;; Auto-generated. Do not edit!

(when (boundp 'robotnik\_msgs\_new::SetLaserMode)

(if (not (find-package "ROBOTNIK\_MSGS\_NEW"))

(make-package "ROBOTNIK\_MSGS\_NEW"))

(shadow 'SetLaserMode (find-package "ROBOTNIK\_MSGS\_NEW")))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::SETLASERMODE")

(make-package "ROBOTNIK\_MSGS\_NEW::SETLASERMODE"))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::SETLASERMODEREQUEST")

(make-package "ROBOTNIK\_MSGS\_NEW::SETLASERMODEREQUEST"))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::SETLASERMODERESPONSE")

(make-package "ROBOTNIK\_MSGS\_NEW::SETLASERMODERESPONSE"))

(in-package "ROS")

(defclass robotnik\_msgs\_new::SetLaserModeRequest

:super ros::object

:slots (\_mode ))

(defmethod robotnik\_msgs\_new::SetLaserModeRequest

(:init

(&key

((:mode \_\_mode) "")

)

(send-super :init)

(setq \_mode (string \_\_mode))

self)

(:mode

(&optional \_\_mode)

(if \_\_mode (setq \_mode \_\_mode)) \_mode)

(:serialization-length

()

(+

;; string \_mode

4 (length \_mode)

))

(:serialize

(&optional strm)

(let ((s (if strm strm

(make-string-output-stream (send self :serialization-length)))))

;; string \_mode

(write-long (length \_mode) s) (princ \_mode s)

;;

(if (null strm) (get-output-stream-string s))))

(:deserialize

(buf &optional (ptr- 0))

;; string \_mode

(let (n) (setq n (sys::peek buf ptr- :integer)) (incf ptr- 4) (setq \_mode (subseq buf ptr- (+ ptr- n))) (incf ptr- n))

;;

self)

)

(defclass robotnik\_msgs\_new::SetLaserModeResponse

:super ros::object

:slots (\_ret ))

(defmethod robotnik\_msgs\_new::SetLaserModeResponse

(:init

(&key

((:ret \_\_ret) nil)

)

(send-super :init)

(setq \_ret \_\_ret)

self)

(:ret

(&optional \_\_ret)

(if \_\_ret (setq \_ret \_\_ret)) \_ret)

(:serialization-length

()

(+

;; bool \_ret

1

))

(:serialize

(&optional strm)

(let ((s (if strm strm

(make-string-output-stream (send self :serialization-length)))))

;; bool \_ret

(if \_ret (write-byte -1 s) (write-byte 0 s))

;;

(if (null strm) (get-output-stream-string s))))

(:deserialize

(buf &optional (ptr- 0))

;; bool \_ret

(setq \_ret (not (= 0 (sys::peek buf ptr- :char)))) (incf ptr- 1)

;;

self)

)

(defclass robotnik\_msgs\_new::SetLaserMode

:super ros::object

:slots ())

(setf (get robotnik\_msgs\_new::SetLaserMode :md5sum-) "b696448a6984c2e37a93990a5f048086")

(setf (get robotnik\_msgs\_new::SetLaserMode :datatype-) "robotnik\_msgs\_new/SetLaserMode")

(setf (get robotnik\_msgs\_new::SetLaserMode :request) robotnik\_msgs\_new::SetLaserModeRequest)

(setf (get robotnik\_msgs\_new::SetLaserMode :response) robotnik\_msgs\_new::SetLaserModeResponse)

(defmethod robotnik\_msgs\_new::SetLaserModeRequest

(:response () (instance robotnik\_msgs\_new::SetLaserModeResponse :init)))

(setf (get robotnik\_msgs\_new::SetLaserModeRequest :md5sum-) "b696448a6984c2e37a93990a5f048086")

(setf (get robotnik\_msgs\_new::SetLaserModeRequest :datatype-) "robotnik\_msgs\_new/SetLaserModeRequest")

(setf (get robotnik\_msgs\_new::SetLaserModeRequest :definition-)

"string mode

---

bool ret

")

(setf (get robotnik\_msgs\_new::SetLaserModeResponse :md5sum-) "b696448a6984c2e37a93990a5f048086")

(setf (get robotnik\_msgs\_new::SetLaserModeResponse :datatype-) "robotnik\_msgs\_new/SetLaserModeResponse")

(setf (get robotnik\_msgs\_new::SetLaserModeResponse :definition-)

"string mode

---

bool ret

")

(provide :robotnik\_msgs\_new/SetLaserMode "b696448a6984c2e37a93990a5f048086")