;; Auto-generated. Do not edit!

(when (boundp 'robotnik\_msgs\_new::SetBuzzer)

(if (not (find-package "ROBOTNIK\_MSGS\_NEW"))

(make-package "ROBOTNIK\_MSGS\_NEW"))

(shadow 'SetBuzzer (find-package "ROBOTNIK\_MSGS\_NEW")))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::SETBUZZER")

(make-package "ROBOTNIK\_MSGS\_NEW::SETBUZZER"))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::SETBUZZERREQUEST")

(make-package "ROBOTNIK\_MSGS\_NEW::SETBUZZERREQUEST"))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::SETBUZZERRESPONSE")

(make-package "ROBOTNIK\_MSGS\_NEW::SETBUZZERRESPONSE"))

(in-package "ROS")

(defclass robotnik\_msgs\_new::SetBuzzerRequest

:super ros::object

:slots (\_enable \_beep\_freq \_time\_enabled ))

(defmethod robotnik\_msgs\_new::SetBuzzerRequest

(:init

(&key

((:enable \_\_enable) nil)

((:beep\_freq \_\_beep\_freq) 0.0)

((:time\_enabled \_\_time\_enabled) 0.0)

)

(send-super :init)

(setq \_enable \_\_enable)

(setq \_beep\_freq (float \_\_beep\_freq))

(setq \_time\_enabled (float \_\_time\_enabled))

self)

(:enable

(&optional \_\_enable)

(if \_\_enable (setq \_enable \_\_enable)) \_enable)

(:beep\_freq

(&optional \_\_beep\_freq)

(if \_\_beep\_freq (setq \_beep\_freq \_\_beep\_freq)) \_beep\_freq)

(:time\_enabled

(&optional \_\_time\_enabled)

(if \_\_time\_enabled (setq \_time\_enabled \_\_time\_enabled)) \_time\_enabled)

(:serialization-length

()

(+

;; bool \_enable

1

;; float64 \_beep\_freq

8

;; float64 \_time\_enabled

8

))

(:serialize

(&optional strm)

(let ((s (if strm strm

(make-string-output-stream (send self :serialization-length)))))

;; bool \_enable

(if \_enable (write-byte -1 s) (write-byte 0 s))

;; float64 \_beep\_freq

(sys::poke \_beep\_freq (send s :buffer) (send s :count) :double) (incf (stream-count s) 8)

;; float64 \_time\_enabled

(sys::poke \_time\_enabled (send s :buffer) (send s :count) :double) (incf (stream-count s) 8)

;;

(if (null strm) (get-output-stream-string s))))

(:deserialize

(buf &optional (ptr- 0))

;; bool \_enable

(setq \_enable (not (= 0 (sys::peek buf ptr- :char)))) (incf ptr- 1)

;; float64 \_beep\_freq

(setq \_beep\_freq (sys::peek buf ptr- :double)) (incf ptr- 8)

;; float64 \_time\_enabled

(setq \_time\_enabled (sys::peek buf ptr- :double)) (incf ptr- 8)

;;

self)

)

(defclass robotnik\_msgs\_new::SetBuzzerResponse

:super ros::object

:slots (\_msg \_ret ))

(defmethod robotnik\_msgs\_new::SetBuzzerResponse

(:init

(&key

((:msg \_\_msg) "")

((:ret \_\_ret) nil)

)

(send-super :init)

(setq \_msg (string \_\_msg))

(setq \_ret \_\_ret)

self)

(:msg

(&optional \_\_msg)

(if \_\_msg (setq \_msg \_\_msg)) \_msg)

(:ret

(&optional \_\_ret)

(if \_\_ret (setq \_ret \_\_ret)) \_ret)

(:serialization-length

()

(+

;; string \_msg

4 (length \_msg)

;; bool \_ret

1

))

(:serialize

(&optional strm)

(let ((s (if strm strm

(make-string-output-stream (send self :serialization-length)))))

;; string \_msg

(write-long (length \_msg) s) (princ \_msg s)

;; bool \_ret

(if \_ret (write-byte -1 s) (write-byte 0 s))

;;

(if (null strm) (get-output-stream-string s))))

(:deserialize

(buf &optional (ptr- 0))

;; string \_msg

(let (n) (setq n (sys::peek buf ptr- :integer)) (incf ptr- 4) (setq \_msg (subseq buf ptr- (+ ptr- n))) (incf ptr- n))

;; bool \_ret

(setq \_ret (not (= 0 (sys::peek buf ptr- :char)))) (incf ptr- 1)

;;

self)

)

(defclass robotnik\_msgs\_new::SetBuzzer

:super ros::object

:slots ())

(setf (get robotnik\_msgs\_new::SetBuzzer :md5sum-) "41793a7387718993b9d0e132905ea3e3")

(setf (get robotnik\_msgs\_new::SetBuzzer :datatype-) "robotnik\_msgs\_new/SetBuzzer")

(setf (get robotnik\_msgs\_new::SetBuzzer :request) robotnik\_msgs\_new::SetBuzzerRequest)

(setf (get robotnik\_msgs\_new::SetBuzzer :response) robotnik\_msgs\_new::SetBuzzerResponse)

(defmethod robotnik\_msgs\_new::SetBuzzerRequest

(:response () (instance robotnik\_msgs\_new::SetBuzzerResponse :init)))

(setf (get robotnik\_msgs\_new::SetBuzzerRequest :md5sum-) "41793a7387718993b9d0e132905ea3e3")

(setf (get robotnik\_msgs\_new::SetBuzzerRequest :datatype-) "robotnik\_msgs\_new/SetBuzzerRequest")

(setf (get robotnik\_msgs\_new::SetBuzzerRequest :definition-)

"bool enable

float64 beep\_freq

float64 time\_enabled

---

string msg

bool ret

")

(setf (get robotnik\_msgs\_new::SetBuzzerResponse :md5sum-) "41793a7387718993b9d0e132905ea3e3")

(setf (get robotnik\_msgs\_new::SetBuzzerResponse :datatype-) "robotnik\_msgs\_new/SetBuzzerResponse")

(setf (get robotnik\_msgs\_new::SetBuzzerResponse :definition-)

"bool enable

float64 beep\_freq

float64 time\_enabled

---

string msg

bool ret

")

(provide :robotnik\_msgs\_new/SetBuzzer "41793a7387718993b9d0e132905ea3e3")