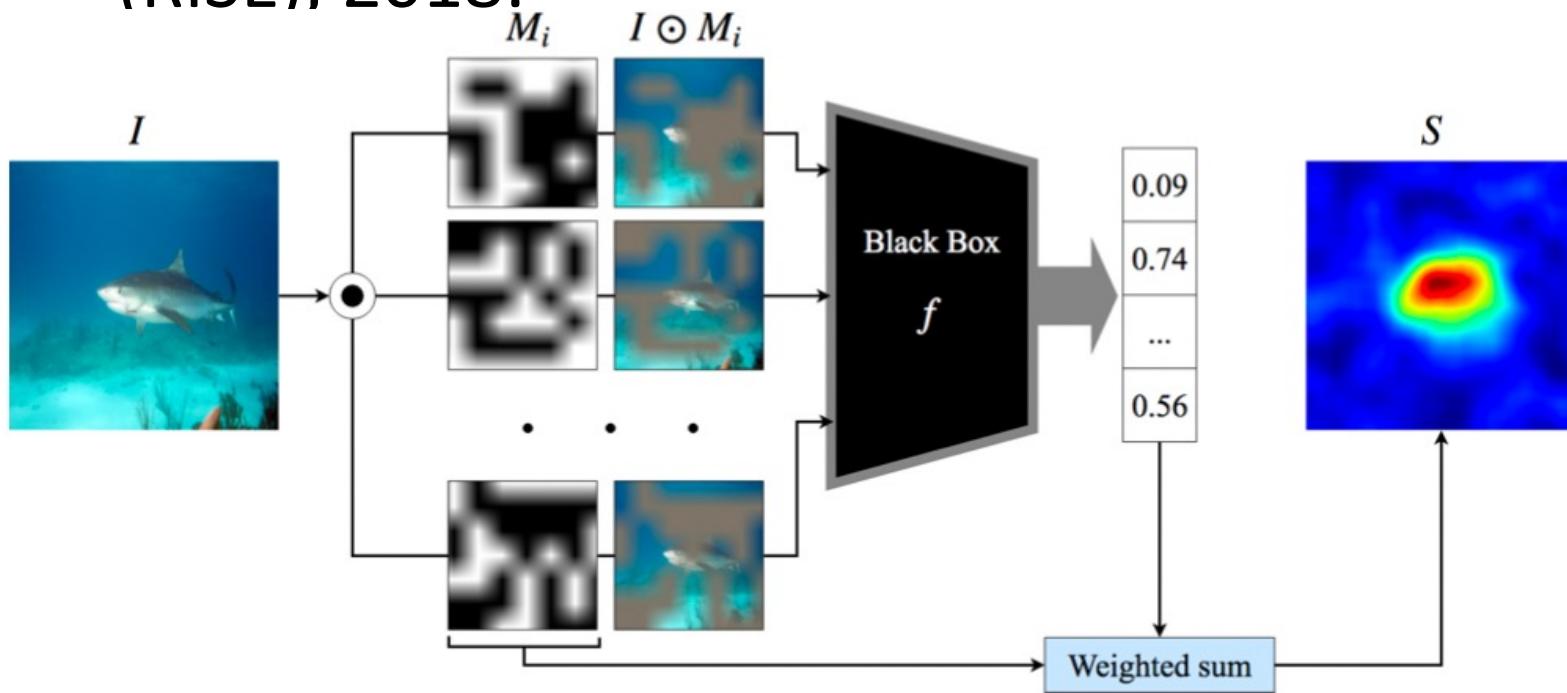
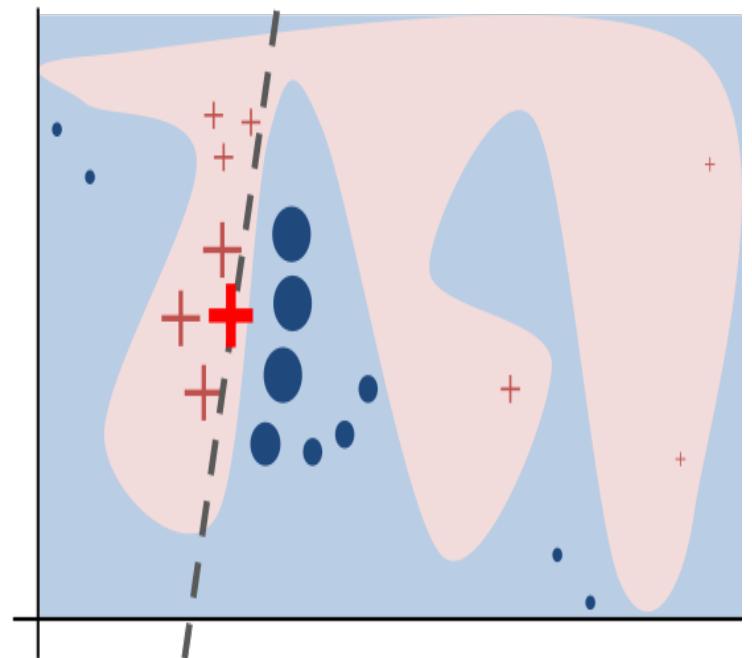


Figure 3: Overview of RISE: Input image I is element-wise multiplied with random masks M_i and the masked images are fed to the base model. The saliency map is a linear combination of the masks where the weights come from the score of the target class corresponding to the respective masked inputs.

Perturbation XAI, LIME

- Black-box model's complex decision function (unknown to LIME) is the blue/pink background
 - It cannot be approximated.
- Bold red cross is the instance being explained.
- LIME samples instances, gets predictions using f , and weighs them by the proximity to the instance being explained (represented by size).
- The dashed line is the learned explanation that is locally faithful.



From M. T. Ribeiro et al. 2016

Perturbation XAI, LIME

- Iteratively probing a trained model with different variations of the inputs
- Local Interpretable Model-agnostic Explanations (LIME), 2016:



(a) Original Image

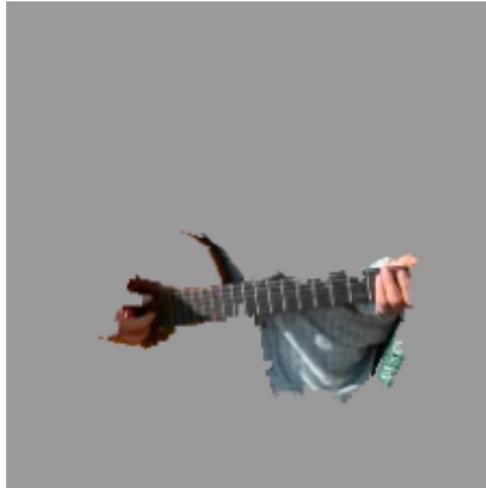
Figure 4: Explaining an image classification prediction made by Google's Inception neural network. The top 3 classes predicted are "Electric Guitar" ($p = 0.32$), "Acoustic guitar" ($p = 0.24$) and "Labrador" ($p = 0.21$)

Perturbation XAI, LIME

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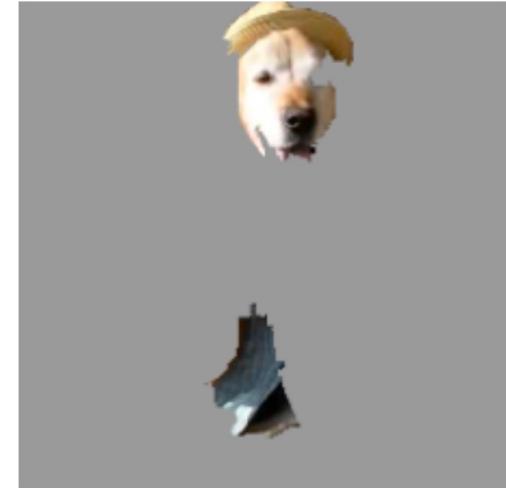
(a) Original Image



(b) Explaining *Electric guitar*



(c) Explaining *Acoustic guitar*

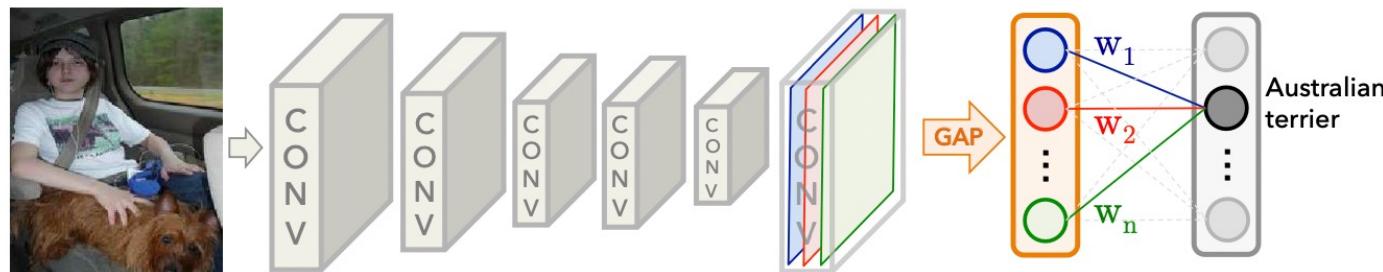


(d) Explaining *Labrador*

Figure 4: Explaining an image classification prediction made by Google's Inception neural network. The top 3 classes predicted are "Electric Guitar" ($p = 0.32$), "Acoustic guitar" ($p = 0.24$) and "Labrador" ($p = 0.21$)

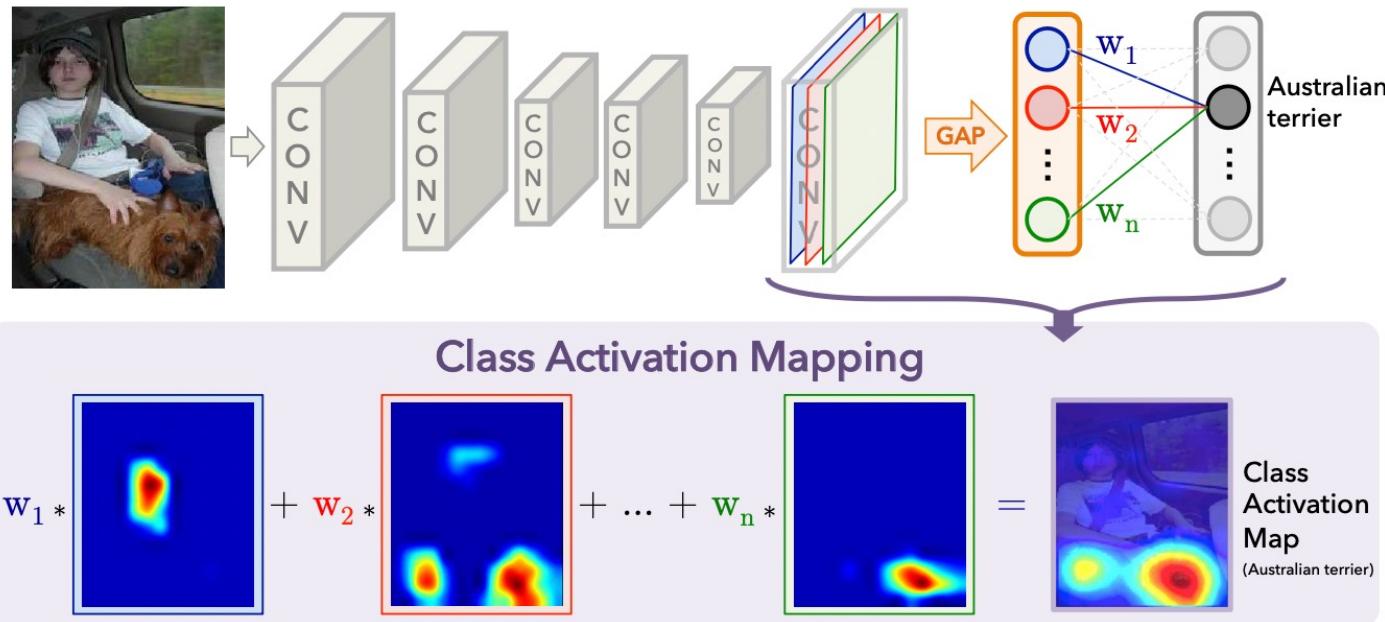
BackProp XAI, CAM

- Class Activation Maps (CAM), Zhou et al. CVPR 2016
- GAP outputs the spatial average of the feature map of each unit at the last convolutional layer



BackProp XAI, CAM

- Class Activation Maps (CAM), Zhou et al. CVPR 2016
- GAP outputs the spatial average of the feature map of each unit at the last convolutional layer
- GAP has remarkable localization ability despite being trained on image-level labels



BackProp XAI, GradCAM

- CAM uses a restricted class of image classification CNNs which do **not contain any fully-connected layers**.
- In contrast, GradCAM make existing state-of-the-art deep models interpretable without altering their architecture

Grad-CAM:

Visual Explanations from Deep Networks via Gradient-based Localization

ICCV 2017

Ramprasaath R. Selvaraju^{1*} Michael Cogswell¹ Abhishek Das¹ Ramakrishna Vedantam^{1*}
Devi Parikh^{1,2} Dhruv Batra^{1,2}

¹Georgia Institute of Technology ²Facebook AI Research

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The false hope of current approaches to explainable artificial intelligence in health care

The Lancet Digital Health, 2021

Marzyeh Ghassemi, Luke Oakden-Rayner, Andrew L Beam

- For limited complexity input, the relationships between inputs and the outputs is termed **inherent explainability**.
 - Linear regression model, where a coefficient measures the strength of the relationship between the weight of a car and the fuel efficiency.
- In contrast to inherently explainable models, the data and models are too complex in many modern AI use cases
- Another challenge: explanations have no performance guarantees. The performance of explanations is rarely tested, and rely on heuristic measures.
- Many drugs and medical devices function as black boxes, eg. acetaminophen, which, despite having been used for more than a century, has a mechanism of action that is partially understood

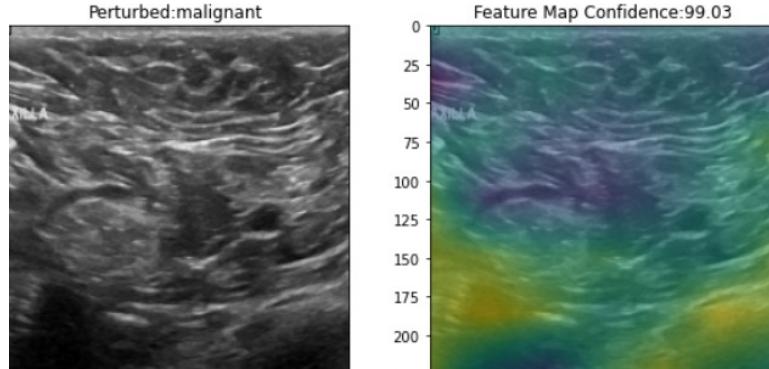
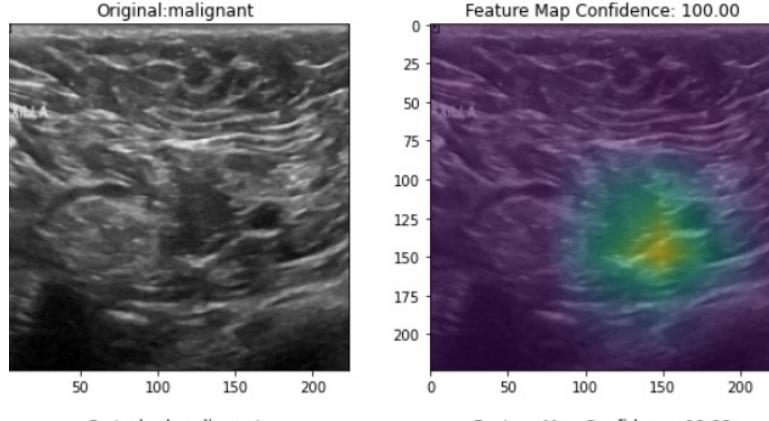
Explainable AI and susceptibility to adversarial attacks: a case study in classification of breast ultrasound images

IEEE IUS 2021

Hamza Rasaee

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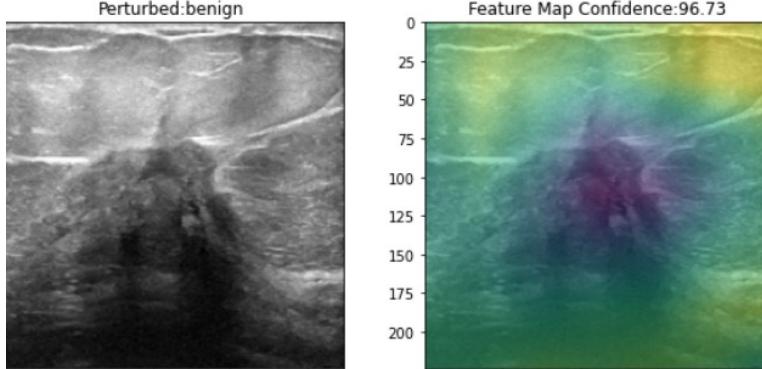
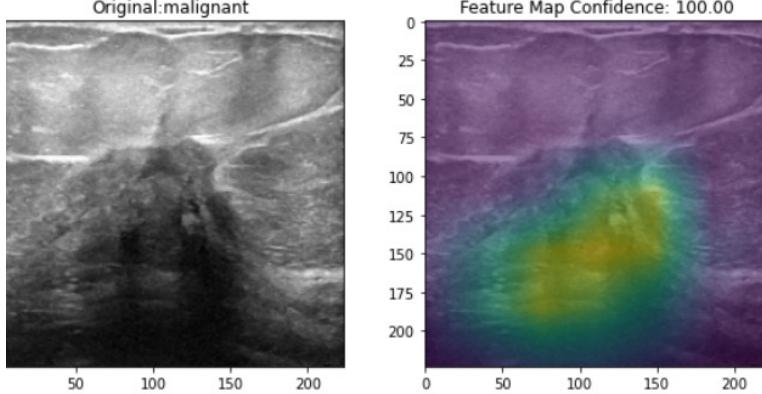
h_rasaee@encs.concordia.ca



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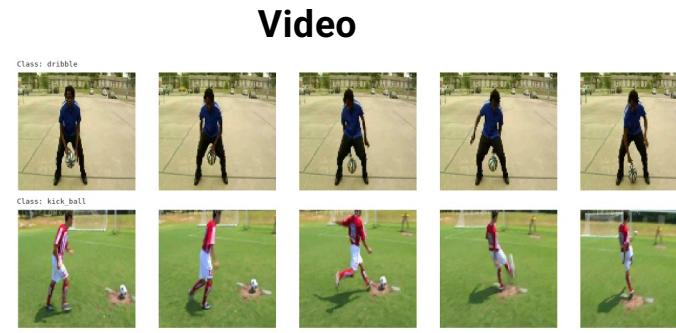
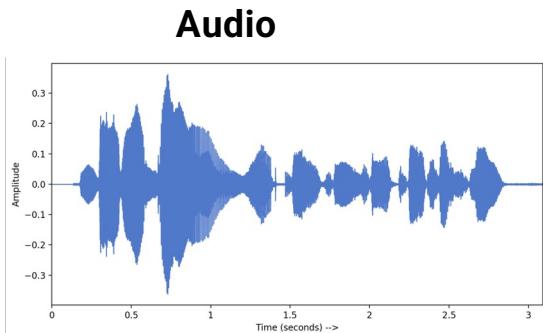
Generative models for XAI?



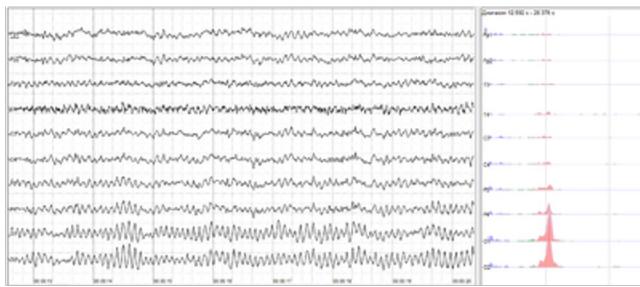
Made by Imagen. Prompt: the most beautiful punk rock cat singing into a microphone. From:
https://twitter.com/DynamicWebPaige/status/1538315418355412997?s=20&t=qqxXBHhg6MCJxU_mTRloA

Recurrent Neural Networks

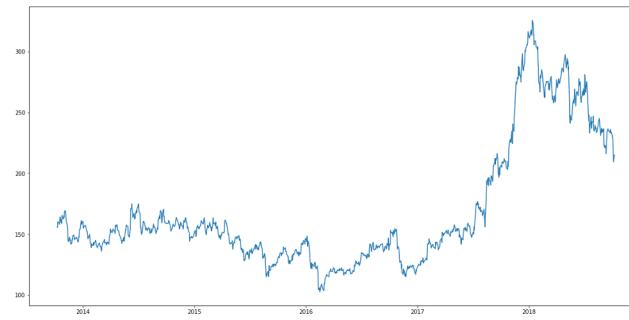
- Many real-life data are actually **sequences** (e.g., time series):



EEG Brain signals

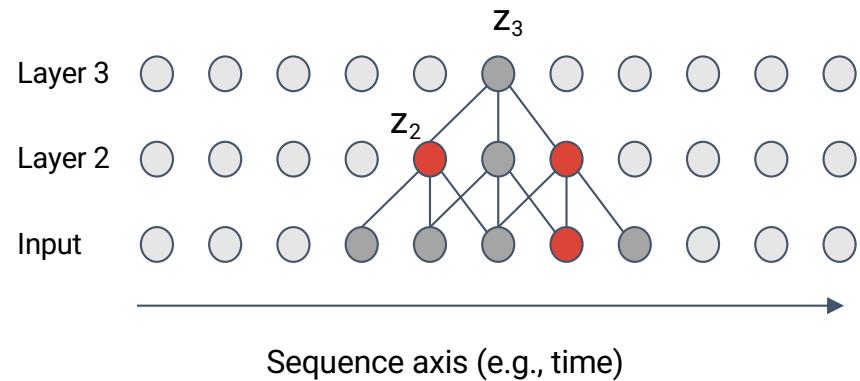


Stock Price Prediction



Courtesy of Prof. Mirco Ravanelli

Recurrent Neural Networks



- For some types of signals, we want to learn **long-term dependencies**.
- For instance, we might want to have a model whose neurons depend on the **full history** (i.e., **all the past elements**).
- CNNs are designed to **capture local dependencies** (i.e, the ones available in the receptive field).

Courtesy of Prof. Mirco Ravanelli

Recurrent Neural Networks

- In **Recurrent Neural Networks** (RNNs), the **current output** depends on **all the previous inputs**.
- The general form for an RNN is the following:

$$\mathbf{h}_t = f(\mathbf{x}_t, \mathbf{h}_{t-1}, \mathbf{W})$$

The **current state** \mathbf{h}_t depends on:

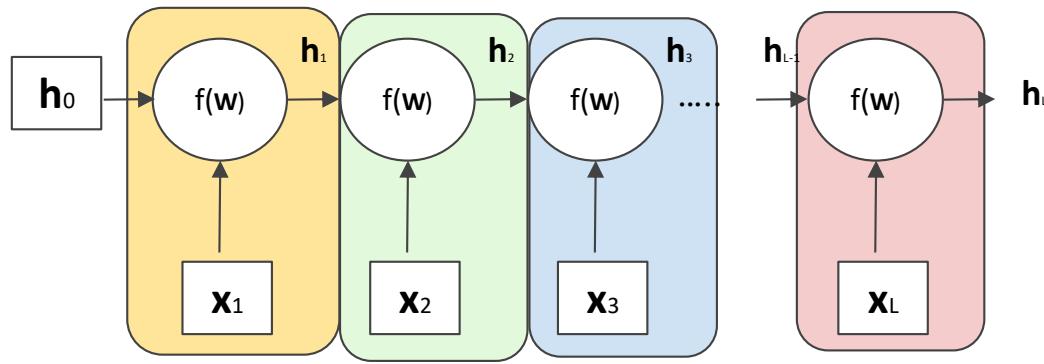
- The current input \mathbf{x}_t
- The previous state \mathbf{h}_{t-1}
- A set of learnable parameters \mathbf{W}

Courtesy of Prof. Mirco Ravanelli

Recurrent Neural Networks

- We can **unfold** the recurrent neural networks in this way:

$$\mathbf{h}_t = f(\mathbf{x}_t, \mathbf{h}_{t-1}, \mathbf{W})$$



- The current state \mathbf{h}_t depends on the current input \mathbf{x}_t and all the previous ones.
- The final state \mathbf{h}_L depends on **all the inputs**.

$$\mathbf{h}_0 = 0$$

$$\mathbf{h}_1 = f(\mathbf{x}_1, \mathbf{h}_0, \mathbf{W})$$

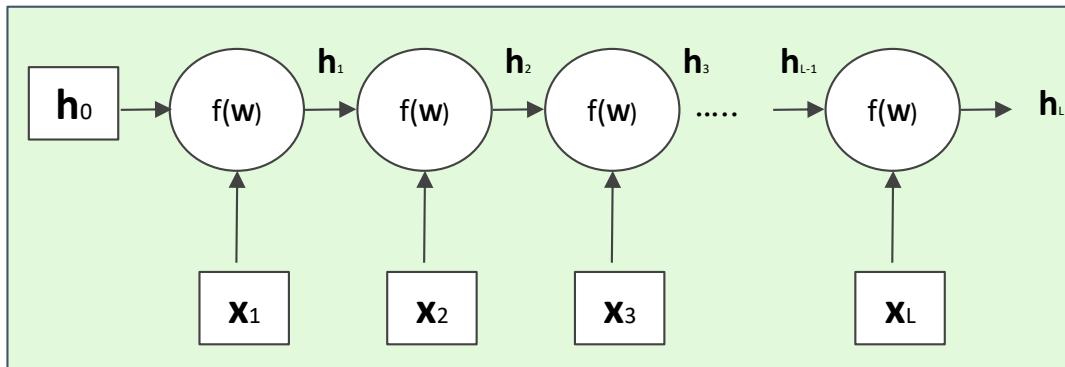
$$\mathbf{h}_2 = f(\mathbf{x}_2, \mathbf{h}_1, \mathbf{W})$$

$$\mathbf{h}_3 = f(\mathbf{x}_3, \mathbf{h}_2, \mathbf{W})$$

$$\mathbf{h}_L = f(\mathbf{x}_L, \mathbf{h}_{L-1}, \mathbf{W})$$

Courtesy of Prof. Mirco Ravanelli

Recurrent Neural Networks

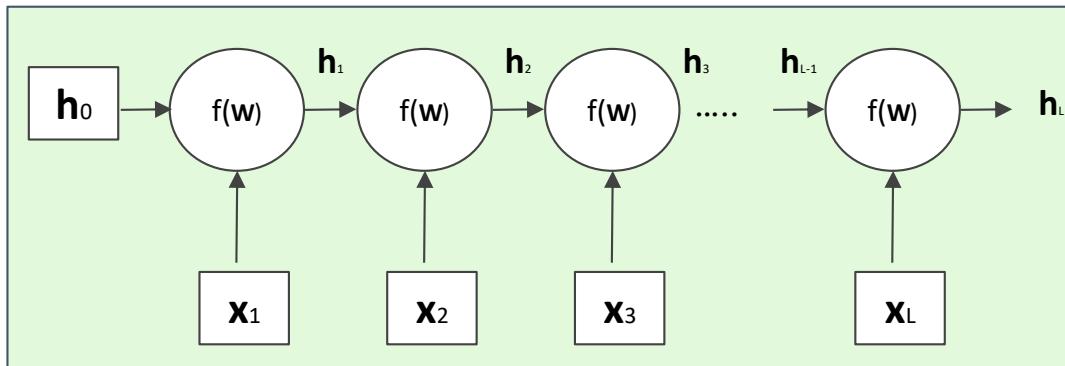


$$\mathbf{h}_t = f(\mathbf{x}_t, \mathbf{h}_{t-1}, \mathbf{W})$$

- We apply the same neural network f for all the sequence steps (**weight sharing**). Where else do we do this?
- As seen for CNNs, applying the **same weights** over the input helps **find patterns** in the data.
- In CNNs, we share the same filter over the inputs, for RNNs we share a **full neural network**.
- Moreover, RNNs we can find **arbitrary long patterns** because the state vector acts as a memory of the previous inputs.

Courtesy of Prof. Mirco Ravanelli

Recurrent Neural Networks

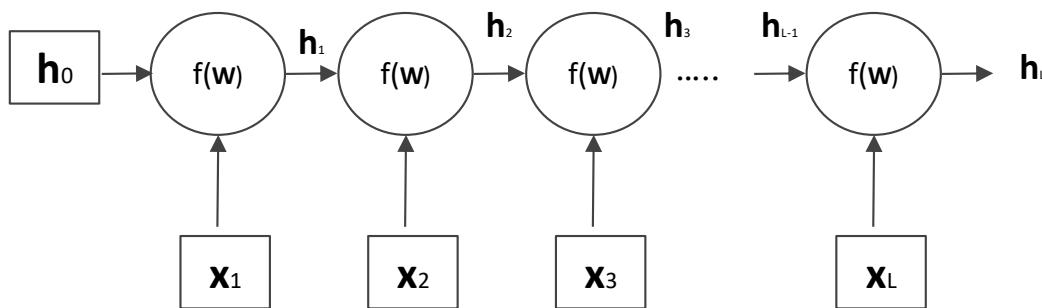
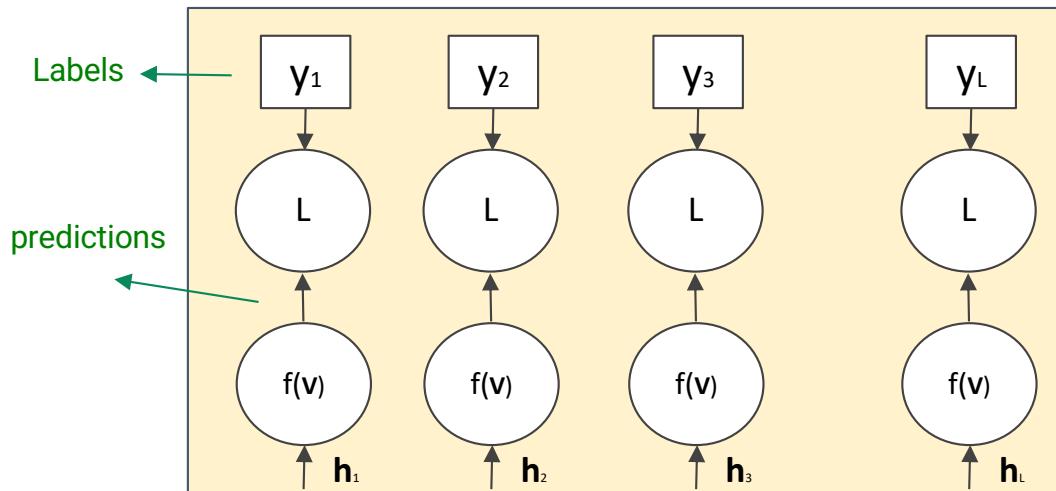


$$\mathbf{h}_t = f(\mathbf{x}_t, \mathbf{h}_{t-1}, \mathbf{W})$$

- Once unfolded, RNN can be represented as a single **big computational graph**.
- We can see a recurrent neural network as a **deep neural network**, which is deep in the **time axis**.
- RNNs can be used in **different types of problems**, that include:
 - Problems where we need a **prediction at each time step** (Many-to-many).
 - Problems where we need a single **prediction at the end** (Many-to-one).
 - Problems where we want to turn the **input sequence** of length T into an **output sequence of length S** (**Seq-to-seq**).

Courtesy of Prof. Mirco Ravanelli

Many-to-Many Problems

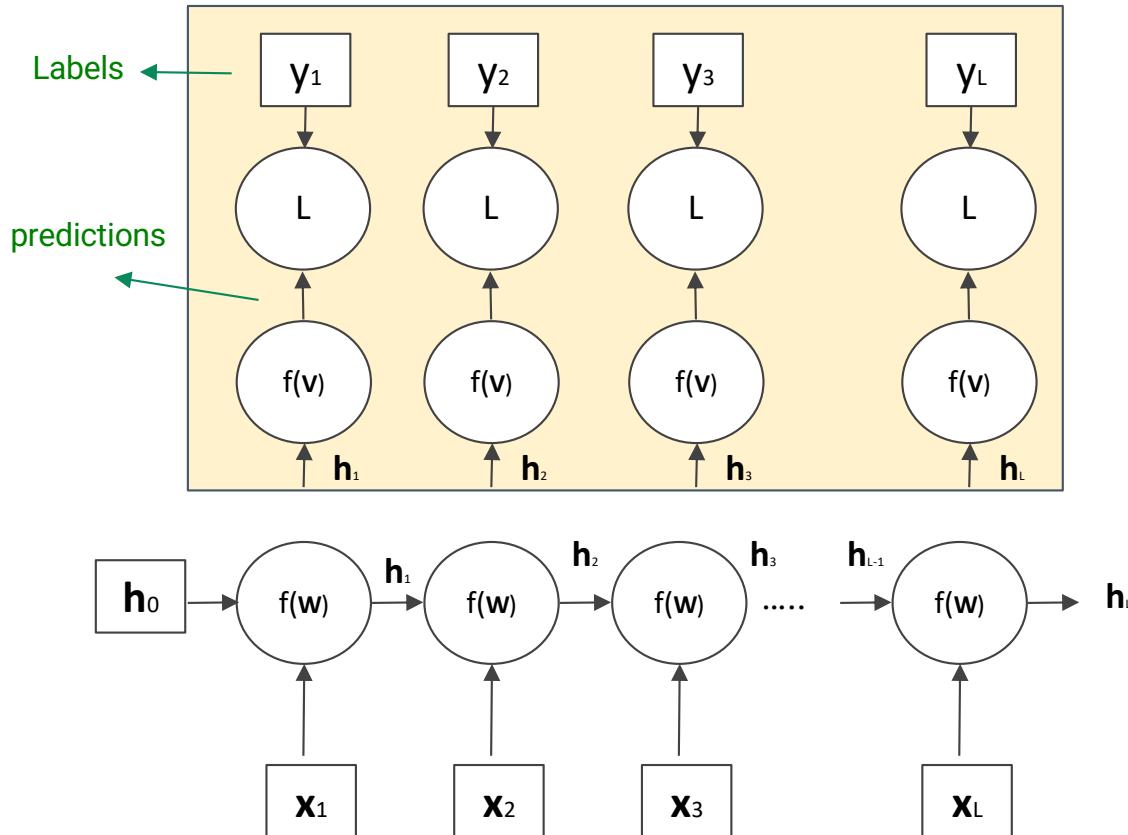


When we need a **single prediction at each time step** (many-to-many problem), we have to:

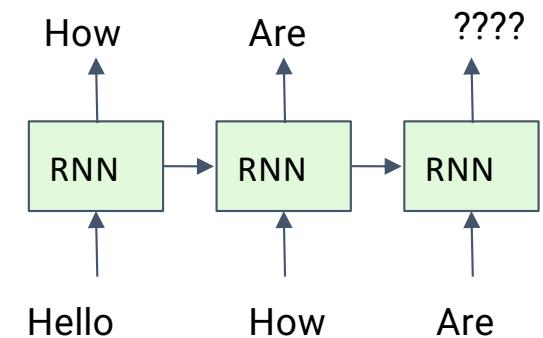
- Apply a **final transformation** (e.g., linear model) on top of each hidden state.
- Apply a **loss function at each time step** (e.g., Categorical Cross-Entropy for multi-class classification, MSE for regression).
- The **total loss** will be the **sum** (or **average**) of all the losses at each time step.

Courtesy of Prof. Mirco Ravanelli

Many-to-Many Problems

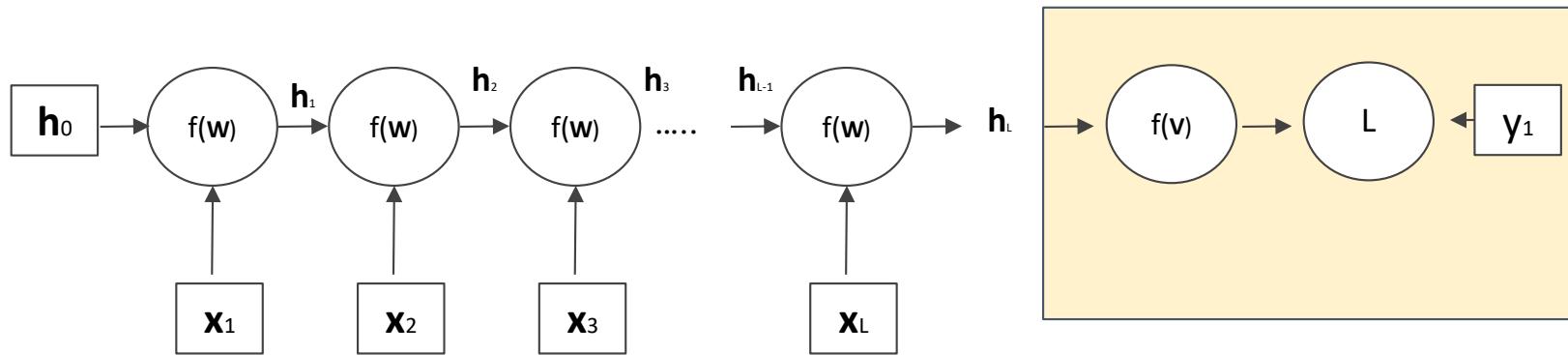


- Examples of problems like this are **stock predictions**, where we need to predict a value every day or hour.
- Another example is **language modeling**, where we want to predict the next word given the previous ones.



Courtesy of Prof. Mirco Ravanelli

Many-to-one Problems



When we need a **single prediction** in output (many-to-one problem), we can do the following:

- Apply a **final transformation** (e.g., linear model) on top of the **last hidden state** (which depends on all the inputs).
- Apply a **loss function** on top of it (e.g., Categorical Cross-Entropy for multi-class classification, MSE for regression).

Examples of problems like this are **speaker identification**, emotion recognition from text, etc.

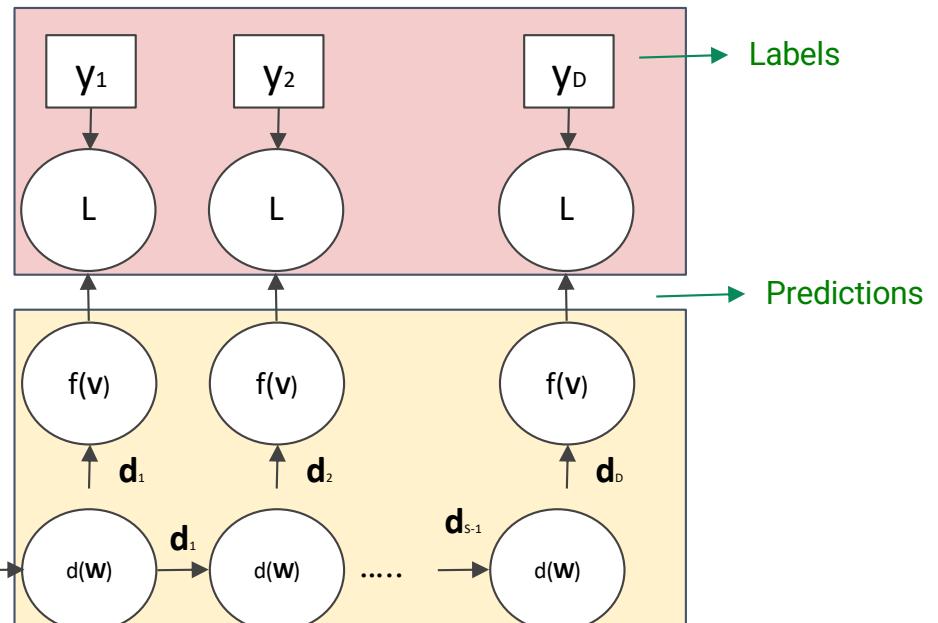
Courtesy of Prof. Mirco Ravanelli

Sequence-to-Sequence Problems

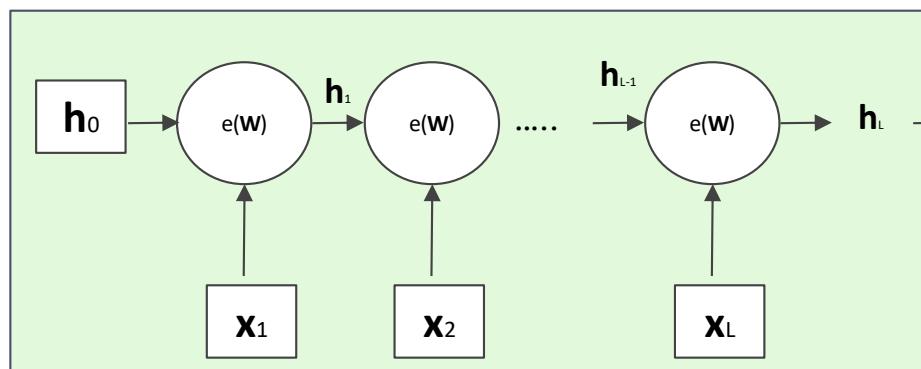
- RNNs can also be used for **sequence-to-sequence problems**:
- We employ an RNN-based **encoder** that encodes all the L inputs.
- We employ an RNN-based **decoder** that takes one of many encoded states and generates (one-by-one) the output elements.
- A **loss** is computed on top of **each prediction**.



Attention mechanisms are often used to connect encoder and decoder states.



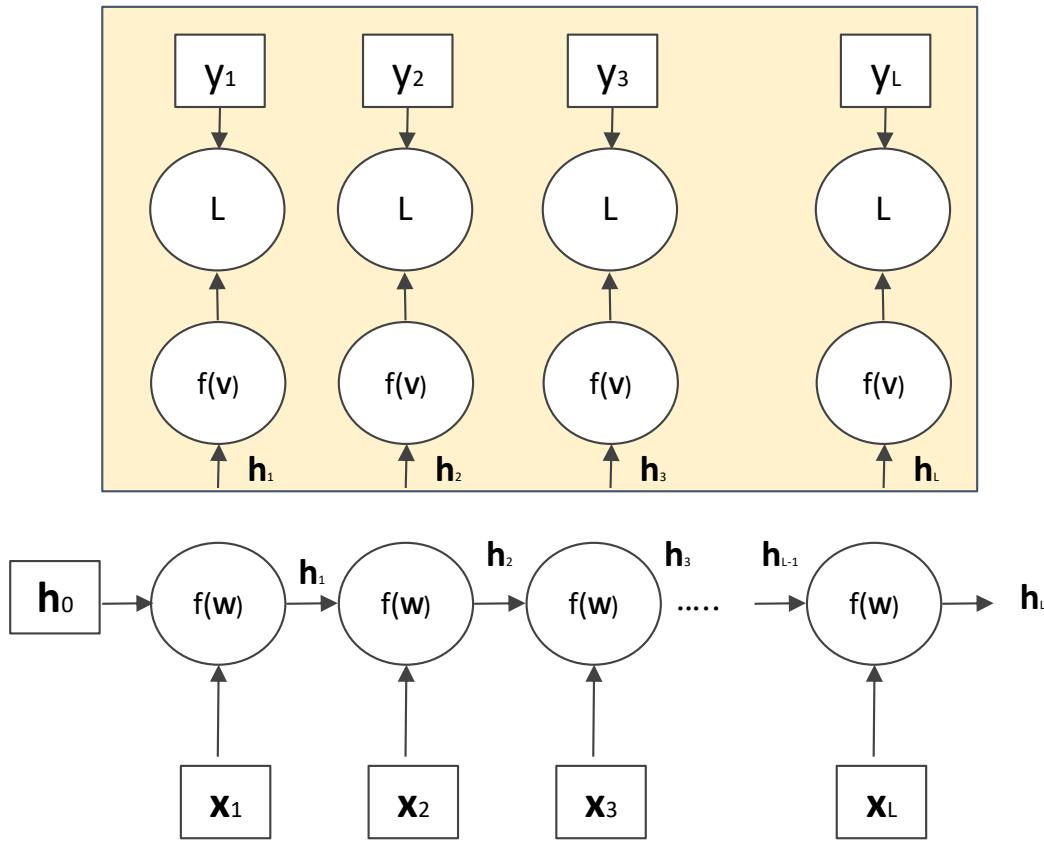
- Example of seq2seq problems is **machine translation**



Courtesy of Prof. Mirco Ravanelli

Training

- How can we train an RNN?



- After unfolding it, the RNN becomes a standard **computational graph** that employs long chains of computations.
- We can thus compute the gradient with the **backpropagation algorithm**.
- To highlight that the gradient is mainly propagated over time, it is sometimes called **backpropagation through time**.
- Once we have the gradient, we can update the parameters with **gradient descend** (and all its variants seen so far).

Courtesy of Prof. Mirco Ravanelli

Vanilla RNN

- The simplest RNN is called **Vanilla RNN** (or Elman RNN) is based on the following equation:

$$\mathbf{h}_t = \tanh(\mathbf{W}^{(in)T} \mathbf{x}_t + \mathbf{W}^{(hh)T} \mathbf{h}_{t-1})$$

We perform a **linear transformation** of both the current input and the previous state.

$$\mathbf{W}^{(in)} = \begin{bmatrix} w_{0,1}^{(in)} & w_{0,2}^{(in)} & \dots & w_{0,M}^{(in)} \\ w_{1,1}^{(in)} & w_{1,2}^{(in)} & \dots & w_{1,M}^{(in)} \\ \dots & \dots & \dots & \dots \\ w_{D,1}^{(in)} & w_{D,2}^{(in)} & \dots & w_{D,M}^{(in)} \end{bmatrix} \quad \mathbf{x}_t = [1, x_{t,1}, x_{t,2}, \dots, x_{t,D}]^T$$

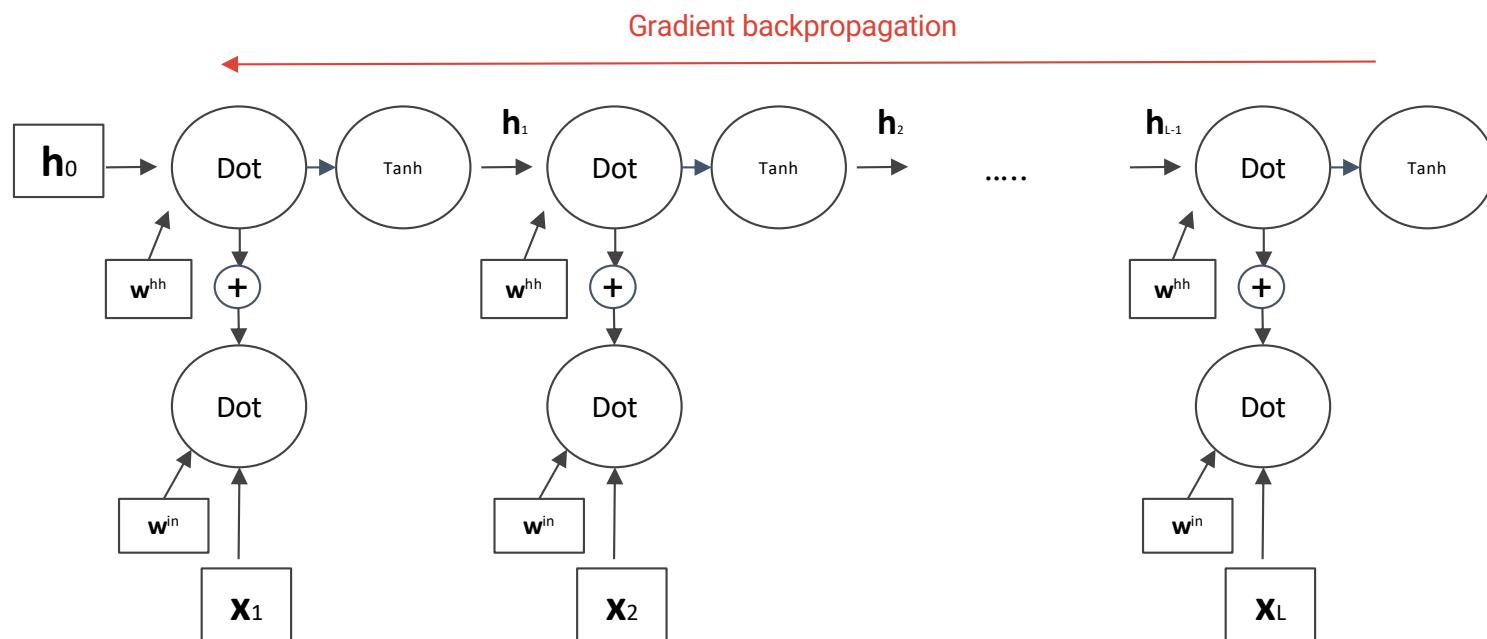
We sum them up and apply a **non-linearity** (Tanh or ReLU).

$$\mathbf{W}^{(hh)} = \begin{bmatrix} w_{1,1}^{(hh)} & w_{1,2}^{(hh)} & \dots & w_{1,M}^{(hh)} \\ w_{2,1}^{(hh)} & w_{2,2}^{(hh)} & \dots & w_{2,M}^{(hh)} \\ \dots & \dots & \dots & \dots \\ w_{M,1}^{(hh)} & w_{M,2}^{(hh)} & \dots & w_{M,M}^{(hh)} \end{bmatrix} \quad \mathbf{h}_t = [h_{t,1}, h_{t,2}, \dots, h_{t,M}]^T$$

Courtesy of Prof. Mirco Ravanelli

Vanishing Gradient

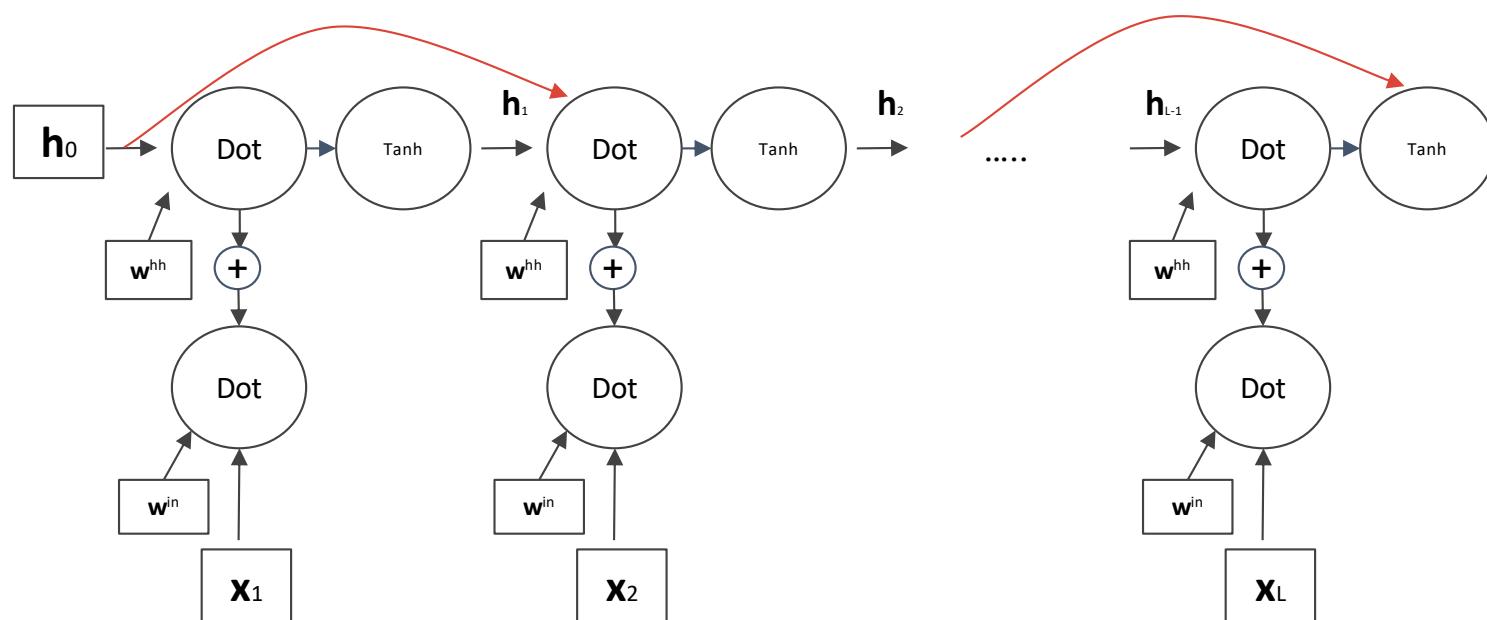
- When using RNNs, we have to backpropagate the gradient through a **long temporal** chain.
- As we have seen, this might cause **exploding gradients** or **vanishing gradients**.
- The vanishing gradient problem prevents the model to learn **long-term dependencies**.



Courtesy of Prof. Mirco Ravanelli

Vanishing Gradient

- As we have seen in the previous lecture, we can add **shortcuts** in the architecture to fight vanishing gradients.
- In this case, we can consider shortcuts across **time steps**.



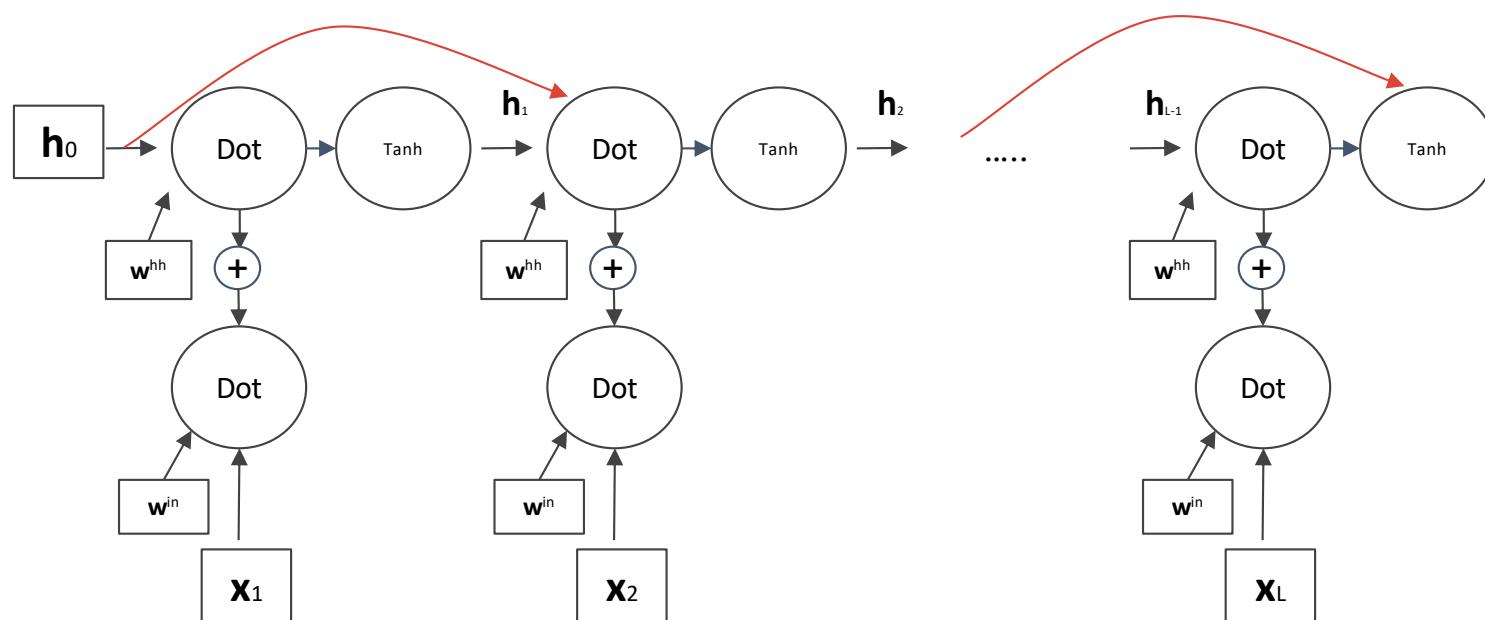
Courtesy of Prof. Mirco Ravanelli

Vanishing Gradient



Instead of **hard-coding pre-defined shortcuts**, why don't we try to **learn** them?

Ideally, we want to learn "**dynamic**" **shortcuts** that connect relevant time steps.



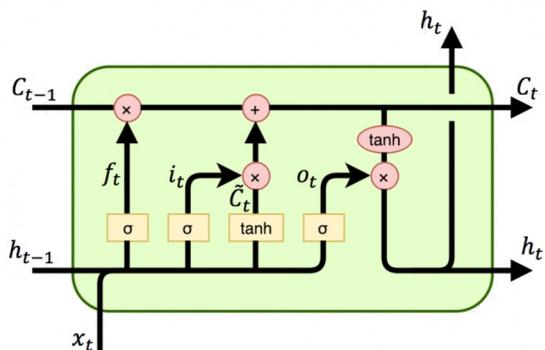
Courtesy of Prof. Mirco Ravanelli

LSTM, Gated RNNs

- This is exactly what we are trying to do with **multiplicative gates**:

Long Short-Term Memory (LSTM)

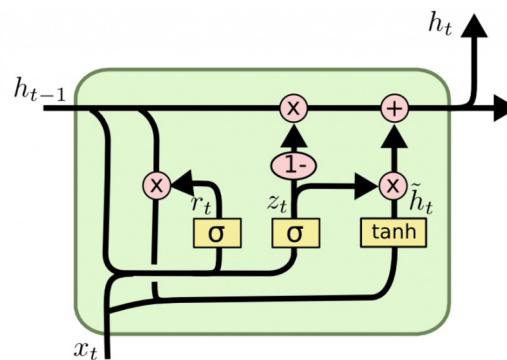
$$\begin{aligned} f_t &= \sigma_g(W_f x_t + U_f h_{t-1} + b_f) \\ i_t &= \sigma_g(W_i x_t + U_i h_{t-1} + b_i) \\ o_t &= \sigma_g(W_o x_t + U_o h_{t-1} + b_o) \\ \tilde{c}_t &= \sigma_c(W_c x_t + U_c h_{t-1} + b_c) \\ c_t &= f_t \circ c_{t-1} + i_t \circ \tilde{c}_t \\ h_t &= o_t \circ \sigma_h(c_t) \end{aligned}$$



4 multiplicative gates

Gated Recurrent Units (GRU)

$$\begin{aligned} z_t &= \sigma_g(W_z x_t + U_z h_{t-1} + b_z) \\ r_t &= \sigma_g(W_r x_t + U_r h_{t-1} + b_r) \\ \hat{h}_t &= \phi_h(W_h x_t + U_h(r_t \odot h_{t-1}) + b_h) \\ h_t &= (1 - z_t) \odot h_{t-1} + z_t \odot \hat{h}_t \end{aligned}$$



2 multiplicative gates

Light Gated Recurrent Units (Li-GRU)

$$\begin{aligned} z_t &= \sigma(BN(W_z x_t) + U_z h_{t-1}) \\ \tilde{h}_t &= \text{ReLU}(BN(W_h x_t) + U_h h_{t-1}) \\ h_t &= z_t \odot h_{t-1} + (1 - z_t) \odot \tilde{h}_t \end{aligned}$$



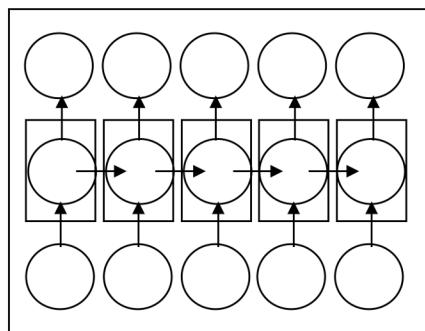
If the update gate z is 1, we can remember forever the state h (thus learning arbitrary **long-term dependencies**)

1 multiplicative gate

Courtesy of Prof. Mirco Ravanelli

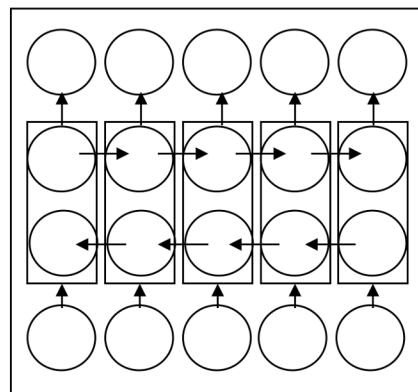
Bidirectional RNN

- In some cases, we want to make a prediction at each time step based on the **whole input elements** and not only the **previous ones**.



(a)

Structure overview
(a) unidirectional RNN
(b) bidirectional RNN



(b)

We can employ two RNNs running in **opposite directions**.

These RNNs use different parameters or share them.

At each layer, we can **combine the forward and the backward state** by concatenating them or summing them up.

Examples of applications are *speech recognition, machine translation, handwritten recognition*.

Courtesy of Prof. Mirco Ravanelli



'and the Fair Play for Cuba'.

▶ the Fair Play For Cuba 1:55 / 14:44



Spooky Coincidences?

Spooky Coincidences?

633K DISLIKE SHARE ↓ DO



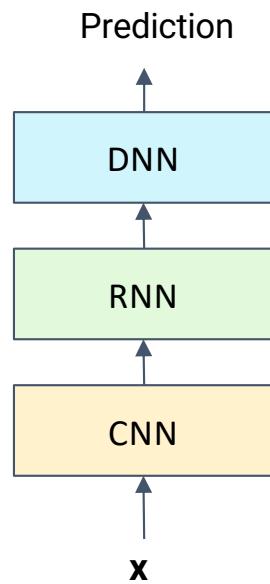
Vsauce ✓

17.8M subscribers

<https://youtu.be/sHCHEykUxP4?t=115>

CNNs + RNNs + MLPs

- We can make RNNs even deeper by **stacking multiple RNN layers**.
- We can also combine CNNs, RNNs, and DNNs (MLPs):



This model is called CRDNN and is very powerful:

- It first learns **local contexts** with a **CNN**.
- It then captures **long-term dependencies** with an **RNN**.
- Finally, it performs a **final classification** with an **MLP**.

All the blocks are **jointly trained**.

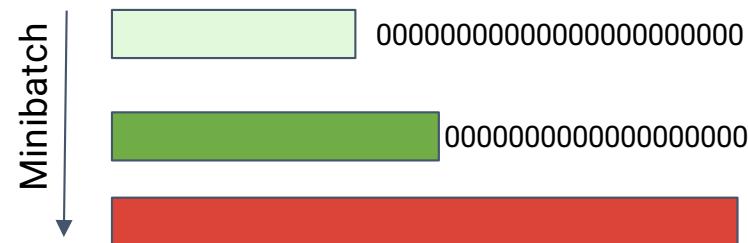
- This is one of the models used in SpeechBrain (<https://speechbrain.github.io/>) to process speech signals.

Courtesy of Prof. Mirco Ravanelli

Variable-Length Sequences

- Often, the sequences in input to the RNN have **different lengths**.
- For instance, think about a speech signal: in some cases, we might have long recordings, in some others short ones.
- How can we manage variable-length sequences?

We can handle it by **zero-padding**: within each minibatch, we pad with zeros the inputs to match the length of the longest one .



If the length of the inputs is very different, this is **computationally inefficient** because we waste time processing zeros.

Variable-Length Sequences

- One way to mitigate this issue is to **sort** the inputs by length (in ascending or descending order) before creating the minibatches.



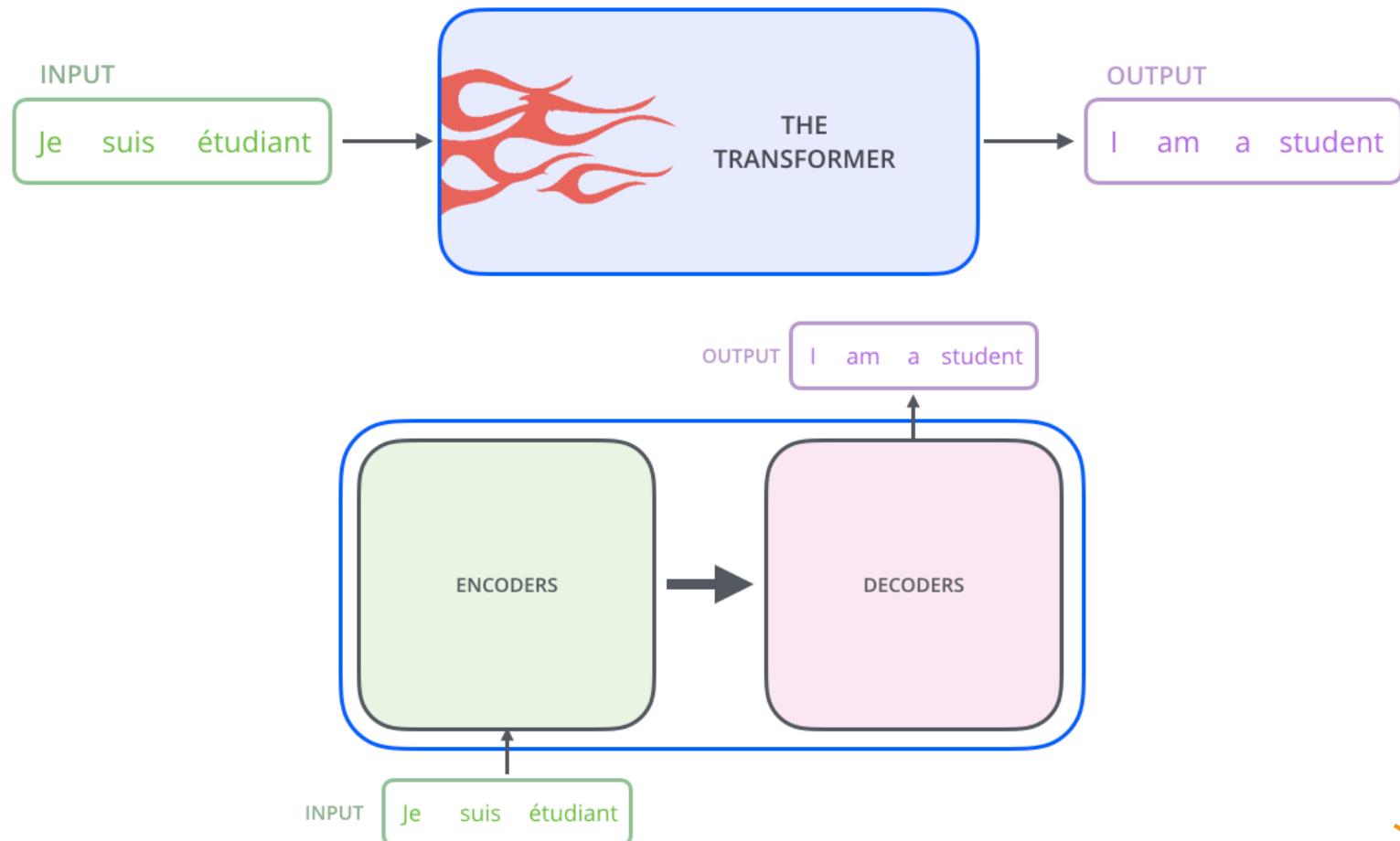
This minimizes the need for zero-padding, but **sacrifices randomness** in the minibatch creation:

since we sorted the data, minibatches composed of the same data are shown across epochs.

- A compromise solution can be implemented through **bucketing**:
- We split data in buckets such that each bucket contains **inputs of similar lengths**.
- When creating minibatches, we sample random inputs from the **same bucket**.

Transformers

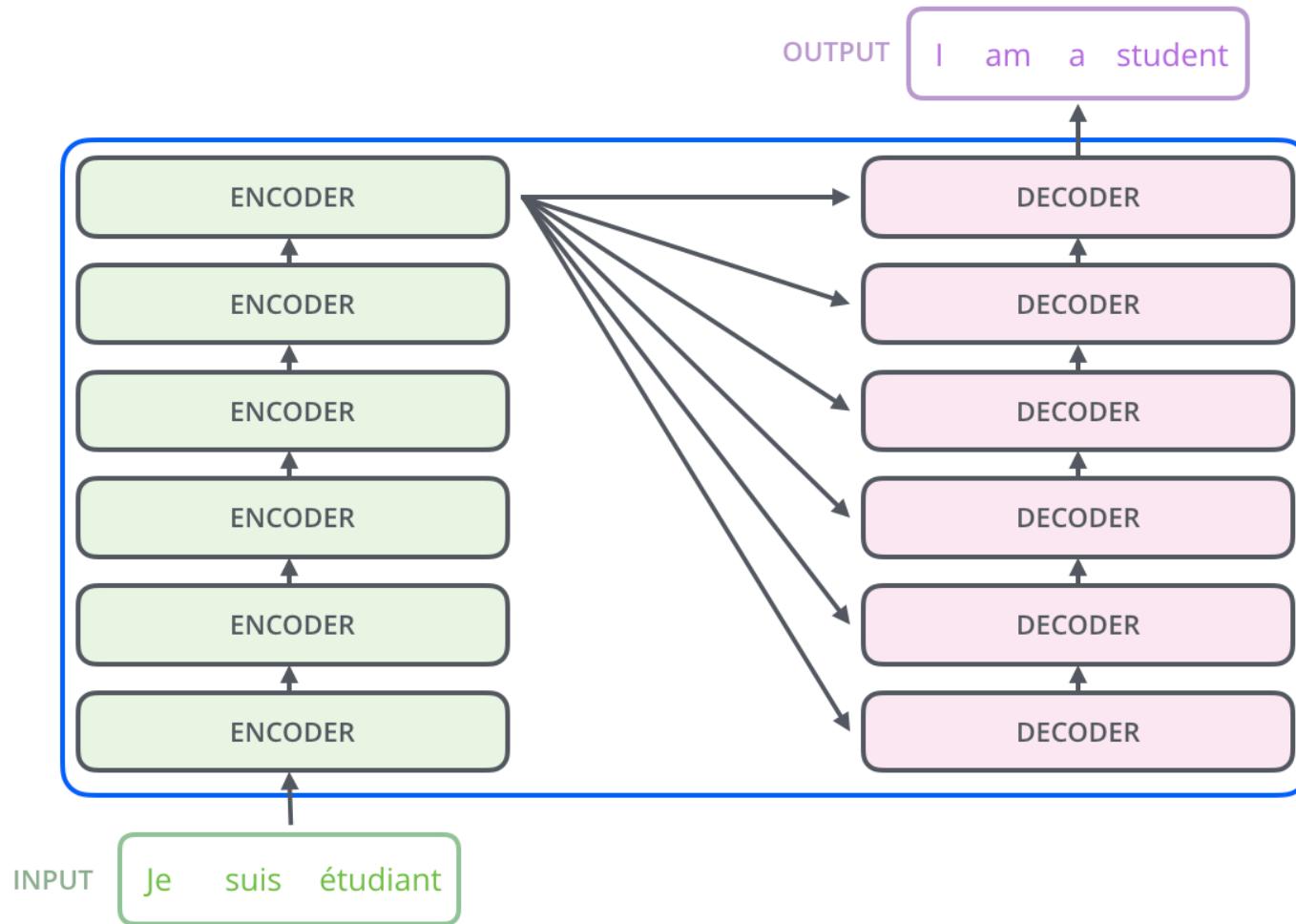
A sentence input in one language, and outputs its translation in another.



From: <https://jalammar.github.io/illustrated-transformer/>

Transformers

Here we are using 6 encoders and 6 decoders

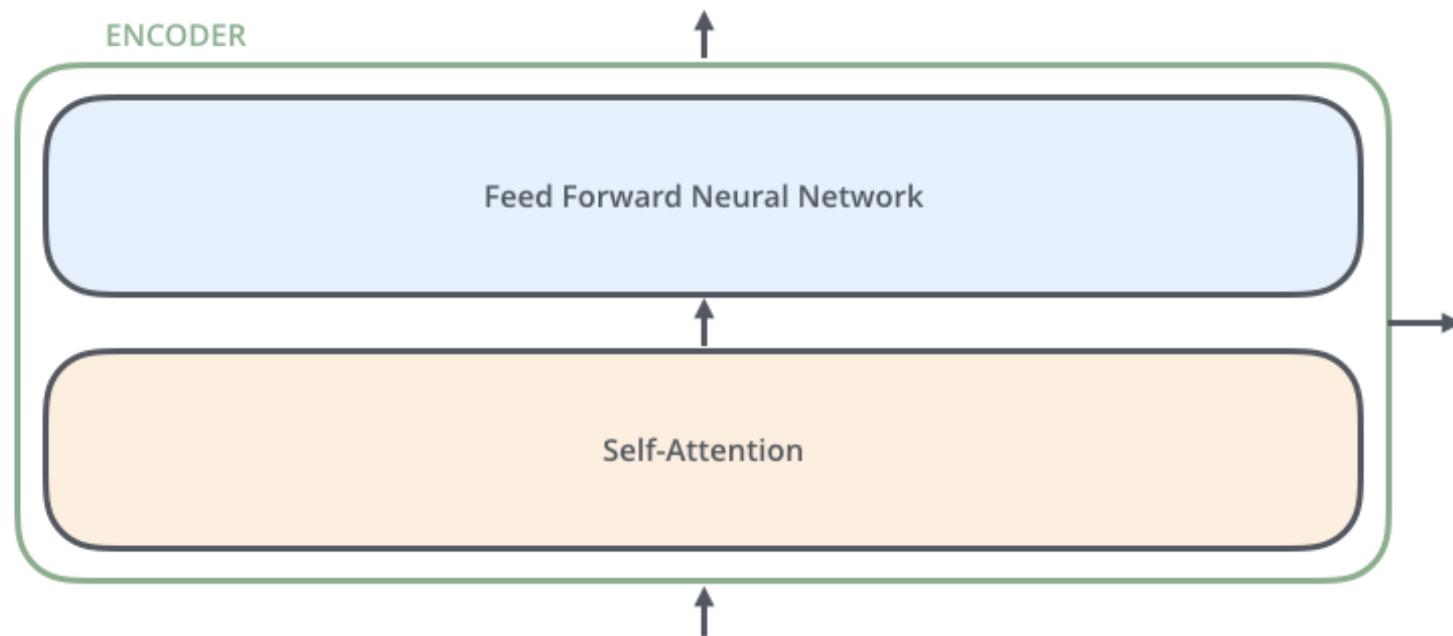


From: <https://jalammar.github.io/illustrated-transformer/>

Encoders

The encoders are all identical in structure (yet do not share weights).

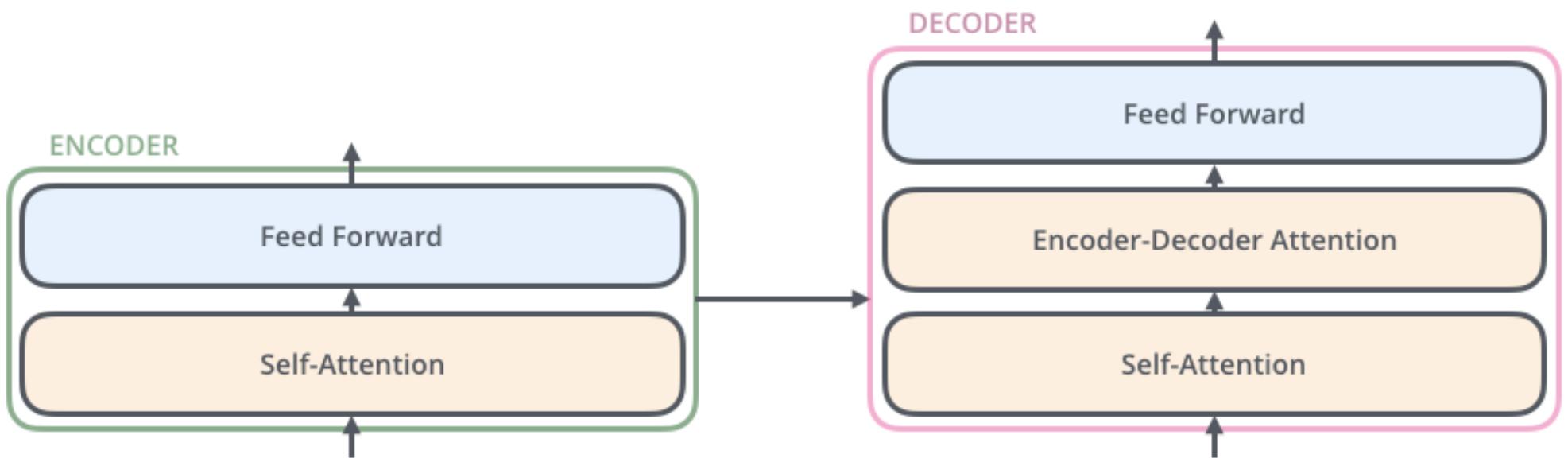
Each encoder is broken down into two sub-layers:



From: <https://jalammar.github.io/illustrated-transformer/>

Decoders

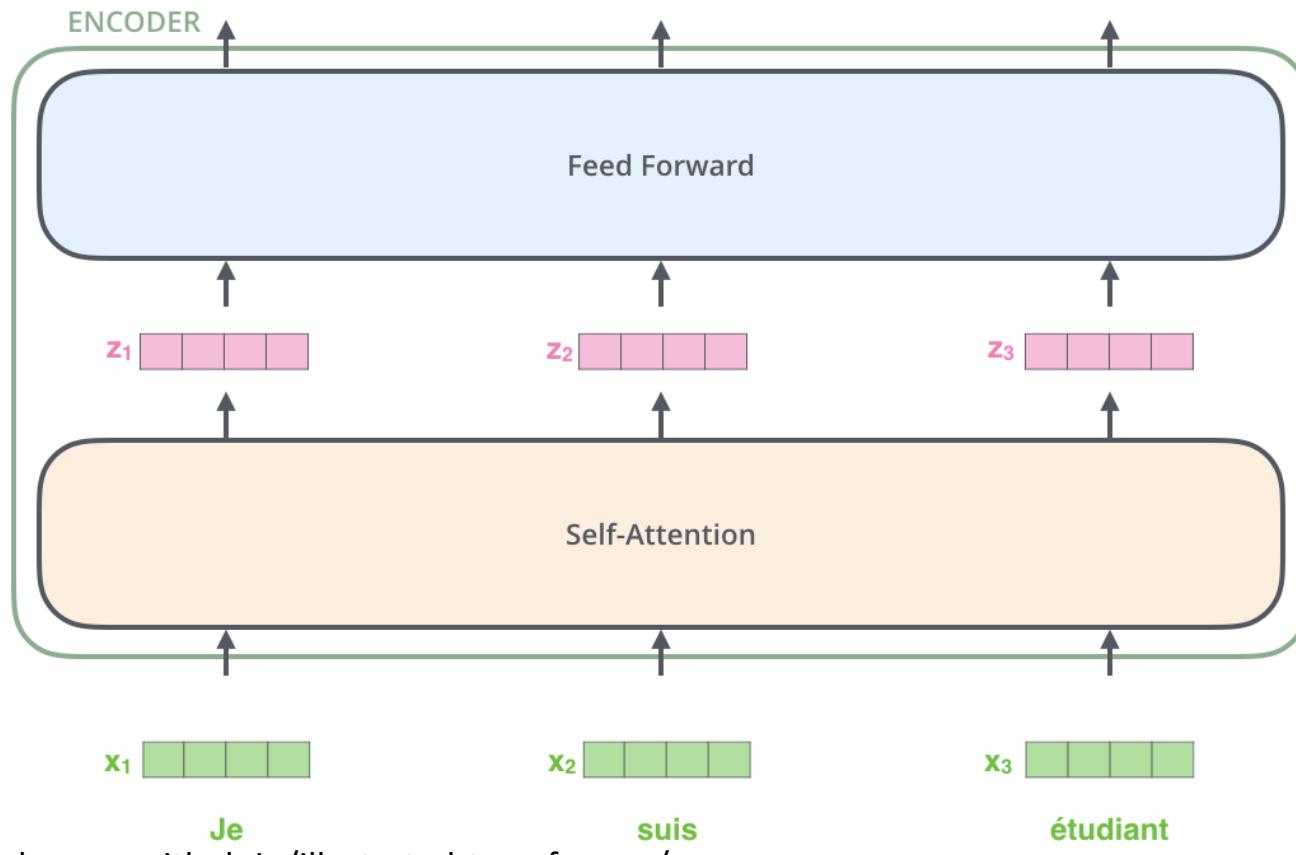
The decoder has both those layers, but between them is an attention layer that helps the decoder focus on relevant parts of the input sentence:



From: <https://jalammar.github.io/illustrated-transformer/>

The encoder

- A key property of the Transformer is that the word in each position flows through its own path in the encoder.
- There are dependencies between these paths in the self-attention layer.
- The feed-forward layer does not have those dependencies, and thus various paths can be executed in parallel while flowing through the feed-forward layer



From: <https://jalammar.github.io/illustrated-transformer/>

Self-Attention

- What does the word it refer to?
- As the model processes each word (each position in the input sequence), self attention allows it to look at other positions in the input sequence for clues that can help lead to a better encoding for this word.

The_
animal_
didn_
'_
t_
cross_
the_
street_
because_
it_
was_
too_
tire
d_

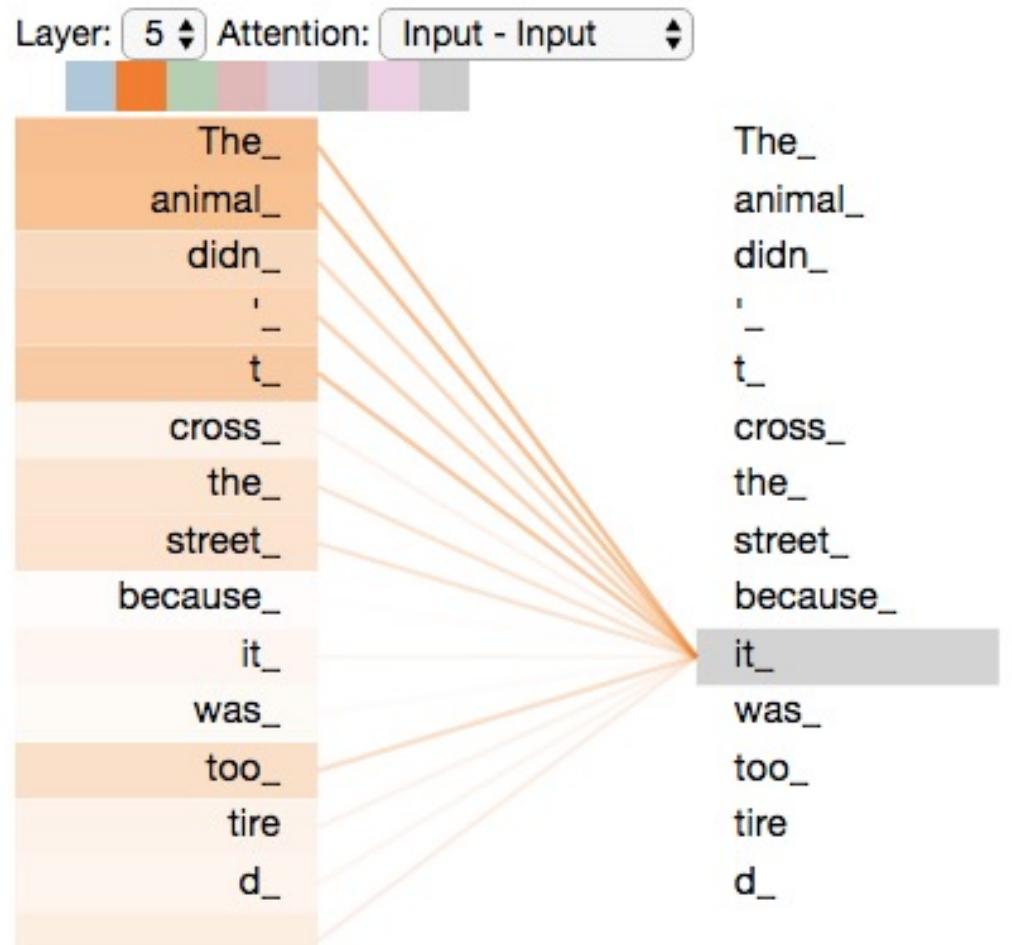
Notebook to visually inspect a Transformer model:

https://colab.research.google.com/github/tensorflow/tensor2tensor/blob/master/tensor2tensor/notebooks/hello_t2t.ipynb

From: <https://jalammar.github.io/illustrated-transformer/>

Self-Attention

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Notebook to visually inspect a Transformer model:

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From: <https://jalammar.github.io/illustrated-transformer/>

ViT

AN IMAGE IS WORTH 16x16 WORDS: TRANSFORMERS FOR IMAGE RECOGNITION AT SCALE

ICLR 2021

Alexey Dosovitskiy*,†, Lucas Beyer*, Alexander Kolesnikov*, Dirk Weissenborn*,
Xiaohua Zhai*, Thomas Unterthiner, Mostafa Dehghani, Matthias Minderer,
Georg Heigold, Sylvain Gelly, Jakob Uszkoreit, Neil Houlsby*,†

*equal technical contribution, †equal advising

Google Research, Brain Team

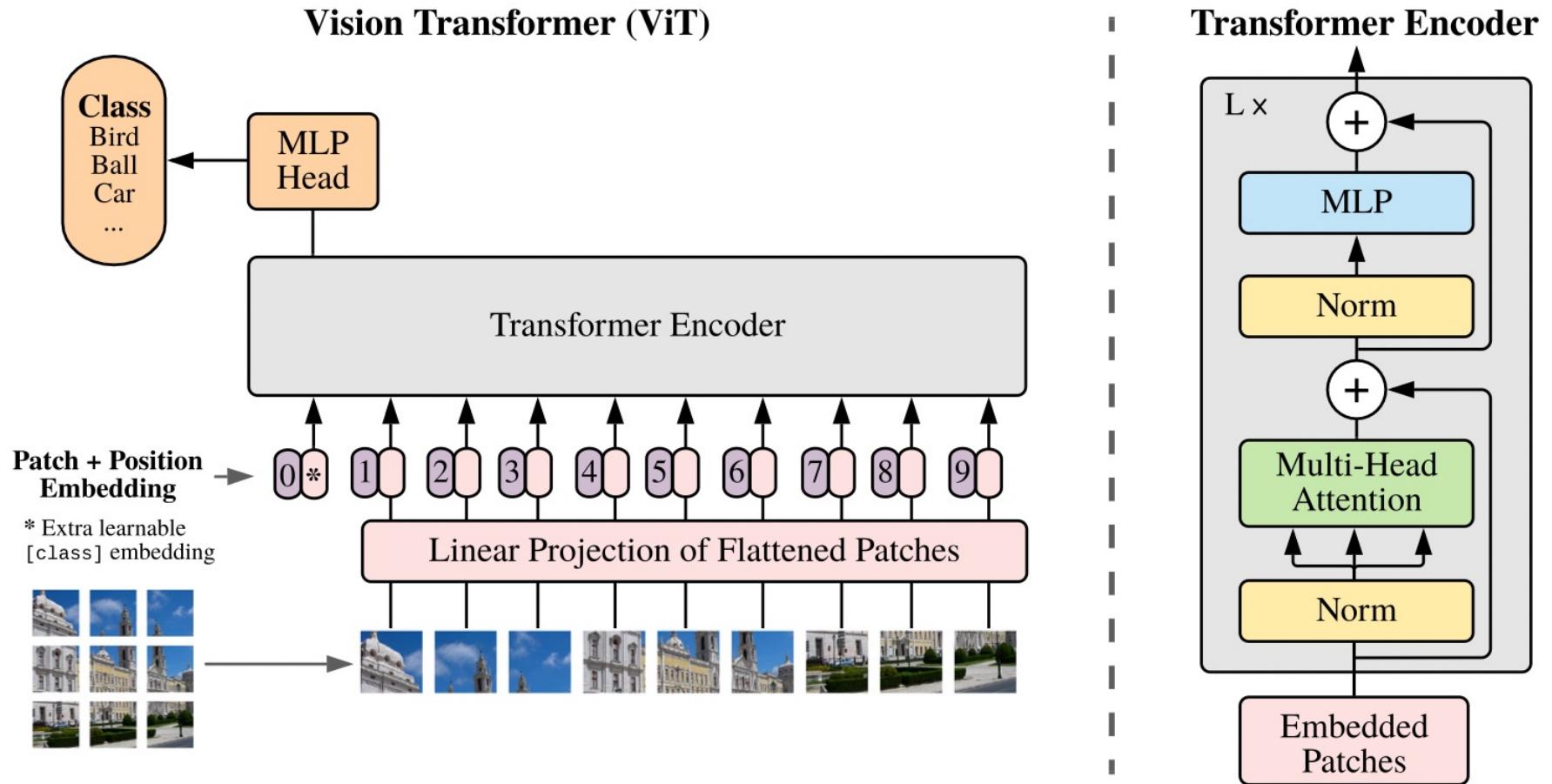
- In computer vision, convolutional architectures remain dominant
- A pure transformer applied directly to sequences of image patches can perform very well on image classification tasks.
- When pre-trained on large amounts of data and transferred to multiple mid-sized or small image recognition benchmarks (ImageNet, CIFAR, etc.), Vision Transformer (ViT) attains excellent results compared to SOTA CNNs while requiring substantially fewer computational resources to train

ViT

- Inspired by the Transformer scaling successes in NLP, apply a standard Transformer to images
- Split an image into patches and provide the sequence of linear embeddings of these patches as an input to a Transformer
- Image patches are treated same as tokens (words) in NLP
- Supervised training of model on image classification

ViT

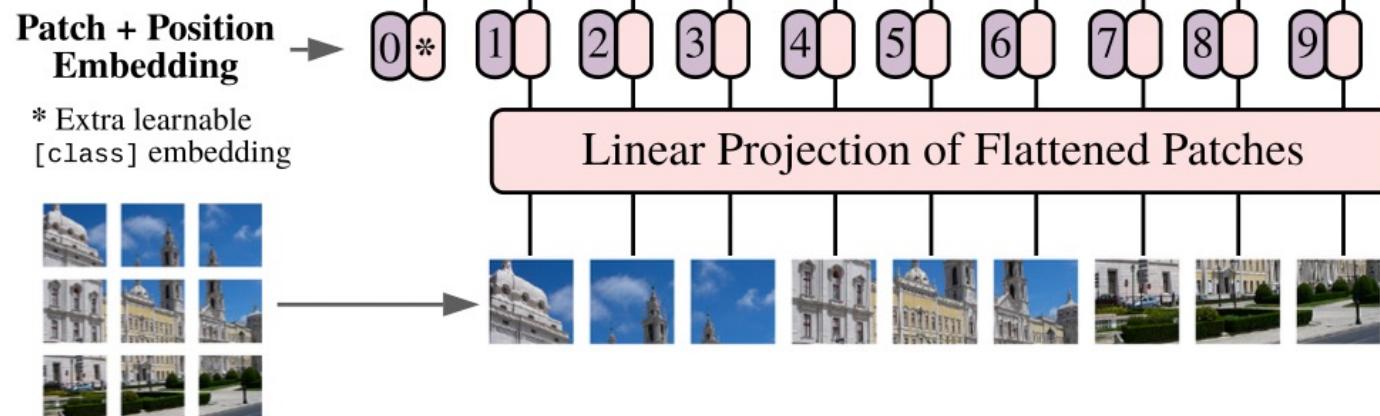
- When trained on mid-sized datasets (eg ImageNet) without strong regularization, these models yield modest accuracies (few points below ResNets)
 - Transformers lack some of the inductive biases of CNNs (translation equivariance and locality)
- The picture changes if the models are trained on larger datasets (14M-300M images).
- **Large scale training trumps inductive bias.**



- Flatten the patches and map to D dimensions with a trainable linear projection
- Position embeddings are added to the patch embeddings to retain positional information (the numbers 1 to 9 in the above example). We use standard 1D position embeddings, since we have not observed significant performance gains from using more advanced 2D-aware position embeddings

Linear projection in ViT

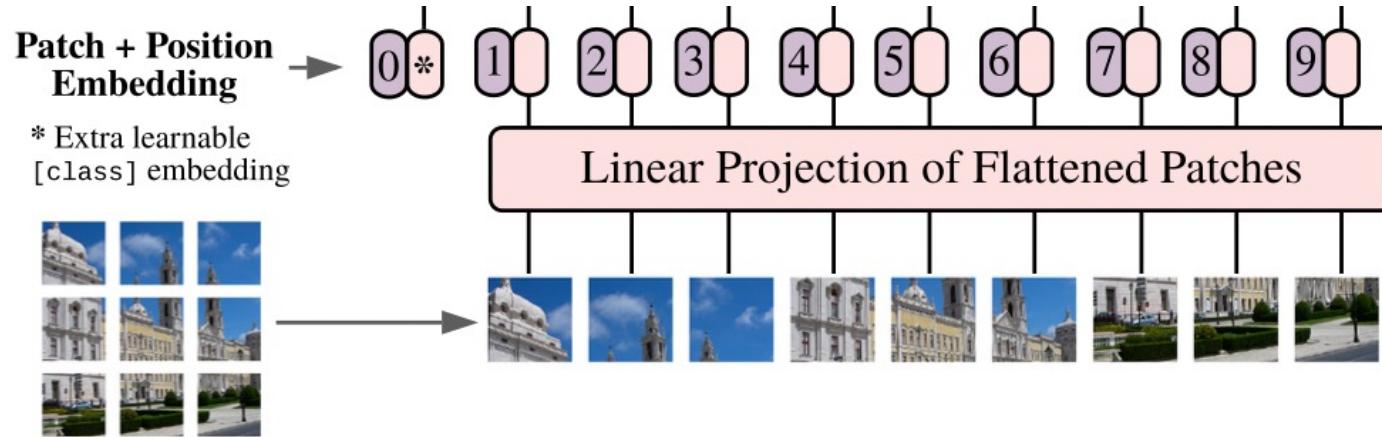
- Naive application of self-attention to images would require that each pixel attends to every other pixel.
 - Computationally expensive
- Instead, apply self-attention to N patches (N=9 here):



- Reshape image x to flattened 2D patches $\mathbf{x}_p \in \mathbb{R}^{N \times (P^2 \cdot C)}$.
C: number of channels, P^2 : size of each patch, $N=HW / P^2$: number of patches

$$\mathbf{z}_0 = [\mathbf{x}_{\text{class}}; \mathbf{x}_p^1 \mathbf{E}; \mathbf{x}_p^2 \mathbf{E}; \dots; \mathbf{x}_p^N \mathbf{E}] + \mathbf{E}_{pos}, \quad \mathbf{E} \in \mathbb{R}^{(P^2 \cdot C) \times D}, \mathbf{E}_{pos} \in \mathbb{R}^{(N+1) \times D}$$

Hybrid ViT



- In the hybrid model, the patch embedding projection E is applied to patches extracted from a CNN feature map.

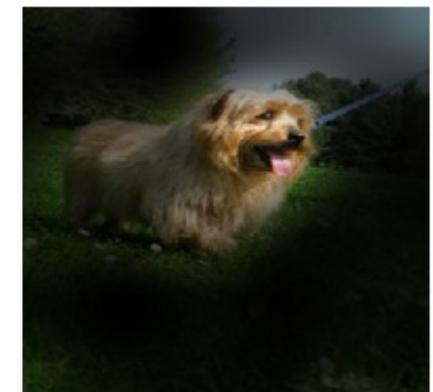
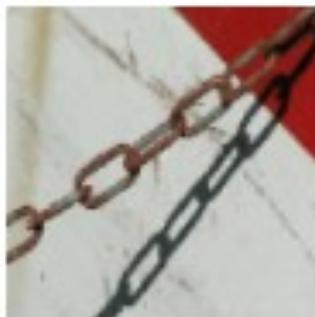
$$\mathbf{z}_0 = [\mathbf{x}_{\text{class}}; \mathbf{x}_p^1 \mathbf{E}; \mathbf{x}_p^2 \mathbf{E}; \dots; \mathbf{x}_p^N \mathbf{E}] + \mathbf{E}_{pos}, \quad \mathbf{E} \in \mathbb{R}^{(P^2 \cdot C) \times D}, \mathbf{E}_{pos} \in \mathbb{R}^{(N+1) \times D}$$

ViT Attention Maps

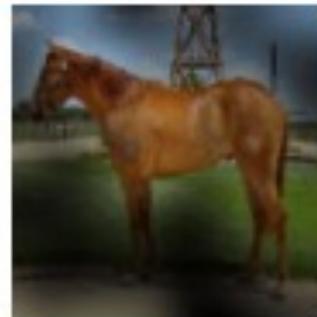
Input Attention

- Attention from the output token to the input space:

91



92



Masked Autoencoders Are Scalable Vision Learners

CVPR 2022

Kaiming He^{*,†} Xinlei Chen^{*} Saining Xie Yanghao Li Piotr Dollár Ross Girshick

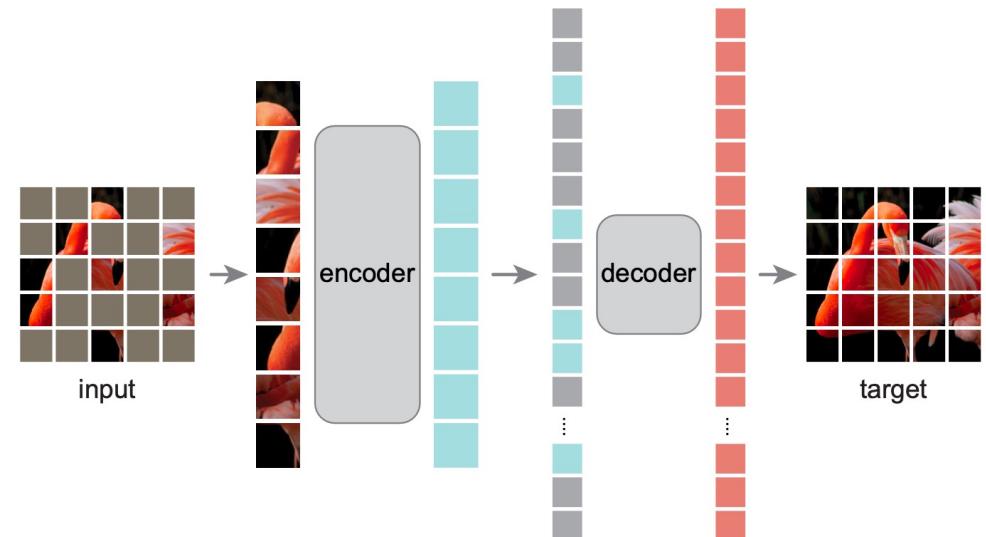
^{*}equal technical contribution [†]project lead

Facebook AI Research (FAIR)

Masked autoencoders (MAE) are scalable self-supervised learners.

1. asymmetric encoder-decoder:

1. encoder that operates only on the visible subset of patches
2. lightweight decoder reconstructs the image from the latent representation and mask tokens



Masked Autoencoders Are Scalable Vision Learners

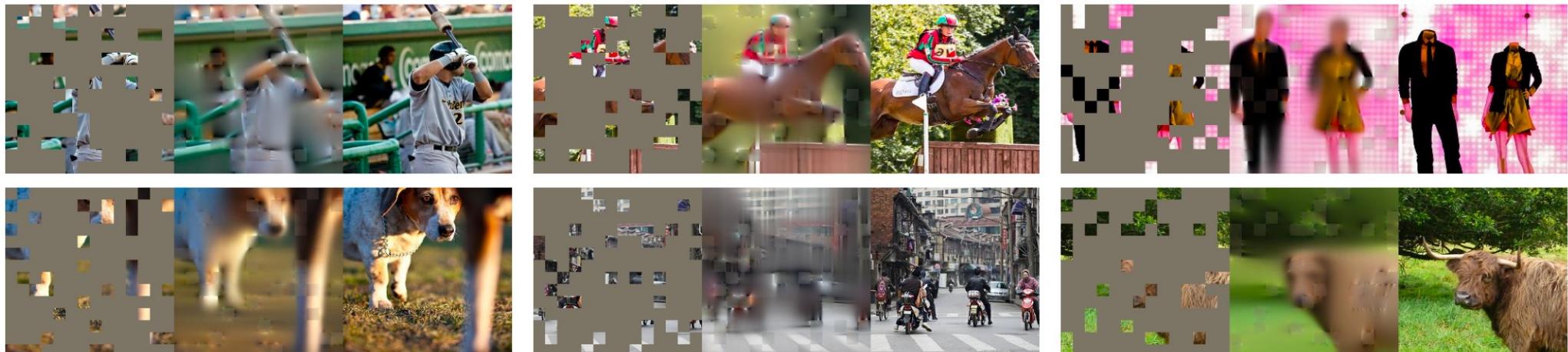
CVPR 2022

Kaiming He^{*,†} Xinlei Chen^{*} Saining Xie Yanghao Li Piotr Dollár Ross Girshick

*equal technical contribution †project lead

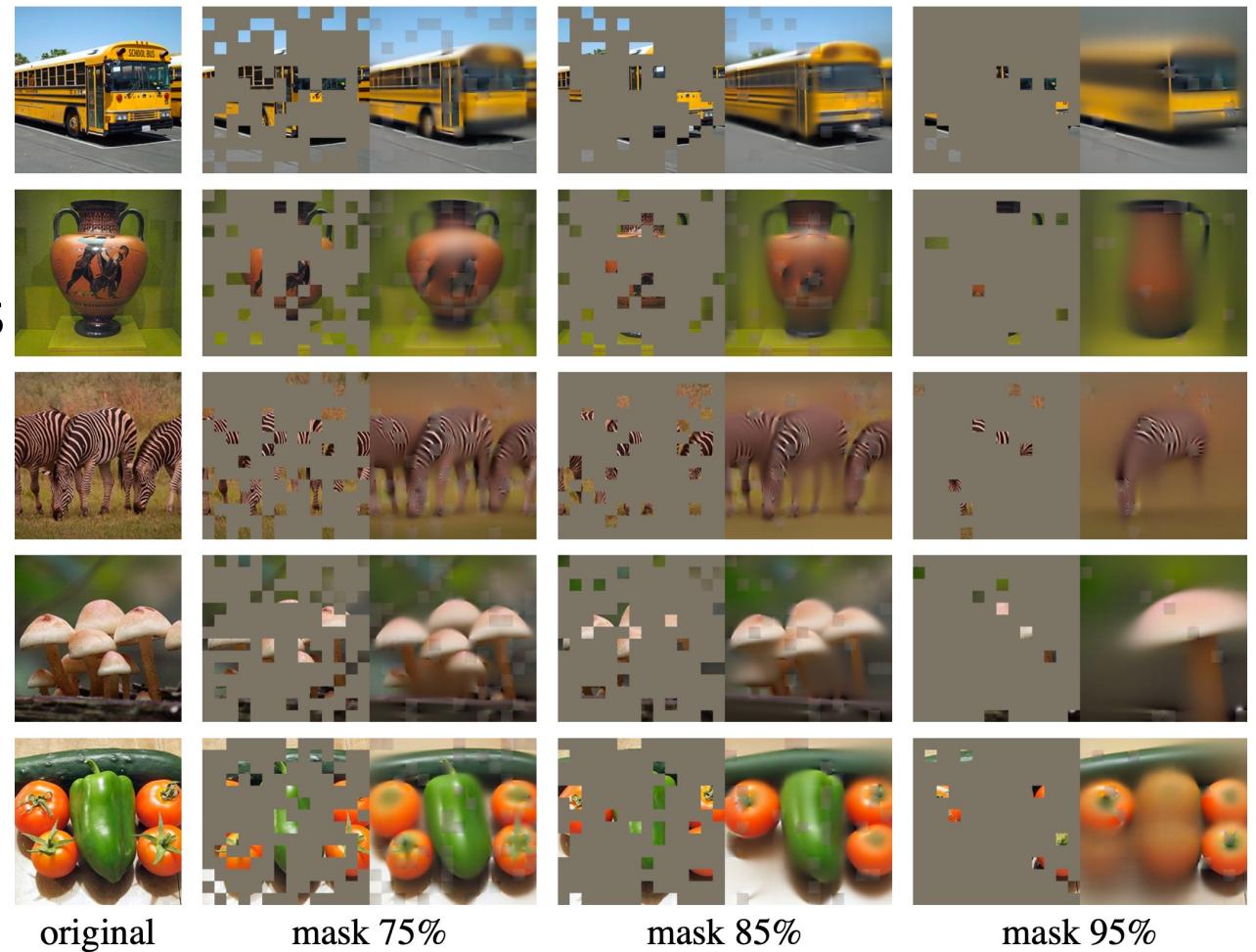
Facebook AI Research (FAIR)

- Images have heavy spatial redundancy
 - missing patch can be recovered from neighboring patches with little high-level understanding
- Mask very high portion of random patches



Masked Autoencoder

- MAE pre-trained with a masking ratio of 75% but applied on inputs with higher masking ratios.
- The predictions differ plausibly from the original images, showing that the method can generalize.



Recovering masked regions

AN IMAGE IS WORTH 16X16 WORDS:
TRANSFORMERS FOR IMAGE RECOGNITION AT SCALE

ICLR 2021

Alexey Dosovitskiy^{*,†}, Lucas Beyer^{*}, Alexander Kolesnikov^{*}, Dirk Weissenborn^{*},
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Georg Heigold, Sylvain Gelly, Jakob Uszkoreit, Neil Houlsby^{*,†}

*equal technical contribution, †equal advising

Google Research, Brain Team

{adosovitskiy, neilhoulsby}@google.com

Stacked Denoising Autoencoders: Learning Useful Representations in a Deep Network with a Local Denoising Criterion

JML 2010

Pascal Vincent

Département d'informatique et de recherche opérationnelle
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2920, chemin de la Tour
Montréal, Québec, H3T 1J8, Canada

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44th Annual International Conference of
**the IEEE Engineering in
Medicine and Biology Society**

11-15 July 2022  Glasgow, Scotland, UK



Vision Transformers for Classification of Breast Ultrasound Images

B. Gheflati, H. Rivaz

Department of Electrical and Computer Engineering,
Concordia University, Montreal, Canada.

I. Introduction

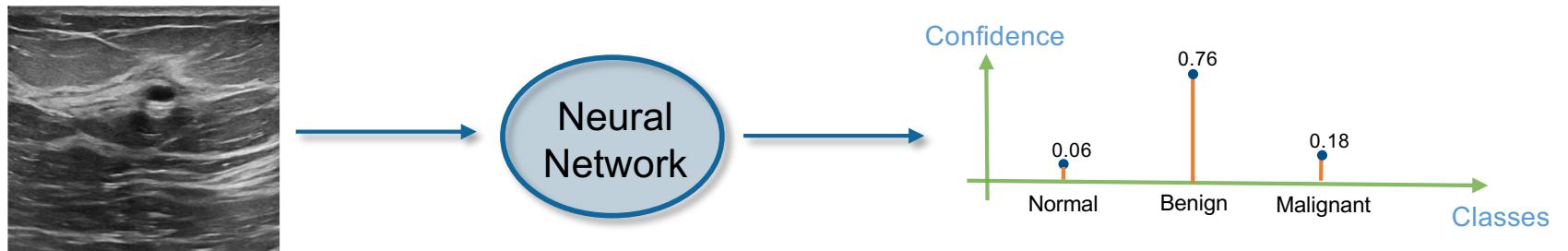
- Problem Statement

- ✓ **Breast cancer** is the most frequent cause of cancer mortality among women.

- ✓ Medical **ultrasound (US)** imaging

- ✓ Availability
- ✓ Real-time display
- ✓ Cost-efficiency
- ✓ Non-invasive nature

- ✓ Medical images classification



II. Related Work

- ✓ A common approach in medical images Classification



Convolutional Neural Networks (CNNs)

{ ResNet
VGG
AlexNet
GoogLeNet
NASNET

Pre-trained CNN models

Transfer Learning (TL)



transferring the pre-trained models based on a specific task

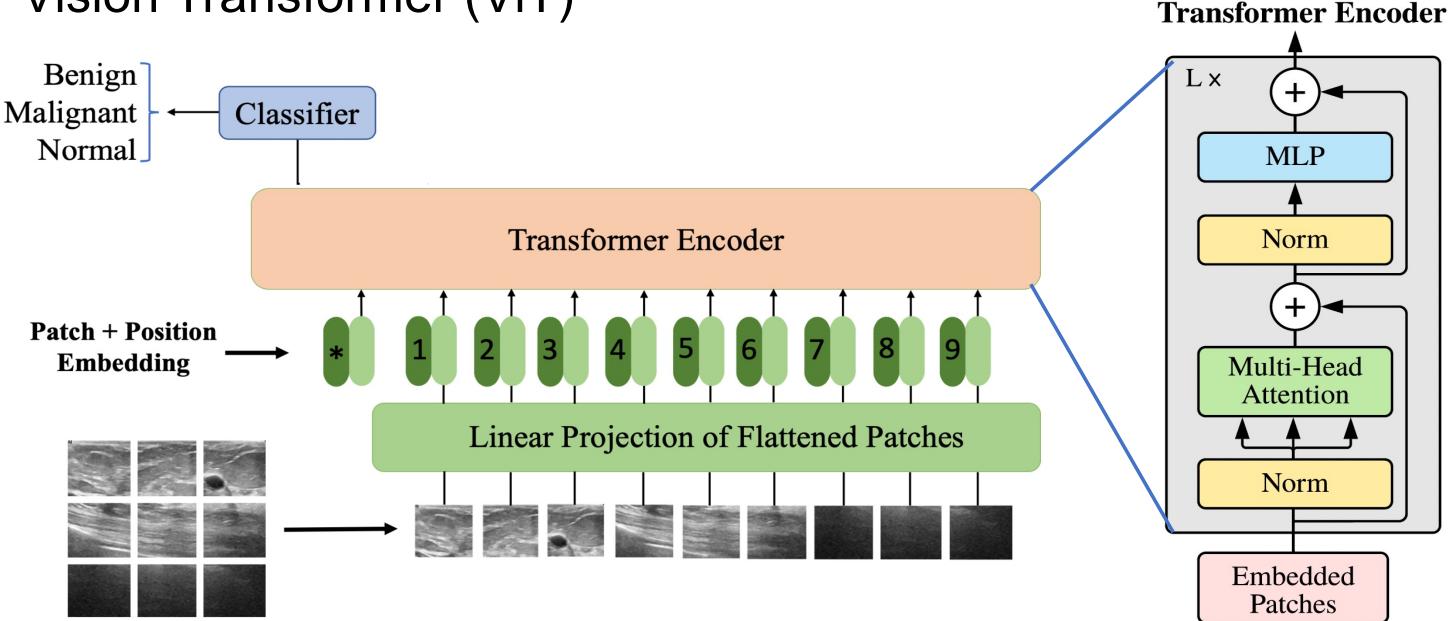
References	Pre-trained models	Application
Lazo <i>et al.</i> [1]	VGG-16 IncceptionV3	Lesion detection in breast US images.
Al-Dhabyani <i>et al.</i> [2]	VGG16, ResNet, Inception, and NASNet	Breast masses classification

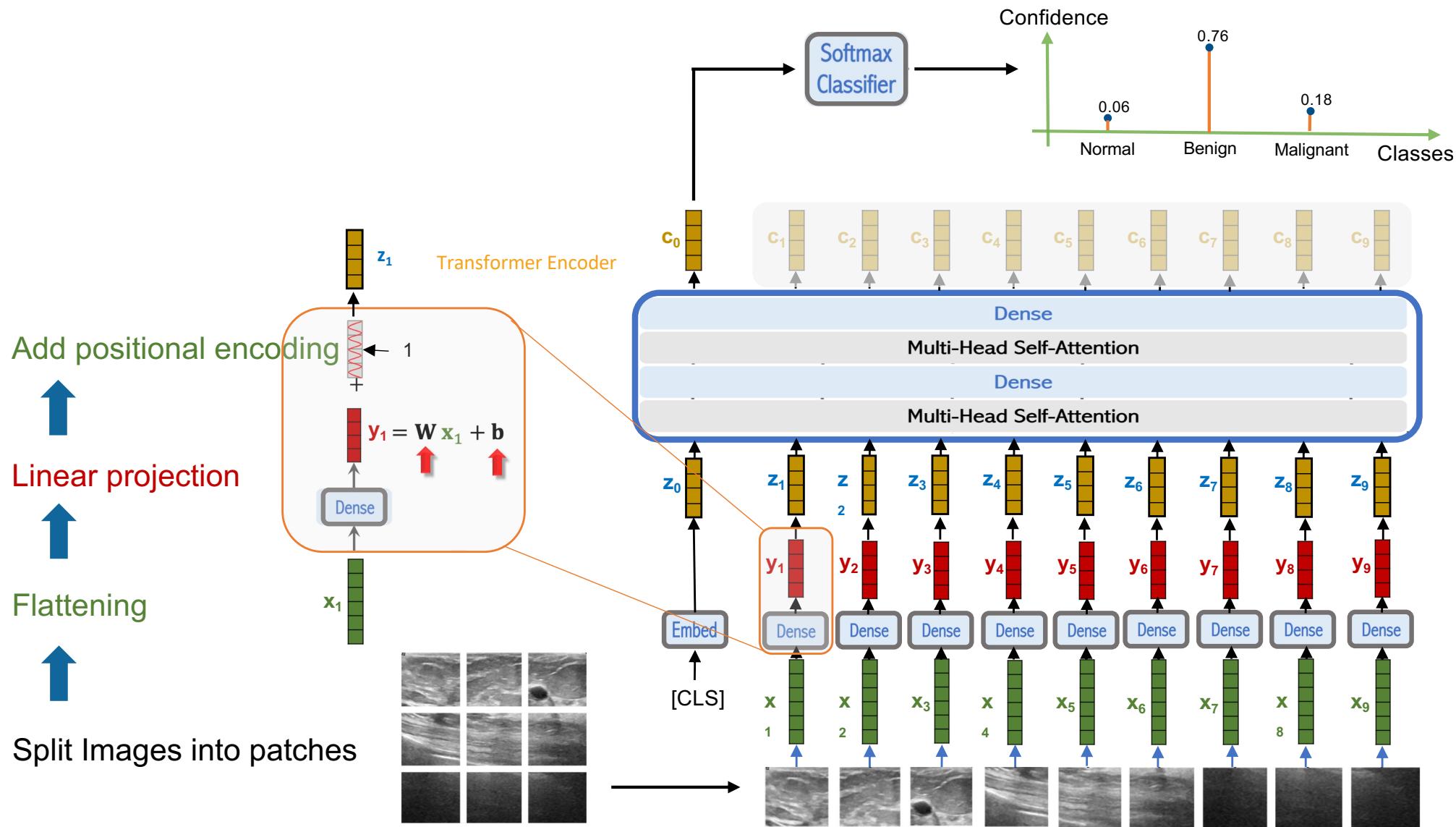
II. Related Work

- **Motivation**

Recently, Vision Transformer (ViT)^[3] designs have shown great potential to be an alternative to CNNs.

- ✓ **Vision Transformer (ViT)**





II. Related Work

- ViT applications
 - ✓ Image Classification
 - ✓ Image Segmentation
 - ✓ Object detection

Reference	Application
Karimi <i>et al.</i> [4]	3-D Medical Image Segmentation
Hatamizadeh <i>et al.</i> [5]	3-D Medical Image Segmentation
Dai <i>et al.</i> [6]	Multi-modal images classification
Carion <i>et al.</i> [7]	Object detection

III. Hypotheses

- Goal: The potential application of self-attention models to classify breast US images
- Contributions
 - ✓ Comparing different pre-trained ViT models.
 - ✓ Transferring pre-trained ViT models to the classification of breast US images.
 - ✓ Fine-tuning SOTA CNN networks to classify US images.
 - ✓ Adopting a weighted cross-entropy loss function.

IV. Method

- **Dataset**



- BUSI : 780 breast US images^[8]
 - B : 163 images^[9]

133 Normal
437 Malignant
210 Benign

 110 Benign
53 Malignant

Malignant

Normal

- **Evaluation Metrics**

Classification Accuracy Area Under the ROC Curve (AUC)



IV. Method

- **Models**
 - CNN
 - VGG16
 - ResNet50
 - InceptionV3
 - NASNetLarge
 - ViT
 - ViT models (ViT-Ti, ViT-S, ViT-B)
 - hybrid ViT+ResNet models (R+Ti, R26+S)^[10]
- **Fine-tuning details**
 - Splitting all datasets to 70%, 15% and 15% for training, validation and testing.
 - 5-fold cross-validation (CV) for the final evaluation.
 - Weighted cross-entropy loss (imbalanced training dataset).

IV. Method

A summary of our method is as follows:

- ✓ Classification of BUSI+B dataset using TL based on CNN models.
- ✓ Classification of BUSI+B dataset using TL based on ViT-based networks.
- ✓ Classification of augmented BUSI+B dataset using TL based on ViT-based networks.
- ✓ Classification of three B, BUSI, and BUSI+B datasets using TL based on two ViT-based and CNN networks.

V. Results

- **Convolutional Neural Network (CNN) Models**

- Dataset: BUSU + B

Evaluation	ResNet	VGG	Inception	NASNET
ACC	85.3%	82%	80%	79%
AUC	0.94	0.92	0.92	0.917

- ResNet50 model has the best results with 85.3% Acc and 0.95 AUC.

- **ViT-based Models**

- Dataset: BUSU + B

Evaluation	R+Ti/16	S/32	B/32	Ti/16	R26+S/16
ACC	85.7%	86%	86.7%	85%	86.4%
AUC	0.94	0.95	0.95	0.94	0.95

- ViT models shows comparable or even better results comparing to the CNN models.

VI. Conclusion

This study shows the potential of ViT models in US image classification and, therefore, the effectiveness of learning the global anatomical dependencies of US medical images.

VII. Acknowledgment

We acknowledge the support of the Natural Sciences and Engineering Research Council of Canada (NSERC), and thank NVIDIA for the donation of the GPU.

VIII. References

- [1] J. F. Lazo, S. Moccia, E. Frontoni, and E. De Momi, "Comparison of different cnns for breast tumor classification from ultrasound images," *arXiv preprint arXiv:2012.14517*, 2020.
- [2] W. Al-Dhabyani, M. Gomaa, H. Khaled, and F. Aly, "Deep learning approaches for data augmentation and classification of breast masses using ultrasound images," *Int. J. Adv. Comput. Sci. Appl.*, vol. 10, no. 5, pp. 1–11, 2019.
- [3] A. Dosovitskiy, L. Beyer, A. Kolesnikov, D. Weissenborn, X. Zhai, T. Unterthiner, M. Dehghani, M. Minderer, G. Heigold, S. Gelly *et al.*, "An image is worth 16x16 words: Transformers for image recognition at scale," *arXiv preprint arXiv:2010.11929*, 2020.
- [4] D. Karimi, S. Vasylechko, and A. Gholipour, "Convolution-free medical image segmentation using transformers," *arXiv preprint arXiv:2102.13645*, 2021.
- [5] A. Hatamizadeh, D. Yang, H. Roth, and D. Xu, "Unetr: Transformers for 3d medical image segmentation," *arXiv preprint arXiv:2103.10504*, 2021.
- [6] Y. Dai, Y. Gao, and F. Liu, "Transmed: Transformers advance multi- modal medical image classification," *Diagnostics*, vol. 11, no. 8, p. 1384, 2021.
- [7] N. Carion, F. Massa, G. Synnaeve, N. Usunier, A. Kirillov, and S. Zagoruyko, "End-to-end object detection with transformers," in *European Conference on Computer Vision*. Springer, 2020, pp. 213– 229.
- [8] W. Al-Dhabyani, M. Gomaa, H. Khaled, and A. Fahmy, "Dataset of breast ultrasound images," *Data in brief*, vol. 28, p. 104863, 2020.
- [9] M. H. Yap, G. Pons, J. Martí, S. Ganau, M. Sentís, R. Zwiggelaar, A. K. Davison, and R. Martí, "Automated breast ultrasound lesions detection using convolutional neural networks," *IEEE journal of biomedical and health informatics*, vol. 22, no. 4, pp. 1218–1226, 2017.
- [10] A. Steiner, A. Kolesnikov, X. Zhai, R. Wightman, J. Uszkoreit, and L. Beyer, "How to train your vit? data, augmentation, and regularization in vision transformers," *arXiv preprint arXiv:2106.10270*, 2021.

Ultrasound Imaging

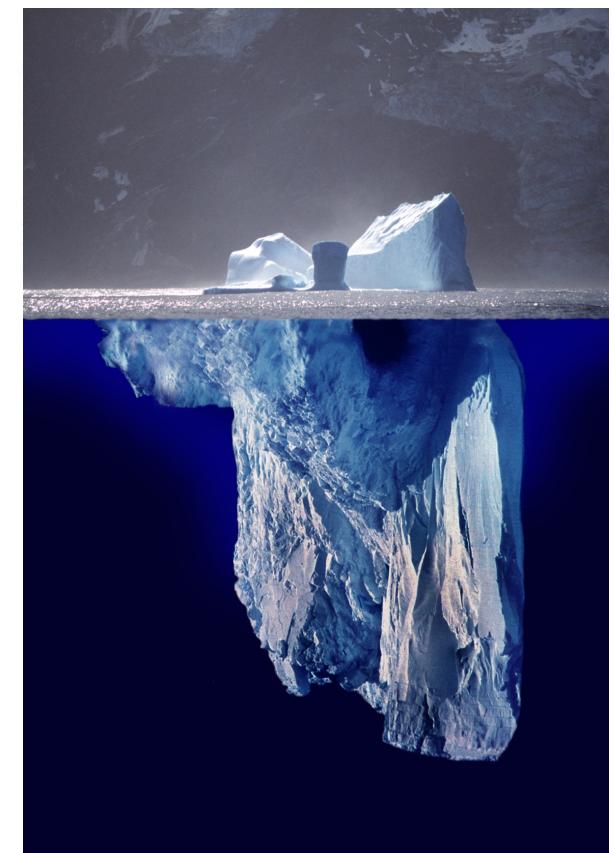
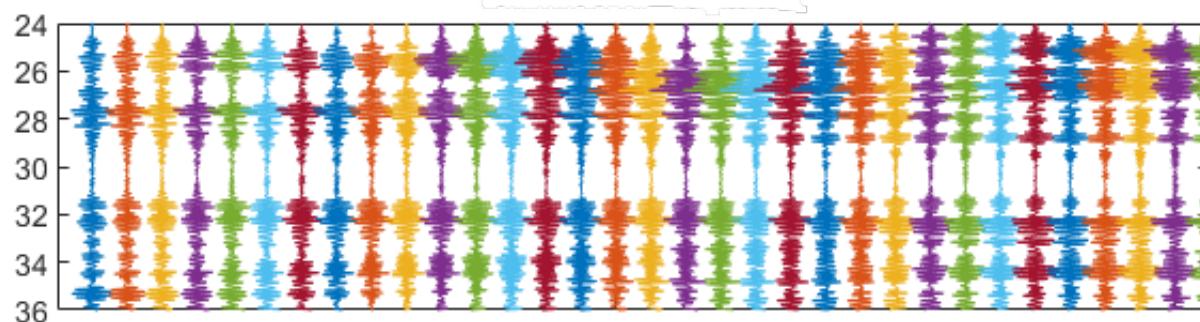
One of the most used imaging modalities

- Real-time
- Inexpensive
- Safe
- Portable
- Big ultrasound manufacturers have closely guarded raw data



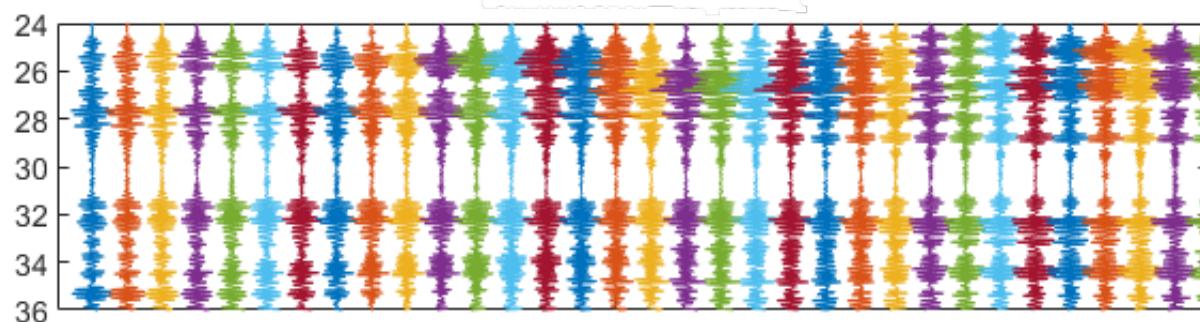
AI-Driven Ultrasound

- B-mode US (the familiar gray-scale images) only contains a small percentage of all data

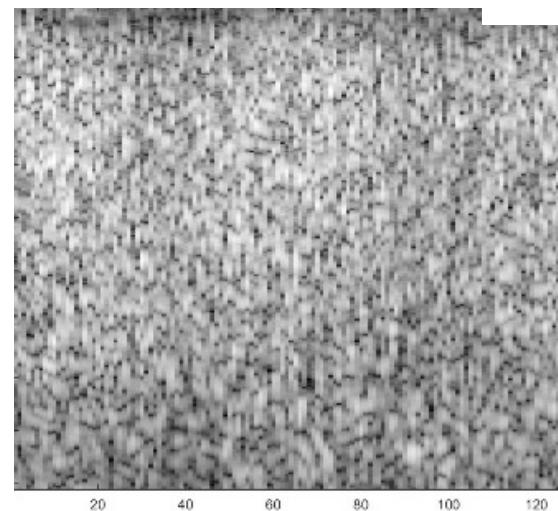
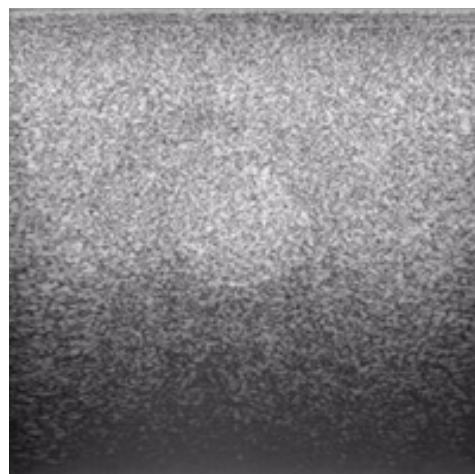
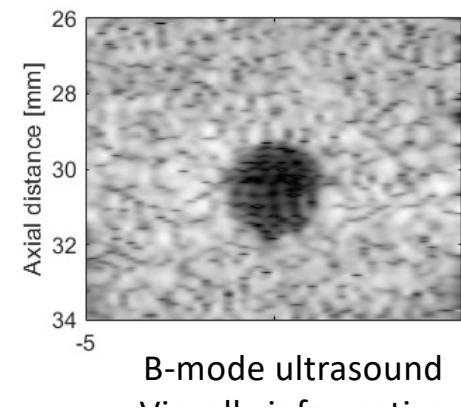


AI-Driven Ultrasound

- B-mode US (the familiar gray-scale images) only contains a small percentage of all data



- US has a **very high frame rate**





Collection and Interpretation is hard



US and rendered MR

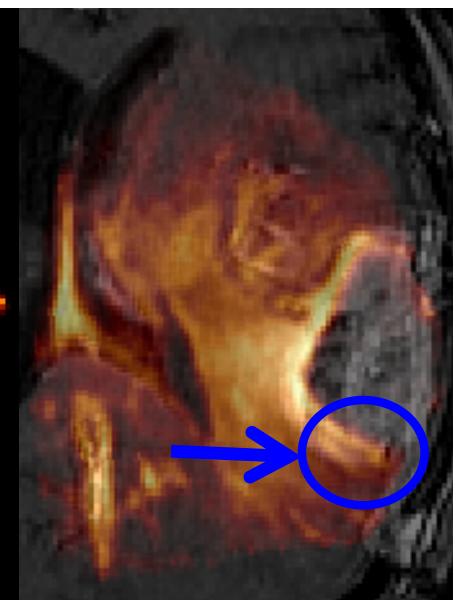
Rivaz, H, Chen, S, Collins, DL, IEEE TMI, 2015



Pre-operative MR



Post-resection US
(tumour is resected)



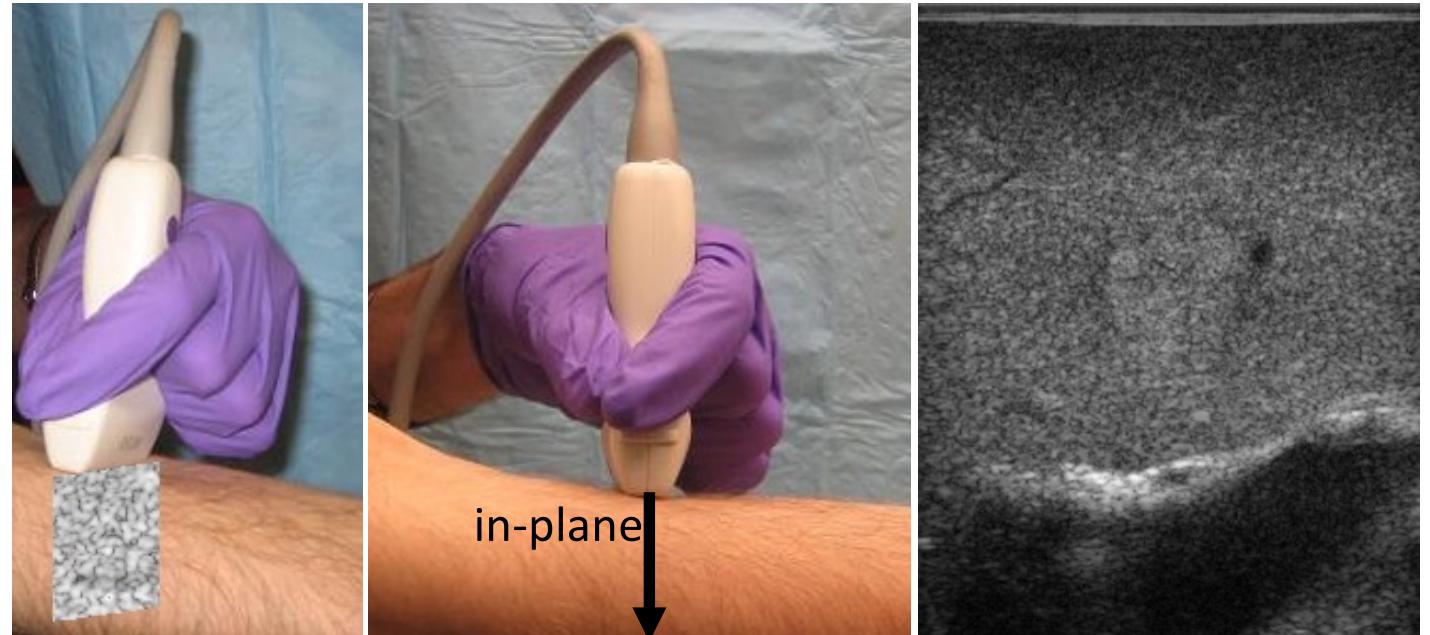
Residual tumour

AI-Driven Ultrasound

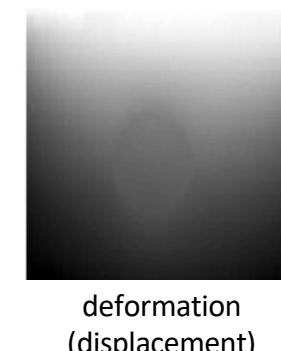
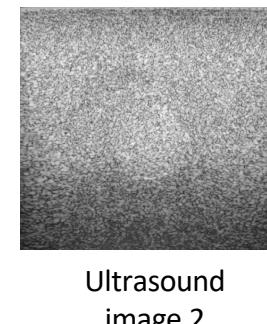
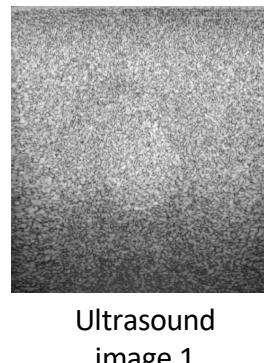
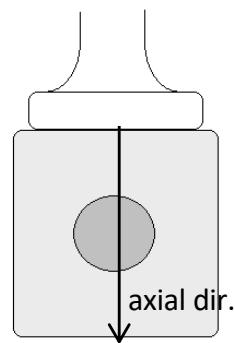
- Better use of raw radio-frequency (RF) data
 - Elastography
 - Quantitative ultrasound (qUS)
 - Faster US acquisition
 - Aberration correction for transcranial imaging & focusing
 - Deep beamforming
- Aid collection & interpretation
 - Image Registration
 - US to MRI
 - US to US
 - Image segmentation
 - Explainable AI (XAI)
 - Image selection

Ultrasound Elastography

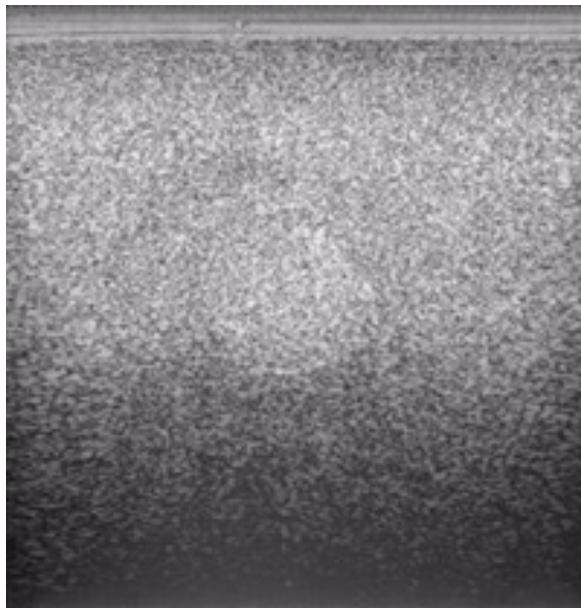
Deformation can reveal mechanical properties of tissue



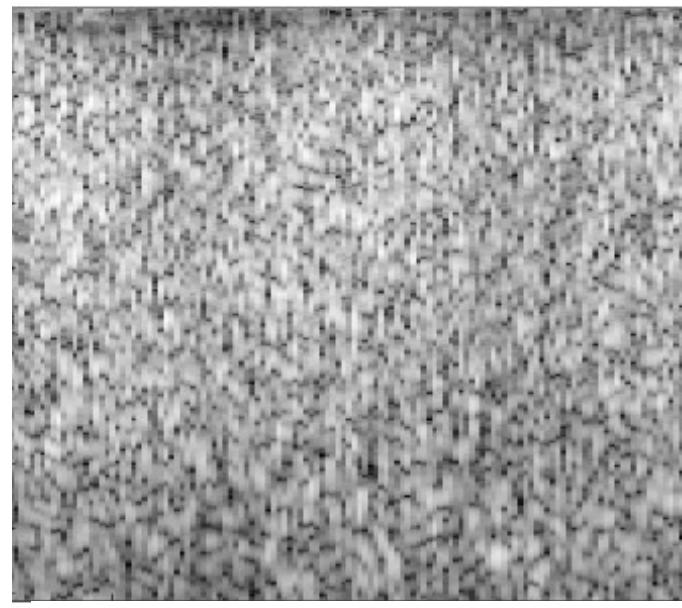
Estimating tissue deformation gives clues to the mechanical properties of tissue



Common Step of Elastography: Displacement Estimation



B-mode images from
quasi-static
compression
(focused imaging)



B-mode images after acoustic
radiation force
(plane-wave imaging)

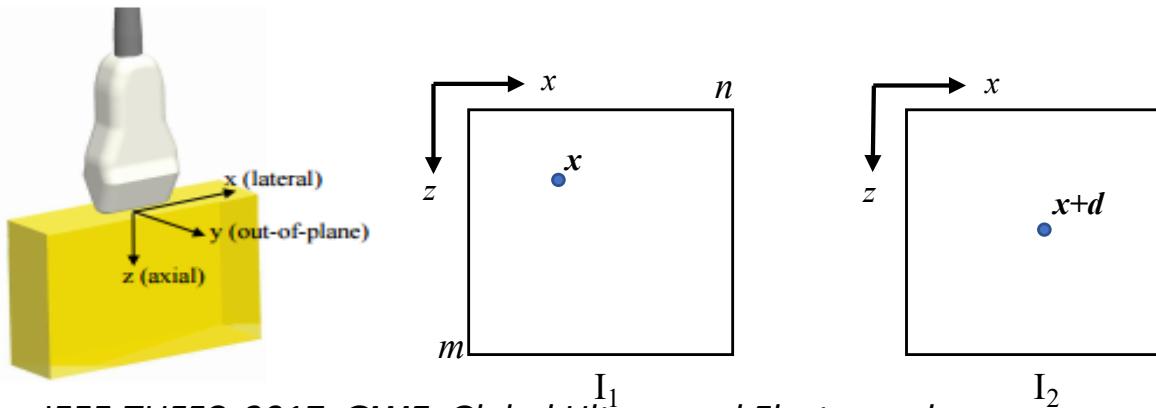


Real-Time Displacement Estimation

- Goal: minimize cost function $C(\mathbf{d})$:

$$C(\mathbf{d}) = \sum (D(\mathbf{d}) + R(\mathbf{d}))$$

- C is a nonlinear equation.
- There are >1 million variables.



Hashemi & Rivaz, IEEE TUFFC, 2017, **GLUE**: Global Ultrasound Elastography

Mirzaei, Asif, Rivaz, IEEE TMI, 2019, **OverWind**: tOtal Variation Regularization and WINdow-based Elastography

Ashikuzzaman, Rivaz, IEEE TUFFC, 2022, **L1-SOUL**: Second-Order Elastography

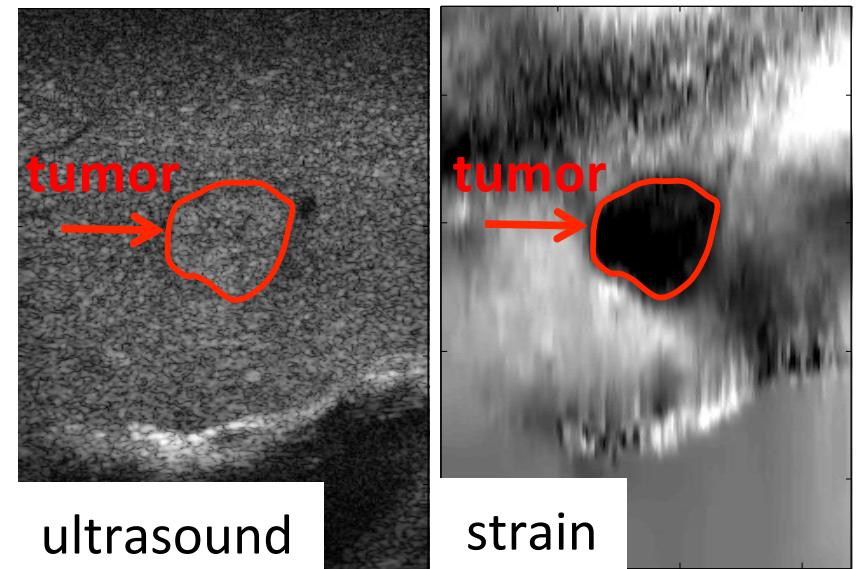
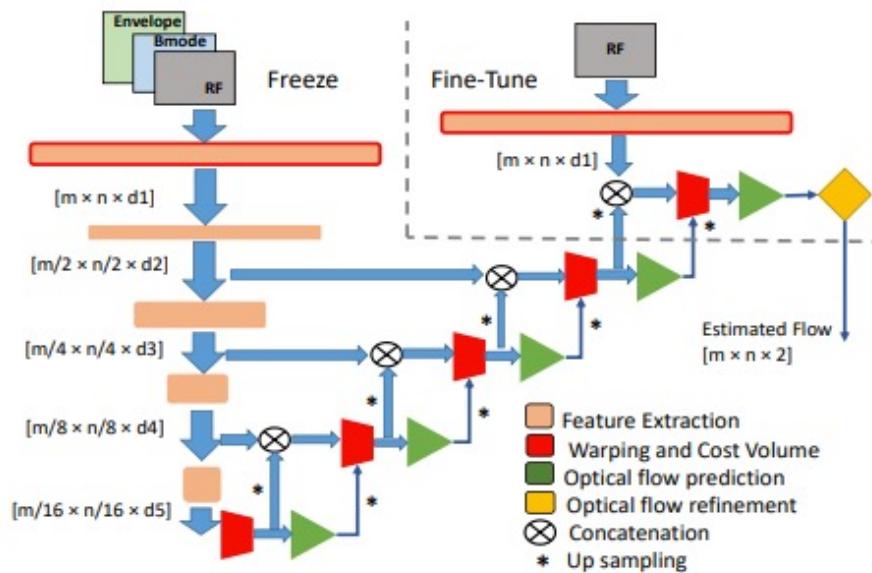
73

Code available online at code.sonography.ai



CNN for displacement estimation

Radio-Frequency (RF) Modified PWC-Net



In collaboration with Johns Hopkins University

Tehrani*, Mirzaei*, Rivaz, MICCAI 2020

Kibria*, Rivaz, MICCAI POCUS 2018

Tehrani*, Rivaz, IEEE Trans. UFFC special issue on deep learning, 2020

Supervised Learning

- There is no ground truth in real data
- Using simulated ultrasound images with known displacement
- Issues:
 - Simulation is simplistic (domain shift)
 - Many different imaging settings (domain shift)
- We have thousands of real images, but **without** ground truth

Kibria*, Rivaz, MICCAI POCUS 2018

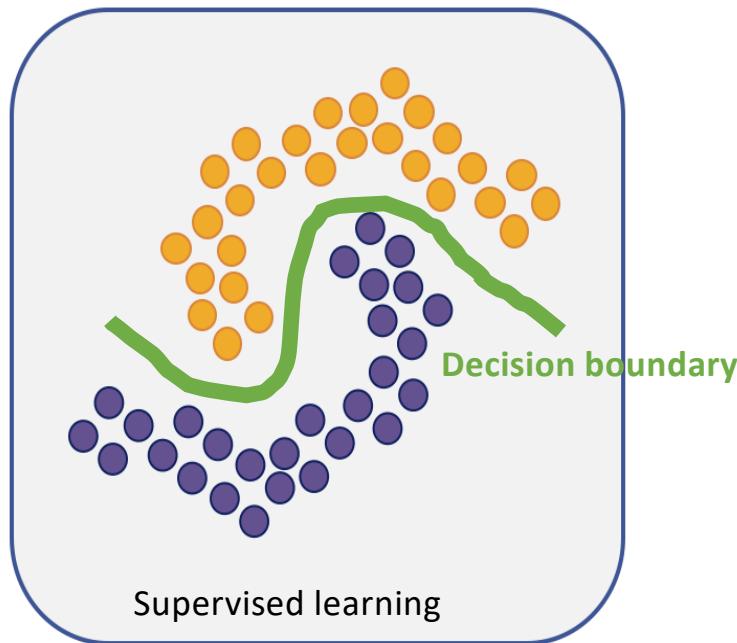
Tehrani*, Rivaz, IEEE Trans. UFFC special issue on deep learning, 2020



In collaboration with Johns Hopkins University

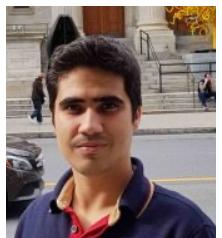


Semi-Supervised Learning (SSL)



- In this work, we fine-tuned the weights on real-data without knowing the ground truth

A Tehrani*, M Mirzaei*, H Rivaz, Bi-Directional Semi-Supervised Elastography, MICCAI 2020
A Tehrani* M Sharifzadeh, E Boctor, H Rivaz, IEEE TUFFC 2022

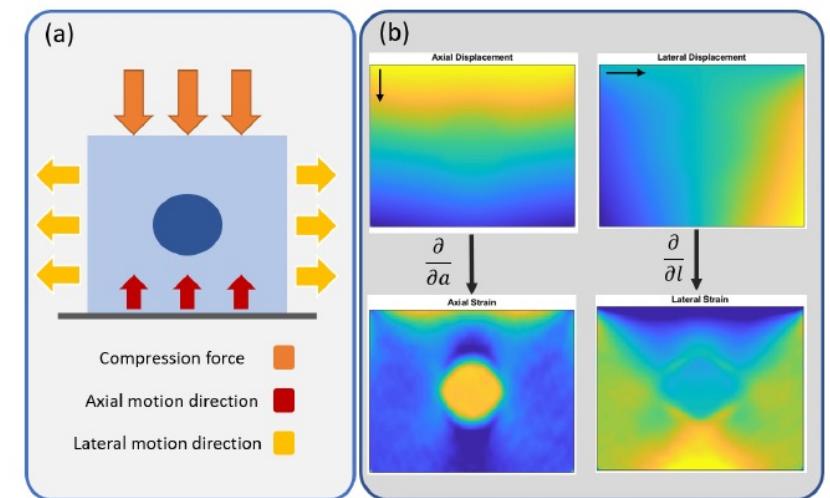
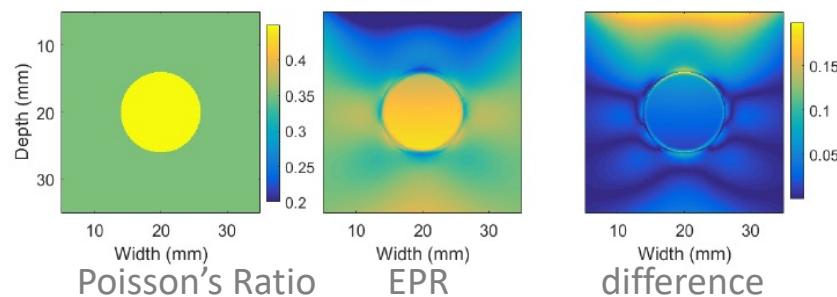


Incorporating Physics into Loss Function

- Homogeneous materials without boundary condition (Hook's law):
$$\text{lateral strain} = -\text{Poisson's Ratio} \times \text{axial strain}$$

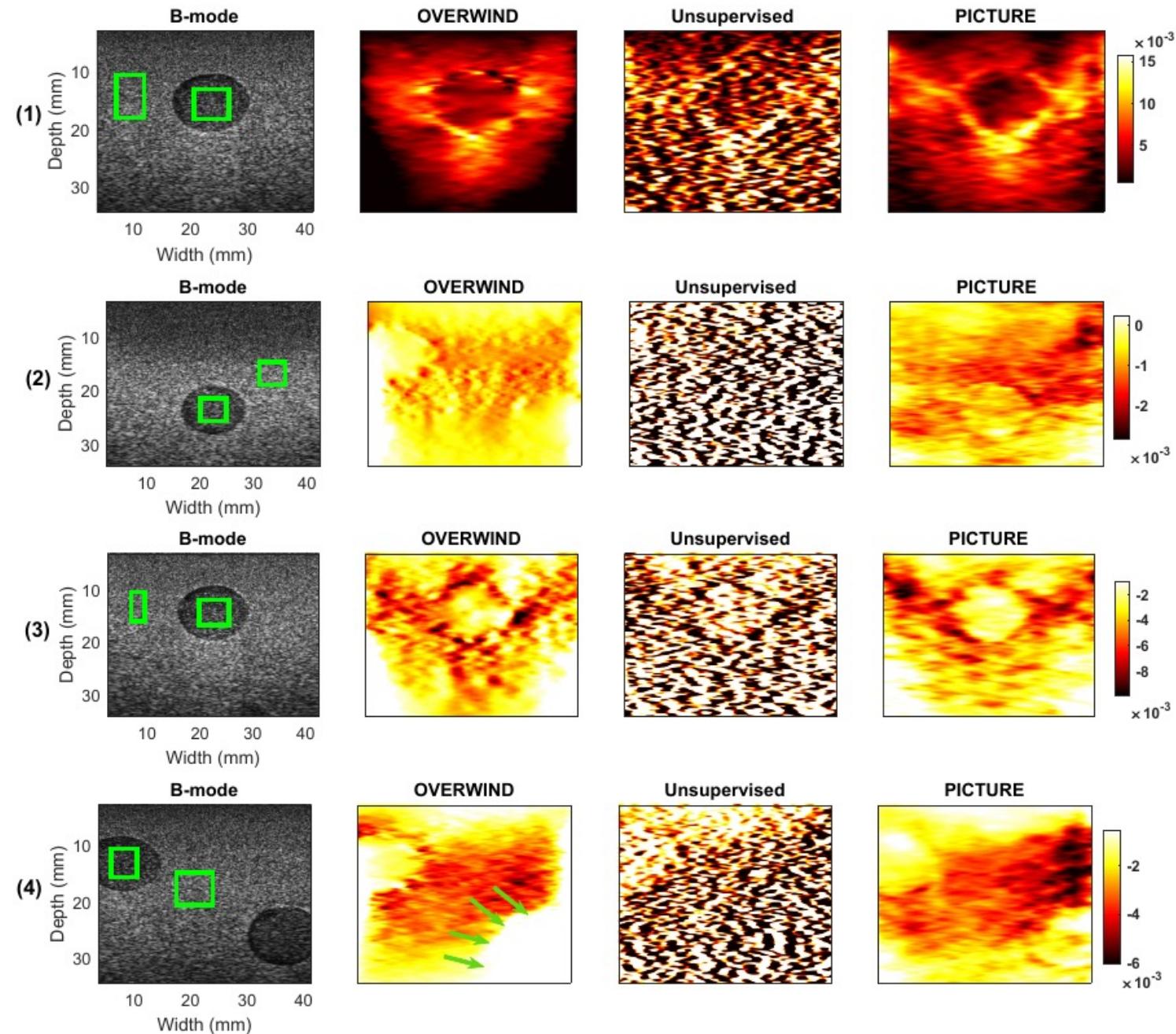
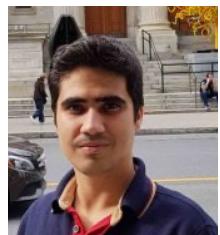
- Inhomogeneous media with boundary condition:

$$\text{Effective Poisson's Ratio (EPR)}: \frac{-\text{lateral strain}}{\text{axial strain}}$$



- $EPR \neq \text{Poisson's Ratio}$ but it has the same range as Poisson's Ratio (0.2 – 0.5).
We propose penalizing out of range EPRs.

Tehrani*, Rivaz, MICCAI 2022 (accepted)

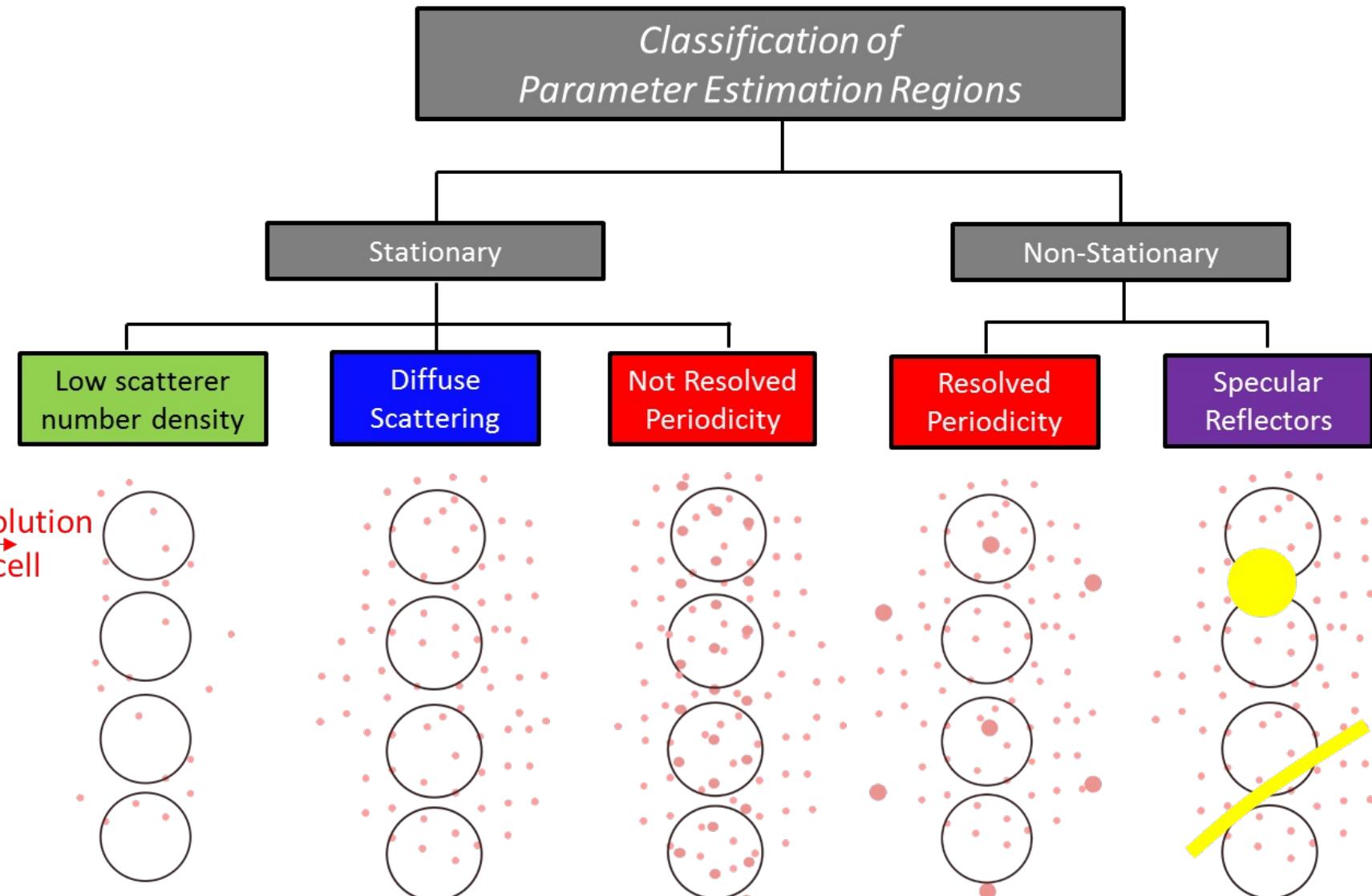


PICTURE: Tehrani*, Rivaz, MICCAI 2022 (accepted)

AI-Driven Ultrasound

- Better use of raw radio-frequency (RF) data
 - Elastography
 - Quantitative ultrasound (qUS)
 - Faster US acquisition
 - Aberration correction for transcranial imaging & focusing
 - Deep beamforming

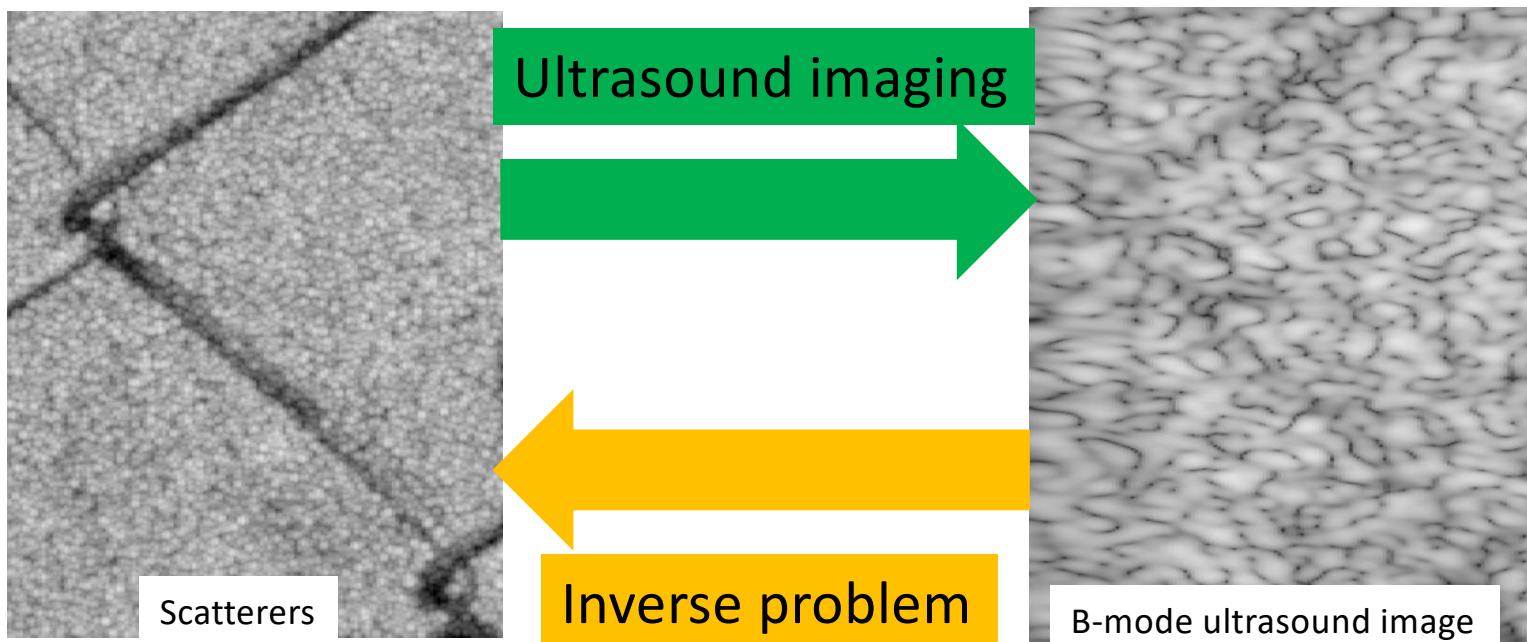
Quantitative US (qUS)



Slide courtesy of Tim Hall and Ivan Rosado-Mendez, UW-Madison

Inferring cell properties from RF data

- Estimate quantitative properties of tissue (cell size, density, scattering, attenuation)
- Open window into quantitative cells properties



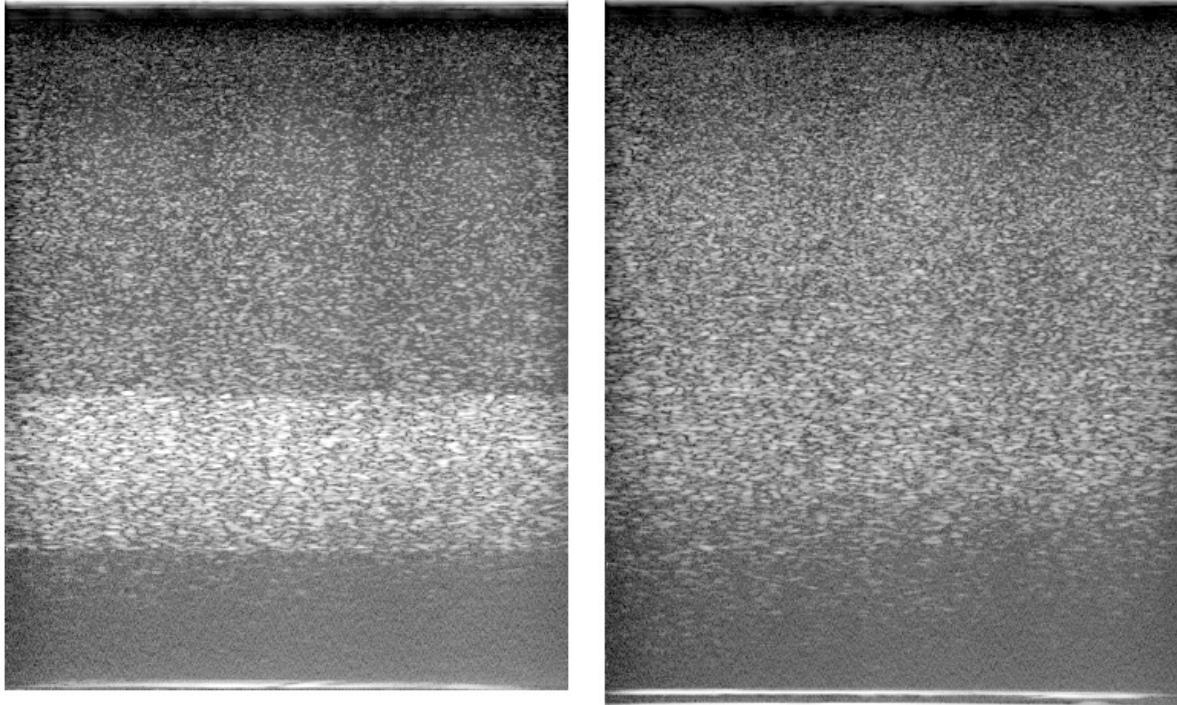


In collaboration with, UW-Madison



qUS

Layers visible in B-mode Layers invisible in B-mode



- Quantitative tissue properties (attenuation and backscattering) can be estimated with low variance from spectrum of RF data

Vajahi*, Rosado-Mendez, Hall, Rivaz, IEEE Trans. UFFC (TUFFC), 2018

Jafarpisheh*, Hall, Rivaz, Rosado-Mendez, IEEE Trans UFFC, 2021

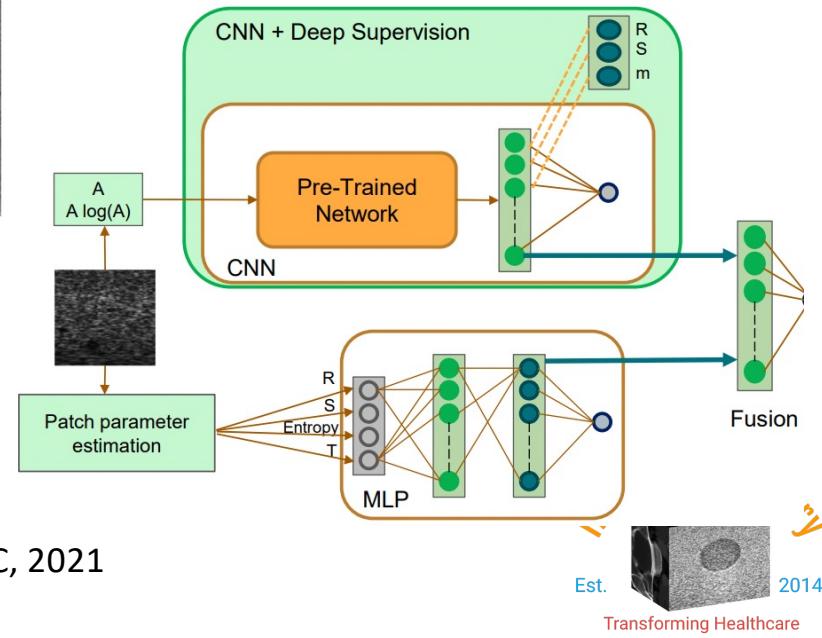
A Tehrani*, M Amiri* | Rosado-Mendez, T J Hall, H Rivaz, IEEE Trans UFFC, 2021

$$\sum_{l=1}^{N_F} \sum_{i=1}^{N_R} w_a(l,i) (X(f_l, z_i) - b_i - n_i \ln(f_l) + 4a_i f_l z_i)^2$$

Data

$$\sum_{i=2}^{N_R} w_a(a_i - a_{i-1})^2 + w_b |b_i - b_{i-1}| + w_n |n_i - n_{i-1}|$$

Physics-based regularization
ADMM Optimization

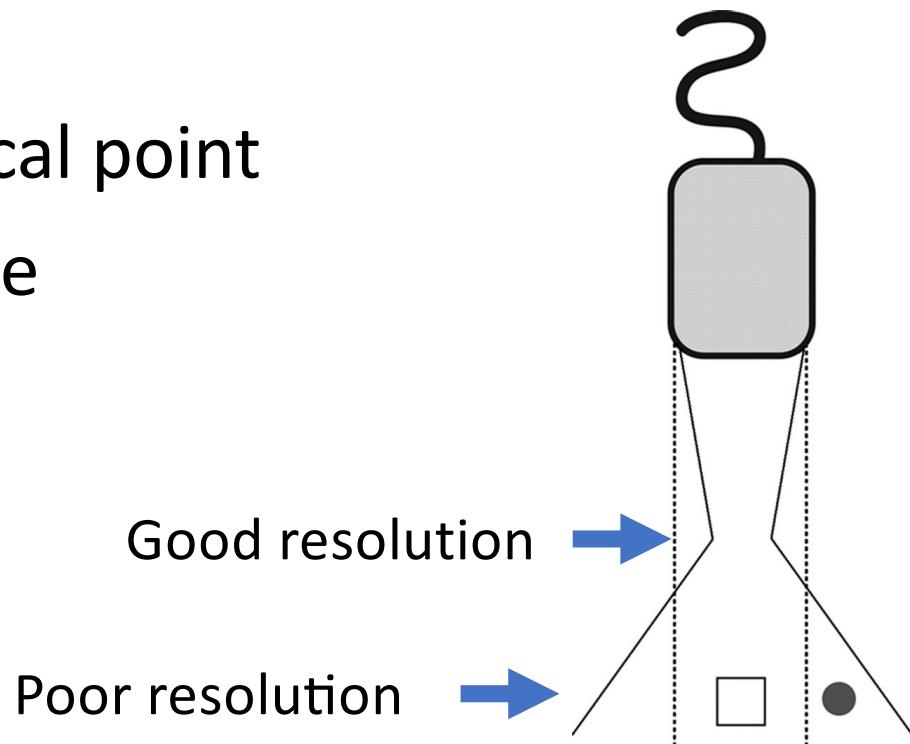


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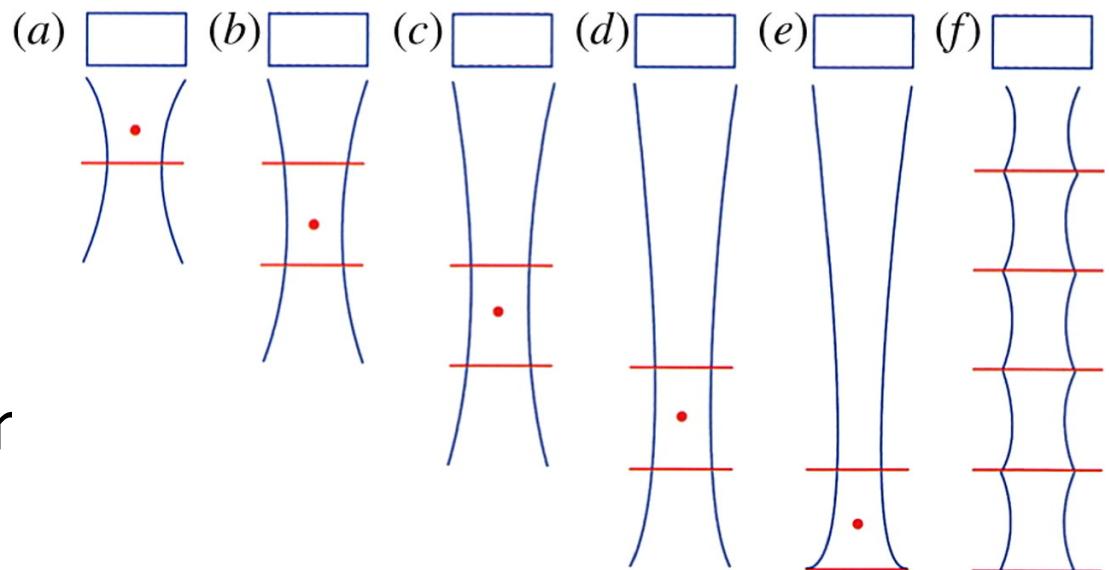
Focusing the Transmit Beam

- Transmit focusing
- Good resolution at focal point
- Not so good elsewhere



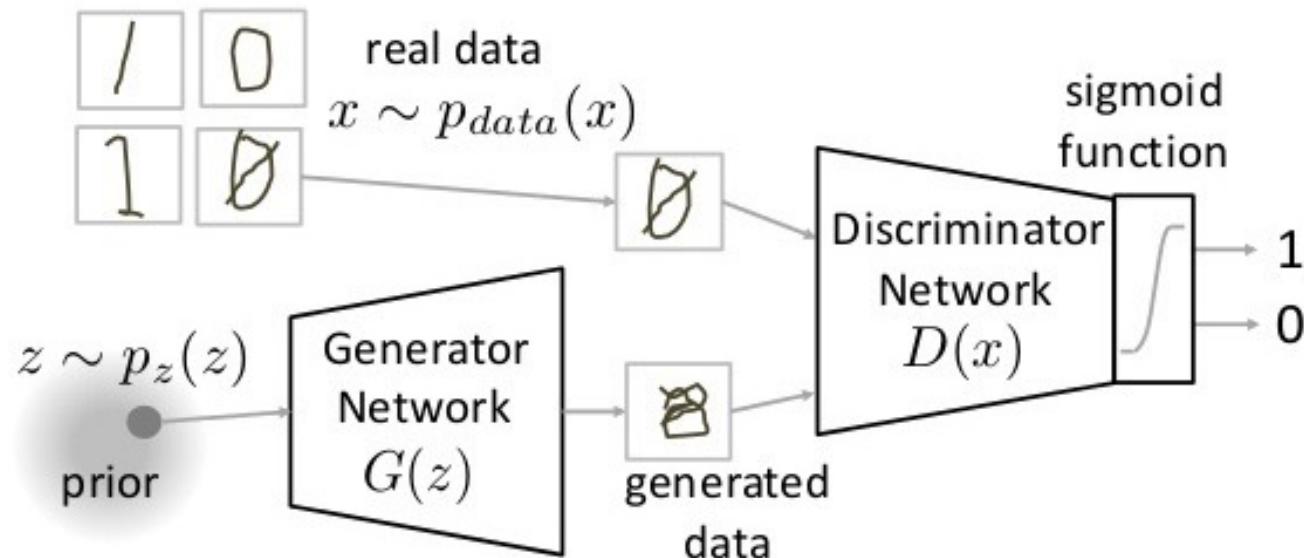
Multi-Focus US Imaging

- Good spatial resolution
- Poor temporal resolution
- Susceptible to motion blurring



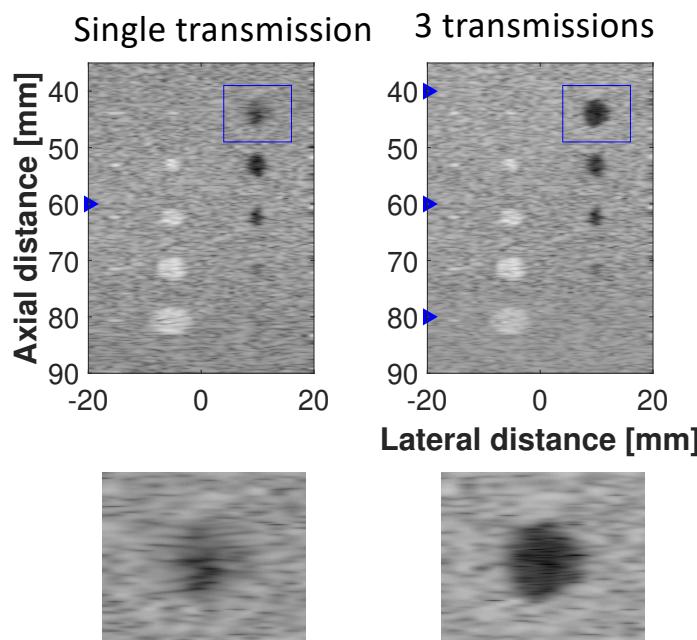
Generative Adversarial Network (GAN)

- What is a GAN?





Can We Obtain Multi-Focus US With GAN?



Goudarzi*, Asif, Rivaz, IEEE ISBI 2019
Goudarzi*, Asif, Rivaz, IEEE Transactions Computational Imaging, 2020



Can We Obtain Multi-Focus US With GAN?

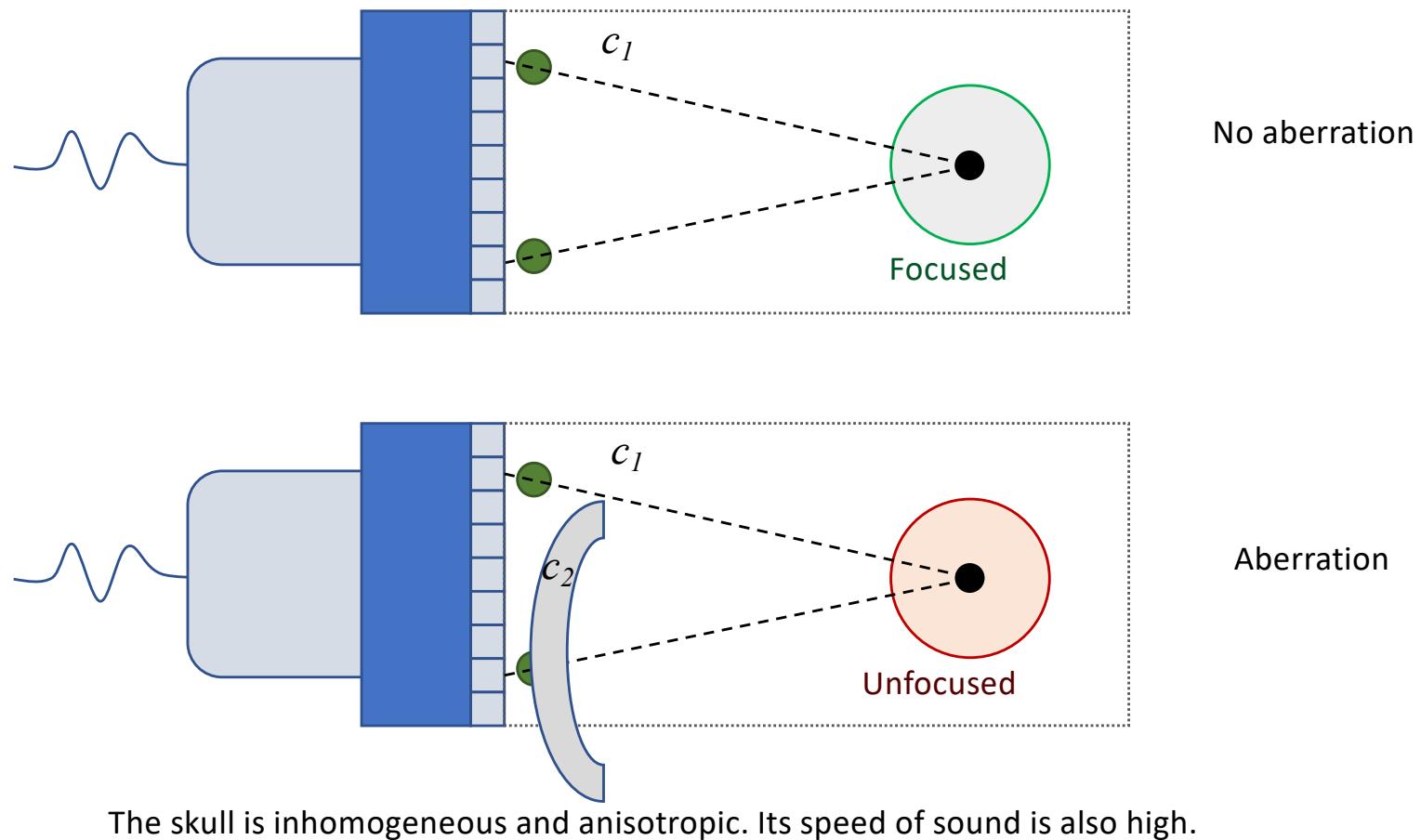


Goudarzi*, Asif, Rivaz, IEEE Transactions Computational Imaging, 2020

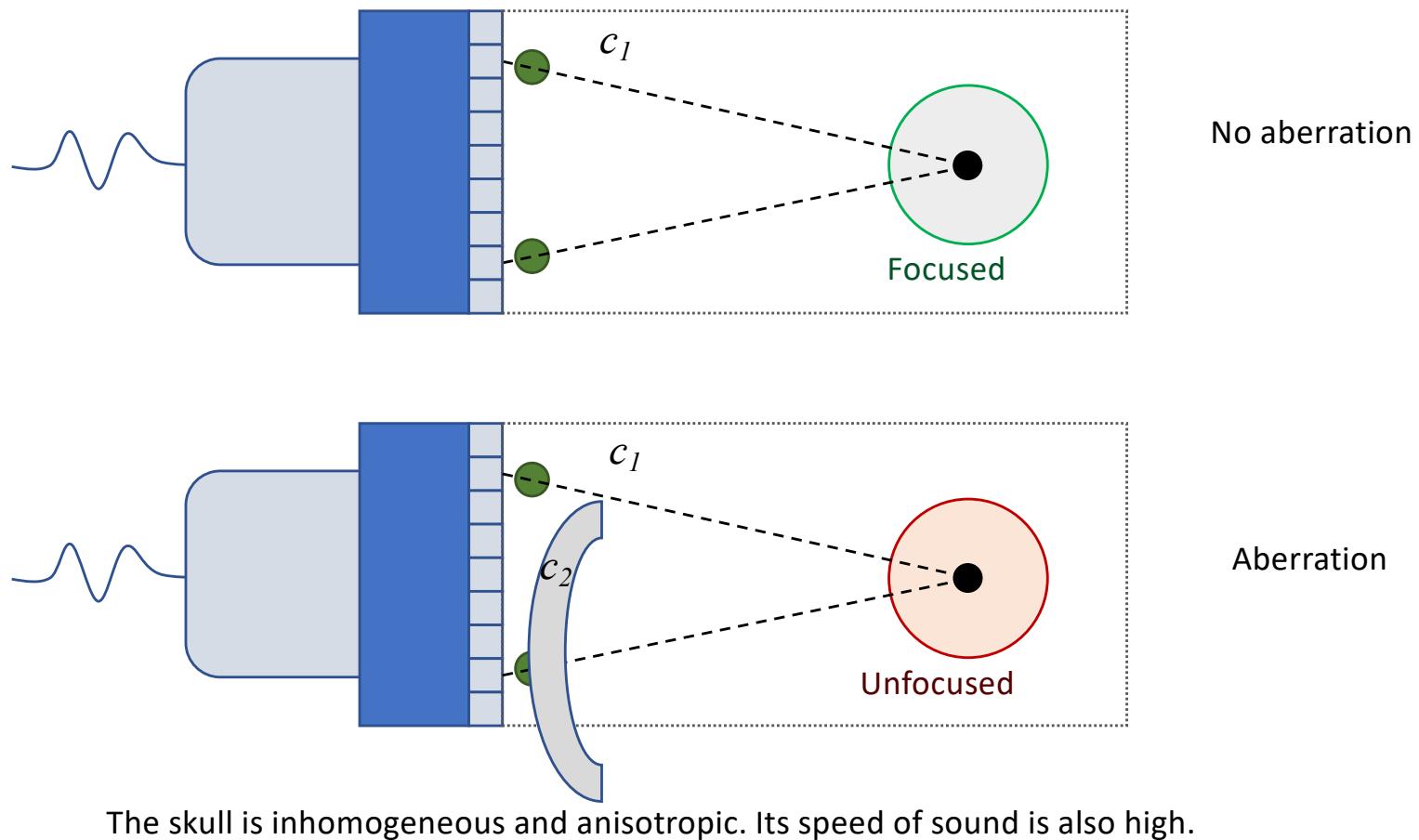
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Phase aberration in US



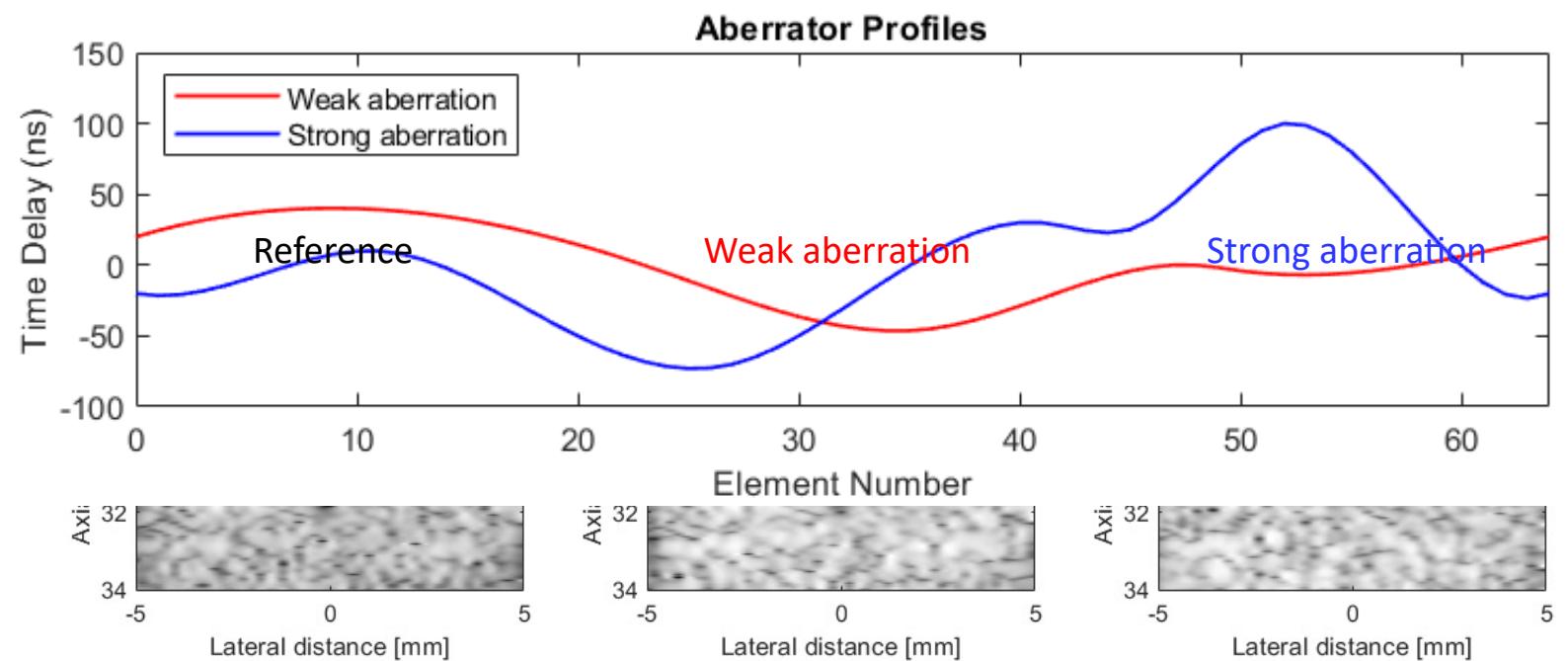
Phase aberration in US





Phase aberration in transcranial US

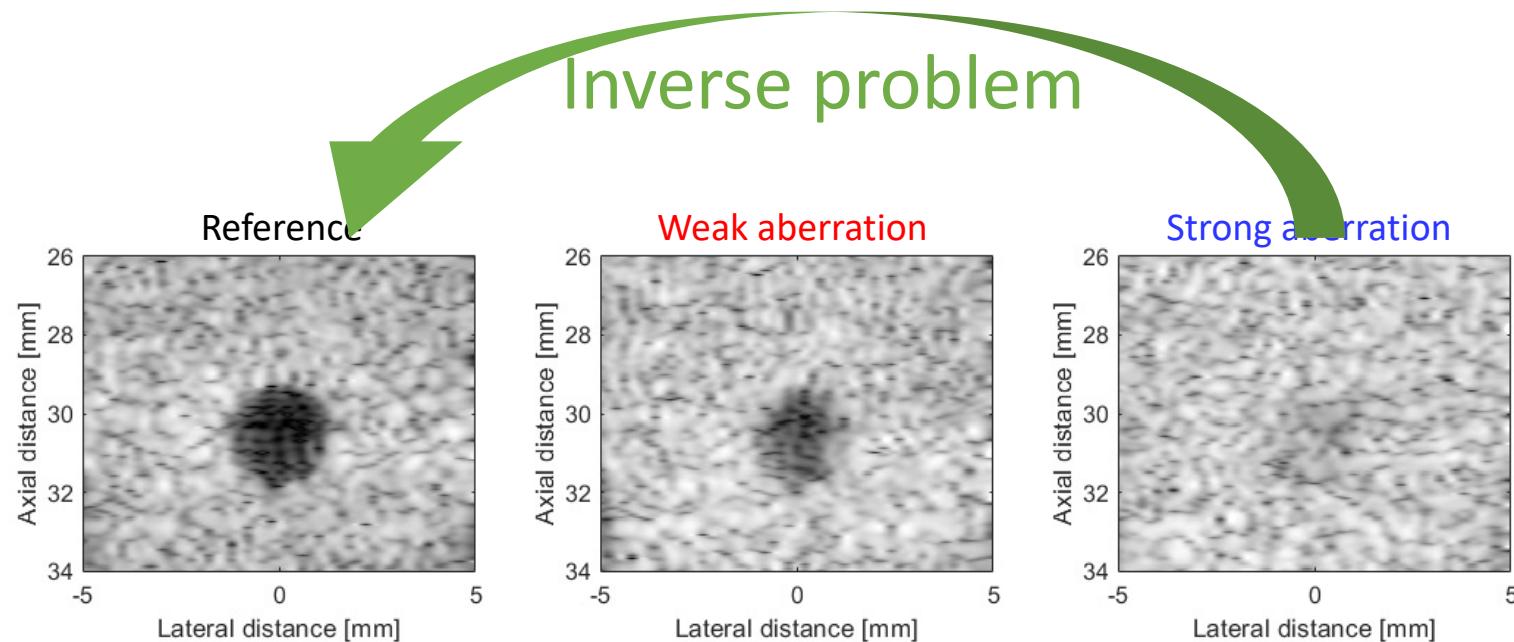
- Apply an aberrator profile to the transducer's elements in both transmit and receive cases.



Sharifzadeh*, Benali, Rivaz, IEEE Access 2020



Phase aberration in transcranial US



- Transcranial imaging
- LIFU for modulating brain function
- HIFU for drug delivery/ablation

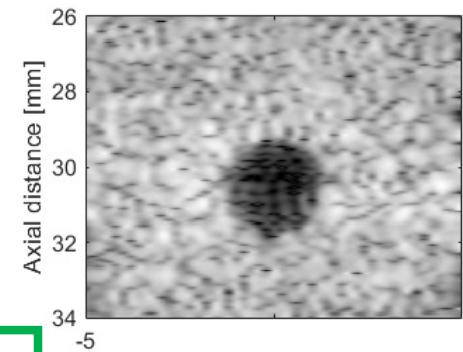
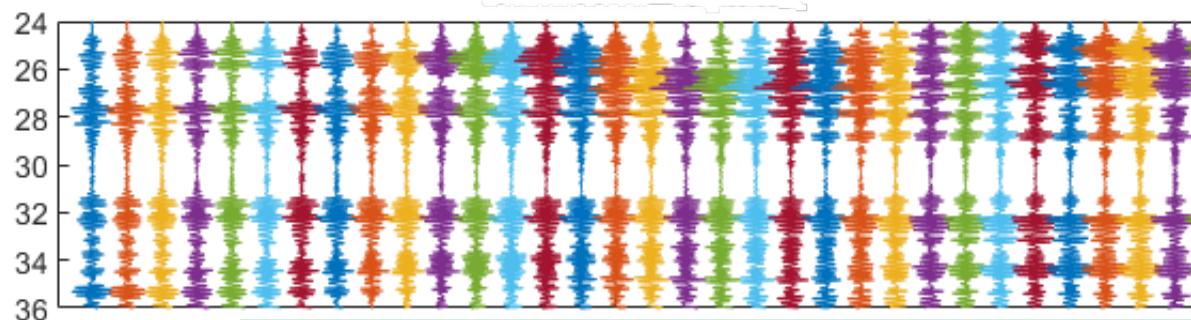
Sharifzadeh*, Benali, Rivaz, IEEE Access 2020

Making Sense of Data Trove in Ultrasound

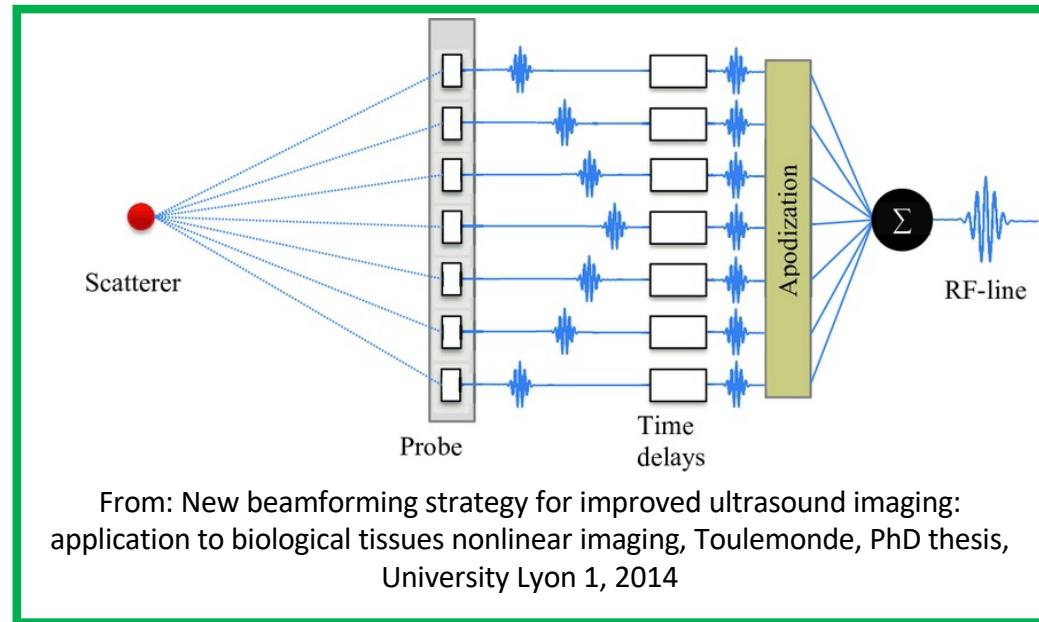
- Better use of raw radio-frequency (RF) data
 - Elastography
 - Quantitative ultrasound (qUS)
 - Faster US acquisition
 - Aberration correction in transcranial ultrasound
 - Deep beamforming

Deep Learning in Ultrasound Imaging

- B-mode US (the familiar gray-scale images) only contains a small percentage of all data



B-mode ultrasound
Visually informative





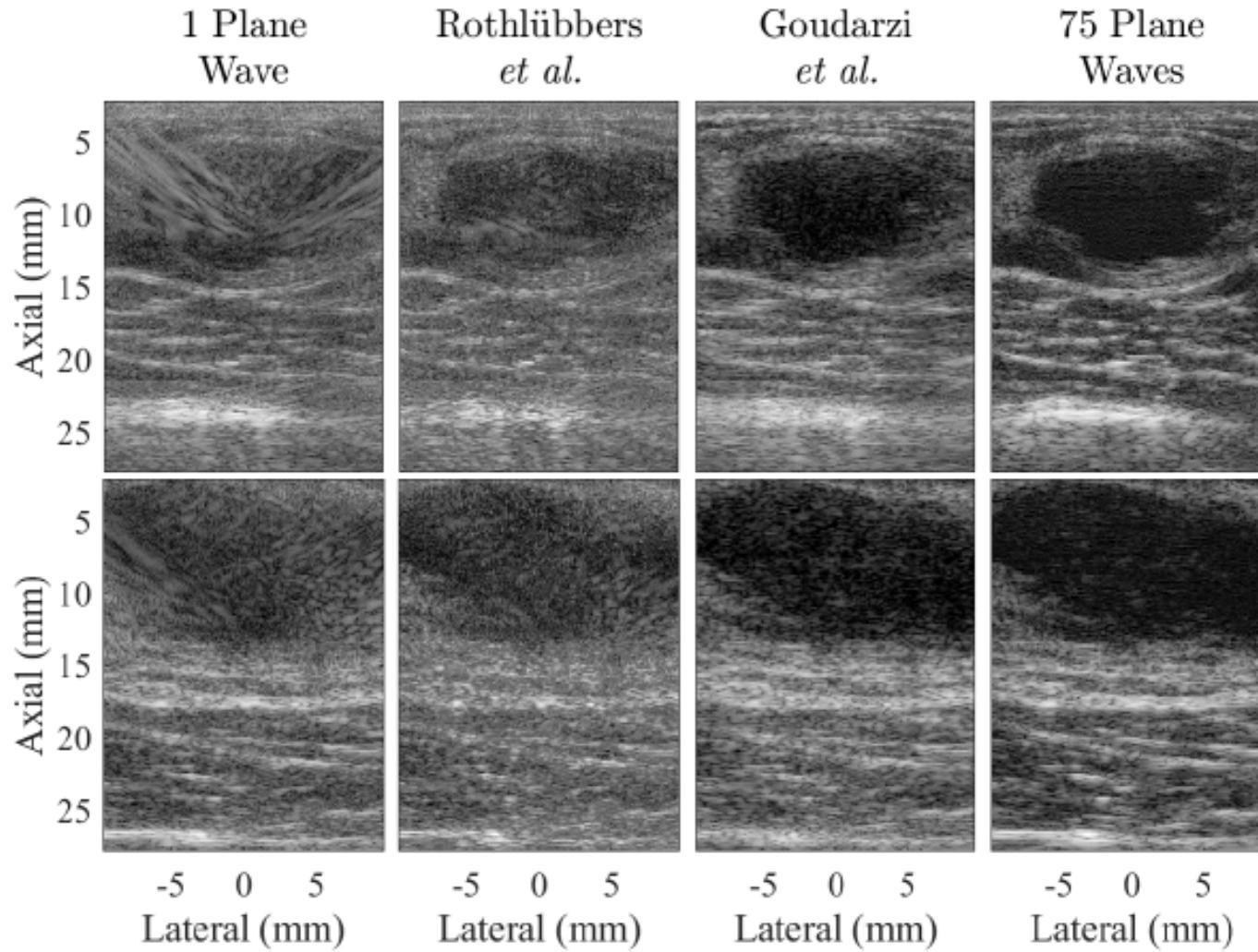
Challenges of deep beamforming

- Scarcity of training data
- Lack of ground truth in real data
- Domain shift between real and simulation data
- Apply Minimum Variance Beamforming (MVB) to real data
 - A set of closed-form mathematical steps
 - Train on each pixel separately, so lots of training data
 - Training directly on real data

S. Goudarzi*, A. Asif, and H. Rivaz, Ultrasound Beamforming using MobileNetV2, IEEE IUS, 2020
Ranked First (tied) in IEEE IUS Challenge on Ultrasound Beamforming with Deep Learning (CUBDL)



Results on Breast Ultrasound



Hyun, D, et al. "Deep Learning for Ultrasound Image Formation: CUBDL Evaluation Framework & Open Datasets." *IEEE Transactions on UFFC* (2021).

Clinical Applications

Breast Cancer Related Lymphedema

- Localized fluid retention and tissue swelling caused by a compromised lymphatic system
- Most frequently a complication of cancer treatment
- It's debilitating. Some patients refer to it as being worse than cancer
- Pitting test is commonly performed for staging
- Ultrasound cannot accurately stage it



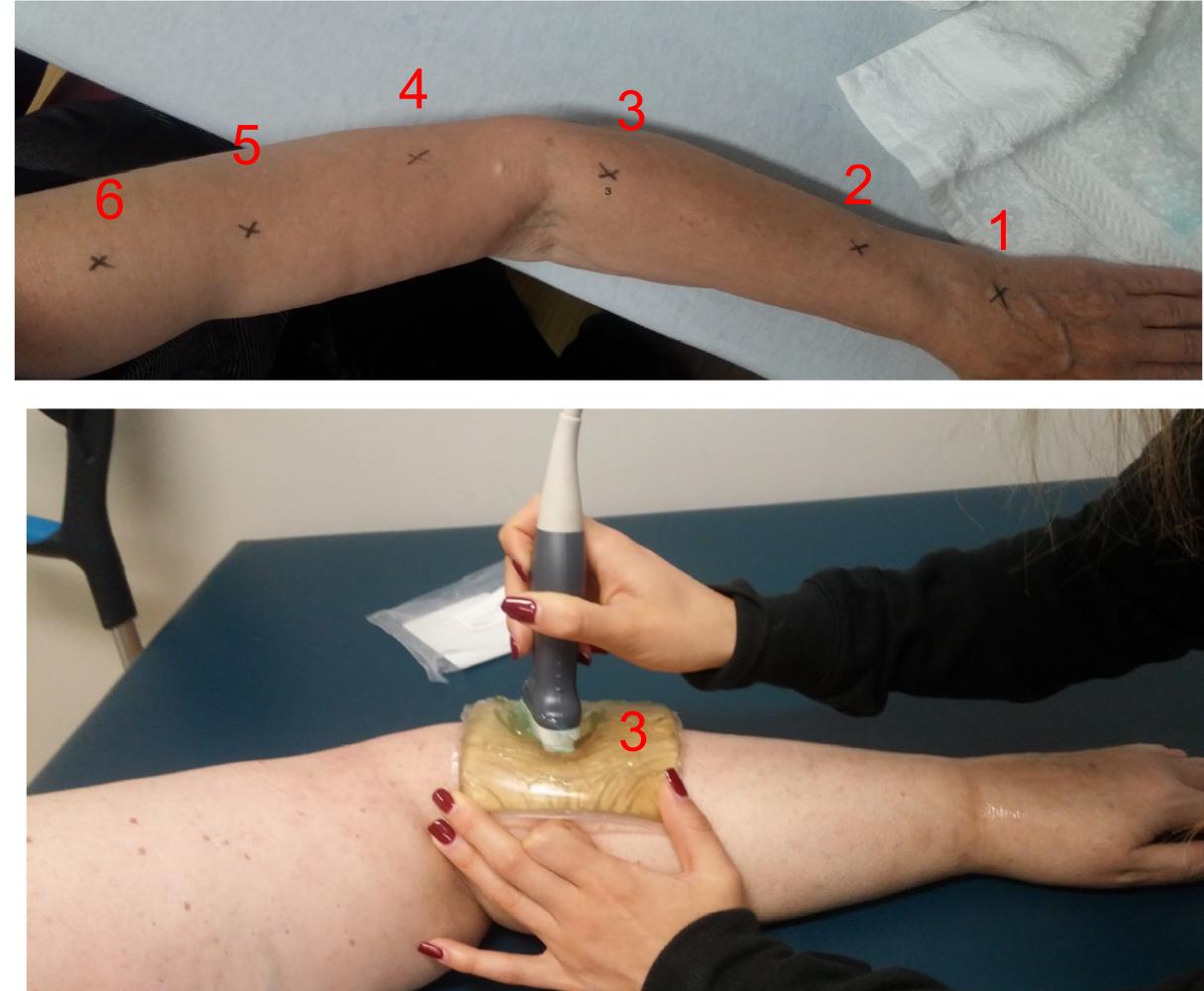


In collaboration with McGill University



Staging Lymphedema

- Significant difference in strain between affected and unaffected arms
- Deep models can help clinicians



Hashemi*, Fallone, Boily, Towers, Kilgour, Rivaz, IEEE Transactions UFFC, 2019

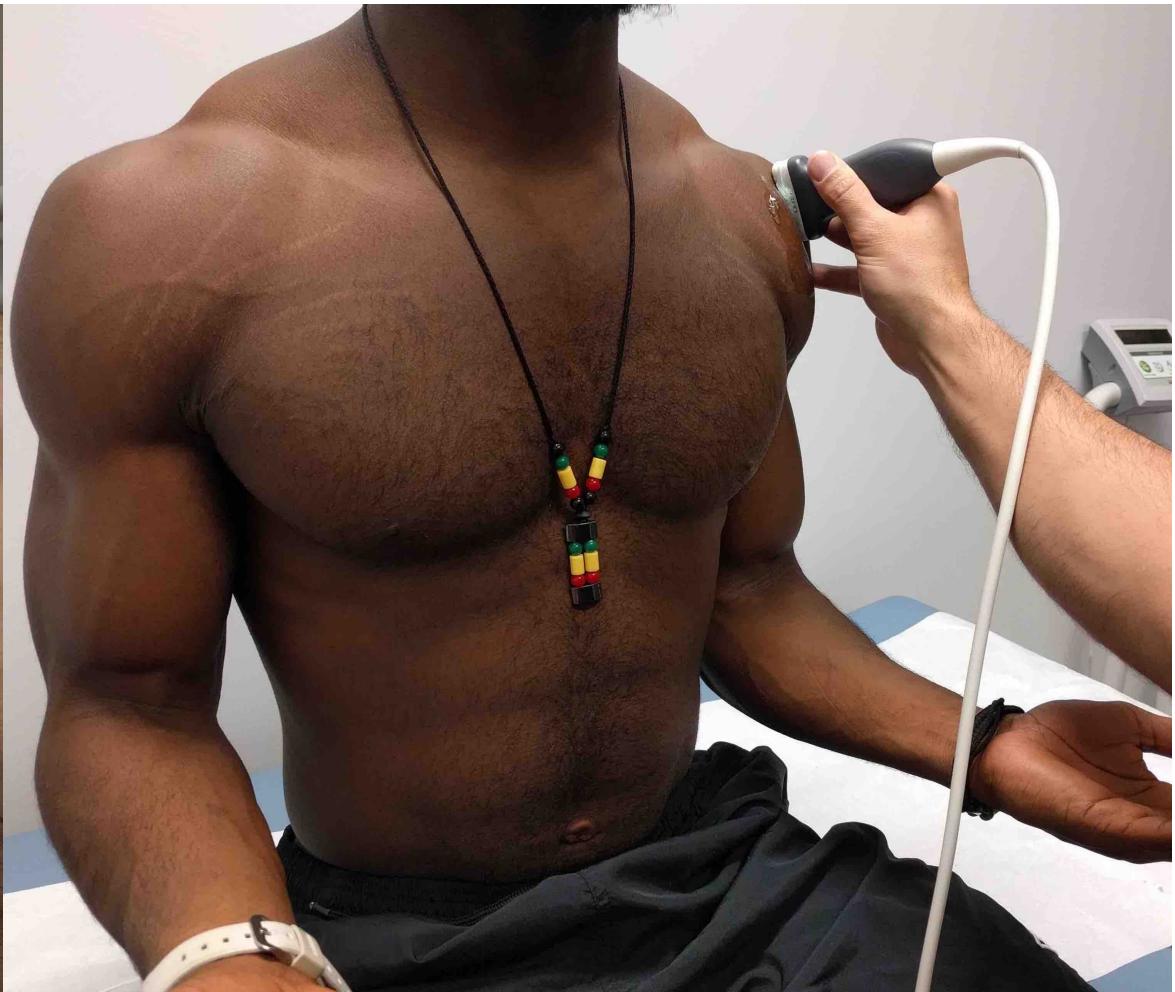
Goudarzi*, Whyte, Boily, Towers, Kilgour, Rivaz, IEEE Transactions BME, under review



In collaboration with McGill University Health Centre



Tendon and Ligament Elastography

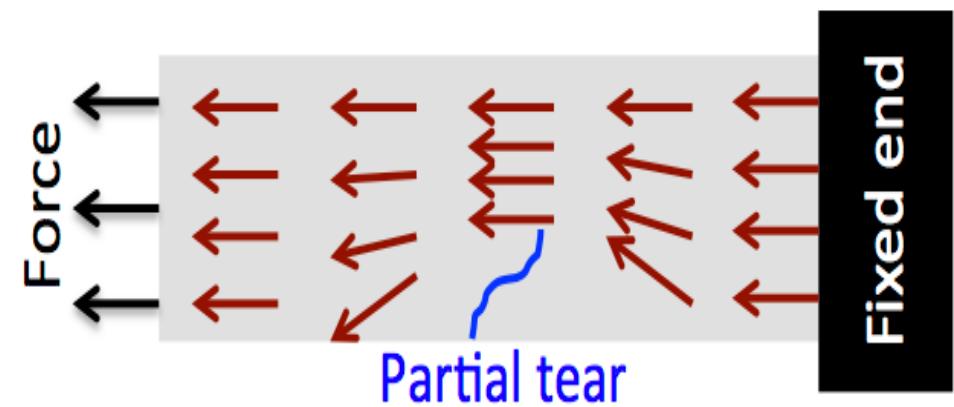
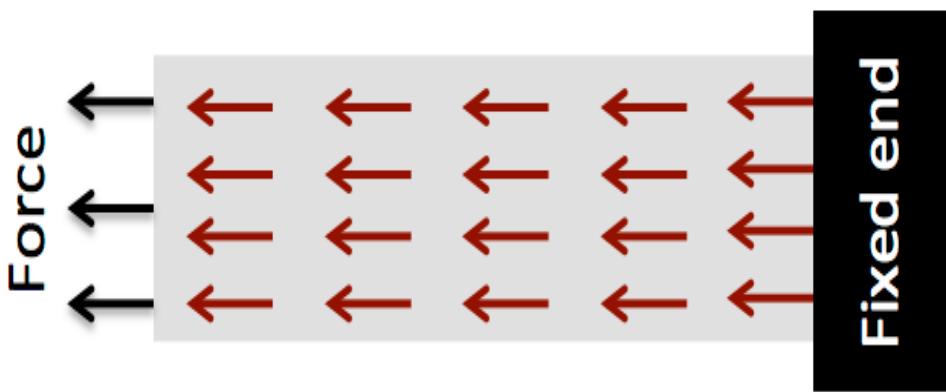


Hashemi*, Boily, Martineau, Rivaz, SPIE Med. Imag. 2017

Shams*, Boily, Martineau, Rivaz, SPIE Med. Imag. 2016, finalist for the Best Paper Award



Diagnosis with Deformation Pattern

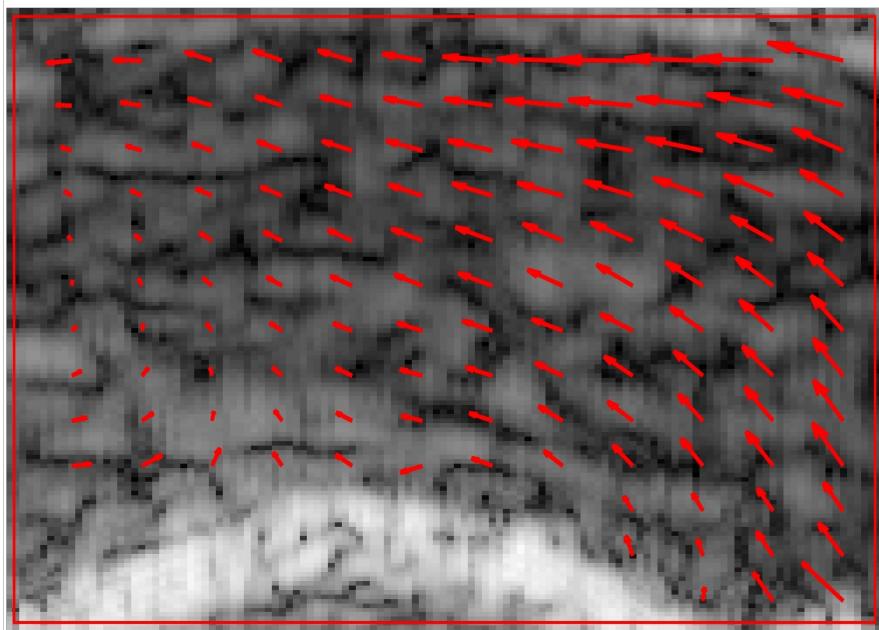
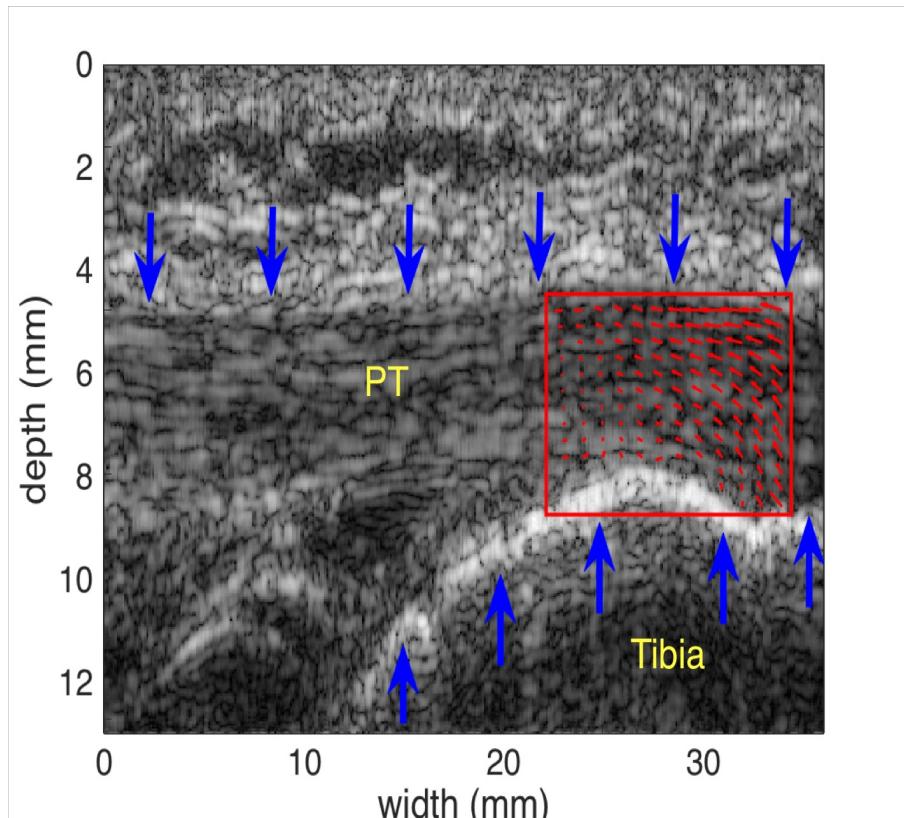


Hashemi*, Boily, Martineau, Rivaz, SPIE Med. Imag. 2017

Shams*, Boily, Martineau, Rivaz, SPIE Med. Imag. 2016, finalist for best paper award



Diagnosis with Deformation Pattern

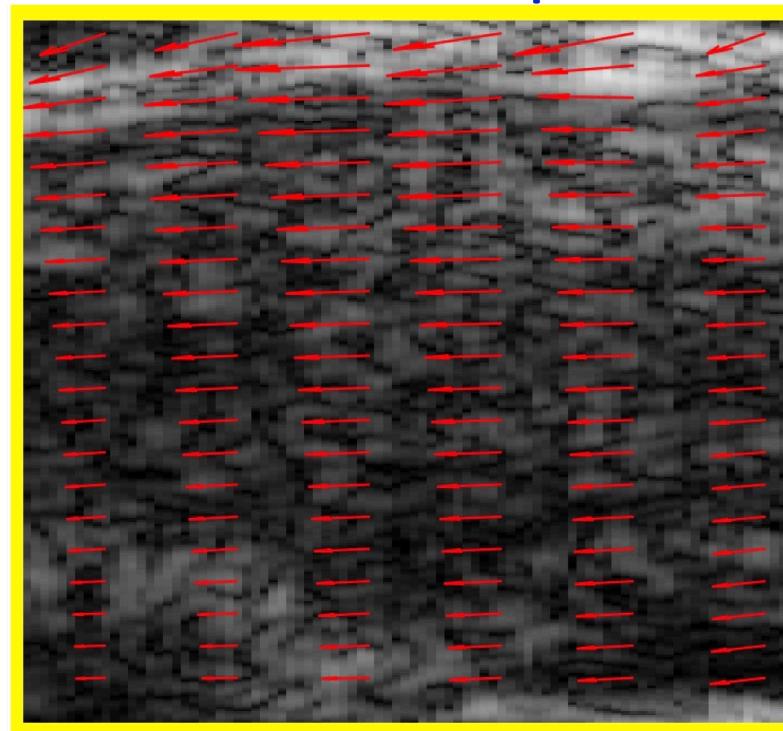
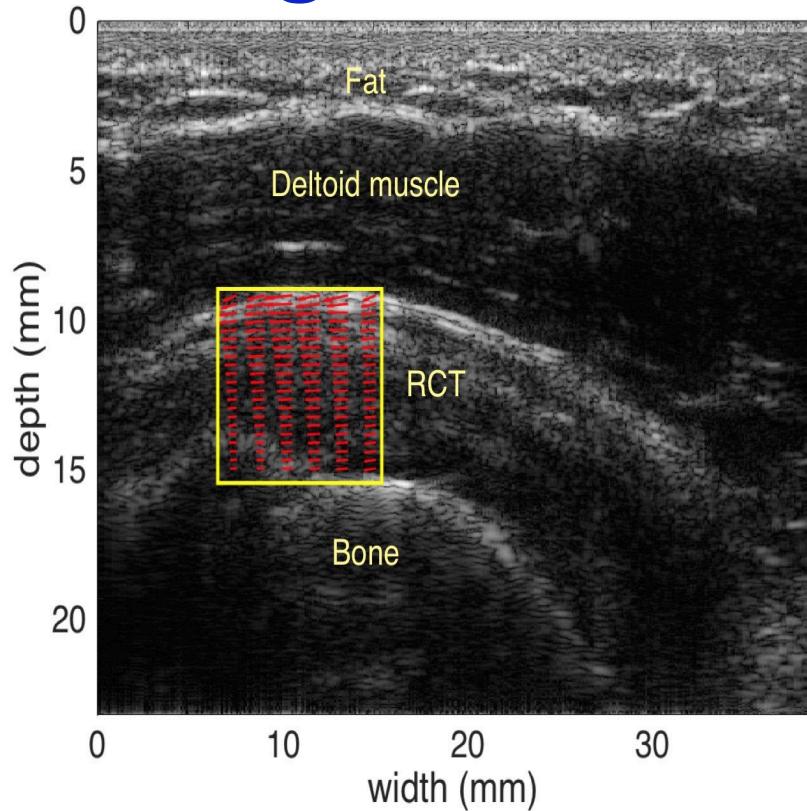


Hashemi*, Boily, Martineau, Rivaz, SPIE Med. Imag. 2017

Shams*, Boily, Martineau, Rivaz, SPIE Med. Imag. 2016, finalist for best paper award



Diagnosis with deformation pattern



Hashemi*, Boily, Martineau, Rivaz, SPIE Med. Imag. 2017

Shams*, Boily, Martineau, Rivaz, SPIE Med. Imag. 2016, finalist for best paper award

AI-Driven Ultrasound

- Better use of raw radio-frequency (RF) data
 - Elastography
 - Quantitative ultrasound (qUS)
 - Faster US acquisition
 - Aberration correction for transcranial imaging & focusing
 - Deep beamforming
- Aid collection & interpretation
 - Image Registration
 - US to MRI
 - US to US
 - Image segmentation
 - Explainable AI (XAI)
 - Image selection

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- B-mode ultrasound is hard to collect & interpret
 - **Image Registration**
 - US to MRI
 - US to US
 - Image segmentation
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 - Image selection

Brainshift

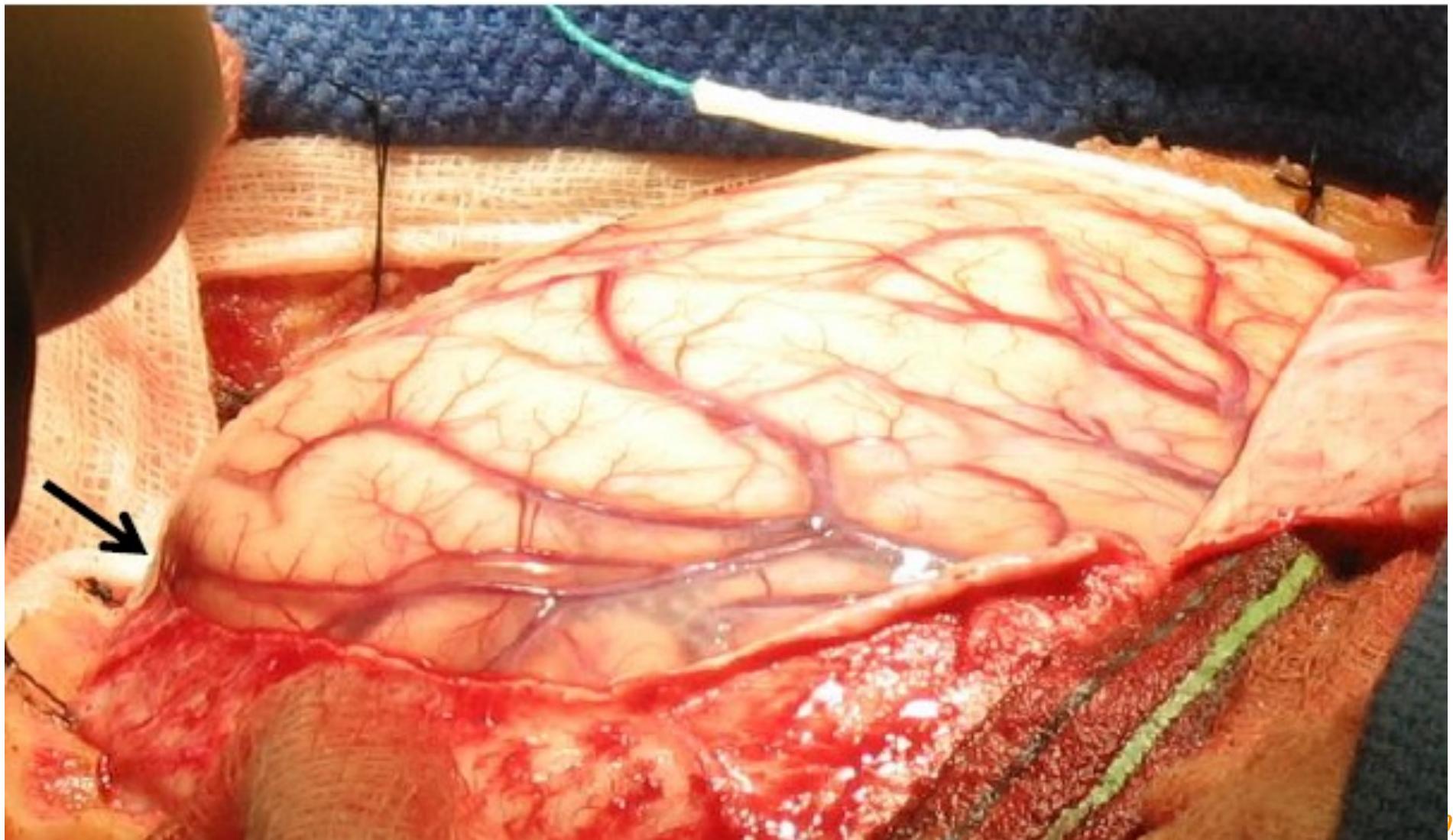
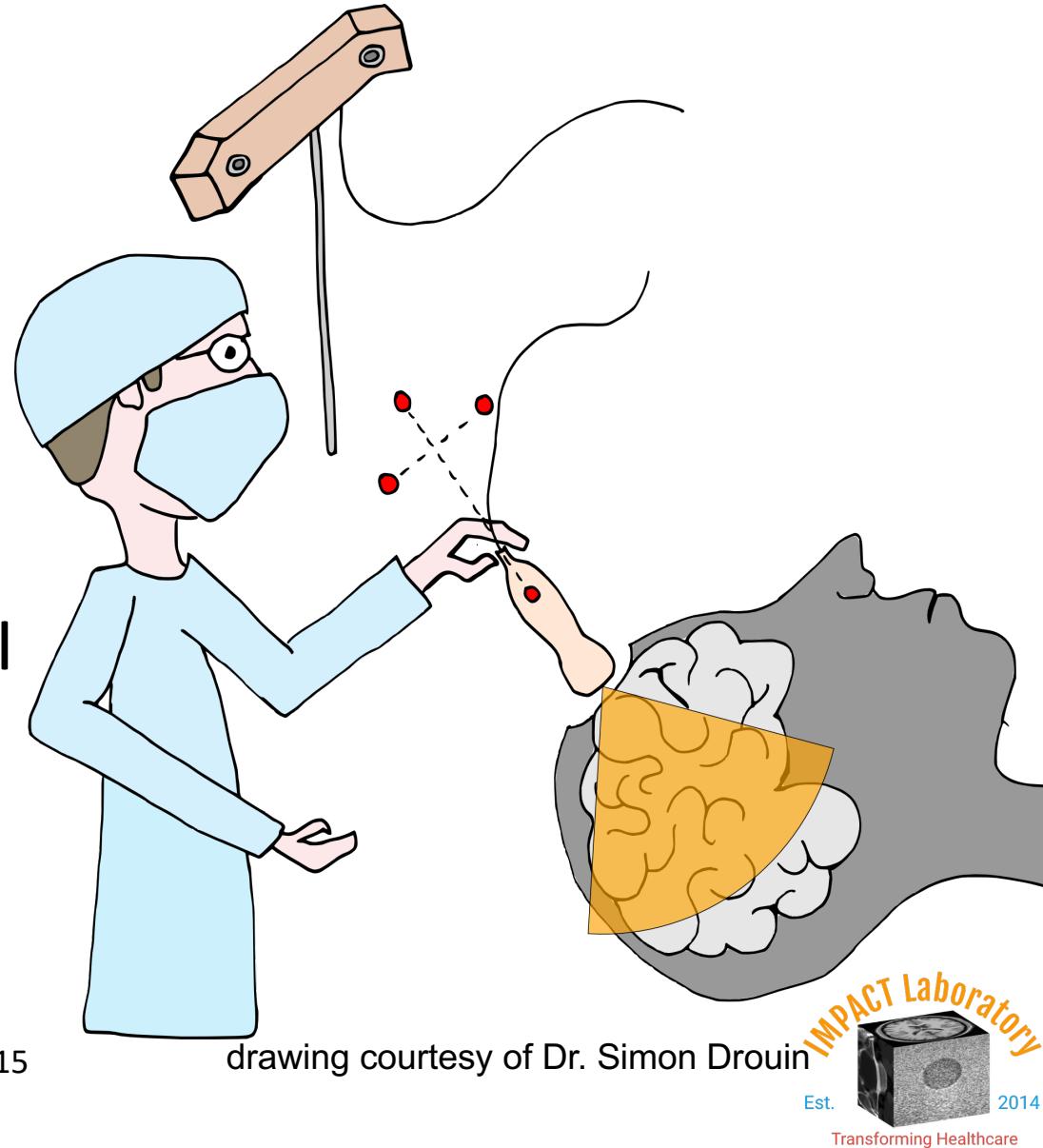


Photo courtesy of Sean Chen, MNI

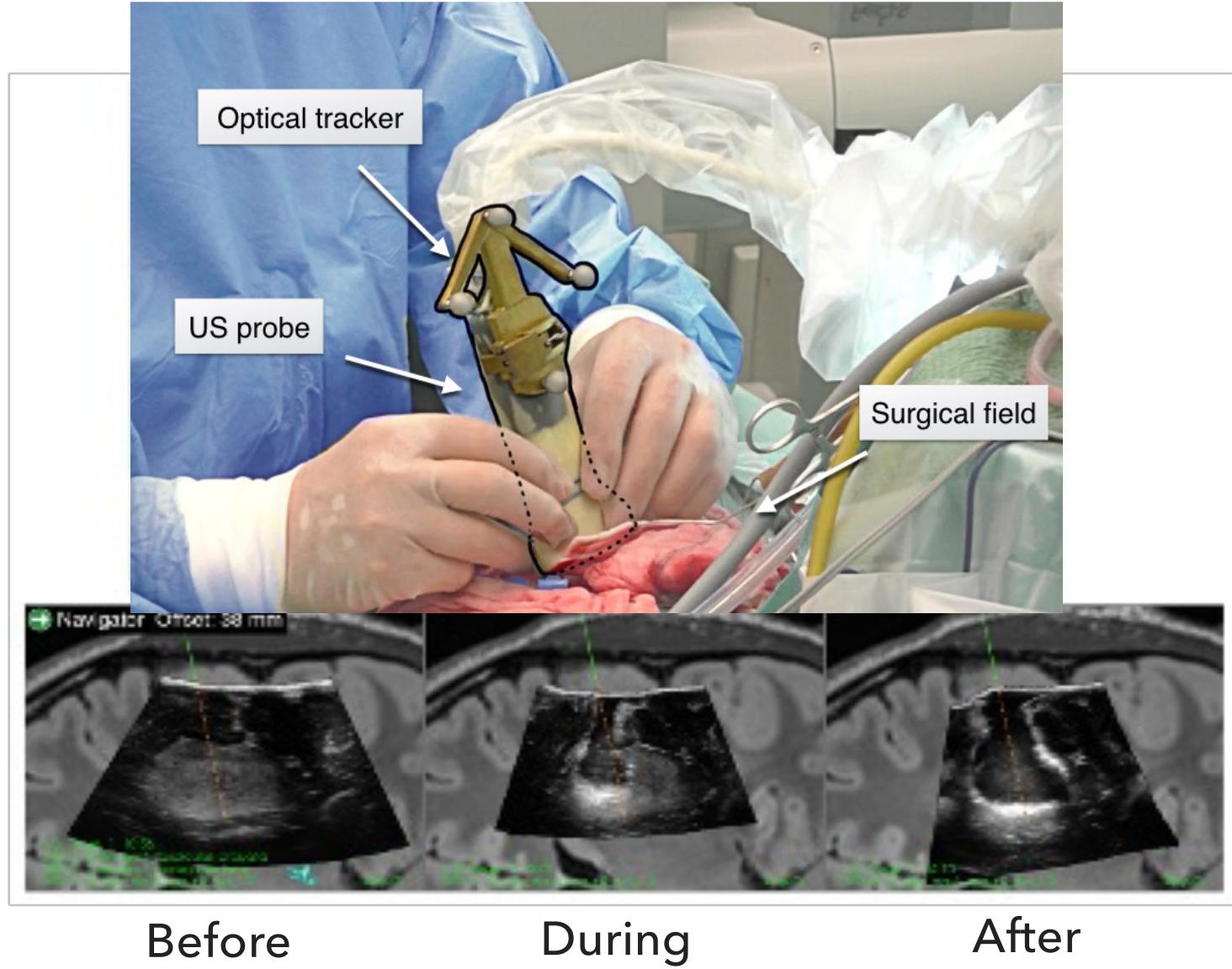
Image-Guided Neurosurgery

- Due to the brainshift, tracked US is used in the OR
- US images are hard to interpret and are noisy
- Pre-op MRI is available
- Deform the pre-op MRI to match intra-op US

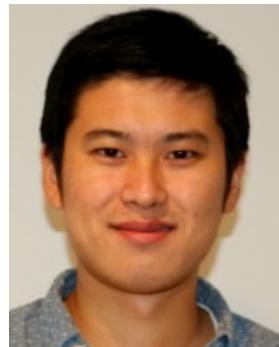




Not Just at the Beginning of Operation



Y. Xiao, M. Fortin, G. Unsgard, H. Rivaz, I. Reinertsen, Med Phys 2017



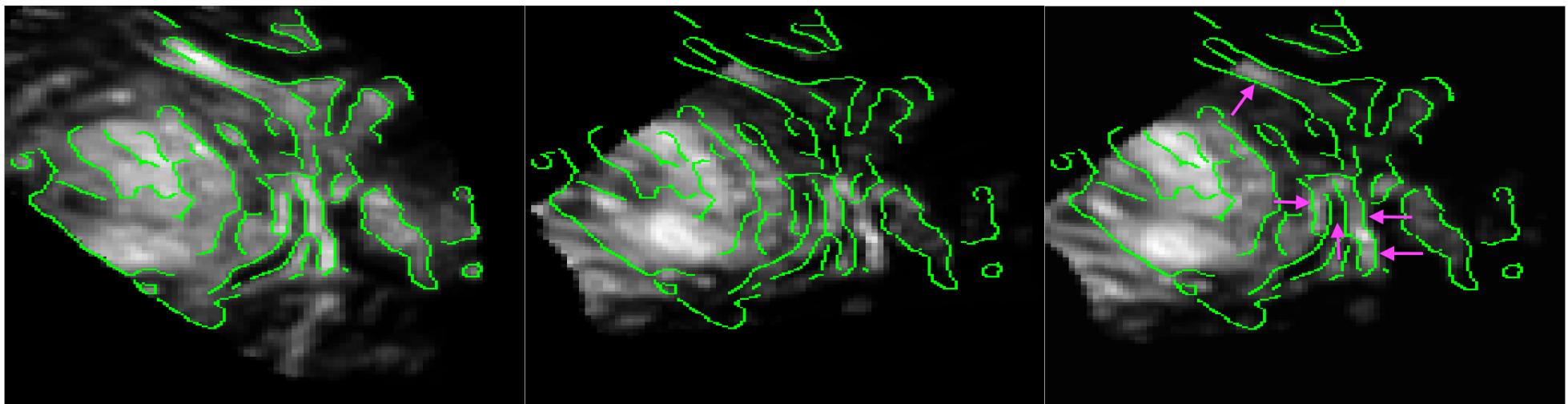
Registration of Pre- and Post-Resection US

- The quality of post-resection US image is poor due to the resection cavity
- Registration of pre- and post-resection US images is challenging due to missing tissue

pre-resection

post-resection, initial alignment

post-resection, after registration



Zhou* & Rivaz, IEEE Journal Biomedical Health Informatics (JBHI), 2016. selected for submission of full paper to JBHI, **only 10 selections out of 2948 submissions to IEEE EMBC**

Finding the Residual Tumor



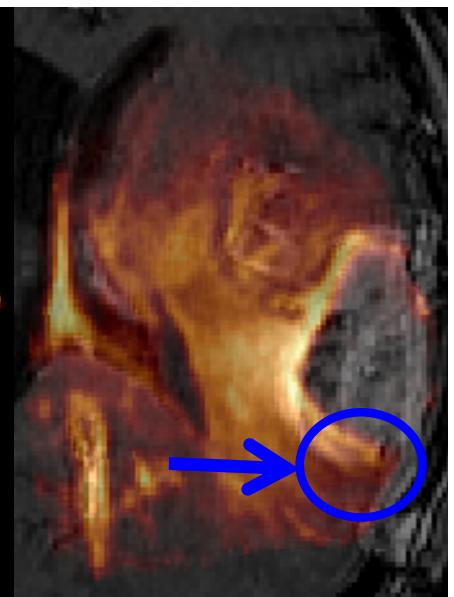
US and rendered MR



Pre-operative MR



Post-resection US
(tumour is resected)



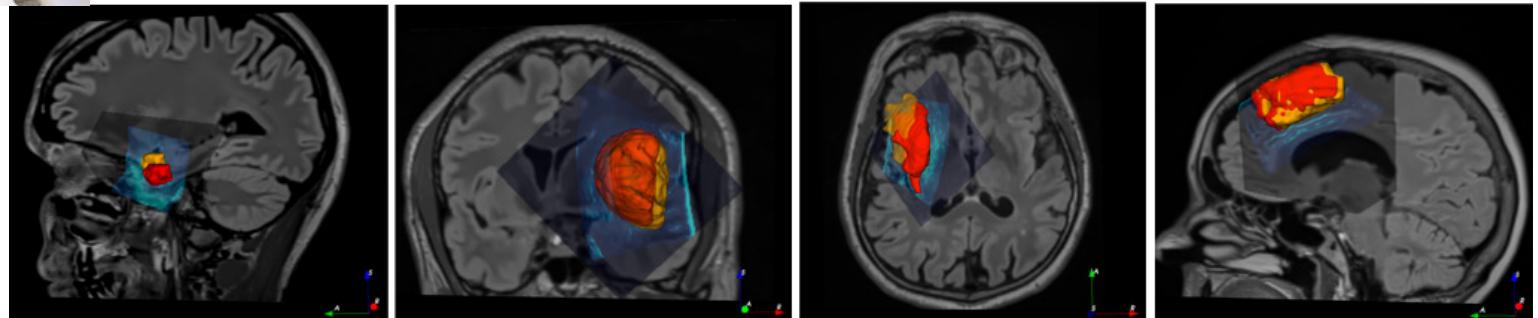
Residual tumour

Rivaz, H, Chen, S, Collins, DL, IEEE Trans. Med. Imag. 2015

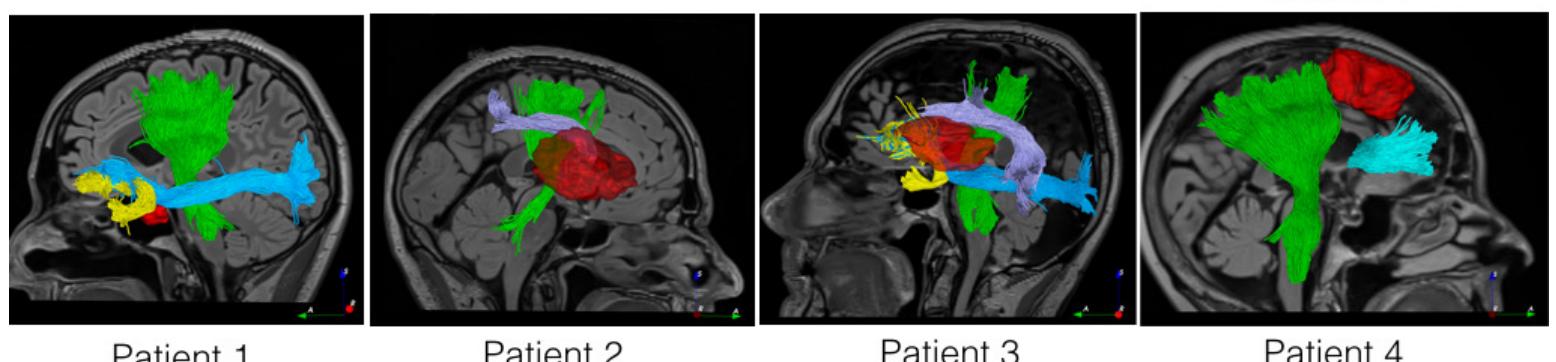


Brainshift in Tractography

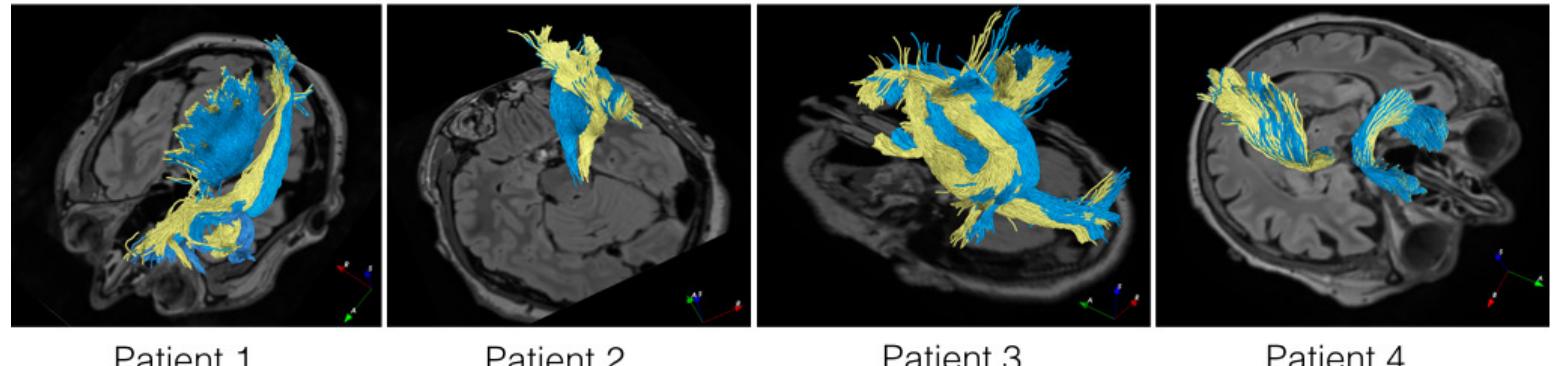
cortico-spinal tract



uncinate fasciculus



superior
longitudinal fasciculus



inferior
fronto-occipital tract

CC-genu

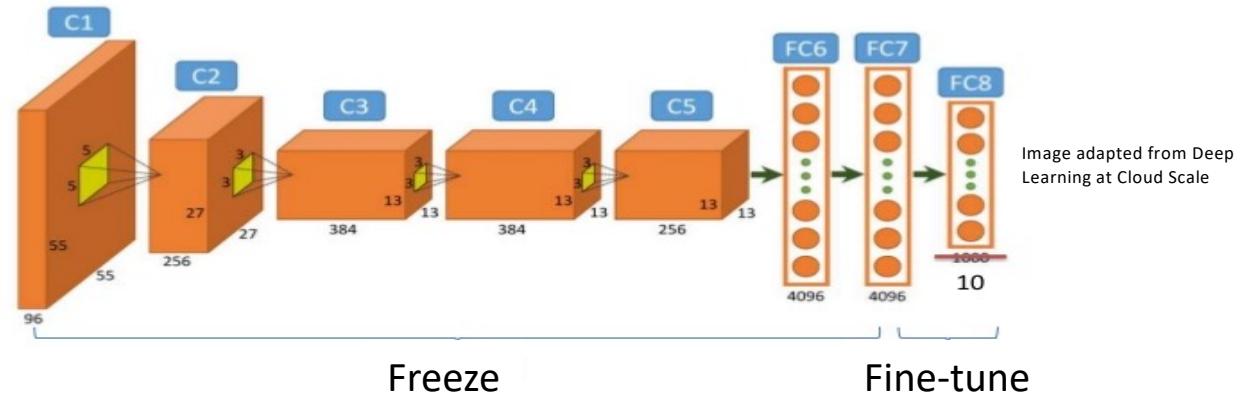
Xiao*, Eikenes, Reinertsen, Rivaz, IJCARS 2018

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Transfer learning in ultrasound

- Why: Low number of images available
- Shallow layers: Low-level features (usually common between different classes)
- Deep layers: High-level features (usually different in each class)

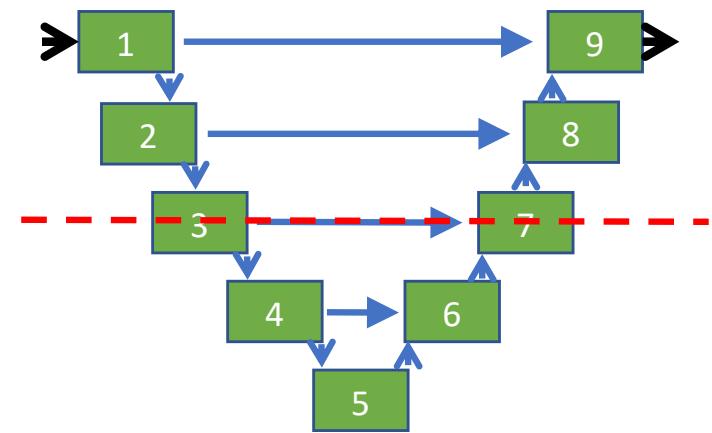


- Speckle pattern/textture is important in ultrasound

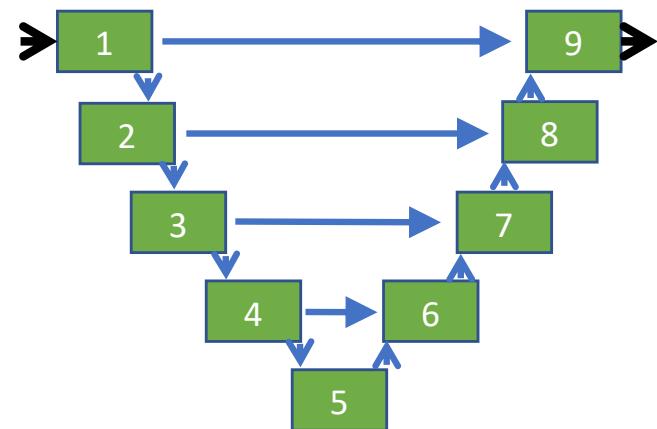


Transfer learning in ultrasound

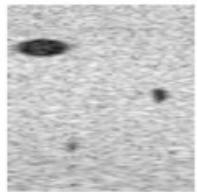
- Because of skip connections, the notion of shallow深深 is not well-defined
- **Findings:**
- Shallow layers are important!
- Fine-tuning only the last layers is not a good practice in ultrasound image segmentation using U-Net



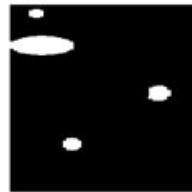
M. Amiri*, R. Brooks, H. Rivaz, IEEE Transactions UFFC, Special Issue on Deep Learning, 2020



B-Mode



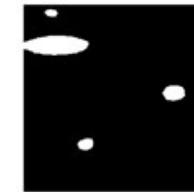
GT



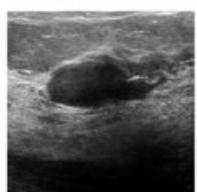
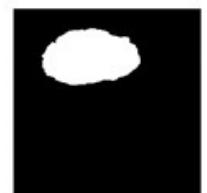
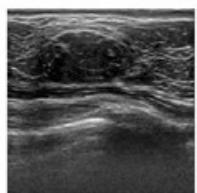
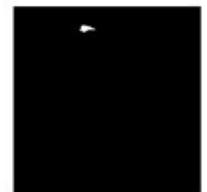
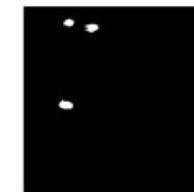
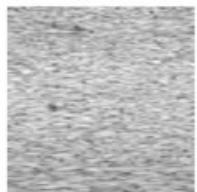
Pre-trained



All except block 5



Block 5

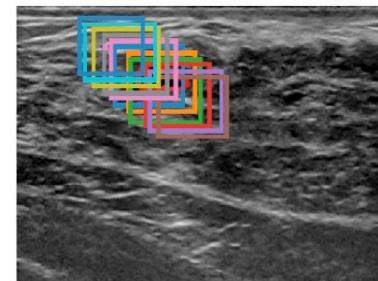




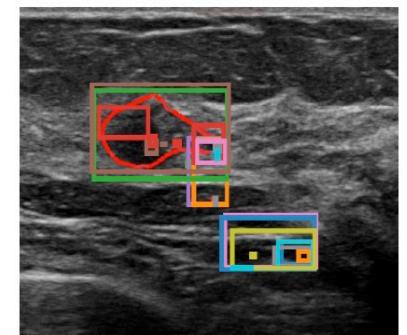
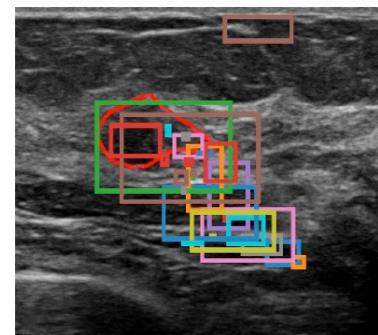
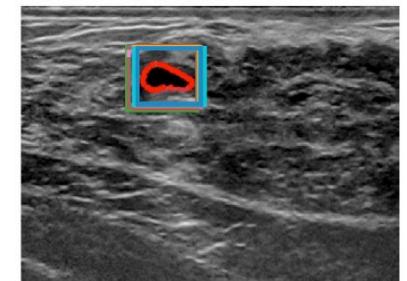
Test-time augmentation

- Shifting
- Dropout uncertainty
(dropout ON at test time)
- Valid detection is
insensitivity to shift and
dropout

Detected regions



Shifted back regions

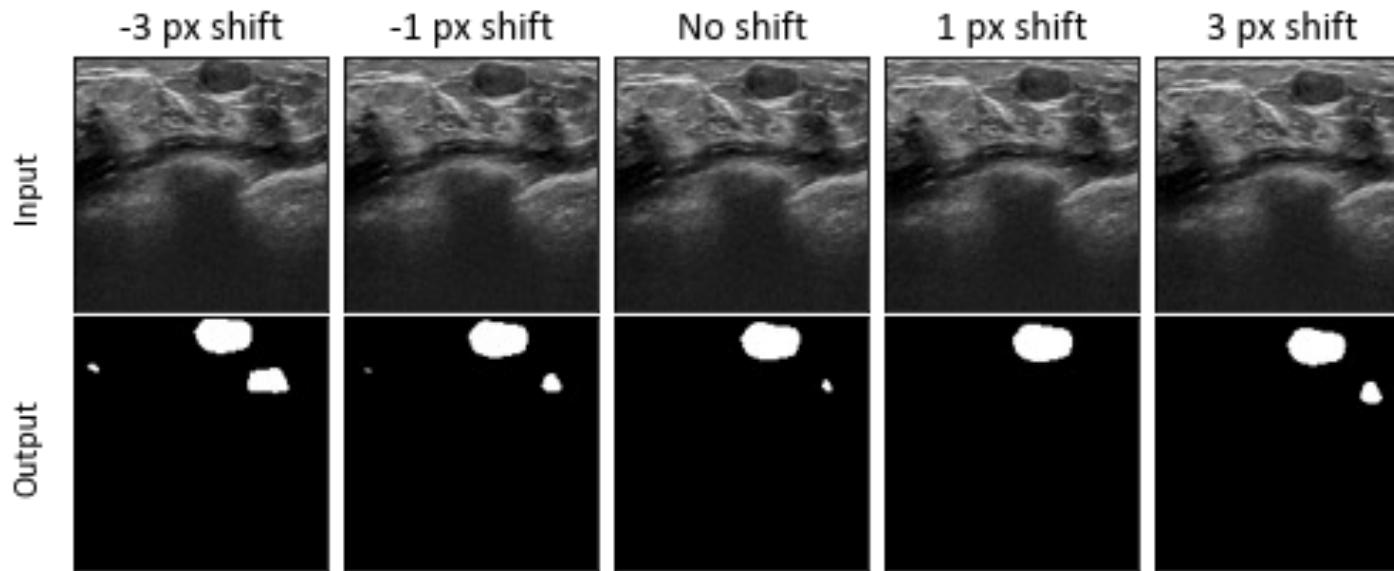


M. Amiri*, R. Brooks, B. Behboodi*, H. Rivaz, Springer IJCARS, 2020

The Shift-Variance Problem

Convolutional neural networks (CNNs) have attracted growing interest in automatic ultrasound image segmentation recently.

However, most modern CNNs are not shift-equivariant.



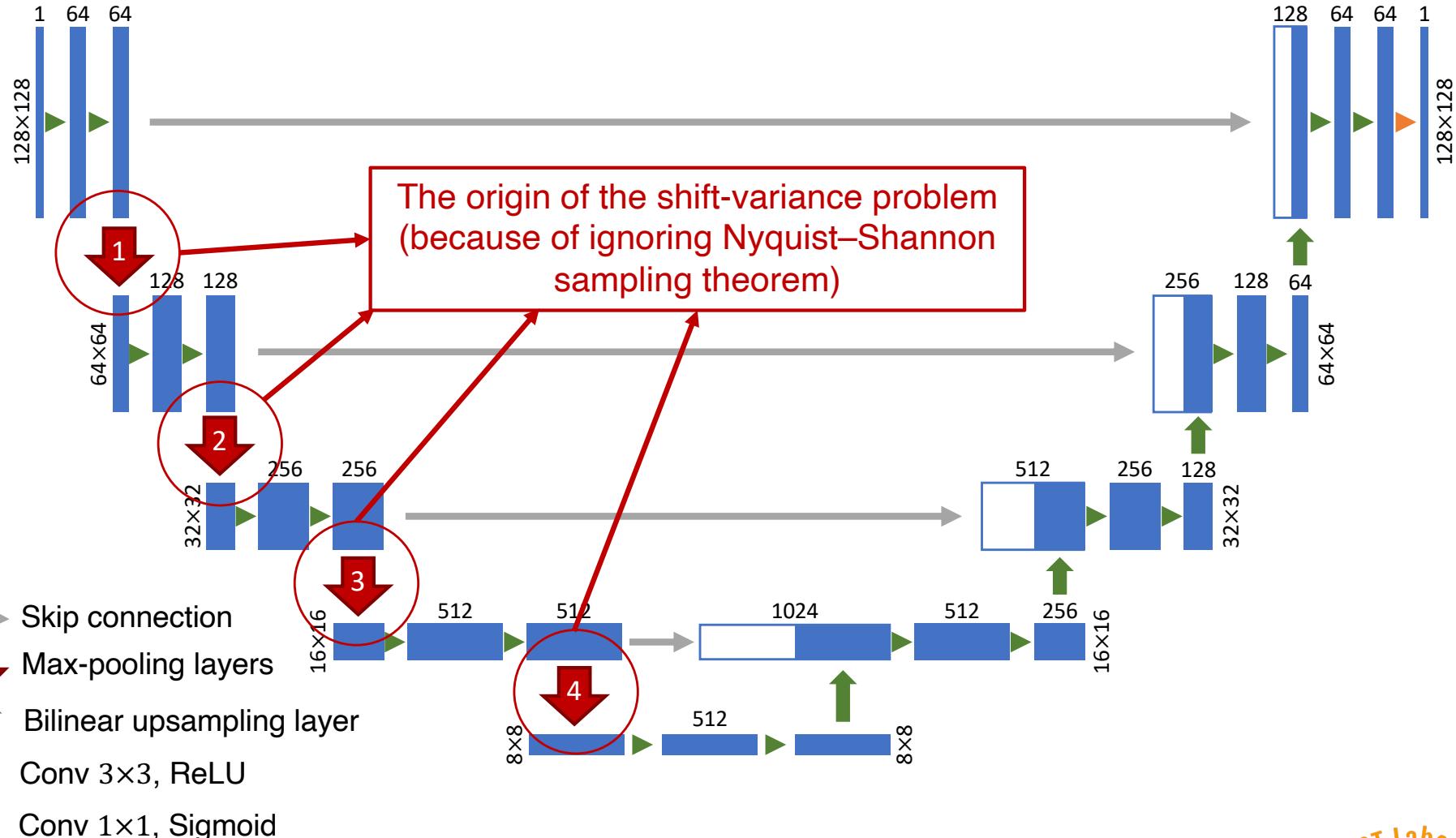
The Shift-Variance Problem

Output consistency is crucial in applications such as monitoring the patients' response to treatment, measuring the progression or regression of the disease, reaching a diagnosis, or treatment planning.

The main focus has primarily been on improving segmentation accuracy metrics.

The output robustness against input translations should not be overlooked, especially in medical applications.

U-Net as the Baseline



Methods

Baseline:

To investigate the shift-variance problem in this application for the first time.



Max-pool (kernel = 2×2 , stride = 2)

BlurPooling¹ $m \times m$:

To evaluate the performance of a recently published method in this application. It integrates anti-aliasing filters to mitigate the shift-variance problem.



Max-BlurPool (blur kernel = $m \times m$)

Pyramidal BlurPooling (PBP):

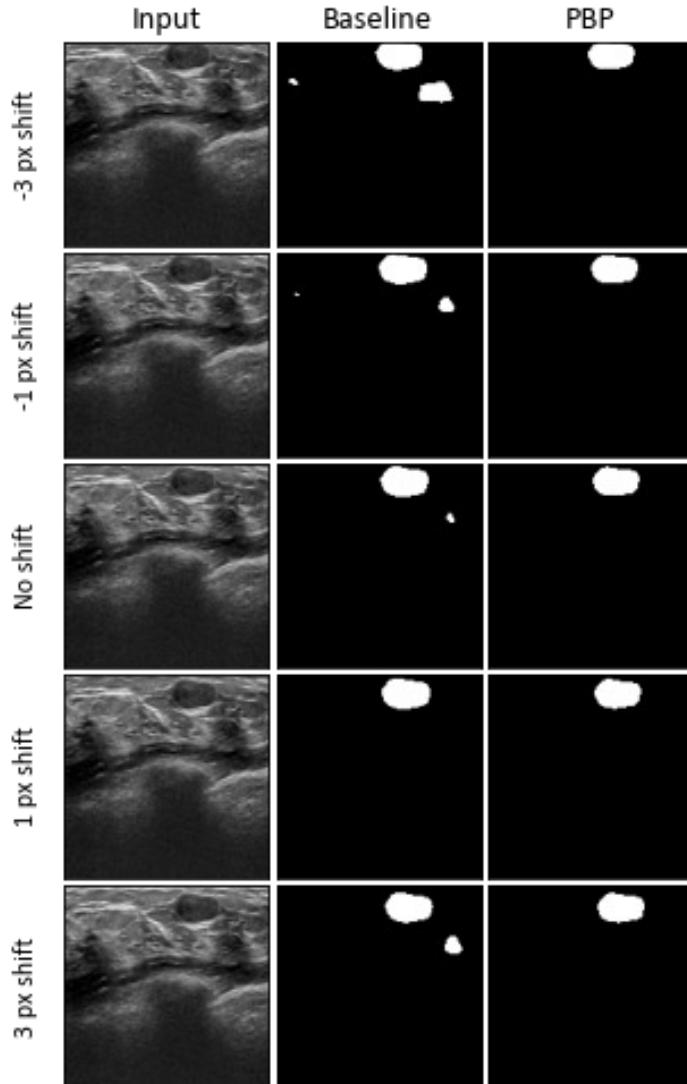
The proposed method.



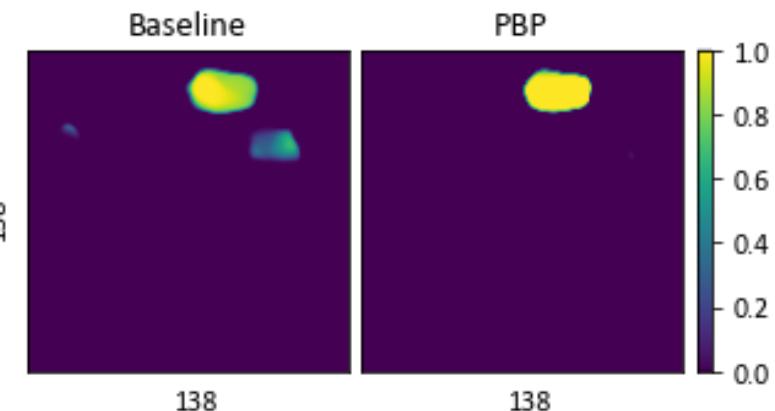
12
1

¹R. Zhang, "Making convolutional networks shift-invariant again," 2019

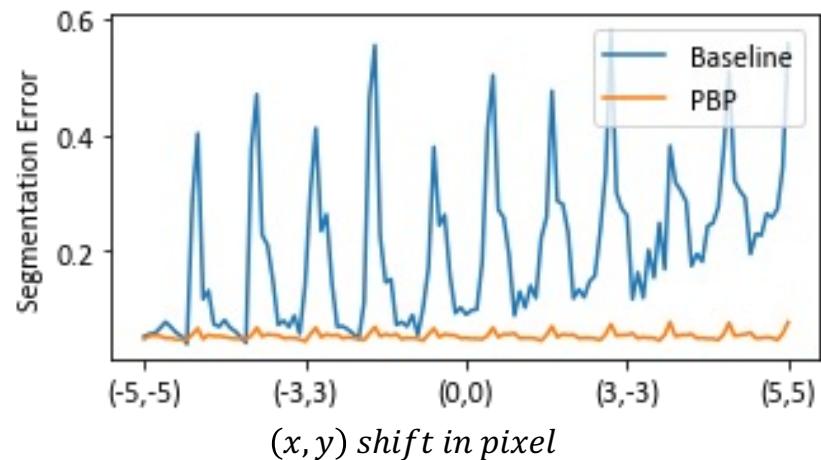
Results



Averaged outputs over 121 input translations (x, y) ,
where $\{x, y \in N \mid -5 \leq x, y \leq 5\}$

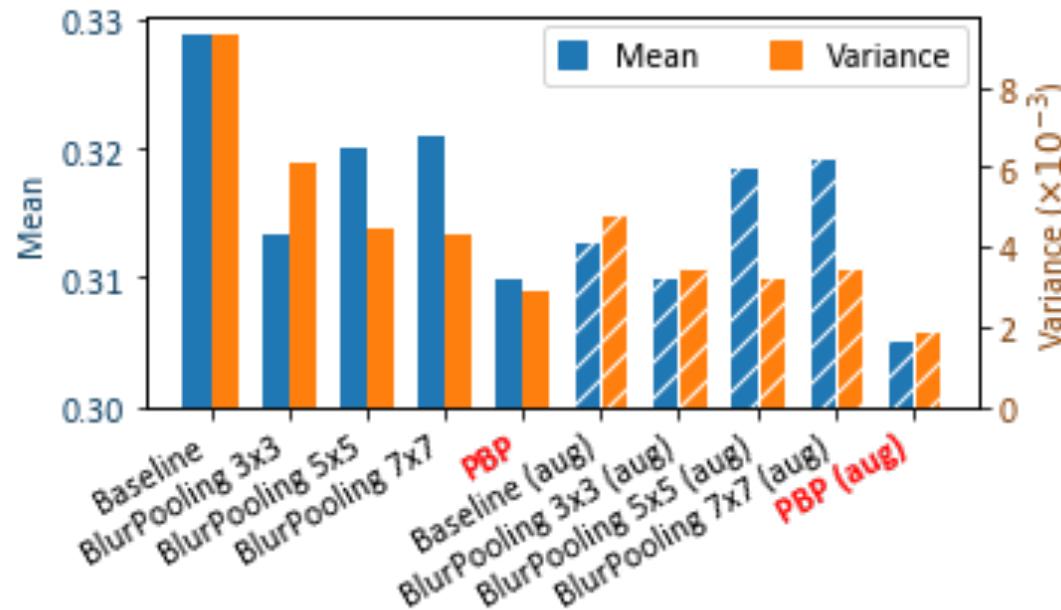


Segmentation Error:
 $(1 - \text{Dice similarity coefficient})$



Results

Lower error mean: Higher segmentation accuracy
Lower error variance: Higher output consistency
(aug): Repeated with data augmentation



More details and experiments on additional datasets:
“Investigating Shift-Variance of Convolutional Neural Networks in Ultrasound Image Segmentation”
IEEE TUFFC 2022

Source Code:
<https://git.io/pbpunet>

Bright future for AI and ultrasound



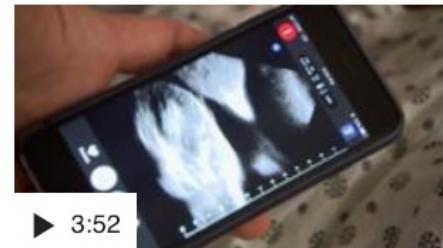
Trump nominee: 'I will not be bullied'

William Barr was also quizzed on why he last year called an aspect of the inquiry "fatally misconceived".



YouTube bans dangerous or harmful pranks

The move comes in response to so-called "challenges" that sometimes resulted in death or injury.



The ultrasound scan you can do yourself

A US company has produced an ultrasound scanner that plugs into an iPhone and costs \$2,000 (£1,555).



Germany steps up monitoring of far right

The move will not yet amount to full-scale surveillance of the nation's main opposition party.

⌚ 9h | US & Canada

⌚ 1h | Technology

⌚ 3h | Business

⌚ 11h | Europe



IMPACT lab:

IMage Processing And
Characterization of Tissue



Richard and Edith
Strauss Foundation



Collaborators

H. Benali, C. Gauthier, M. Fortin, Y. Xiao, M. Kersten R. Kilgour (Concordia)

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R. Brooks (Nuance, Microsoft)

P. Brisson, S. Rottoo, M Mirzaei (THINK Surgical)

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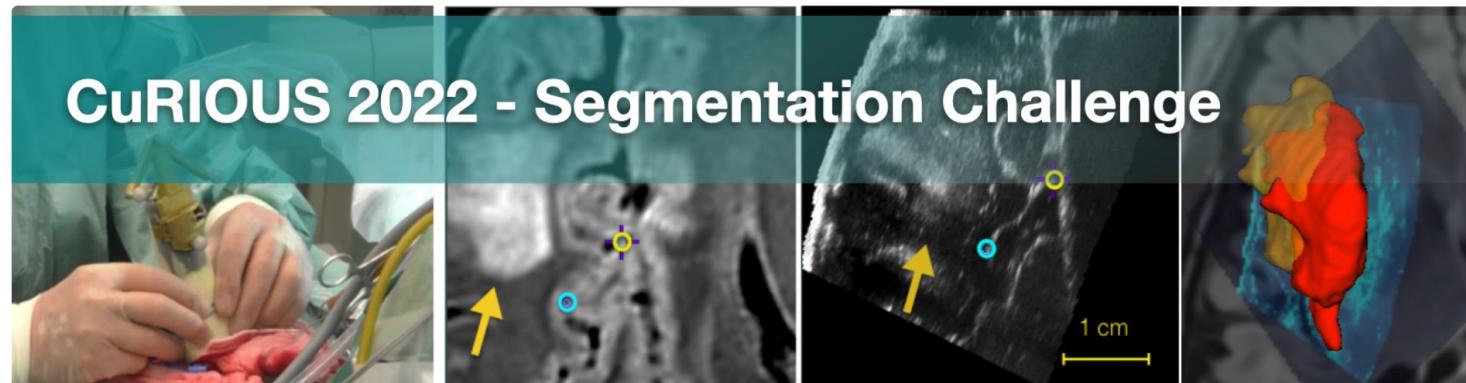
E. Boctor, M. Choti, G. Hager (Johns Hopkins)

Brain tumor segmentation in ultrasound, MICCAI 2022 Challenge

Grand Challenge Challenges Algorithms ...

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Challenges / Brain shift with Intraoperative Ultrasound - Segmentation tasks / Curious2022



i Info

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Motivation

Early brain tumor resection can effectively improve the patient's survival rate. However, resection quality and safety can often be heavily affected by intra-operative brain tissue shift due to factors, such as gravity, drug administration, intracranial pressure change, and tissue removal. Such tissue shift can displace the surgical target and vital structures (e.g., blood vessels) shown in pre-operative images while these displacements may not be directly visible in the surgeon's field of view.

<https://curious2022.grand-challenge.org/>

Thanks!

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