;; Auto-generated. Do not edit!

(when (boundp 'robotnik\_msgs\_new::SetElevatorGoal)

(if (not (find-package "ROBOTNIK\_MSGS\_NEW"))

(make-package "ROBOTNIK\_MSGS\_NEW"))

(shadow 'SetElevatorGoal (find-package "ROBOTNIK\_MSGS\_NEW")))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::SETELEVATORGOAL")

(make-package "ROBOTNIK\_MSGS\_NEW::SETELEVATORGOAL"))

(in-package "ROS")

;;//! \htmlinclude SetElevatorGoal.msg.html

(defclass robotnik\_msgs\_new::SetElevatorGoal

:super ros::object

:slots (\_action ))

(defmethod robotnik\_msgs\_new::SetElevatorGoal

(:init

(&key

((:action \_\_action) (instance robotnik\_msgs\_new::ElevatorAction :init))

)

(send-super :init)

(setq \_action \_\_action)

self)

(:action

(&rest \_\_action)

(if (keywordp (car \_\_action))

(send\* \_action \_\_action)

(progn

(if \_\_action (setq \_action (car \_\_action)))

\_action)))

(:serialization-length

()

(+

;; robotnik\_msgs\_new/ElevatorAction \_action

(send \_action :serialization-length)

))

(:serialize

(&optional strm)

(let ((s (if strm strm

(make-string-output-stream (send self :serialization-length)))))

;; robotnik\_msgs\_new/ElevatorAction \_action

(send \_action :serialize s)

;;

(if (null strm) (get-output-stream-string s))))

(:deserialize

(buf &optional (ptr- 0))

;; robotnik\_msgs\_new/ElevatorAction \_action

(send \_action :deserialize buf ptr-) (incf ptr- (send \_action :serialization-length))

;;

self)

)

(setf (get robotnik\_msgs\_new::SetElevatorGoal :md5sum-) "ba01edad69e94d31f2469c9b6db50a0e")

(setf (get robotnik\_msgs\_new::SetElevatorGoal :datatype-) "robotnik\_msgs\_new/SetElevatorGoal")

(setf (get robotnik\_msgs\_new::SetElevatorGoal :definition-)

"# ====== DO NOT MODIFY! AUTOGENERATED FROM AN ACTION DEFINITION ======

robotnik\_msgs\_new/ElevatorAction action

================================================================================

MSG: robotnik\_msgs\_new/ElevatorAction

int32 RAISE=1

int32 LOWER=-1

int32 STOP=0

int32 NO\_ACTION=1000

int32 action

# speed, height for future applications

")

(provide :robotnik\_msgs\_new/SetElevatorGoal "ba01edad69e94d31f2469c9b6db50a0e")