;; Auto-generated. Do not edit!

(when (boundp 'robotnik\_msgs\_new::ResetFromSubState)

(if (not (find-package "ROBOTNIK\_MSGS\_NEW"))

(make-package "ROBOTNIK\_MSGS\_NEW"))

(shadow 'ResetFromSubState (find-package "ROBOTNIK\_MSGS\_NEW")))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::RESETFROMSUBSTATE")

(make-package "ROBOTNIK\_MSGS\_NEW::RESETFROMSUBSTATE"))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::RESETFROMSUBSTATEREQUEST")

(make-package "ROBOTNIK\_MSGS\_NEW::RESETFROMSUBSTATEREQUEST"))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::RESETFROMSUBSTATERESPONSE")

(make-package "ROBOTNIK\_MSGS\_NEW::RESETFROMSUBSTATERESPONSE"))

(in-package "ROS")

(defclass robotnik\_msgs\_new::ResetFromSubStateRequest

:super ros::object

:slots (\_subState ))

(defmethod robotnik\_msgs\_new::ResetFromSubStateRequest

(:init

(&key

((:subState \_\_subState) 0)

)

(send-super :init)

(setq \_subState (round \_\_subState))

self)

(:subState

(&optional \_\_subState)

(if \_\_subState (setq \_subState \_\_subState)) \_subState)

(:serialization-length

()

(+

;; int32 \_subState

4

))

(:serialize

(&optional strm)

(let ((s (if strm strm

(make-string-output-stream (send self :serialization-length)))))

;; int32 \_subState

(write-long \_subState s)

;;

(if (null strm) (get-output-stream-string s))))

(:deserialize

(buf &optional (ptr- 0))

;; int32 \_subState

(setq \_subState (sys::peek buf ptr- :integer)) (incf ptr- 4)

;;

self)

)

(defclass robotnik\_msgs\_new::ResetFromSubStateResponse

:super ros::object

:slots (\_currentSubState \_success \_msg ))

(defmethod robotnik\_msgs\_new::ResetFromSubStateResponse

(:init

(&key

((:currentSubState \_\_currentSubState) 0)

((:success \_\_success) nil)

((:msg \_\_msg) "")

)

(send-super :init)

(setq \_currentSubState (round \_\_currentSubState))

(setq \_success \_\_success)

(setq \_msg (string \_\_msg))

self)

(:currentSubState

(&optional \_\_currentSubState)

(if \_\_currentSubState (setq \_currentSubState \_\_currentSubState)) \_currentSubState)

(:success

(&optional \_\_success)

(if \_\_success (setq \_success \_\_success)) \_success)

(:msg

(&optional \_\_msg)

(if \_\_msg (setq \_msg \_\_msg)) \_msg)

(:serialization-length

()

(+

;; int32 \_currentSubState

4

;; bool \_success

1

;; string \_msg

4 (length \_msg)

))

(:serialize

(&optional strm)

(let ((s (if strm strm

(make-string-output-stream (send self :serialization-length)))))

;; int32 \_currentSubState

(write-long \_currentSubState s)

;; bool \_success

(if \_success (write-byte -1 s) (write-byte 0 s))

;; string \_msg

(write-long (length \_msg) s) (princ \_msg s)

;;

(if (null strm) (get-output-stream-string s))))

(:deserialize

(buf &optional (ptr- 0))

;; int32 \_currentSubState

(setq \_currentSubState (sys::peek buf ptr- :integer)) (incf ptr- 4)

;; bool \_success

(setq \_success (not (= 0 (sys::peek buf ptr- :char)))) (incf ptr- 1)

;; string \_msg

(let (n) (setq n (sys::peek buf ptr- :integer)) (incf ptr- 4) (setq \_msg (subseq buf ptr- (+ ptr- n))) (incf ptr- n))

;;

self)

)

(defclass robotnik\_msgs\_new::ResetFromSubState

:super ros::object

:slots ())

(setf (get robotnik\_msgs\_new::ResetFromSubState :md5sum-) "0692f61f0c43fdbd6f19facf658f4c39")

(setf (get robotnik\_msgs\_new::ResetFromSubState :datatype-) "robotnik\_msgs\_new/ResetFromSubState")

(setf (get robotnik\_msgs\_new::ResetFromSubState :request) robotnik\_msgs\_new::ResetFromSubStateRequest)

(setf (get robotnik\_msgs\_new::ResetFromSubState :response) robotnik\_msgs\_new::ResetFromSubStateResponse)

(defmethod robotnik\_msgs\_new::ResetFromSubStateRequest

(:response () (instance robotnik\_msgs\_new::ResetFromSubStateResponse :init)))

(setf (get robotnik\_msgs\_new::ResetFromSubStateRequest :md5sum-) "0692f61f0c43fdbd6f19facf658f4c39")

(setf (get robotnik\_msgs\_new::ResetFromSubStateRequest :datatype-) "robotnik\_msgs\_new/ResetFromSubStateRequest")

(setf (get robotnik\_msgs\_new::ResetFromSubStateRequest :definition-)

"#new substate

int32 subState

---

# substate of the component when change

int32 currentSubState

# The change is correct

bool success

# Text message - additional status information

string msg

")

(setf (get robotnik\_msgs\_new::ResetFromSubStateResponse :md5sum-) "0692f61f0c43fdbd6f19facf658f4c39")

(setf (get robotnik\_msgs\_new::ResetFromSubStateResponse :datatype-) "robotnik\_msgs\_new/ResetFromSubStateResponse")

(setf (get robotnik\_msgs\_new::ResetFromSubStateResponse :definition-)

"#new substate

int32 subState

---

# substate of the component when change

int32 currentSubState

# The change is correct

bool success

# Text message - additional status information

string msg

")

(provide :robotnik\_msgs\_new/ResetFromSubState "0692f61f0c43fdbd6f19facf658f4c39")