;; Auto-generated. Do not edit!

(when (boundp 'robotnik\_msgs\_new::get\_mode)

(if (not (find-package "ROBOTNIK\_MSGS\_NEW"))

(make-package "ROBOTNIK\_MSGS\_NEW"))

(shadow 'get\_mode (find-package "ROBOTNIK\_MSGS\_NEW")))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::GET\_MODE")

(make-package "ROBOTNIK\_MSGS\_NEW::GET\_MODE"))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::GET\_MODEREQUEST")

(make-package "ROBOTNIK\_MSGS\_NEW::GET\_MODEREQUEST"))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::GET\_MODERESPONSE")

(make-package "ROBOTNIK\_MSGS\_NEW::GET\_MODERESPONSE"))

(in-package "ROS")

(defclass robotnik\_msgs\_new::get\_modeRequest

:super ros::object

:slots ())

(defmethod robotnik\_msgs\_new::get\_modeRequest

(:init

(&key

)

(send-super :init)

self)

(:serialization-length

()

(+

0

))

(:serialize

(&optional strm)

(let ((s (if strm strm

(make-string-output-stream (send self :serialization-length)))))

;;

(if (null strm) (get-output-stream-string s))))

(:deserialize

(buf &optional (ptr- 0))

;;

self)

)

(defclass robotnik\_msgs\_new::get\_modeResponse

:super ros::object

:slots (\_mode ))

(defmethod robotnik\_msgs\_new::get\_modeResponse

(:init

(&key

((:mode \_\_mode) 0)

)

(send-super :init)

(setq \_mode (round \_\_mode))

self)

(:mode

(&optional \_\_mode)

(if \_\_mode (setq \_mode \_\_mode)) \_mode)

(:serialization-length

()

(+

;; int8 \_mode

1

))

(:serialize

(&optional strm)

(let ((s (if strm strm

(make-string-output-stream (send self :serialization-length)))))

;; int8 \_mode

(write-byte \_mode s)

;;

(if (null strm) (get-output-stream-string s))))

(:deserialize

(buf &optional (ptr- 0))

;; int8 \_mode

(setq \_mode (sys::peek buf ptr- :char)) (incf ptr- 1)

(if (> \_mode 127) (setq \_mode (- \_mode 256)))

;;

self)

)

(defclass robotnik\_msgs\_new::get\_mode

:super ros::object

:slots ())

(setf (get robotnik\_msgs\_new::get\_mode :md5sum-) "418c02483a8ca57215fb7b31c5c87234")

(setf (get robotnik\_msgs\_new::get\_mode :datatype-) "robotnik\_msgs\_new/get\_mode")

(setf (get robotnik\_msgs\_new::get\_mode :request) robotnik\_msgs\_new::get\_modeRequest)

(setf (get robotnik\_msgs\_new::get\_mode :response) robotnik\_msgs\_new::get\_modeResponse)

(defmethod robotnik\_msgs\_new::get\_modeRequest

(:response () (instance robotnik\_msgs\_new::get\_modeResponse :init)))

(setf (get robotnik\_msgs\_new::get\_modeRequest :md5sum-) "418c02483a8ca57215fb7b31c5c87234")

(setf (get robotnik\_msgs\_new::get\_modeRequest :datatype-) "robotnik\_msgs\_new/get\_modeRequest")

(setf (get robotnik\_msgs\_new::get\_modeRequest :definition-)

"---

int8 mode

")

(setf (get robotnik\_msgs\_new::get\_modeResponse :md5sum-) "418c02483a8ca57215fb7b31c5c87234")

(setf (get robotnik\_msgs\_new::get\_modeResponse :datatype-) "robotnik\_msgs\_new/get\_modeResponse")

(setf (get robotnik\_msgs\_new::get\_modeResponse :definition-)

"---

int8 mode

")

(provide :robotnik\_msgs\_new/get\_mode "418c02483a8ca57215fb7b31c5c87234")