;; Auto-generated. Do not edit!

(when (boundp 'robotnik\_msgs\_new::set\_mode)

(if (not (find-package "ROBOTNIK\_MSGS\_NEW"))

(make-package "ROBOTNIK\_MSGS\_NEW"))

(shadow 'set\_mode (find-package "ROBOTNIK\_MSGS\_NEW")))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::SET\_MODE")

(make-package "ROBOTNIK\_MSGS\_NEW::SET\_MODE"))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::SET\_MODEREQUEST")

(make-package "ROBOTNIK\_MSGS\_NEW::SET\_MODEREQUEST"))

(unless (find-package "ROBOTNIK\_MSGS\_NEW::SET\_MODERESPONSE")

(make-package "ROBOTNIK\_MSGS\_NEW::SET\_MODERESPONSE"))

(in-package "ROS")

(defclass robotnik\_msgs\_new::set\_modeRequest

:super ros::object

:slots (\_mode ))

(defmethod robotnik\_msgs\_new::set\_modeRequest

(:init

(&key

((:mode \_\_mode) 0)

)

(send-super :init)

(setq \_mode (round \_\_mode))

self)

(:mode

(&optional \_\_mode)

(if \_\_mode (setq \_mode \_\_mode)) \_mode)

(:serialization-length

()

(+

;; int8 \_mode

1

))

(:serialize

(&optional strm)

(let ((s (if strm strm

(make-string-output-stream (send self :serialization-length)))))

;; int8 \_mode

(write-byte \_mode s)

;;

(if (null strm) (get-output-stream-string s))))

(:deserialize

(buf &optional (ptr- 0))

;; int8 \_mode

(setq \_mode (sys::peek buf ptr- :char)) (incf ptr- 1)

(if (> \_mode 127) (setq \_mode (- \_mode 256)))

;;

self)

)

(defclass robotnik\_msgs\_new::set\_modeResponse

:super ros::object

:slots (\_ret ))

(defmethod robotnik\_msgs\_new::set\_modeResponse

(:init

(&key

((:ret \_\_ret) nil)

)

(send-super :init)

(setq \_ret \_\_ret)

self)

(:ret

(&optional \_\_ret)

(if \_\_ret (setq \_ret \_\_ret)) \_ret)

(:serialization-length

()

(+

;; bool \_ret

1

))

(:serialize

(&optional strm)

(let ((s (if strm strm

(make-string-output-stream (send self :serialization-length)))))

;; bool \_ret

(if \_ret (write-byte -1 s) (write-byte 0 s))

;;

(if (null strm) (get-output-stream-string s))))

(:deserialize

(buf &optional (ptr- 0))

;; bool \_ret

(setq \_ret (not (= 0 (sys::peek buf ptr- :char)))) (incf ptr- 1)

;;

self)

)

(defclass robotnik\_msgs\_new::set\_mode

:super ros::object

:slots ())

(setf (get robotnik\_msgs\_new::set\_mode :md5sum-) "961700910d81510cfbb56c2b771e2e2f")

(setf (get robotnik\_msgs\_new::set\_mode :datatype-) "robotnik\_msgs\_new/set\_mode")

(setf (get robotnik\_msgs\_new::set\_mode :request) robotnik\_msgs\_new::set\_modeRequest)

(setf (get robotnik\_msgs\_new::set\_mode :response) robotnik\_msgs\_new::set\_modeResponse)

(defmethod robotnik\_msgs\_new::set\_modeRequest

(:response () (instance robotnik\_msgs\_new::set\_modeResponse :init)))

(setf (get robotnik\_msgs\_new::set\_modeRequest :md5sum-) "961700910d81510cfbb56c2b771e2e2f")

(setf (get robotnik\_msgs\_new::set\_modeRequest :datatype-) "robotnik\_msgs\_new/set\_modeRequest")

(setf (get robotnik\_msgs\_new::set\_modeRequest :definition-)

"# Set control / kinematic / etc. mode

int8 mode

---

bool ret

")

(setf (get robotnik\_msgs\_new::set\_modeResponse :md5sum-) "961700910d81510cfbb56c2b771e2e2f")

(setf (get robotnik\_msgs\_new::set\_modeResponse :datatype-) "robotnik\_msgs\_new/set\_modeResponse")

(setf (get robotnik\_msgs\_new::set\_modeResponse :definition-)

"# Set control / kinematic / etc. mode

int8 mode

---

bool ret

")

(provide :robotnik\_msgs\_new/set\_mode "961700910d81510cfbb56c2b771e2e2f")