/usr/bin/c++ -fPIC -shared -Wl,-soname,libur3\_moveit\_plugin\_new.so -o /home/adi/Downloads/GazeboSimulation/devel/lib/libur3\_moveit\_plugin\_new.so CMakeFiles/ur3\_moveit\_plugin\_new.dir/src/ur\_moveit\_plugin.cpp.o -Wl,-rpath,/opt/ros/melodic/lib:/home/adi/Downloads/GazeboSimulation/devel/lib: /opt/ros/melodic/lib/libmoveit\_rdf\_loader.so /opt/ros/melodic/lib/libmoveit\_kinematics\_plugin\_loader.so /opt/ros/melodic/lib/libmoveit\_robot\_model\_loader.so /opt/ros/melodic/lib/libmoveit\_constraint\_sampler\_manager\_loader.so /opt/ros/melodic/lib/libmoveit\_planning\_pipeline.so /opt/ros/melodic/lib/libmoveit\_trajectory\_execution\_manager.so /opt/ros/melodic/lib/libmoveit\_plan\_execution.so /opt/ros/melodic/lib/libmoveit\_planning\_scene\_monitor.so /opt/ros/melodic/lib/libmoveit\_collision\_plugin\_loader.so /opt/ros/melodic/lib/libdynamic\_reconfigure\_config\_init\_mutex.so /opt/ros/melodic/lib/libmoveit\_ros\_occupancy\_map\_monitor.so /opt/ros/melodic/lib/libmoveit\_exceptions.so /opt/ros/melodic/lib/libmoveit\_background\_processing.so /opt/ros/melodic/lib/libmoveit\_kinematics\_base.so /opt/ros/melodic/lib/libmoveit\_robot\_model.so /opt/ros/melodic/lib/libmoveit\_transforms.so /opt/ros/melodic/lib/libmoveit\_robot\_state.so /opt/ros/melodic/lib/libmoveit\_robot\_trajectory.so /opt/ros/melodic/lib/libmoveit\_planning\_interface.so /opt/ros/melodic/lib/libmoveit\_collision\_detection.so /opt/ros/melodic/lib/libmoveit\_collision\_detection\_fcl.so /opt/ros/melodic/lib/libmoveit\_kinematic\_constraints.so /opt/ros/melodic/lib/libmoveit\_planning\_scene.so /opt/ros/melodic/lib/libmoveit\_constraint\_samplers.so /opt/ros/melodic/lib/libmoveit\_planning\_request\_adapter.so /opt/ros/melodic/lib/libmoveit\_profiler.so /opt/ros/melodic/lib/libmoveit\_python\_tools.so /opt/ros/melodic/lib/libmoveit\_trajectory\_processing.so /opt/ros/melodic/lib/libmoveit\_distance\_field.so /opt/ros/melodic/lib/libmoveit\_collision\_distance\_field.so /opt/ros/melodic/lib/libmoveit\_kinematics\_metrics.so /opt/ros/melodic/lib/libmoveit\_dynamics\_solver.so /opt/ros/melodic/lib/libmoveit\_utils.so /opt/ros/melodic/lib/libmoveit\_test\_utils.so -lboost\_iostreams -lfcl /opt/ros/melodic/lib/libkdl\_parser.so /opt/ros/melodic/lib/liburdf.so -lurdfdom\_sensor -lurdfdom\_model\_state -lurdfdom\_model -lurdfdom\_world /opt/ros/melodic/lib/librosconsole\_bridge.so /opt/ros/melodic/lib/libsrdfdom.so -ltinyxml /opt/ros/melodic/lib/libgeometric\_shapes.so /opt/ros/melodic/lib/liboctomap.so /opt/ros/melodic/lib/liboctomath.so /opt/ros/melodic/lib/librandom\_numbers.so /opt/ros/melodic/lib/liborocos-kdl.so /opt/ros/melodic/lib/libclass\_loader.so -lPocoFoundation -ldl /opt/ros/melodic/lib/libroslib.so /opt/ros/melodic/lib/librospack.so -lpython2.7 -lboost\_program\_options -ltinyxml2 /opt/ros/melodic/lib/libtf\_conversions.so /opt/ros/melodic/lib/libkdl\_conversions.so /opt/ros/melodic/lib/liborocos-kdl.so.1.4.0 /opt/ros/melodic/lib/libtf.so /opt/ros/melodic/lib/libtf2\_ros.so /opt/ros/melodic/lib/libactionlib.so /opt/ros/melodic/lib/libmessage\_filters.so /opt/ros/melodic/lib/libroscpp.so -lboost\_filesystem /opt/ros/melodic/lib/libxmlrpcpp.so /opt/ros/melodic/lib/libtf2.so /opt/ros/melodic/lib/libroscpp\_serialization.so /opt/ros/melodic/lib/librosconsole.so /opt/ros/melodic/lib/librosconsole\_log4cxx.so /opt/ros/melodic/lib/librosconsole\_backend\_interface.so -llog4cxx -lboost\_regex /opt/ros/melodic/lib/librostime.so /opt/ros/melodic/lib/libcpp\_common.so -lboost\_system -lboost\_thread -lboost\_chrono -lboost\_date\_time -lboost\_atomic -lpthread /usr/lib/x86\_64-linux-gnu/libconsole\_bridge.so.0.4 -lboost\_system /home/adi/Downloads/GazeboSimulation/devel/lib/libur3\_kin\_new.so -lboost\_thread -lboost\_chrono -lboost\_date\_time -lboost\_atomic -lpthread /usr/lib/x86\_64-linux-gnu/libconsole\_bridge.so.0.4