/usr/bin/c++ -fPIC -std=c++11 -shared -Wl,-soname,libroboticsgroup\_gazebo\_disable\_link\_plugin\_new.so -o /home/adi/Downloads/GazeboSimulation/devel/lib/libroboticsgroup\_gazebo\_disable\_link\_plugin\_new.so CMakeFiles/roboticsgroup\_gazebo\_disable\_link\_plugin\_new.dir/src/disable\_link\_plugin.cpp.o -L/usr/lib/x86\_64-linux-gnu/gazebo-9/plugins -Wl,-rpath,/usr/lib/x86\_64-linux-gnu/gazebo-9/plugins:/home/adi/Downloads/GazeboSimulation/devel/lib:/opt/ros/melodic/lib: /home/adi/Downloads/GazeboSimulation/devel/lib/libgazebo\_ros\_new\_api\_plugin.so /home/adi/Downloads/GazeboSimulation/devel/lib/libgazebo\_ros\_new\_paths\_plugin.so /opt/ros/melodic/lib/libroslib.so /opt/ros/melodic/lib/librospack.so -lpython2.7 -lboost\_program\_options -ltinyxml2 /opt/ros/melodic/lib/libtf.so /opt/ros/melodic/lib/libtf2\_ros.so /opt/ros/melodic/lib/libactionlib.so /opt/ros/melodic/lib/libmessage\_filters.so /opt/ros/melodic/lib/libtf2.so /opt/ros/melodic/lib/libcontrol\_toolbox.so -ltinyxml /opt/ros/melodic/lib/libdynamic\_reconfigure\_config\_init\_mutex.so /opt/ros/melodic/lib/librealtime\_tools.so /opt/ros/melodic/lib/libroscpp.so -lboost\_filesystem /opt/ros/melodic/lib/librosconsole.so /opt/ros/melodic/lib/librosconsole\_log4cxx.so /opt/ros/melodic/lib/librosconsole\_backend\_interface.so -llog4cxx -lboost\_regex /opt/ros/melodic/lib/libxmlrpcpp.so /opt/ros/melodic/lib/libroscpp\_serialization.so /opt/ros/melodic/lib/librostime.so /opt/ros/melodic/lib/libcpp\_common.so -lboost\_system -lboost\_thread -lboost\_chrono -lboost\_date\_time -lboost\_atomic -lpthread /usr/lib/x86\_64-linux-gnu/libconsole\_bridge.so.0.4 -lBulletSoftBody -lBulletDynamics -lBulletCollision -lLinearMath -lSimTKsimbody -lSimTKmath -lSimTKcommon -lblas -llapack -lblas -lpthread -lrt -ldl -lm -lgazebo -lgazebo\_client -lgazebo\_gui -lgazebo\_sensors -lgazebo\_rendering -lgazebo\_physics -lgazebo\_ode -lgazebo\_transport -lgazebo\_msgs -lgazebo\_util -lgazebo\_common -lgazebo\_gimpact -lgazebo\_opcode -lgazebo\_opende\_ou -lboost\_thread -lboost\_signals -lboost\_system -lboost\_filesystem -lboost\_program\_options -lboost\_regex -lboost\_iostreams -lboost\_date\_time -lboost\_chrono -lboost\_atomic -lpthread -lprotobuf -lpthread -lsdformat -lOgreMain -lboost\_thread -lboost\_date\_time -lboost\_system -lboost\_atomic -lboost\_chrono -lboost\_chrono -lpthread -lOgreTerrain -lOgrePaging /usr/lib/x86\_64-linux-gnu/libignition-transport4.so.4.0.0 /usr/lib/x86\_64-linux-gnu/libignition-msgs1.so.1.0.0 /usr/lib/x86\_64-linux-gnu/libignition-common1.so.1.0.1 /usr/lib/x86\_64-linux-gnu/libignition-fuel\_tools1.so.1.0.0 /usr/lib/x86\_64-linux-gnu/libprotobuf.so /usr/lib/x86\_64-linux-gnu/libignition-math4.so.4.0.0 /usr/lib/x86\_64-linux-gnu/libuuid.so -luuid /usr/lib/x86\_64-linux-gnu/libswscale.so -lswscale /usr/lib/x86\_64-linux-gnu/libavdevice.so -lavdevice /usr/lib/x86\_64-linux-gnu/libavformat.so -lavformat /usr/lib/x86\_64-linux-gnu/libavcodec.so -lavcodec /usr/lib/x86\_64-linux-gnu/libavutil.so -lavutil -llapack -lpthread -lrt -ldl -lm -lgazebo -lgazebo\_client -lgazebo\_gui -lgazebo\_sensors -lgazebo\_rendering -lgazebo\_physics -lgazebo\_ode -lgazebo\_transport -lgazebo\_msgs -lgazebo\_util -lgazebo\_common -lgazebo\_gimpact -lgazebo\_opcode -lgazebo\_opende\_ou -lboost\_signals -lboost\_program\_options -ltinyxml2 /opt/ros/melodic/lib/libtf.so /opt/ros/melodic/lib/libtf2\_ros.so /opt/ros/melodic/lib/libactionlib.so /opt/ros/melodic/lib/libmessage\_filters.so /opt/ros/melodic/lib/libtf2.so /opt/ros/melodic/lib/libdynamic\_reconfigure\_config\_init\_mutex.so /opt/ros/melodic/lib/libroscpp.so -lboost\_filesystem /opt/ros/melodic/lib/librosconsole.so /opt/ros/melodic/lib/librosconsole\_log4cxx.so /opt/ros/melodic/lib/librosconsole\_backend\_interface.so -llog4cxx /opt/ros/melodic/lib/libxmlrpcpp.so -lboost\_regex /opt/ros/melodic/lib/libroscpp\_serialization.so /opt/ros/melodic/lib/librostime.so /opt/ros/melodic/lib/libcpp\_common.so -lboost\_iostreams -lprotobuf -lpthread -lsdformat -lOgreMain -lboost\_system -lboost\_thread -lboost\_chrono -lboost\_date\_time -lboost\_atomic -lpthread /usr/lib/x86\_64-linux-gnu/libconsole\_bridge.so.0.4 -lboost\_system -lboost\_thread -lboost\_chrono -lboost\_date\_time -lboost\_atomic -lpthread /usr/lib/x86\_64-linux-gnu/libconsole\_bridge.so.0.4 -lOgreTerrain -lOgrePaging