;; Auto-generated. Do not edit!

(when (boundp 'robotnik\_msgs\_new::get\_alarms)

(if (not (find-package "ROBOTNIK\_MSGS\_NEW"))

(make-package "ROBOTNIK\_MSGS\_NEW"))

(shadow 'get\_alarms (find-package "ROBOTNIK\_MSGS\_NEW")))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::GET\_ALARMS")

(make-package "ROBOTNIK\_MSGS\_NEW::GET\_ALARMS"))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::GET\_ALARMSREQUEST")

(make-package "ROBOTNIK\_MSGS\_NEW::GET\_ALARMSREQUEST"))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::GET\_ALARMSRESPONSE")

(make-package "ROBOTNIK\_MSGS\_NEW::GET\_ALARMSRESPONSE"))

(in-package "ROS")

(defclass robotnik\_msgs\_new::get\_alarmsRequest

:super ros::object

:slots ())

(defmethod robotnik\_msgs\_new::get\_alarmsRequest

(:init

(&key

)

(send-super :init)

self)

(:serialization-length

()

(+

0

))

(:serialize

(&optional strm)

(let ((s (if strm strm

(make-string-output-stream (send self :serialization-length)))))

;;

(if (null strm) (get-output-stream-string s))))

(:deserialize

(buf &optional (ptr- 0))

;;

self)

)

(defclass robotnik\_msgs\_new::get\_alarmsResponse

:super ros::object

:slots (\_alarms ))

(defmethod robotnik\_msgs\_new::get\_alarmsResponse

(:init

(&key

((:alarms \_\_alarms) (instance robotnik\_msgs\_new::alarmsmonitor :init))

)

(send-super :init)

(setq \_alarms \_\_alarms)

self)

(:alarms

(&rest \_\_alarms)

(if (keywordp (car \_\_alarms))

(send\* \_alarms \_\_alarms)

(progn

(if \_\_alarms (setq \_alarms (car \_\_alarms)))

\_alarms)))

(:serialization-length

()

(+

;; robotnik\_msgs\_new/alarmsmonitor \_alarms

(send \_alarms :serialization-length)

))

(:serialize

(&optional strm)

(let ((s (if strm strm

(make-string-output-stream (send self :serialization-length)))))

;; robotnik\_msgs\_new/alarmsmonitor \_alarms

(send \_alarms :serialize s)

;;

(if (null strm) (get-output-stream-string s))))

(:deserialize

(buf &optional (ptr- 0))

;; robotnik\_msgs\_new/alarmsmonitor \_alarms

(send \_alarms :deserialize buf ptr-) (incf ptr- (send \_alarms :serialization-length))

;;

self)

)

(defclass robotnik\_msgs\_new::get\_alarms

:super ros::object

:slots ())

(setf (get robotnik\_msgs\_new::get\_alarms :md5sum-) "4550354b6bec7529a93833858063eaed")

(setf (get robotnik\_msgs\_new::get\_alarms :datatype-) "robotnik\_msgs\_new/get\_alarms")

(setf (get robotnik\_msgs\_new::get\_alarms :request) robotnik\_msgs\_new::get\_alarmsRequest)

(setf (get robotnik\_msgs\_new::get\_alarms :response) robotnik\_msgs\_new::get\_alarmsResponse)

(defmethod robotnik\_msgs\_new::get\_alarmsRequest

(:response () (instance robotnik\_msgs\_new::get\_alarmsResponse :init)))

(setf (get robotnik\_msgs\_new::get\_alarmsRequest :md5sum-) "4550354b6bec7529a93833858063eaed")

(setf (get robotnik\_msgs\_new::get\_alarmsRequest :datatype-) "robotnik\_msgs\_new/get\_alarmsRequest")

(setf (get robotnik\_msgs\_new::get\_alarmsRequest :definition-)

"

---

alarmsmonitor alarms

================================================================================

MSG: robotnik\_msgs\_new/alarmsmonitor

alarmmonitor[] alarms

================================================================================

MSG: robotnik\_msgs\_new/alarmmonitor

# type: error, warning, event

string type

# displaing number for monitoring

int32 display

# component

string component

# To be shown in HMI

bool hmi

# group: alarm group all alarms of same group will be reset at same time

string group

# text: more explained information about alarm, should include group, time, conditions, etc

string text

# seconds active

uint64 seconds\_active

")

(setf (get robotnik\_msgs\_new::get\_alarmsResponse :md5sum-) "4550354b6bec7529a93833858063eaed")

(setf (get robotnik\_msgs\_new::get\_alarmsResponse :datatype-) "robotnik\_msgs\_new/get\_alarmsResponse")

(setf (get robotnik\_msgs\_new::get\_alarmsResponse :definition-)

"

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(provide :robotnik\_msgs\_new/get\_alarms "4550354b6bec7529a93833858063eaed")