;; Auto-generated. Do not edit!

(when (boundp 'robotnik\_msgs\_new::set\_height)

(if (not (find-package "ROBOTNIK\_MSGS\_NEW"))

(make-package "ROBOTNIK\_MSGS\_NEW"))

(shadow 'set\_height (find-package "ROBOTNIK\_MSGS\_NEW")))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::SET\_HEIGHT")

(make-package "ROBOTNIK\_MSGS\_NEW::SET\_HEIGHT"))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::SET\_HEIGHTREQUEST")

(make-package "ROBOTNIK\_MSGS\_NEW::SET\_HEIGHTREQUEST"))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::SET\_HEIGHTRESPONSE")

(make-package "ROBOTNIK\_MSGS\_NEW::SET\_HEIGHTRESPONSE"))

(in-package "ROS")

(defclass robotnik\_msgs\_new::set\_heightRequest

:super ros::object

:slots (\_height ))

(defmethod robotnik\_msgs\_new::set\_heightRequest

(:init

(&key

((:height \_\_height) 0.0)

)

(send-super :init)

(setq \_height (float \_\_height))

self)

(:height

(&optional \_\_height)

(if \_\_height (setq \_height \_\_height)) \_height)

(:serialization-length

()

(+

;; float32 \_height

4

))

(:serialize

(&optional strm)

(let ((s (if strm strm

(make-string-output-stream (send self :serialization-length)))))

;; float32 \_height

(sys::poke \_height (send s :buffer) (send s :count) :float) (incf (stream-count s) 4)

;;

(if (null strm) (get-output-stream-string s))))

(:deserialize

(buf &optional (ptr- 0))

;; float32 \_height

(setq \_height (sys::peek buf ptr- :float)) (incf ptr- 4)

;;

self)

)

(defclass robotnik\_msgs\_new::set\_heightResponse

:super ros::object

:slots (\_ret ))

(defmethod robotnik\_msgs\_new::set\_heightResponse

(:init

(&key

((:ret \_\_ret) nil)

)

(send-super :init)

(setq \_ret \_\_ret)

self)

(:ret

(&optional \_\_ret)

(if \_\_ret (setq \_ret \_\_ret)) \_ret)

(:serialization-length

()

(+

;; bool \_ret

1

))

(:serialize

(&optional strm)

(let ((s (if strm strm

(make-string-output-stream (send self :serialization-length)))))

;; bool \_ret

(if \_ret (write-byte -1 s) (write-byte 0 s))

;;

(if (null strm) (get-output-stream-string s))))

(:deserialize

(buf &optional (ptr- 0))

;; bool \_ret

(setq \_ret (not (= 0 (sys::peek buf ptr- :char)))) (incf ptr- 1)

;;

self)

)

(defclass robotnik\_msgs\_new::set\_height

:super ros::object

:slots ())

(setf (get robotnik\_msgs\_new::set\_height :md5sum-) "30c54779fb893ca6d32239f321774b5f")

(setf (get robotnik\_msgs\_new::set\_height :datatype-) "robotnik\_msgs\_new/set\_height")

(setf (get robotnik\_msgs\_new::set\_height :request) robotnik\_msgs\_new::set\_heightRequest)

(setf (get robotnik\_msgs\_new::set\_height :response) robotnik\_msgs\_new::set\_heightResponse)

(defmethod robotnik\_msgs\_new::set\_heightRequest

(:response () (instance robotnik\_msgs\_new::set\_heightResponse :init)))

(setf (get robotnik\_msgs\_new::set\_heightRequest :md5sum-) "30c54779fb893ca6d32239f321774b5f")

(setf (get robotnik\_msgs\_new::set\_heightRequest :datatype-) "robotnik\_msgs\_new/set\_heightRequest")

(setf (get robotnik\_msgs\_new::set\_heightRequest :definition-)

"# New reference position (m)

float32 height

---

bool ret

")

(setf (get robotnik\_msgs\_new::set\_heightResponse :md5sum-) "30c54779fb893ca6d32239f321774b5f")

(setf (get robotnik\_msgs\_new::set\_heightResponse :datatype-) "robotnik\_msgs\_new/set\_heightResponse")

(setf (get robotnik\_msgs\_new::set\_heightResponse :definition-)

"# New reference position (m)

float32 height

---

bool ret

")

(provide :robotnik\_msgs\_new/set\_height "30c54779fb893ca6d32239f321774b5f")