Drone simulator

Start Mavproxy so we can connect both the Companion PC(where we have python script) and the mission planner(where we have drone).
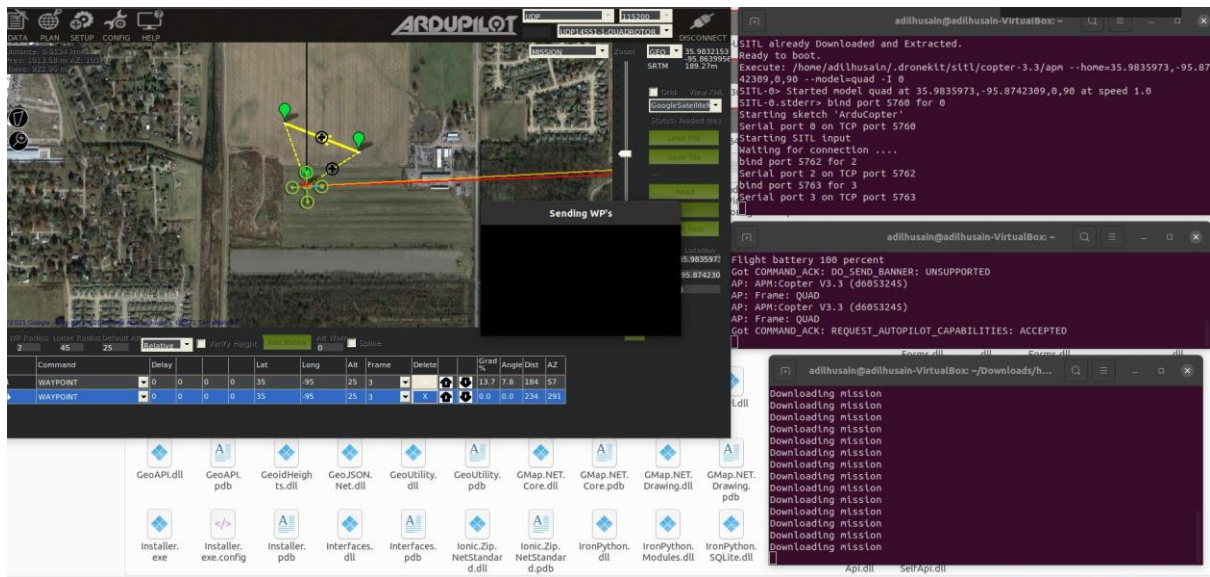
Running python script to download the mission in our drone
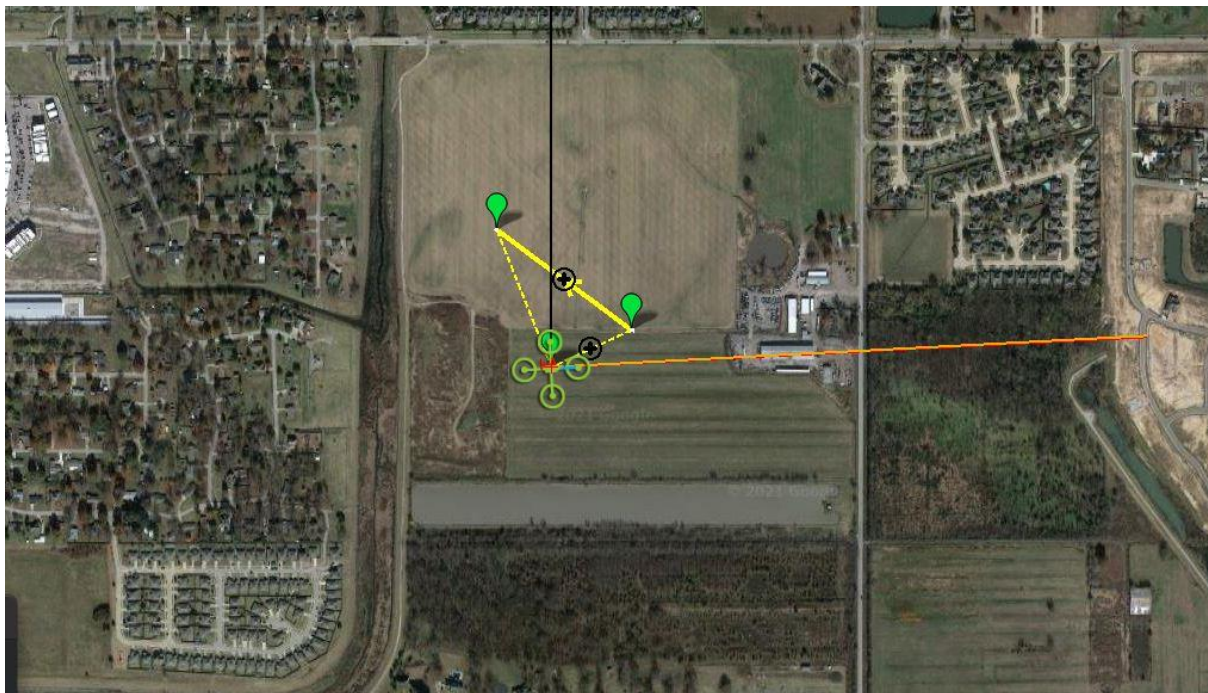
After downloading mission we cann allot the waypoints to our drone so it can have to follow the partiular path to complete the mission.

Whole process in this screenshot.