;; Auto-generated. Do not edit!

(when (boundp 'robotnik\_msgs\_new::GetBool)

(if (not (find-package "ROBOTNIK\_MSGS\_NEW"))

(make-package "ROBOTNIK\_MSGS\_NEW"))

(shadow 'GetBool (find-package "ROBOTNIK\_MSGS\_NEW")))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::GETBOOL")

(make-package "ROBOTNIK\_MSGS\_NEW::GETBOOL"))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::GETBOOLREQUEST")

(make-package "ROBOTNIK\_MSGS\_NEW::GETBOOLREQUEST"))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::GETBOOLRESPONSE")

(make-package "ROBOTNIK\_MSGS\_NEW::GETBOOLRESPONSE"))

(in-package "ROS")

(defclass robotnik\_msgs\_new::GetBoolRequest

:super ros::object

:slots ())

(defmethod robotnik\_msgs\_new::GetBoolRequest

(:init

(&key

)

(send-super :init)

self)

(:serialization-length

()

(+

0

))

(:serialize

(&optional strm)

(let ((s (if strm strm

(make-string-output-stream (send self :serialization-length)))))

;;

(if (null strm) (get-output-stream-string s))))

(:deserialize

(buf &optional (ptr- 0))

;;

self)

)

(defclass robotnik\_msgs\_new::GetBoolResponse

:super ros::object

:slots (\_data \_success \_message ))

(defmethod robotnik\_msgs\_new::GetBoolResponse

(:init

(&key

((:data \_\_data) nil)

((:success \_\_success) nil)

((:message \_\_message) "")

)

(send-super :init)

(setq \_data \_\_data)

(setq \_success \_\_success)

(setq \_message (string \_\_message))

self)

(:data

(&optional \_\_data)

(if \_\_data (setq \_data \_\_data)) \_data)

(:success

(&optional \_\_success)

(if \_\_success (setq \_success \_\_success)) \_success)

(:message

(&optional \_\_message)

(if \_\_message (setq \_message \_\_message)) \_message)

(:serialization-length

()

(+

;; bool \_data

1

;; bool \_success

1

;; string \_message

4 (length \_message)

))

(:serialize

(&optional strm)

(let ((s (if strm strm

(make-string-output-stream (send self :serialization-length)))))

;; bool \_data

(if \_data (write-byte -1 s) (write-byte 0 s))

;; bool \_success

(if \_success (write-byte -1 s) (write-byte 0 s))

;; string \_message

(write-long (length \_message) s) (princ \_message s)

;;

(if (null strm) (get-output-stream-string s))))

(:deserialize

(buf &optional (ptr- 0))

;; bool \_data

(setq \_data (not (= 0 (sys::peek buf ptr- :char)))) (incf ptr- 1)

;; bool \_success

(setq \_success (not (= 0 (sys::peek buf ptr- :char)))) (incf ptr- 1)

;; string \_message

(let (n) (setq n (sys::peek buf ptr- :integer)) (incf ptr- 4) (setq \_message (subseq buf ptr- (+ ptr- n))) (incf ptr- n))

;;

self)

)

(defclass robotnik\_msgs\_new::GetBool

:super ros::object

:slots ())

(setf (get robotnik\_msgs\_new::GetBool :md5sum-) "43f76a855b16e988566e147b692f2fab")

(setf (get robotnik\_msgs\_new::GetBool :datatype-) "robotnik\_msgs\_new/GetBool")

(setf (get robotnik\_msgs\_new::GetBool :request) robotnik\_msgs\_new::GetBoolRequest)

(setf (get robotnik\_msgs\_new::GetBool :response) robotnik\_msgs\_new::GetBoolResponse)

(defmethod robotnik\_msgs\_new::GetBoolRequest

(:response () (instance robotnik\_msgs\_new::GetBoolResponse :init)))

(setf (get robotnik\_msgs\_new::GetBoolRequest :md5sum-) "43f76a855b16e988566e147b692f2fab")

(setf (get robotnik\_msgs\_new::GetBoolRequest :datatype-) "robotnik\_msgs\_new/GetBoolRequest")

(setf (get robotnik\_msgs\_new::GetBoolRequest :definition-)

"---

bool data

bool success # indicate successful run of triggered service

string message # informational, e.g. for error messages

")

(setf (get robotnik\_msgs\_new::GetBoolResponse :md5sum-) "43f76a855b16e988566e147b692f2fab")

(setf (get robotnik\_msgs\_new::GetBoolResponse :datatype-) "robotnik\_msgs\_new/GetBoolResponse")

(setf (get robotnik\_msgs\_new::GetBoolResponse :definition-)

"---

bool data

bool success # indicate successful run of triggered service

string message # informational, e.g. for error messages

")

(provide :robotnik\_msgs\_new/GetBool "43f76a855b16e988566e147b692f2fab")