;;

;; DO NOT EDIT THIS FILE

;;

;; THIS FILE IS AUTOMATICALLY GENERATED

;; FROM /home/adi/Downloads/GazeboSimulation/src/rb\_kairos\_sim\_new/gazebo\_ros\_pkgs\_new/gazebo\_msgs\_new/package.xml (2.5.19)

;; USING /opt/ros/melodic/lib/python2.7/dist-packages/geneus/geneus\_main.pyc /opt/ros/melodic/share/geneus/package.xml (2.2.6)

;;

(ros::load-ros-package "geometry\_msgs")

(ros::load-ros-package "sensor\_msgs")

(ros::load-ros-package "std\_msgs")

(ros::load-ros-package "std\_srvs")

(ros::load-ros-package "trajectory\_msgs")

(ros::load-ros-package "gazebo\_msgs\_new")