;; Auto-generated. Do not edit!

(when (boundp 'robotnik\_msgs\_new::enable\_disable)

(if (not (find-package "ROBOTNIK\_MSGS\_NEW"))

(make-package "ROBOTNIK\_MSGS\_NEW"))

(shadow 'enable\_disable (find-package "ROBOTNIK\_MSGS\_NEW")))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::ENABLE\_DISABLE")

(make-package "ROBOTNIK\_MSGS\_NEW::ENABLE\_DISABLE"))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::ENABLE\_DISABLEREQUEST")

(make-package "ROBOTNIK\_MSGS\_NEW::ENABLE\_DISABLEREQUEST"))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::ENABLE\_DISABLERESPONSE")

(make-package "ROBOTNIK\_MSGS\_NEW::ENABLE\_DISABLERESPONSE"))

(in-package "ROS")

(defclass robotnik\_msgs\_new::enable\_disableRequest

:super ros::object

:slots (\_value ))

(defmethod robotnik\_msgs\_new::enable\_disableRequest

(:init

(&key

((:value \_\_value) nil)

)

(send-super :init)

(setq \_value \_\_value)

self)

(:value

(&optional \_\_value)

(if \_\_value (setq \_value \_\_value)) \_value)

(:serialization-length

()

(+

;; bool \_value

1

))

(:serialize

(&optional strm)

(let ((s (if strm strm

(make-string-output-stream (send self :serialization-length)))))

;; bool \_value

(if \_value (write-byte -1 s) (write-byte 0 s))

;;

(if (null strm) (get-output-stream-string s))))

(:deserialize

(buf &optional (ptr- 0))

;; bool \_value

(setq \_value (not (= 0 (sys::peek buf ptr- :char)))) (incf ptr- 1)

;;

self)

)

(defclass robotnik\_msgs\_new::enable\_disableResponse

:super ros::object

:slots (\_ret ))

(defmethod robotnik\_msgs\_new::enable\_disableResponse

(:init

(&key

((:ret \_\_ret) nil)

)

(send-super :init)

(setq \_ret \_\_ret)

self)

(:ret

(&optional \_\_ret)

(if \_\_ret (setq \_ret \_\_ret)) \_ret)

(:serialization-length

()

(+

;; bool \_ret

1

))

(:serialize

(&optional strm)

(let ((s (if strm strm

(make-string-output-stream (send self :serialization-length)))))

;; bool \_ret

(if \_ret (write-byte -1 s) (write-byte 0 s))

;;

(if (null strm) (get-output-stream-string s))))

(:deserialize

(buf &optional (ptr- 0))

;; bool \_ret

(setq \_ret (not (= 0 (sys::peek buf ptr- :char)))) (incf ptr- 1)

;;

self)

)

(defclass robotnik\_msgs\_new::enable\_disable

:super ros::object

:slots ())

(setf (get robotnik\_msgs\_new::enable\_disable :md5sum-) "44aff93ccf05e13b2ec5d62303a837a2")

(setf (get robotnik\_msgs\_new::enable\_disable :datatype-) "robotnik\_msgs\_new/enable\_disable")

(setf (get robotnik\_msgs\_new::enable\_disable :request) robotnik\_msgs\_new::enable\_disableRequest)

(setf (get robotnik\_msgs\_new::enable\_disable :response) robotnik\_msgs\_new::enable\_disableResponse)

(defmethod robotnik\_msgs\_new::enable\_disableRequest

(:response () (instance robotnik\_msgs\_new::enable\_disableResponse :init)))

(setf (get robotnik\_msgs\_new::enable\_disableRequest :md5sum-) "44aff93ccf05e13b2ec5d62303a837a2")

(setf (get robotnik\_msgs\_new::enable\_disableRequest :datatype-) "robotnik\_msgs\_new/enable\_disableRequest")

(setf (get robotnik\_msgs\_new::enable\_disableRequest :definition-)

"bool value

---

bool ret

")

(setf (get robotnik\_msgs\_new::enable\_disableResponse :md5sum-) "44aff93ccf05e13b2ec5d62303a837a2")

(setf (get robotnik\_msgs\_new::enable\_disableResponse :datatype-) "robotnik\_msgs\_new/enable\_disableResponse")

(setf (get robotnik\_msgs\_new::enable\_disableResponse :definition-)

"bool value

---

bool ret

")

(provide :robotnik\_msgs\_new/enable\_disable "44aff93ccf05e13b2ec5d62303a837a2")