;; Auto-generated. Do not edit!

(when (boundp 'robotnik\_msgs\_new::SetElevatorFeedback)

(if (not (find-package "ROBOTNIK\_MSGS\_NEW"))

(make-package "ROBOTNIK\_MSGS\_NEW"))

(shadow 'SetElevatorFeedback (find-package "ROBOTNIK\_MSGS\_NEW")))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::SETELEVATORFEEDBACK")

(make-package "ROBOTNIK\_MSGS\_NEW::SETELEVATORFEEDBACK"))

(in-package "ROS")

;;//! \htmlinclude SetElevatorFeedback.msg.html

(defclass robotnik\_msgs\_new::SetElevatorFeedback

:super ros::object

:slots (\_status ))

(defmethod robotnik\_msgs\_new::SetElevatorFeedback

(:init

(&key

((:status \_\_status) (instance robotnik\_msgs\_new::ElevatorStatus :init))

)

(send-super :init)

(setq \_status \_\_status)

self)

(:status

(&rest \_\_status)

(if (keywordp (car \_\_status))

(send\* \_status \_\_status)

(progn

(if \_\_status (setq \_status (car \_\_status)))

\_status)))

(:serialization-length

()

(+

;; robotnik\_msgs\_new/ElevatorStatus \_status

(send \_status :serialization-length)

))

(:serialize

(&optional strm)

(let ((s (if strm strm

(make-string-output-stream (send self :serialization-length)))))

;; robotnik\_msgs\_new/ElevatorStatus \_status

(send \_status :serialize s)

;;

(if (null strm) (get-output-stream-string s))))

(:deserialize

(buf &optional (ptr- 0))

;; robotnik\_msgs\_new/ElevatorStatus \_status

(send \_status :deserialize buf ptr-) (incf ptr- (send \_status :serialization-length))

;;

self)

)

(setf (get robotnik\_msgs\_new::SetElevatorFeedback :md5sum-) "47e3f709643220443260a9d8c1f901ea")

(setf (get robotnik\_msgs\_new::SetElevatorFeedback :datatype-) "robotnik\_msgs\_new/SetElevatorFeedback")

(setf (get robotnik\_msgs\_new::SetElevatorFeedback :definition-)

"# ====== DO NOT MODIFY! AUTOGENERATED FROM AN ACTION DEFINITION ======

robotnik\_msgs\_new/ElevatorStatus status

================================================================================

MSG: robotnik\_msgs\_new/ElevatorStatus

# state

string RAISING=raising

string LOWERING=lowering

string IDLE=idle

string ERROR\_G\_IO=error\_getting\_io

string ERROR\_S\_IO=error\_setting\_io

string ERROR\_TIMEOUT=error\_timeout\_in\_action

# position

string UP=up

string DOWN=down

string UNKNOWN=unknown

# IDLE, RAISING, LOWERING

string state

# UP, DOWN, UNKNOWN

string position

float32 height

")

(provide :robotnik\_msgs\_new/SetElevatorFeedback "47e3f709643220443260a9d8c1f901ea")