;; Auto-generated. Do not edit!

(when (boundp 'robotnik\_msgs\_new::ElevatorAction)

(if (not (find-package "ROBOTNIK\_MSGS\_NEW"))

(make-package "ROBOTNIK\_MSGS\_NEW"))

(shadow 'ElevatorAction (find-package "ROBOTNIK\_MSGS\_NEW")))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::ELEVATORACTION")

(make-package "ROBOTNIK\_MSGS\_NEW::ELEVATORACTION"))

(in-package "ROS")

;;//! \htmlinclude ElevatorAction.msg.html

(intern "\*RAISE\*" (find-package "ROBOTNIK\_MSGS\_NEW::ELEVATORACTION"))

(shadow '\*RAISE\* (find-package "ROBOTNIK\_MSGS\_NEW::ELEVATORACTION"))

(defconstant robotnik\_msgs\_new::ElevatorAction::\*RAISE\* 1)

(intern "\*LOWER\*" (find-package "ROBOTNIK\_MSGS\_NEW::ELEVATORACTION"))

(shadow '\*LOWER\* (find-package "ROBOTNIK\_MSGS\_NEW::ELEVATORACTION"))

(defconstant robotnik\_msgs\_new::ElevatorAction::\*LOWER\* -1)

(intern "\*STOP\*" (find-package "ROBOTNIK\_MSGS\_NEW::ELEVATORACTION"))

(shadow '\*STOP\* (find-package "ROBOTNIK\_MSGS\_NEW::ELEVATORACTION"))

(defconstant robotnik\_msgs\_new::ElevatorAction::\*STOP\* 0)

(intern "\*NO\_ACTION\*" (find-package "ROBOTNIK\_MSGS\_NEW::ELEVATORACTION"))

(shadow '\*NO\_ACTION\* (find-package "ROBOTNIK\_MSGS\_NEW::ELEVATORACTION"))

(defconstant robotnik\_msgs\_new::ElevatorAction::\*NO\_ACTION\* 1000)

(defclass robotnik\_msgs\_new::ElevatorAction

:super ros::object

:slots (\_action ))

(defmethod robotnik\_msgs\_new::ElevatorAction

(:init

(&key

((:action \_\_action) 0)

)

(send-super :init)

(setq \_action (round \_\_action))

self)

(:action

(&optional \_\_action)

(if \_\_action (setq \_action \_\_action)) \_action)

(:serialization-length

()

(+

;; int32 \_action

4

))

(:serialize

(&optional strm)

(let ((s (if strm strm

(make-string-output-stream (send self :serialization-length)))))

;; int32 \_action

(write-long \_action s)

;;

(if (null strm) (get-output-stream-string s))))

(:deserialize

(buf &optional (ptr- 0))

;; int32 \_action

(setq \_action (sys::peek buf ptr- :integer)) (incf ptr- 4)

;;

self)

)

(setf (get robotnik\_msgs\_new::ElevatorAction :md5sum-) "632c616886d6575f7d7145cd0384a359")

(setf (get robotnik\_msgs\_new::ElevatorAction :datatype-) "robotnik\_msgs\_new/ElevatorAction")

(setf (get robotnik\_msgs\_new::ElevatorAction :definition-)

"int32 RAISE=1

int32 LOWER=-1

int32 STOP=0

int32 NO\_ACTION=1000

int32 action

# speed, height for future applications

")

(provide :robotnik\_msgs\_new/ElevatorAction "632c616886d6575f7d7145cd0384a359")