;; Auto-generated. Do not edit!

(when (boundp 'robotnik\_msgs\_new::ElevatorStatus)

(if (not (find-package "ROBOTNIK\_MSGS\_NEW"))

(make-package "ROBOTNIK\_MSGS\_NEW"))

(shadow 'ElevatorStatus (find-package "ROBOTNIK\_MSGS\_NEW")))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::ELEVATORSTATUS")

(make-package "ROBOTNIK\_MSGS\_NEW::ELEVATORSTATUS"))

(in-package "ROS")

;;//! \htmlinclude ElevatorStatus.msg.html

(intern "\*RAISING\*" (find-package "ROBOTNIK\_MSGS\_NEW::ELEVATORSTATUS"))

(shadow '\*RAISING\* (find-package "ROBOTNIK\_MSGS\_NEW::ELEVATORSTATUS"))

(defconstant robotnik\_msgs\_new::ElevatorStatus::\*RAISING\* "raising")

(intern "\*LOWERING\*" (find-package "ROBOTNIK\_MSGS\_NEW::ELEVATORSTATUS"))

(shadow '\*LOWERING\* (find-package "ROBOTNIK\_MSGS\_NEW::ELEVATORSTATUS"))

(defconstant robotnik\_msgs\_new::ElevatorStatus::\*LOWERING\* "lowering")

(intern "\*IDLE\*" (find-package "ROBOTNIK\_MSGS\_NEW::ELEVATORSTATUS"))

(shadow '\*IDLE\* (find-package "ROBOTNIK\_MSGS\_NEW::ELEVATORSTATUS"))

(defconstant robotnik\_msgs\_new::ElevatorStatus::\*IDLE\* "idle")

(intern "\*ERROR\_G\_IO\*" (find-package "ROBOTNIK\_MSGS\_NEW::ELEVATORSTATUS"))

(shadow '\*ERROR\_G\_IO\* (find-package "ROBOTNIK\_MSGS\_NEW::ELEVATORSTATUS"))

(defconstant robotnik\_msgs\_new::ElevatorStatus::\*ERROR\_G\_IO\* "error\_getting\_io")

(intern "\*ERROR\_S\_IO\*" (find-package "ROBOTNIK\_MSGS\_NEW::ELEVATORSTATUS"))

(shadow '\*ERROR\_S\_IO\* (find-package "ROBOTNIK\_MSGS\_NEW::ELEVATORSTATUS"))

(defconstant robotnik\_msgs\_new::ElevatorStatus::\*ERROR\_S\_IO\* "error\_setting\_io")

(intern "\*ERROR\_TIMEOUT\*" (find-package "ROBOTNIK\_MSGS\_NEW::ELEVATORSTATUS"))

(shadow '\*ERROR\_TIMEOUT\* (find-package "ROBOTNIK\_MSGS\_NEW::ELEVATORSTATUS"))

(defconstant robotnik\_msgs\_new::ElevatorStatus::\*ERROR\_TIMEOUT\* "error\_timeout\_in\_action")

(intern "\*UP\*" (find-package "ROBOTNIK\_MSGS\_NEW::ELEVATORSTATUS"))

(shadow '\*UP\* (find-package "ROBOTNIK\_MSGS\_NEW::ELEVATORSTATUS"))

(defconstant robotnik\_msgs\_new::ElevatorStatus::\*UP\* "up")

(intern "\*DOWN\*" (find-package "ROBOTNIK\_MSGS\_NEW::ELEVATORSTATUS"))

(shadow '\*DOWN\* (find-package "ROBOTNIK\_MSGS\_NEW::ELEVATORSTATUS"))

(defconstant robotnik\_msgs\_new::ElevatorStatus::\*DOWN\* "down")

(intern "\*UNKNOWN\*" (find-package "ROBOTNIK\_MSGS\_NEW::ELEVATORSTATUS"))

(shadow '\*UNKNOWN\* (find-package "ROBOTNIK\_MSGS\_NEW::ELEVATORSTATUS"))

(defconstant robotnik\_msgs\_new::ElevatorStatus::\*UNKNOWN\* "unknown")

(defclass robotnik\_msgs\_new::ElevatorStatus

:super ros::object

:slots (\_state \_position \_height ))

(defmethod robotnik\_msgs\_new::ElevatorStatus

(:init

(&key

((:state \_\_state) "")

((:position \_\_position) "")

((:height \_\_height) 0.0)

)

(send-super :init)

(setq \_state (string \_\_state))

(setq \_position (string \_\_position))

(setq \_height (float \_\_height))

self)

(:state

(&optional \_\_state)

(if \_\_state (setq \_state \_\_state)) \_state)

(:position

(&optional \_\_position)

(if \_\_position (setq \_position \_\_position)) \_position)

(:height

(&optional \_\_height)

(if \_\_height (setq \_height \_\_height)) \_height)

(:serialization-length

()

(+

;; string \_state

4 (length \_state)

;; string \_position

4 (length \_position)

;; float32 \_height

4

))

(:serialize

(&optional strm)

(let ((s (if strm strm

(make-string-output-stream (send self :serialization-length)))))

;; string \_state

(write-long (length \_state) s) (princ \_state s)

;; string \_position

(write-long (length \_position) s) (princ \_position s)

;; float32 \_height

(sys::poke \_height (send s :buffer) (send s :count) :float) (incf (stream-count s) 4)

;;

(if (null strm) (get-output-stream-string s))))

(:deserialize

(buf &optional (ptr- 0))

;; string \_state

(let (n) (setq n (sys::peek buf ptr- :integer)) (incf ptr- 4) (setq \_state (subseq buf ptr- (+ ptr- n))) (incf ptr- n))

;; string \_position

(let (n) (setq n (sys::peek buf ptr- :integer)) (incf ptr- 4) (setq \_position (subseq buf ptr- (+ ptr- n))) (incf ptr- n))

;; float32 \_height

(setq \_height (sys::peek buf ptr- :float)) (incf ptr- 4)

;;

self)

)

(setf (get robotnik\_msgs\_new::ElevatorStatus :md5sum-) "4718bff9866c729031e595e6565fdb82")

(setf (get robotnik\_msgs\_new::ElevatorStatus :datatype-) "robotnik\_msgs\_new/ElevatorStatus")

(setf (get robotnik\_msgs\_new::ElevatorStatus :definition-)

"# state

string RAISING=raising

string LOWERING=lowering

string IDLE=idle

string ERROR\_G\_IO=error\_getting\_io

string ERROR\_S\_IO=error\_setting\_io

string ERROR\_TIMEOUT=error\_timeout\_in\_action

# position

string UP=up

string DOWN=down

string UNKNOWN=unknown

# IDLE, RAISING, LOWERING

string state

# UP, DOWN, UNKNOWN

string position

float32 height

")

(provide :robotnik\_msgs\_new/ElevatorStatus "4718bff9866c729031e595e6565fdb82")