;; Auto-generated. Do not edit!

(when (boundp 'robotnik\_msgs\_new::BoolArray)

(if (not (find-package "ROBOTNIK\_MSGS\_NEW"))

(make-package "ROBOTNIK\_MSGS\_NEW"))

(shadow 'BoolArray (find-package "ROBOTNIK\_MSGS\_NEW")))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::BOOLARRAY")

(make-package "ROBOTNIK\_MSGS\_NEW::BOOLARRAY"))

(in-package "ROS")

;;//! \htmlinclude BoolArray.msg.html

(defclass robotnik\_msgs\_new::BoolArray

:super ros::object

:slots (\_data ))

(defmethod robotnik\_msgs\_new::BoolArray

(:init

(&key

((:data \_\_data) (let (r) (dotimes (i 0) (push nil r)) r))

)

(send-super :init)

(setq \_data \_\_data)

self)

(:data

(&optional \_\_data)

(if \_\_data (setq \_data \_\_data)) \_data)

(:serialization-length

()

(+

;; bool[] \_data

(\* 1 (length \_data)) 4

))

(:serialize

(&optional strm)

(let ((s (if strm strm

(make-string-output-stream (send self :serialization-length)))))

;; bool[] \_data

(write-long (length \_data) s)

(dotimes (i (length \_data))

(if (elt \_data i) (write-byte -1 s) (write-byte 0 s))

)

;;

(if (null strm) (get-output-stream-string s))))

(:deserialize

(buf &optional (ptr- 0))

;; bool[] \_data

(let (n)

(setq n (sys::peek buf ptr- :integer)) (incf ptr- 4)

(setq \_data (make-list n))

(dotimes (i n)

(setf (elt \_data i) (not (= 0 (sys::peek buf ptr- :char)))) (incf ptr- 1)

))

;;

self)

)

(setf (get robotnik\_msgs\_new::BoolArray :md5sum-) "403a16d9294b908e45c67a6f3c3a5b27")

(setf (get robotnik\_msgs\_new::BoolArray :datatype-) "robotnik\_msgs\_new/BoolArray")

(setf (get robotnik\_msgs\_new::BoolArray :definition-)

"bool[] data

")

(provide :robotnik\_msgs\_new/BoolArray "403a16d9294b908e45c67a6f3c3a5b27")