;; Auto-generated. Do not edit!

(when (boundp 'robotnik\_msgs\_new::named\_inputs\_outputs)

(if (not (find-package "ROBOTNIK\_MSGS\_NEW"))

(make-package "ROBOTNIK\_MSGS\_NEW"))

(shadow 'named\_inputs\_outputs (find-package "ROBOTNIK\_MSGS\_NEW")))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::NAMED\_INPUTS\_OUTPUTS")

(make-package "ROBOTNIK\_MSGS\_NEW::NAMED\_INPUTS\_OUTPUTS"))

(in-package "ROS")

;;//! \htmlinclude named\_inputs\_outputs.msg.html

(defclass robotnik\_msgs\_new::named\_inputs\_outputs

:super ros::object

:slots (\_digital\_inputs \_digital\_outputs ))

(defmethod robotnik\_msgs\_new::named\_inputs\_outputs

(:init

(&key

((:digital\_inputs \_\_digital\_inputs) (let (r) (dotimes (i 0) (push (instance robotnik\_msgs\_new::named\_input\_output :init) r)) r))

((:digital\_outputs \_\_digital\_outputs) (let (r) (dotimes (i 0) (push (instance robotnik\_msgs\_new::named\_input\_output :init) r)) r))

)

(send-super :init)

(setq \_digital\_inputs \_\_digital\_inputs)

(setq \_digital\_outputs \_\_digital\_outputs)

self)

(:digital\_inputs

(&rest \_\_digital\_inputs)

(if (keywordp (car \_\_digital\_inputs))

(send\* \_digital\_inputs \_\_digital\_inputs)

(progn

(if \_\_digital\_inputs (setq \_digital\_inputs (car \_\_digital\_inputs)))

\_digital\_inputs)))

(:digital\_outputs

(&rest \_\_digital\_outputs)

(if (keywordp (car \_\_digital\_outputs))

(send\* \_digital\_outputs \_\_digital\_outputs)

(progn

(if \_\_digital\_outputs (setq \_digital\_outputs (car \_\_digital\_outputs)))

\_digital\_outputs)))

(:serialization-length

()

(+

;; robotnik\_msgs\_new/named\_input\_output[] \_digital\_inputs

(apply #'+ (send-all \_digital\_inputs :serialization-length)) 4

;; robotnik\_msgs\_new/named\_input\_output[] \_digital\_outputs

(apply #'+ (send-all \_digital\_outputs :serialization-length)) 4

))

(:serialize

(&optional strm)

(let ((s (if strm strm

(make-string-output-stream (send self :serialization-length)))))

;; robotnik\_msgs\_new/named\_input\_output[] \_digital\_inputs

(write-long (length \_digital\_inputs) s)

(dolist (elem \_digital\_inputs)

(send elem :serialize s)

)

;; robotnik\_msgs\_new/named\_input\_output[] \_digital\_outputs

(write-long (length \_digital\_outputs) s)

(dolist (elem \_digital\_outputs)

(send elem :serialize s)

)

;;

(if (null strm) (get-output-stream-string s))))

(:deserialize

(buf &optional (ptr- 0))

;; robotnik\_msgs\_new/named\_input\_output[] \_digital\_inputs

(let (n)

(setq n (sys::peek buf ptr- :integer)) (incf ptr- 4)

(setq \_digital\_inputs (let (r) (dotimes (i n) (push (instance robotnik\_msgs\_new::named\_input\_output :init) r)) r))

(dolist (elem- \_digital\_inputs)

(send elem- :deserialize buf ptr-) (incf ptr- (send elem- :serialization-length))

))

;; robotnik\_msgs\_new/named\_input\_output[] \_digital\_outputs

(let (n)

(setq n (sys::peek buf ptr- :integer)) (incf ptr- 4)

(setq \_digital\_outputs (let (r) (dotimes (i n) (push (instance robotnik\_msgs\_new::named\_input\_output :init) r)) r))

(dolist (elem- \_digital\_outputs)

(send elem- :deserialize buf ptr-) (incf ptr- (send elem- :serialization-length))

))

;;

self)

)

(setf (get robotnik\_msgs\_new::named\_inputs\_outputs :md5sum-) "e3301c19a16019595490fc28259868bd")

(setf (get robotnik\_msgs\_new::named\_inputs\_outputs :datatype-) "robotnik\_msgs\_new/named\_inputs\_outputs")

(setf (get robotnik\_msgs\_new::named\_inputs\_outputs :definition-)

"robotnik\_msgs\_new/named\_input\_output[] digital\_inputs

robotnik\_msgs\_new/named\_input\_output[] digital\_outputs

================================================================================

MSG: robotnik\_msgs\_new/named\_input\_output

string name

bool value

")

(provide :robotnik\_msgs\_new/named\_inputs\_outputs "e3301c19a16019595490fc28259868bd")