;; Auto-generated. Do not edit!

(when (boundp 'robotnik\_msgs\_new::MotorsStatusDifferential)

(if (not (find-package "ROBOTNIK\_MSGS\_NEW"))

(make-package "ROBOTNIK\_MSGS\_NEW"))

(shadow 'MotorsStatusDifferential (find-package "ROBOTNIK\_MSGS\_NEW")))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::MOTORSSTATUSDIFFERENTIAL")

(make-package "ROBOTNIK\_MSGS\_NEW::MOTORSSTATUSDIFFERENTIAL"))

(in-package "ROS")

;;//! \htmlinclude MotorsStatusDifferential.msg.html

(defclass robotnik\_msgs\_new::MotorsStatusDifferential

:super ros::object

:slots (\_lwStatus \_rwStatus ))

(defmethod robotnik\_msgs\_new::MotorsStatusDifferential

(:init

(&key

((:lwStatus \_\_lwStatus) (instance robotnik\_msgs\_new::MotorStatus :init))

((:rwStatus \_\_rwStatus) (instance robotnik\_msgs\_new::MotorStatus :init))

)

(send-super :init)

(setq \_lwStatus \_\_lwStatus)

(setq \_rwStatus \_\_rwStatus)

self)

(:lwStatus

(&rest \_\_lwStatus)

(if (keywordp (car \_\_lwStatus))

(send\* \_lwStatus \_\_lwStatus)

(progn

(if \_\_lwStatus (setq \_lwStatus (car \_\_lwStatus)))

\_lwStatus)))

(:rwStatus

(&rest \_\_rwStatus)

(if (keywordp (car \_\_rwStatus))

(send\* \_rwStatus \_\_rwStatus)

(progn

(if \_\_rwStatus (setq \_rwStatus (car \_\_rwStatus)))

\_rwStatus)))

(:serialization-length

()

(+

;; robotnik\_msgs\_new/MotorStatus \_lwStatus

(send \_lwStatus :serialization-length)

;; robotnik\_msgs\_new/MotorStatus \_rwStatus

(send \_rwStatus :serialization-length)

))

(:serialize

(&optional strm)

(let ((s (if strm strm

(make-string-output-stream (send self :serialization-length)))))

;; robotnik\_msgs\_new/MotorStatus \_lwStatus

(send \_lwStatus :serialize s)

;; robotnik\_msgs\_new/MotorStatus \_rwStatus

(send \_rwStatus :serialize s)

;;

(if (null strm) (get-output-stream-string s))))

(:deserialize

(buf &optional (ptr- 0))

;; robotnik\_msgs\_new/MotorStatus \_lwStatus

(send \_lwStatus :deserialize buf ptr-) (incf ptr- (send \_lwStatus :serialization-length))

;; robotnik\_msgs\_new/MotorStatus \_rwStatus

(send \_rwStatus :deserialize buf ptr-) (incf ptr- (send \_rwStatus :serialization-length))

;;

self)

)

(setf (get robotnik\_msgs\_new::MotorsStatusDifferential :md5sum-) "f3eae6344ebc22baab4e7f49de91ea41")

(setf (get robotnik\_msgs\_new::MotorsStatusDifferential :datatype-) "robotnik\_msgs\_new/MotorsStatusDifferential")

(setf (get robotnik\_msgs\_new::MotorsStatusDifferential :definition-)

"MotorStatus lwStatus

MotorStatus rwStatus

================================================================================

MSG: robotnik\_msgs\_new/MotorStatus

string state

string status

string communicationstatus

string statusword

string driveflags

string[] activestatusword

string[] activedriveflags

int32 digitaloutputs

int32 digitalinputs

float32 averagecurrent

float32[] analoginputs

")

(provide :robotnik\_msgs\_new/MotorsStatusDifferential "f3eae6344ebc22baab4e7f49de91ea41")