;; Auto-generated. Do not edit!

(when (boundp 'robotnik\_msgs\_new::GetMotorsHeadingOffset)

(if (not (find-package "ROBOTNIK\_MSGS\_NEW"))

(make-package "ROBOTNIK\_MSGS\_NEW"))

(shadow 'GetMotorsHeadingOffset (find-package "ROBOTNIK\_MSGS\_NEW")))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::GETMOTORSHEADINGOFFSET")

(make-package "ROBOTNIK\_MSGS\_NEW::GETMOTORSHEADINGOFFSET"))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::GETMOTORSHEADINGOFFSETREQUEST")

(make-package "ROBOTNIK\_MSGS\_NEW::GETMOTORSHEADINGOFFSETREQUEST"))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::GETMOTORSHEADINGOFFSETRESPONSE")

(make-package "ROBOTNIK\_MSGS\_NEW::GETMOTORSHEADINGOFFSETRESPONSE"))

(in-package "ROS")

(if (not (find-package "STD\_MSGS"))

(ros::roseus-add-msgs "std\_msgs"))

(defclass robotnik\_msgs\_new::GetMotorsHeadingOffsetRequest

:super ros::object

:slots (\_request ))

(defmethod robotnik\_msgs\_new::GetMotorsHeadingOffsetRequest

(:init

(&key

((:request \_\_request) (instance std\_msgs::Empty :init))

)

(send-super :init)

(setq \_request \_\_request)

self)

(:request

(&rest \_\_request)

(if (keywordp (car \_\_request))

(send\* \_request \_\_request)

(progn

(if \_\_request (setq \_request (car \_\_request)))

\_request)))

(:serialization-length

()

(+

;; std\_msgs/Empty \_request

(send \_request :serialization-length)

))

(:serialize

(&optional strm)

(let ((s (if strm strm

(make-string-output-stream (send self :serialization-length)))))

;; std\_msgs/Empty \_request

(send \_request :serialize s)

;;

(if (null strm) (get-output-stream-string s))))

(:deserialize

(buf &optional (ptr- 0))

;; std\_msgs/Empty \_request

(send \_request :deserialize buf ptr-) (incf ptr- (send \_request :serialization-length))

;;

self)

)

(defclass robotnik\_msgs\_new::GetMotorsHeadingOffsetResponse

:super ros::object

:slots (\_offsets ))

(defmethod robotnik\_msgs\_new::GetMotorsHeadingOffsetResponse

(:init

(&key

((:offsets \_\_offsets) (let (r) (dotimes (i 0) (push (instance robotnik\_msgs\_new::MotorHeadingOffset :init) r)) r))

)

(send-super :init)

(setq \_offsets \_\_offsets)

self)

(:offsets

(&rest \_\_offsets)

(if (keywordp (car \_\_offsets))

(send\* \_offsets \_\_offsets)

(progn

(if \_\_offsets (setq \_offsets (car \_\_offsets)))

\_offsets)))

(:serialization-length

()

(+

;; robotnik\_msgs\_new/MotorHeadingOffset[] \_offsets

(apply #'+ (send-all \_offsets :serialization-length)) 4

))

(:serialize

(&optional strm)

(let ((s (if strm strm

(make-string-output-stream (send self :serialization-length)))))

;; robotnik\_msgs\_new/MotorHeadingOffset[] \_offsets

(write-long (length \_offsets) s)

(dolist (elem \_offsets)

(send elem :serialize s)

)

;;

(if (null strm) (get-output-stream-string s))))

(:deserialize

(buf &optional (ptr- 0))

;; robotnik\_msgs\_new/MotorHeadingOffset[] \_offsets

(let (n)

(setq n (sys::peek buf ptr- :integer)) (incf ptr- 4)

(setq \_offsets (let (r) (dotimes (i n) (push (instance robotnik\_msgs\_new::MotorHeadingOffset :init) r)) r))

(dolist (elem- \_offsets)

(send elem- :deserialize buf ptr-) (incf ptr- (send elem- :serialization-length))

))

;;

self)

)

(defclass robotnik\_msgs\_new::GetMotorsHeadingOffset

:super ros::object

:slots ())

(setf (get robotnik\_msgs\_new::GetMotorsHeadingOffset :md5sum-) "cdf947b0b6f5aca552a9fd0b8e9d235b")

(setf (get robotnik\_msgs\_new::GetMotorsHeadingOffset :datatype-) "robotnik\_msgs\_new/GetMotorsHeadingOffset")

(setf (get robotnik\_msgs\_new::GetMotorsHeadingOffset :request) robotnik\_msgs\_new::GetMotorsHeadingOffsetRequest)

(setf (get robotnik\_msgs\_new::GetMotorsHeadingOffset :response) robotnik\_msgs\_new::GetMotorsHeadingOffsetResponse)

(defmethod robotnik\_msgs\_new::GetMotorsHeadingOffsetRequest

(:response () (instance robotnik\_msgs\_new::GetMotorsHeadingOffsetResponse :init)))

(setf (get robotnik\_msgs\_new::GetMotorsHeadingOffsetRequest :md5sum-) "cdf947b0b6f5aca552a9fd0b8e9d235b")

(setf (get robotnik\_msgs\_new::GetMotorsHeadingOffsetRequest :datatype-) "robotnik\_msgs\_new/GetMotorsHeadingOffsetRequest")

(setf (get robotnik\_msgs\_new::GetMotorsHeadingOffsetRequest :definition-)

"std\_msgs/Empty request

================================================================================

MSG: std\_msgs/Empty

---

robotnik\_msgs\_new/MotorHeadingOffset[] offsets

================================================================================

MSG: robotnik\_msgs\_new/MotorHeadingOffset

int32 motor

float64 value

")

(setf (get robotnik\_msgs\_new::GetMotorsHeadingOffsetResponse :md5sum-) "cdf947b0b6f5aca552a9fd0b8e9d235b")

(setf (get robotnik\_msgs\_new::GetMotorsHeadingOffsetResponse :datatype-) "robotnik\_msgs\_new/GetMotorsHeadingOffsetResponse")

(setf (get robotnik\_msgs\_new::GetMotorsHeadingOffsetResponse :definition-)

"std\_msgs/Empty request

================================================================================

MSG: std\_msgs/Empty

---

robotnik\_msgs\_new/MotorHeadingOffset[] offsets

================================================================================

MSG: robotnik\_msgs\_new/MotorHeadingOffset

int32 motor

float64 value

")

(provide :robotnik\_msgs\_new/GetMotorsHeadingOffset "cdf947b0b6f5aca552a9fd0b8e9d235b")