;;

;; DO NOT EDIT THIS FILE

;;

;; THIS FILE IS AUTOMATICALLY GENERATED

;; FROM /home/adi/Downloads/GazeboSimulation/src/rb\_kairos\_sim\_new/summit\_xl\_common\_new/summit\_xl\_pad\_new/package.xml (1.1.3)

;; USING /opt/ros/melodic/lib/python2.7/dist-packages/geneus/geneus\_main.pyc /opt/ros/melodic/share/geneus/package.xml (2.2.6)

;;

(ros::load-ros-package "actionlib\_msgs")

(ros::load-ros-package "diagnostic\_msgs")

(ros::load-ros-package "geometry\_msgs")

(ros::load-ros-package "robotnik\_msgs\_new")

(ros::load-ros-package "roscpp")

(ros::load-ros-package "rosgraph\_msgs")

(ros::load-ros-package "sensor\_msgs")

(ros::load-ros-package "std\_msgs")

(ros::load-ros-package "summit\_xl\_pad\_new")

(ros::load-ros-package "summit\_xl\_pad\_new")