

Characterising spatial noise to understand performance limitations in Multiple Object Tracking

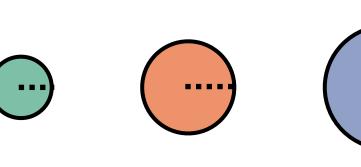
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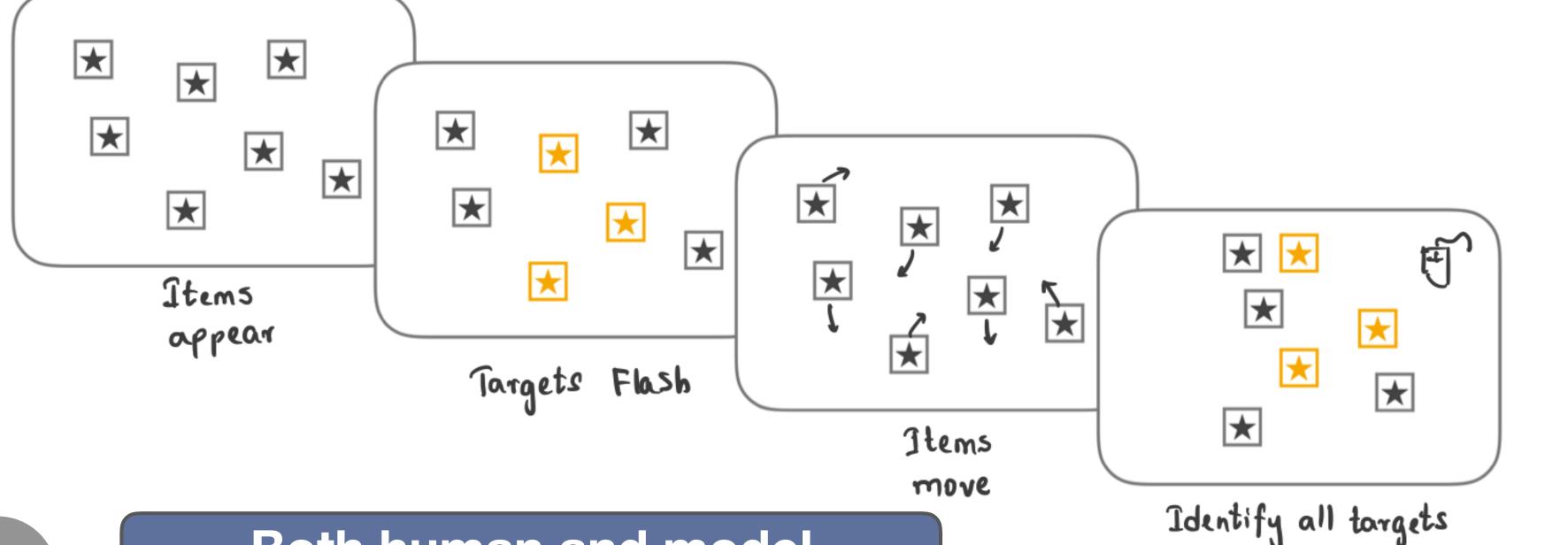


Experiment 1: Manipulate Object size in MOT

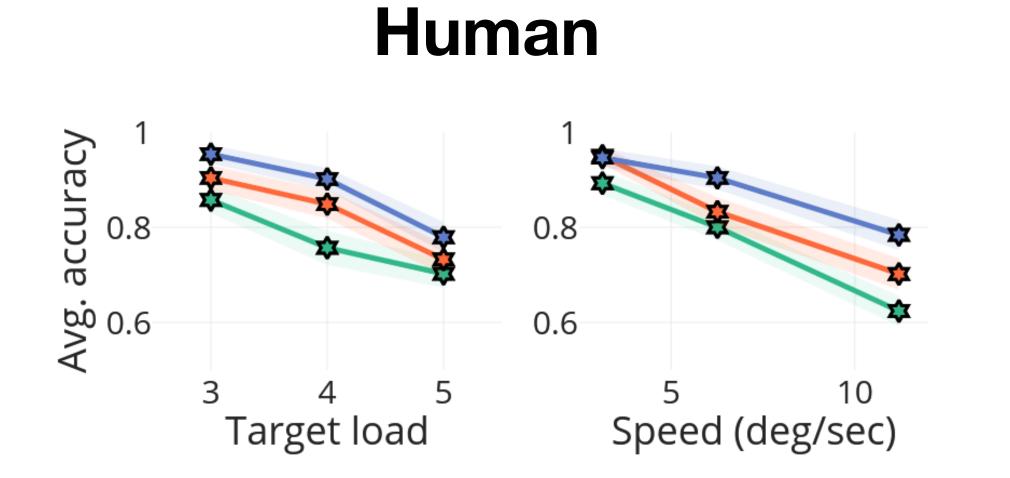
Logic

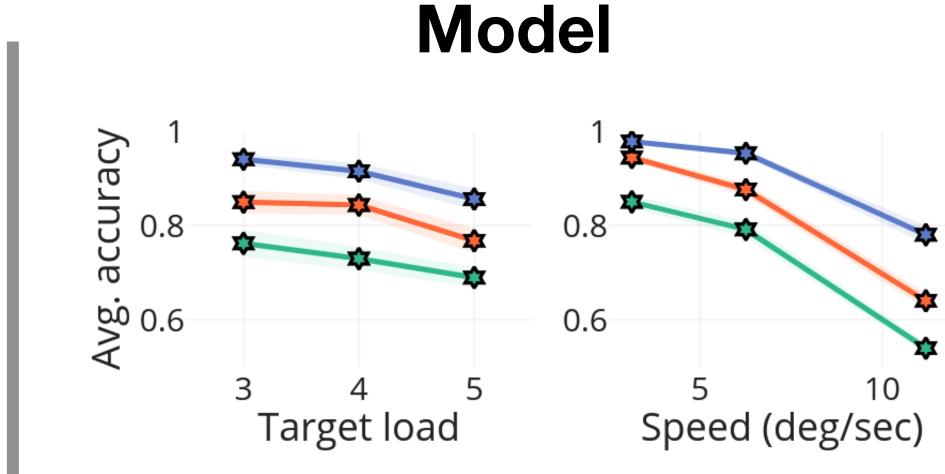
Manipulate object size because it should interact with eccentricity, and it's not usually manipulated. 0.5^o 0.75^o



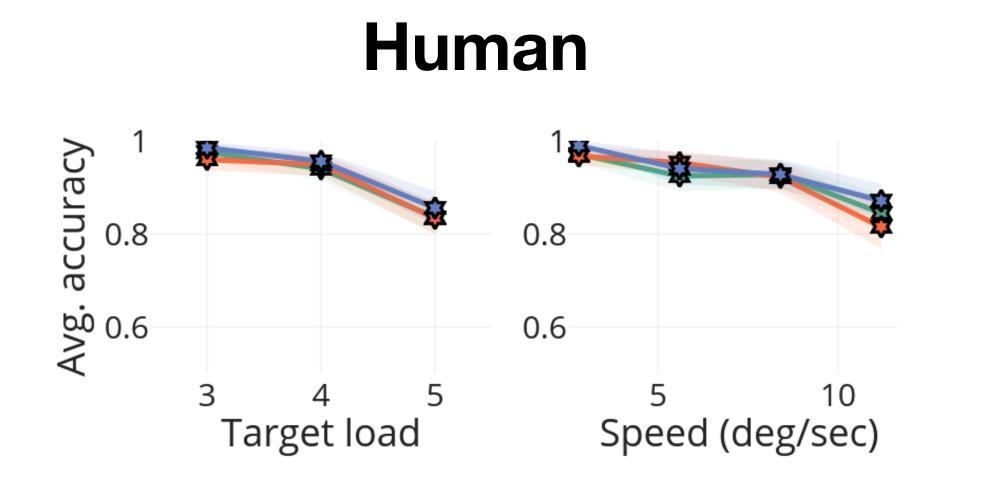


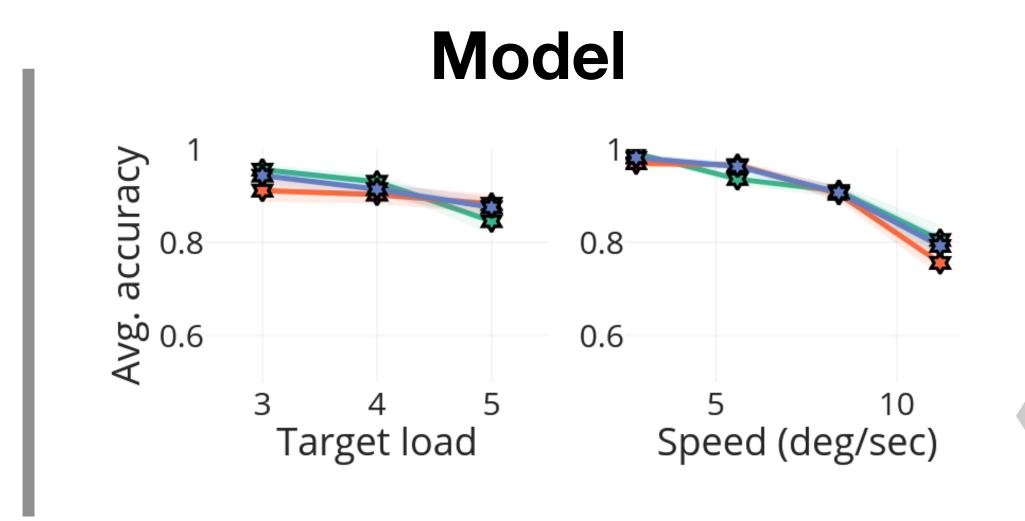
Both human and model performance are affected by size





But not when we control for center to center distances. (by making trajectories for the largest objects, and then using those for all sizes)





A long term goal

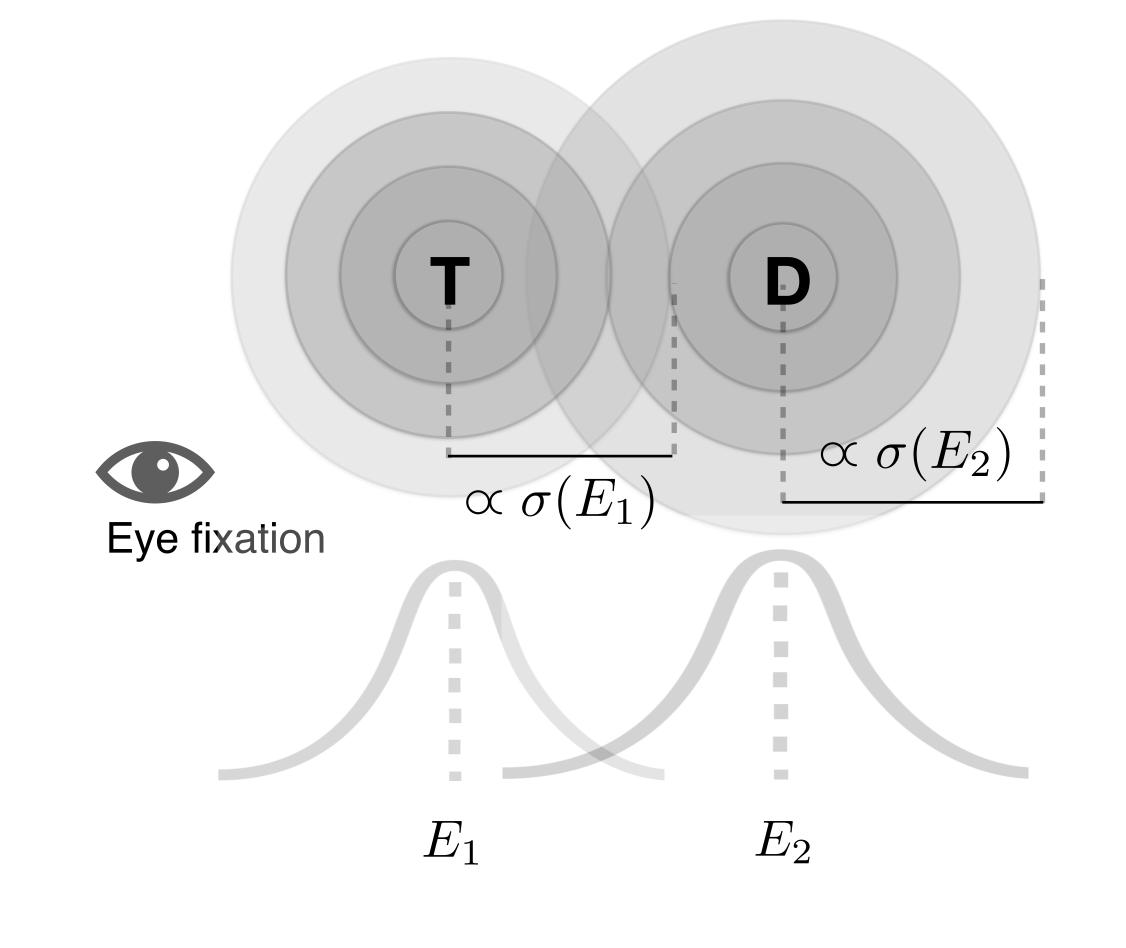
To model Multiple Object Tracking (MOT) in a way that accounts for individual observer eye movements

Why bother with eye movements?

Because where you look during MOT determines how well you do in this task

Human accuracy ranked

The Strategy



Given noisy unlabelled samples from the Ts and Ds in the display, decide which samples came from the Ts.

variance of the distribution depends on the observer's current fixation.

The Problem

yes

So far, we've just been guessing about how the variance depends on fixation

$$\sim \mathcal{N}(E, \sigma = 0.08 * (1 + 0.42 * E))$$

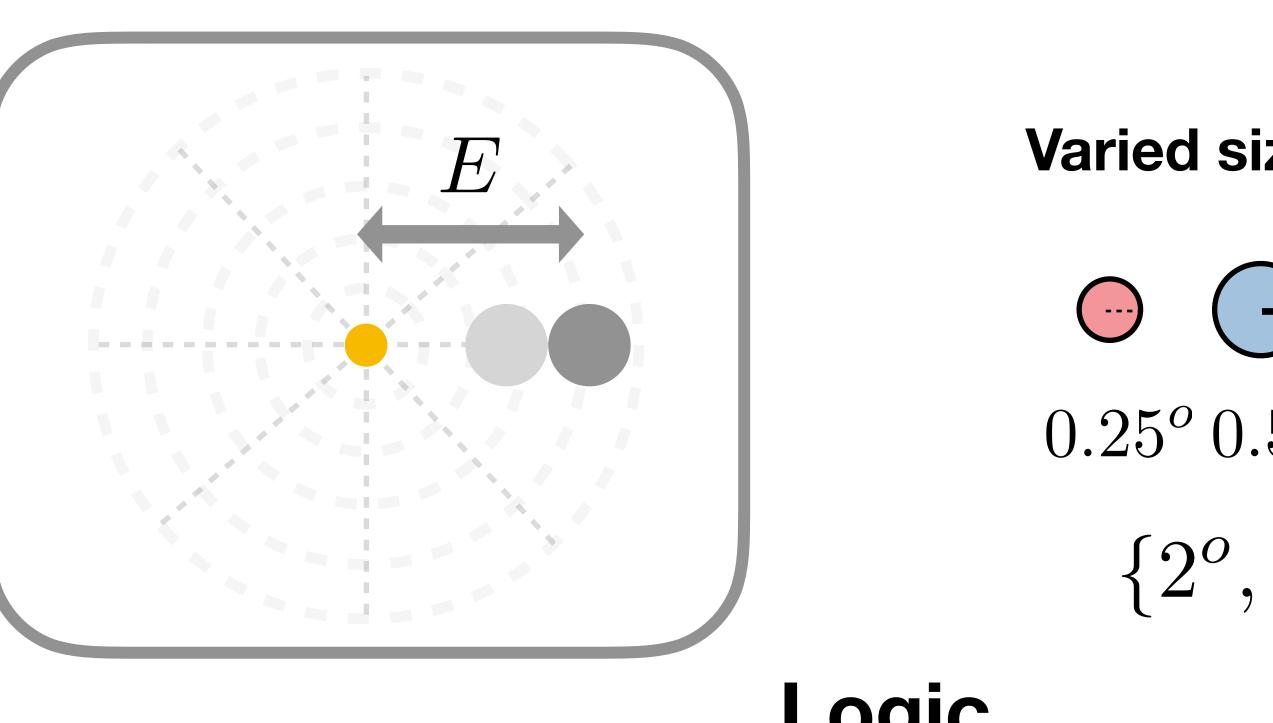
So Is the effect of E independent?

Can we measure it?

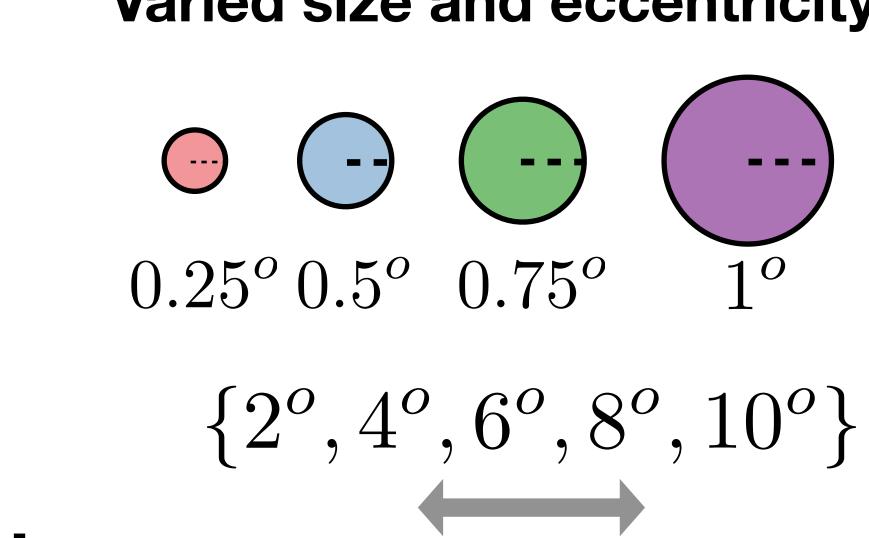
we think so

Experiment 2: Measure the spatial noise equation

2AFC task: Two discs appear side by side (L/R, U/D). Say which is the brighter one while fixating in the center

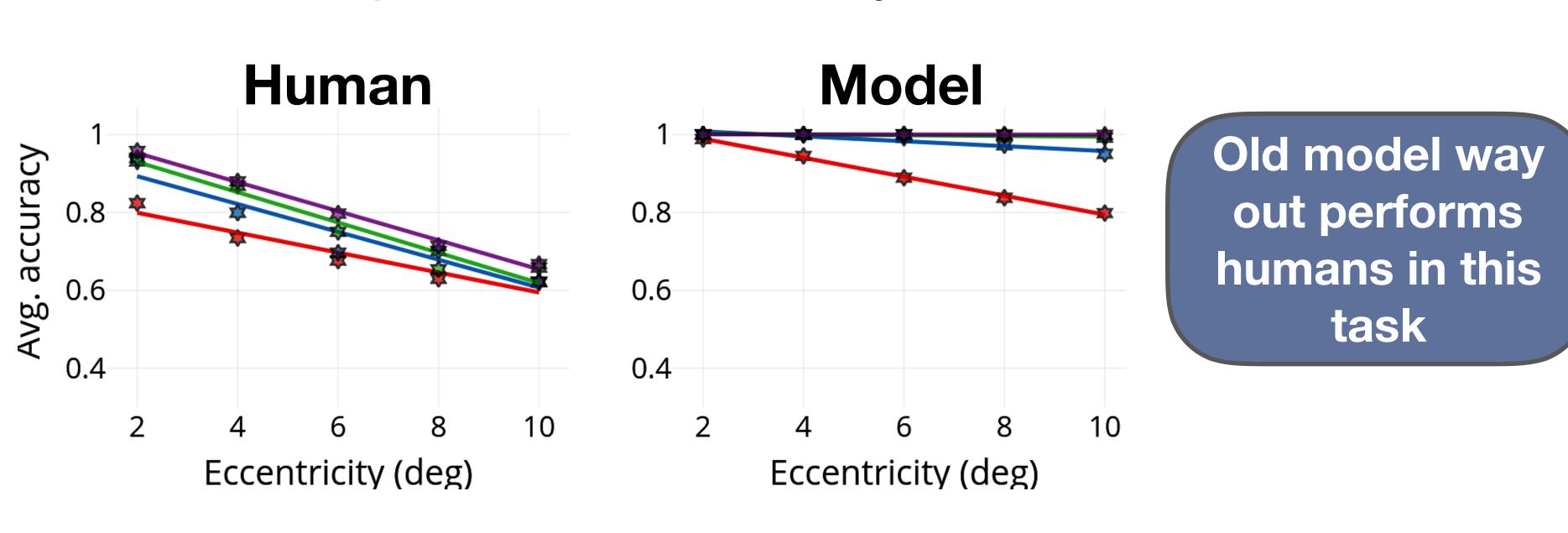


Varied size and eccentricity



Logic

This simple task should reveal the effects of eccentricity on the position confusability of two items.



New eccentricity equation fit using signal detection theory for the 2AFC task

 $\sim \mathcal{N}(0, \sigma = 0.04 + 0.23 * E)$

Ongoing work: Trying to characterise an equation that best explains the human behaviour in both the paradigms!



