;; Auto-generated. Do not edit!

(when (boundp 'robotnik\_msgs\_new::set\_float\_value)

(if (not (find-package "ROBOTNIK\_MSGS\_NEW"))

(make-package "ROBOTNIK\_MSGS\_NEW"))

(shadow 'set\_float\_value (find-package "ROBOTNIK\_MSGS\_NEW")))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::SET\_FLOAT\_VALUE")

(make-package "ROBOTNIK\_MSGS\_NEW::SET\_FLOAT\_VALUE"))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::SET\_FLOAT\_VALUEREQUEST")

(make-package "ROBOTNIK\_MSGS\_NEW::SET\_FLOAT\_VALUEREQUEST"))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::SET\_FLOAT\_VALUERESPONSE")

(make-package "ROBOTNIK\_MSGS\_NEW::SET\_FLOAT\_VALUERESPONSE"))

(in-package "ROS")

(if (not (find-package "STD\_MSGS"))

(ros::roseus-add-msgs "std\_msgs"))

(defclass robotnik\_msgs\_new::set\_float\_valueRequest

:super ros::object

:slots (\_value ))

(defmethod robotnik\_msgs\_new::set\_float\_valueRequest

(:init

(&key

((:value \_\_value) 0.0)

)

(send-super :init)

(setq \_value (float \_\_value))

self)

(:value

(&optional \_\_value)

(if \_\_value (setq \_value \_\_value)) \_value)

(:serialization-length

()

(+

;; float32 \_value

4

))

(:serialize

(&optional strm)

(let ((s (if strm strm

(make-string-output-stream (send self :serialization-length)))))

;; float32 \_value

(sys::poke \_value (send s :buffer) (send s :count) :float) (incf (stream-count s) 4)

;;

(if (null strm) (get-output-stream-string s))))

(:deserialize

(buf &optional (ptr- 0))

;; float32 \_value

(setq \_value (sys::peek buf ptr- :float)) (incf ptr- 4)

;;

self)

)

(defclass robotnik\_msgs\_new::set\_float\_valueResponse

:super ros::object

:slots (\_ret \_errorMessage ))

(defmethod robotnik\_msgs\_new::set\_float\_valueResponse

(:init

(&key

((:ret \_\_ret) nil)

((:errorMessage \_\_errorMessage) (instance std\_msgs::String :init))

)

(send-super :init)

(setq \_ret \_\_ret)

(setq \_errorMessage \_\_errorMessage)

self)

(:ret

(&optional \_\_ret)

(if \_\_ret (setq \_ret \_\_ret)) \_ret)

(:errorMessage

(&rest \_\_errorMessage)

(if (keywordp (car \_\_errorMessage))

(send\* \_errorMessage \_\_errorMessage)

(progn

(if \_\_errorMessage (setq \_errorMessage (car \_\_errorMessage)))

\_errorMessage)))

(:serialization-length

()

(+

;; bool \_ret

1

;; std\_msgs/String \_errorMessage

(send \_errorMessage :serialization-length)

))

(:serialize

(&optional strm)

(let ((s (if strm strm

(make-string-output-stream (send self :serialization-length)))))

;; bool \_ret

(if \_ret (write-byte -1 s) (write-byte 0 s))

;; std\_msgs/String \_errorMessage

(send \_errorMessage :serialize s)

;;

(if (null strm) (get-output-stream-string s))))

(:deserialize

(buf &optional (ptr- 0))

;; bool \_ret

(setq \_ret (not (= 0 (sys::peek buf ptr- :char)))) (incf ptr- 1)

;; std\_msgs/String \_errorMessage

(send \_errorMessage :deserialize buf ptr-) (incf ptr- (send \_errorMessage :serialization-length))

;;

self)

)

(defclass robotnik\_msgs\_new::set\_float\_value

:super ros::object

:slots ())

(setf (get robotnik\_msgs\_new::set\_float\_value :md5sum-) "1040fd23868f733b1106a6a6948ae41b")

(setf (get robotnik\_msgs\_new::set\_float\_value :datatype-) "robotnik\_msgs\_new/set\_float\_value")

(setf (get robotnik\_msgs\_new::set\_float\_value :request) robotnik\_msgs\_new::set\_float\_valueRequest)

(setf (get robotnik\_msgs\_new::set\_float\_value :response) robotnik\_msgs\_new::set\_float\_valueResponse)

(defmethod robotnik\_msgs\_new::set\_float\_valueRequest

(:response () (instance robotnik\_msgs\_new::set\_float\_valueResponse :init)))

(setf (get robotnik\_msgs\_new::set\_float\_valueRequest :md5sum-) "1040fd23868f733b1106a6a6948ae41b")

(setf (get robotnik\_msgs\_new::set\_float\_valueRequest :datatype-) "robotnik\_msgs\_new/set\_float\_valueRequest")

(setf (get robotnik\_msgs\_new::set\_float\_valueRequest :definition-)

"float32 value

---

bool ret

std\_msgs/String errorMessage

================================================================================

MSG: std\_msgs/String

string data

")

(setf (get robotnik\_msgs\_new::set\_float\_valueResponse :md5sum-) "1040fd23868f733b1106a6a6948ae41b")

(setf (get robotnik\_msgs\_new::set\_float\_valueResponse :datatype-) "robotnik\_msgs\_new/set\_float\_valueResponse")

(setf (get robotnik\_msgs\_new::set\_float\_valueResponse :definition-)

"float32 value

---

bool ret

std\_msgs/String errorMessage

================================================================================

MSG: std\_msgs/String

string data

")

(provide :robotnik\_msgs\_new/set\_float\_value "1040fd23868f733b1106a6a6948ae41b")