;; Auto-generated. Do not edit!

(when (boundp 'robotnik\_msgs\_new::get\_digital\_input)

(if (not (find-package "ROBOTNIK\_MSGS\_NEW"))

(make-package "ROBOTNIK\_MSGS\_NEW"))

(shadow 'get\_digital\_input (find-package "ROBOTNIK\_MSGS\_NEW")))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::GET\_DIGITAL\_INPUT")

(make-package "ROBOTNIK\_MSGS\_NEW::GET\_DIGITAL\_INPUT"))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::GET\_DIGITAL\_INPUTREQUEST")

(make-package "ROBOTNIK\_MSGS\_NEW::GET\_DIGITAL\_INPUTREQUEST"))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::GET\_DIGITAL\_INPUTRESPONSE")

(make-package "ROBOTNIK\_MSGS\_NEW::GET\_DIGITAL\_INPUTRESPONSE"))

(in-package "ROS")

(defclass robotnik\_msgs\_new::get\_digital\_inputRequest

:super ros::object

:slots (\_input ))

(defmethod robotnik\_msgs\_new::get\_digital\_inputRequest

(:init

(&key

((:input \_\_input) 0)

)

(send-super :init)

(setq \_input (round \_\_input))

self)

(:input

(&optional \_\_input)

(if \_\_input (setq \_input \_\_input)) \_input)

(:serialization-length

()

(+

;; int8 \_input

1

))

(:serialize

(&optional strm)

(let ((s (if strm strm

(make-string-output-stream (send self :serialization-length)))))

;; int8 \_input

(write-byte \_input s)

;;

(if (null strm) (get-output-stream-string s))))

(:deserialize

(buf &optional (ptr- 0))

;; int8 \_input

(setq \_input (sys::peek buf ptr- :char)) (incf ptr- 1)

(if (> \_input 127) (setq \_input (- \_input 256)))

;;

self)

)

(defclass robotnik\_msgs\_new::get\_digital\_inputResponse

:super ros::object

:slots (\_value ))

(defmethod robotnik\_msgs\_new::get\_digital\_inputResponse

(:init

(&key

((:value \_\_value) nil)

)

(send-super :init)

(setq \_value \_\_value)

self)

(:value

(&optional \_\_value)

(if \_\_value (setq \_value \_\_value)) \_value)

(:serialization-length

()

(+

;; bool \_value

1

))

(:serialize

(&optional strm)

(let ((s (if strm strm

(make-string-output-stream (send self :serialization-length)))))

;; bool \_value

(if \_value (write-byte -1 s) (write-byte 0 s))

;;

(if (null strm) (get-output-stream-string s))))

(:deserialize

(buf &optional (ptr- 0))

;; bool \_value

(setq \_value (not (= 0 (sys::peek buf ptr- :char)))) (incf ptr- 1)

;;

self)

)

(defclass robotnik\_msgs\_new::get\_digital\_input

:super ros::object

:slots ())

(setf (get robotnik\_msgs\_new::get\_digital\_input :md5sum-) "5b85083879fa36068de8cd28363930b7")

(setf (get robotnik\_msgs\_new::get\_digital\_input :datatype-) "robotnik\_msgs\_new/get\_digital\_input")

(setf (get robotnik\_msgs\_new::get\_digital\_input :request) robotnik\_msgs\_new::get\_digital\_inputRequest)

(setf (get robotnik\_msgs\_new::get\_digital\_input :response) robotnik\_msgs\_new::get\_digital\_inputResponse)

(defmethod robotnik\_msgs\_new::get\_digital\_inputRequest

(:response () (instance robotnik\_msgs\_new::get\_digital\_inputResponse :init)))

(setf (get robotnik\_msgs\_new::get\_digital\_inputRequest :md5sum-) "5b85083879fa36068de8cd28363930b7")

(setf (get robotnik\_msgs\_new::get\_digital\_inputRequest :datatype-) "robotnik\_msgs\_new/get\_digital\_inputRequest")

(setf (get robotnik\_msgs\_new::get\_digital\_inputRequest :definition-)

"int8 input

---

bool value

")

(setf (get robotnik\_msgs\_new::get\_digital\_inputResponse :md5sum-) "5b85083879fa36068de8cd28363930b7")

(setf (get robotnik\_msgs\_new::get\_digital\_inputResponse :datatype-) "robotnik\_msgs\_new/get\_digital\_inputResponse")

(setf (get robotnik\_msgs\_new::get\_digital\_inputResponse :definition-)

"int8 input

---

bool value

")

(provide :robotnik\_msgs\_new/get\_digital\_input "5b85083879fa36068de8cd28363930b7")