;; Auto-generated. Do not edit!

(when (boundp 'robotnik\_msgs\_new::axis\_record)

(if (not (find-package "ROBOTNIK\_MSGS\_NEW"))

(make-package "ROBOTNIK\_MSGS\_NEW"))

(shadow 'axis\_record (find-package "ROBOTNIK\_MSGS\_NEW")))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::AXIS\_RECORD")

(make-package "ROBOTNIK\_MSGS\_NEW::AXIS\_RECORD"))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::AXIS\_RECORDREQUEST")

(make-package "ROBOTNIK\_MSGS\_NEW::AXIS\_RECORDREQUEST"))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::AXIS\_RECORDRESPONSE")

(make-package "ROBOTNIK\_MSGS\_NEW::AXIS\_RECORDRESPONSE"))

(in-package "ROS")

(defclass robotnik\_msgs\_new::axis\_recordRequest

:super ros::object

:slots (\_action \_directory \_profile \_id ))

(defmethod robotnik\_msgs\_new::axis\_recordRequest

(:init

(&key

((:action \_\_action) 0)

((:directory \_\_directory) "")

((:profile \_\_profile) "")

((:id \_\_id) "")

)

(send-super :init)

(setq \_action (round \_\_action))

(setq \_directory (string \_\_directory))

(setq \_profile (string \_\_profile))

(setq \_id (string \_\_id))

self)

(:action

(&optional \_\_action)

(if \_\_action (setq \_action \_\_action)) \_action)

(:directory

(&optional \_\_directory)

(if \_\_directory (setq \_directory \_\_directory)) \_directory)

(:profile

(&optional \_\_profile)

(if \_\_profile (setq \_profile \_\_profile)) \_profile)

(:id

(&optional \_\_id)

(if \_\_id (setq \_id \_\_id)) \_id)

(:serialization-length

()

(+

;; int8 \_action

1

;; string \_directory

4 (length \_directory)

;; string \_profile

4 (length \_profile)

;; string \_id

4 (length \_id)

))

(:serialize

(&optional strm)

(let ((s (if strm strm

(make-string-output-stream (send self :serialization-length)))))

;; int8 \_action

(write-byte \_action s)

;; string \_directory

(write-long (length \_directory) s) (princ \_directory s)

;; string \_profile

(write-long (length \_profile) s) (princ \_profile s)

;; string \_id

(write-long (length \_id) s) (princ \_id s)

;;

(if (null strm) (get-output-stream-string s))))

(:deserialize

(buf &optional (ptr- 0))

;; int8 \_action

(setq \_action (sys::peek buf ptr- :char)) (incf ptr- 1)

(if (> \_action 127) (setq \_action (- \_action 256)))

;; string \_directory

(let (n) (setq n (sys::peek buf ptr- :integer)) (incf ptr- 4) (setq \_directory (subseq buf ptr- (+ ptr- n))) (incf ptr- n))

;; string \_profile

(let (n) (setq n (sys::peek buf ptr- :integer)) (incf ptr- 4) (setq \_profile (subseq buf ptr- (+ ptr- n))) (incf ptr- n))

;; string \_id

(let (n) (setq n (sys::peek buf ptr- :integer)) (incf ptr- 4) (setq \_id (subseq buf ptr- (+ ptr- n))) (incf ptr- n))

;;

self)

)

(defclass robotnik\_msgs\_new::axis\_recordResponse

:super ros::object

:slots (\_ret ))

(defmethod robotnik\_msgs\_new::axis\_recordResponse

(:init

(&key

((:ret \_\_ret) nil)

)

(send-super :init)

(setq \_ret \_\_ret)

self)

(:ret

(&optional \_\_ret)

(if \_\_ret (setq \_ret \_\_ret)) \_ret)

(:serialization-length

()

(+

;; bool \_ret

1

))

(:serialize

(&optional strm)

(let ((s (if strm strm

(make-string-output-stream (send self :serialization-length)))))

;; bool \_ret

(if \_ret (write-byte -1 s) (write-byte 0 s))

;;

(if (null strm) (get-output-stream-string s))))

(:deserialize

(buf &optional (ptr- 0))

;; bool \_ret

(setq \_ret (not (= 0 (sys::peek buf ptr- :char)))) (incf ptr- 1)

;;

self)

)

(defclass robotnik\_msgs\_new::axis\_record

:super ros::object

:slots ())

(setf (get robotnik\_msgs\_new::axis\_record :md5sum-) "2c515c47879efbb7383294f44d5255c1")

(setf (get robotnik\_msgs\_new::axis\_record :datatype-) "robotnik\_msgs\_new/axis\_record")

(setf (get robotnik\_msgs\_new::axis\_record :request) robotnik\_msgs\_new::axis\_recordRequest)

(setf (get robotnik\_msgs\_new::axis\_record :response) robotnik\_msgs\_new::axis\_recordResponse)

(defmethod robotnik\_msgs\_new::axis\_recordRequest

(:response () (instance robotnik\_msgs\_new::axis\_recordResponse :init)))

(setf (get robotnik\_msgs\_new::axis\_recordRequest :md5sum-) "2c515c47879efbb7383294f44d5255c1")

(setf (get robotnik\_msgs\_new::axis\_recordRequest :datatype-) "robotnik\_msgs\_new/axis\_recordRequest")

(setf (get robotnik\_msgs\_new::axis\_recordRequest :definition-)

"#

# RECORD = 1, STOP = 2

int8 action

# DIRECTORY TO SAVE THE VIDEO

string directory

# PROFILE TO USE DURING THE RECORDING

string profile

# id / name of the recording

string id

---

bool ret

")

(setf (get robotnik\_msgs\_new::axis\_recordResponse :md5sum-) "2c515c47879efbb7383294f44d5255c1")

(setf (get robotnik\_msgs\_new::axis\_recordResponse :datatype-) "robotnik\_msgs\_new/axis\_recordResponse")

(setf (get robotnik\_msgs\_new::axis\_recordResponse :definition-)

"#

# RECORD = 1, STOP = 2

int8 action

# DIRECTORY TO SAVE THE VIDEO

string directory

# PROFILE TO USE DURING THE RECORDING

string profile

# id / name of the recording

string id

---

bool ret

")

(provide :robotnik\_msgs\_new/axis\_record "2c515c47879efbb7383294f44d5255c1")