view_frames Result Recorded at time: 6.612 odom Broadcaster: /gazebo Average rate: 92.450 Hz Most recent transform: 6.607 (0.005 sec old) Buffer length: 0.649 sec base_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (6.612 sec old) Most recent transform: 0.000 (6.612 sec old) Buffer length: 0.000 sec base_footprint lidar_1_link lidar_2_link torso_link kinect_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 51.613 Hz Average rate: 51.613 Hz Average rate: 51.613 Hz Average rate: 51.613 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (6.612 sec old) Most recent transform: 0.000 (6.612 sec old) Most recent transform: 6.594 (0.018 sec old) Most recent transform: 6.594 (0.018 sec old) Most recent transform: 6.594 (0.018 sec old) Most recent transform: 6.594 (0.018 sec old) Buffer length: 0.620 sec Buffer length: 0.620 sec Buffer length: 0.620 sec Buffer length: 0.000 sec Buffer length: 0.620 sec Buffer length: 0.000 sec mpo_500_omni_wheel_back_left_link camera_link_optical mpo_500_omni_wheel_back_right_link mpo_500_omni_wheel_front_left_link mpo_500_omni_wheel_front_right_link shoulder_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Buffer length: 0.000 sec Buffer length: 0.000 sec ur5_right_base_link ur5_left_base_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 51.613 Hz Average rate: 51.613 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (6.612 sec old) Most recent transform: 6.594 (0.018 sec old) Most recent transform: 0.000 (6.612 sec old) Most recent transform: 6.594 (0.018 sec old) Buffer length: 0.000 sec Buffer length: 0.620 sec Buffer length: 0.000 sec Buffer length: 0.620 sec ur5_left_shoulder_link ur5_left_base ur5_right_base ur5_right_shoulder_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 51.613 Hz Average rate: 51.613 Hz Most recent transform: 6.594 (0.018 sec old) Most recent transform: 6.594 (0.018 sec old) Buffer length: 0.620 sec Buffer length: 0.620 sec ur5_left_upper_arm_link ur5_right_upper_arm_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 51.613 Hz Average rate: 51.613 Hz Most recent transform: 6.594 (0.018 sec old) Most recent transform: 6.594 (0.018 sec old) Buffer length: 0.620 sec Buffer length: 0.620 sec ur5_left_forearm_link ur5_right_forearm_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 51.613 Hz Average rate: 51.613 Hz Most recent transform: 6.594 (0.018 sec old) Most recent transform: 6.594 (0.018 sec old) Buffer length: 0.620 sec Buffer length: 0.620 sec ur5_right_wrist_1_link ur5_left_wrist_1_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 51.613 Hz Average rate: 51.613 Hz Most recent transform: 6.594 (0.018 sec old) Most recent transform: 6.594 (0.018 sec old) Buffer length: 0.620 sec Buffer length: 0.620 sec ur5_left_wrist_2_link ur5_right_wrist_2_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 51.613 Hz Average rate: 51.613 Hz Most recent transform: 6.594 (0.018 sec old) Most recent transform: 6.594 (0.018 sec old) Buffer length: 0.620 sec Buffer length: 0.620 sec ur5_left_wrist_3_link ur5_right_wrist_3_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec ur5_left_tool0 ur5_right_tool0 ur5_left_ee_link ur5_right_ee_link