

HW1-236200

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Question 1:

1. The function we want to minimize is the expected absolute-deviation:

$$E_{\epsilon_Q}^1 = \int_{\phi_L}^{\phi_H} |x - Q(x)| p(x) dx = (*)$$

As for the interval $[\phi_L, \phi_H]$ we partition it using the given decision levels: $\{d_i\}_{i=0}^K$ creating K decisions regions: $D_i = [d_{i-1}, d_i], i = 1, \dots, K$ s.t: $\phi_L = d_0 < d_1 < \dots < d_K = \phi_H$, and for the mapping function, we know that: $Q(x) = r_i | x \in D_i$ for representation levels $\{r_i\}_{i=1}^J$ s.t $r_1 < r_2 < \dots < r_J$. and we get:

$$(*) = \sum_{i=1}^K \int_{d_{i-1}}^{d_i} |x - r_i| p(x) dx$$

and we get that the optimization problem we wish to solve is:

$$\underset{\{d_i\}_{i=0}^K \{r_i\}_{i=1}^J}{\text{minimize}} \sum_{i=1}^K \int_{d_{i-1}}^{d_i} |x - r_i| p(x) dx$$

2. Necessary condition for optimal representation level is given by:

$$\frac{\partial}{\partial r_j} E_{\epsilon_Q}^1 = 0 \text{ for } j = 1, \dots, J$$

↓

$$\begin{aligned} \frac{\partial}{\partial r_j} E_{\epsilon_Q}^1 &= \frac{\partial}{\partial r_j} \sum_{i=1}^K \int_{d_{i-1}}^{d_i} |x - r_j| p(x) dx = \frac{\partial}{\partial r_j} \int_{d_{j-1}}^{d_j} |x - r_j| p(x) dx = \\ &= \int_{d_{j-1}}^{d_j} \frac{\partial}{\partial r_j} |x - r_j| p(x) dx = - \int_{d_{j-1}}^{d_j} \text{sign}(x - r_j) p(x) dx = \end{aligned}$$

$$\begin{aligned}
&= \int_{d_{j-1}}^{r_j} p(x)dx - \int_{r_j}^{d_j} p(x)dx \stackrel{\text{demand}}{=} 0 \\
&\Downarrow \\
&\int_{d_{j-1}}^{r_j} p(x)dx = \int_{r_j}^{d_j} p(x)dx
\end{aligned}$$

From the optimality condition we can see that the optimal r'_j 's devide the interval $[d_{j-1}, d_j]$ into two equal probabily regions, this can be interpereted as the probabilistic median of the interval for the given $p(x)$.

3. Necessery condition for optimal decision level is given by:

$$\frac{\partial}{\partial d_j} E_{\epsilon_Q}^1 = 0 \text{ for } j = 1, \dots, K-1$$

for fixed $d_0 = \phi_L, d_K = \phi_H$

$$\begin{aligned}
&\Downarrow \\
&\frac{\partial}{\partial d_j} E_{\epsilon_Q}^1 = \frac{\partial}{\partial d_j} \sum_{i=1}^K \int_{d_{i-1}}^{d_i} |x - r_j| p(x) dx = \\
&= \frac{\partial}{\partial d_j} \int_{d_{j-1}}^{d_j} |x - r_j| p(x) dx + \frac{\partial}{\partial d_j} \int_{d_j}^{d_{j+1}} |x - r_{j+1}| p(x) dx = \\
&= |d_j - r_j| p(d_j) - |d_j - r_{j+1}| p(d_j) \stackrel{\text{demand}}{=} 0 \\
&\Downarrow \\
&|d_j - r_j| = |d_j - r_{j+1}|
\end{aligned}$$

If we open the absolute value we get two possibilities:

- (a) $d_j - r_j = d_j - r_{j+1} \Rightarrow r_j = r_{j+1}$ This answer is **impossible** as we know that for wach j: $r_j < r_{j+1}$.
- (b) $d_j - r_j = -(d_j - r_{j+1}) \Rightarrow d_j = \frac{r_j + r_{j+1}}{2}$ So given the representation level we get that the optimal decision levels are the mean of the representation levels.

4. the Max-Lloyd procedure for designing a b -bit quantizer that minimizes the expected absolute-deviation for a given input PDF $p(x)$ can be described as:

- (a) Initialization: Set arbitrary decisions levels $\{d_i\}_{i=0}^K$.
- (b) Compute th e optimal representation levels and set to- $\{r_i\}_{i=1}^J$ for the current decision levels $\{d_i\}_{i=0}^K$.
- (c) Compute the optimal decisions levels and set to- $\{d_i\}_{i=0}^K$ for the current representation levels $\{r_i\}_{i=1}^J$.
- (d) If stopping criteria has not met, return to (b).

Question 2

1. We need to formulate an optimal quantizer design that uses $b = 1$ bit

\Downarrow

we have $J = 2^b = 2$ representation levels, labeled r_1, r_2 , and $J + 1 = 3$ decision levels labeled $d_0 = -4a, d_1, d_2 = 4a$.

- (a) As we learned in class we know that for given decision levels the optimal representation levels are:

$$r_j = \frac{\int_{d_{j-1}}^{d_j} xp(x)dx}{\int_{d_{j-1}}^{d_j} p(x)dx} \text{ for } j = 1, 2$$

and for given representation levels the optimal decision levels are:

$$d_j = \frac{r_j + r_{j+1}}{2} \text{ for } j = 0, 1, 2$$

Now we guess the value of the decision level, $d_1 = 0$, and let's calculate the representation levels according to the current decision levels:

$$\begin{aligned} r_1 &= \frac{\int_{-4a}^{-2a} \frac{x}{4a} dx}{\int_{-4a}^{d_{-2a}} \frac{1}{4a} dx} = \frac{\frac{x^2}{8a} \Big|_{-4a}^{-2a}}{\frac{x}{4a} \Big|_{-4a}^{d_{-2a}}} = -3a \\ r_2 &= \frac{\int_{2a}^{3a} x \left(-\frac{1}{4a^2}x + \frac{7}{8a}\right) dx + \int_{3a}^{4a} x \left(\frac{1}{4a^2}x - \frac{5}{8a}\right) dx}{\int_{2a}^{3a} \left(-\frac{1}{4a^2}x + \frac{7}{8a}\right) dx + \int_{3a}^{4a} \left(\frac{1}{4a^2}x - \frac{5}{8a}\right) dx} = \dots = 3a \end{aligned}$$

Now let's calculate the decision level according to the calculated representation levels:

$$d_1 = \frac{r_1 + r_2}{2} = 0$$

The result didn't change, that means that the values we got are the optimal.

- (b) The minimal squared error achieved is:

$$\begin{aligned} E\{\epsilon^2\} &= \int_{-4a}^{4a} p(x) (x - Q(x))^2 dx = \\ &= \int_{-4a}^{-2a} \frac{1}{4a} (x - (-3a))^2 dx + \int_{2a}^{3a} \left(-\frac{1}{4a^2}x + \frac{7}{8a}\right) (x - 3a)^2 dx + \int_{3a}^{4a} \left(\frac{1}{4a^2}x - \frac{5}{8a}\right) (x - 3a)^2 dx = \\ &= \dots = \frac{a^2}{6} + \frac{5a^2}{48} - \frac{a^2}{48} = \frac{a^2}{4} \end{aligned}$$

2. We need to formulate an optimal quantizer design that uses $b = 2$ bit

\Downarrow

we have $J = 2^b = 4$ representation levels, labeled r_1, r_2, r_3, r_4 , and $J + 1 = 5$ decision levels labeled d_0, d_1, d_2, d_3, d_4 .

- (a) We start with a guess for the decision levels: $d_0 = -4a, d_1 = -2a, d_2 = 2a, d_3 = 3a, d_4 = 4a$ and calculate the matching representation levels:

$$r_1 = -3a, r_2 = 0, r_3 = 2\frac{5}{12}a, r_4 = 3\frac{7}{12}a$$

Now we update the decision levels according to the calculated representation levels:

$$d_0 = -4a, d_1 = -1.5a, d_2 = 1\frac{5}{24}a, d_3 = 3a, d_4 = 4a$$

Now we update the representation levels:

$$r_1 = -3a, r_2 = 0, r_3 = 2\frac{5}{12}a, r_4 = 3\frac{7}{12}a$$

We got the same result as the previous calculation, that means that the algorithm converged, and the final answer is:

$$d_0 = -4a, d_1 = -1.5a, d_2 = 1\frac{5}{24}a, d_3 = 3a, d_4 = 4a$$

$$r_1 = -3a, r_2 = 0, r_3 = 2\frac{5}{12}a, r_4 = 3\frac{7}{12}a$$

- (b) The minimal squared error achieved is:

$$\begin{aligned} E \{ \epsilon^2 \} &= \int_{-4a}^{4a} p(x) (x - Q(x))^2 dx = \\ &= \int_{-4a}^{-2a} \frac{1}{4a} (x - (-3a))^2 dx + \int_{-2a}^{3a} \left(-\frac{1}{4a^2}x + \frac{7}{8a} \right) \left(x - 2\frac{5}{12}a \right)^2 dx + \dots \\ &\dots + \int_{3a}^{4a} \left(\frac{1}{4a^2}x - \frac{5}{8a} \right) \left(x - 3\frac{7}{12}a \right)^2 dx = \dots = 0.20466a^2 \end{aligned}$$

Question 3

$$\begin{aligned}
1. \int_{t \in \Delta_i} (t - t_i)^k dt &= \int_{\frac{i-1}{N}}^{\frac{i}{N}} (t - t_i)^k dt = \frac{(t - t_i)^{k+1}}{k+1} \Big|_{\frac{i-1}{N}}^{\frac{i}{N}} = \\
&= \frac{\left(\frac{i}{N} - t_i\right)^{k+1}}{k+1} - \frac{\left(\frac{i-1}{N} - t_i\right)^{k+1}}{k+1} = \frac{\left(\frac{|\Delta_i|}{2}\right)^{k+1} - \left(\frac{-|\Delta_i|}{2}\right)^{k+1}}{k+1} = \\
&= \frac{(1 + (-1)^{k+2}) |\Delta_i|^{k+1}}{2^{k+1}(k+1)} = \begin{cases} 0, k - odd \\ \frac{|\Delta_i|^{k+1}}{2^k(k+1)}, k - even \end{cases}
\end{aligned}$$

2. As we studied in class:

$$MSE = \overbrace{\int_0^1 (\phi(t) - \hat{\phi}(t))^2 dt}^{\text{MSE}_i} = \sum_{i=1}^N \int_{\frac{i-1}{N}}^{\frac{i}{N}} (\phi(t) - a_i(t - t_i) - c_i)^2 dt$$

Find the optimal a_i, c_i by requiring:

$$\frac{\partial}{\partial a_i} MSE_i = 0$$

$$\frac{\partial}{\partial c_i} MSE_i = 0$$

For a_i :

$$\begin{aligned}
\frac{\partial}{\partial a_i} MSE_i &= \frac{\partial}{\partial a_i} \int_{\frac{i-1}{N}}^{\frac{i}{N}} (\phi(t) - a_i(t - t_i) - c_i)^2 dt = \\
&= \int_{\frac{i-1}{N}}^{\frac{i}{N}} \frac{\partial}{\partial a_i} (\phi(t) - a_i(t - t_i) - c_i)^2 dt = -2 \int_{\frac{i-1}{N}}^{\frac{i}{N}} (t - t_i) (\phi(t) - a_i(t - t_i) - c_i) dt = \\
&= -2 \int_{\frac{i-1}{N}}^{\frac{i}{N}} \phi(t) (t - t_i) dt + 2a_i \int_{\frac{i-1}{N}}^{\frac{i}{N}} (t - t_i)^2 dt + 2c_i \int_{\frac{i-1}{N}}^{\frac{i}{N}} (t - t_i) dt
\end{aligned}$$

We calculate seperately the first and second integral, based on the answer from previous section:

$$2a_i \int_{\frac{i-1}{N}}^{\frac{i}{N}} (t - t_i)^2 dt = 2a_i \frac{|\Delta_i|^3}{2^2 3} = \frac{a_i |\Delta_i|^3}{6}$$

$$2c_i \int_{\frac{i-1}{N}}^{\frac{i}{N}} (t - t_i) dt = 0$$

By demanding that $\frac{\partial}{\partial a_i} MSE_i = 0$ we get the equation:

$$-2 \int_{\frac{i-1}{N}}^{\frac{i}{N}} \phi(t) (t - t_i) dt + \frac{a_i |\Delta_i|^3}{6} = 0$$

$$\Downarrow$$

$$a_i = \frac{12}{|\Delta_i|^3} \int_{\frac{i-1}{N}}^{\frac{i}{N}} \phi(t) (t - t_i) dt$$

Now we will optimize c_i :

$$\begin{aligned} \frac{\partial}{\partial c_i} MSE_i &= \frac{\partial}{\partial c_i} \int_{\frac{i-1}{N}}^{\frac{i}{N}} (\phi(t) - a_i (t - t_i) - c_i)^2 dt = \\ &= \int_{\frac{i-1}{N}}^{\frac{i}{N}} \frac{\partial}{\partial c_i} (\phi(t) - a_i (t - t_i) - c_i)^2 dt = -2 \int_{\frac{i-1}{N}}^{\frac{i}{N}} (\phi(t) - a_i (t - t_i) - c_i) dt = \\ &= -2 \int_{\frac{i-1}{N}}^{\frac{i}{N}} \phi(t) dt + 2a_i \int_{\frac{i-1}{N}}^{\frac{i}{N}} (t - t_i) dt + 2c_i \int_{\frac{i-1}{N}}^{\frac{i}{N}} 1 dt \end{aligned}$$

Based on the answer from previous section we get that the middle integral equals zero, and:

$$2c_i \int_{\frac{i-1}{N}}^{\frac{i}{N}} 1 dt = 2c_i |\Delta_i|$$

By demanding that $\frac{\partial}{\partial c_i} MSE_i = 0$ we get that:

$$-2 \int_{\frac{i-1}{N}}^{\frac{i}{N}} \phi(t) dt + 2c_i |\Delta_i| = 0$$

$$\Downarrow$$

$$c_i = \frac{1}{|\Delta_i|} \int_{\frac{i-1}{N}}^{\frac{i}{N}} \phi(t) dt$$

3. The optimal MSE is calculated by using the optimal a_i, c_i (that give us the optimal $\hat{\phi}(t)$):

$$MSE^{opt} = \int_0^1 \left(\phi(t) - \hat{\phi}(t) \right)^2 dt = \sum_{i=1}^N \int_{\frac{i-1}{N}}^{\frac{i}{N}} \left(\phi(t) - a_i^{opt} (t - t_i) - c_i^{opt} \right)^2 dt =$$

$$\begin{aligned}
&= \sum_{i=1}^N \int_{\frac{i-1}{N}}^{\frac{i}{N}} \left(\phi(t)^2 - 2a_i^{opt} \phi(t) (t - t_i) - 2c_i^{opt} \phi(t) + (a_i^{opt})^2 (t - t_i)^2 + 2a_i^{opt} c_i^{opt} (t - t_i) \right. \\
&\quad \left. + (c_i^{opt})^2 dt \right) dt = \\
&= \int_0^1 (\phi(t))^2 dt - 2 \sum_{i=1}^N a_i^{opt} \int_{\frac{i-1}{N}}^{\frac{i}{N}} \phi(t) (t - t_i) dt - 2 \sum_{i=1}^N c_i^{opt} \int_{\frac{i-1}{N}}^{\frac{i}{N}} \phi(t) dt + \\
&\quad + \sum_{i=1}^N (a_i^{opt})^2 \int_{\frac{i-1}{N}}^{\frac{i}{N}} (t - t_i)^2 dt + 2 \sum_{i=1}^N a_i^{opt} c_i^{opt} \int_{\frac{i-1}{N}}^{\frac{i}{N}} (t - t_i) dt + |\Delta| \sum_{i=1}^N (c_i^{opt})^2 = (**)
\end{aligned}$$

Using the outcomes from section 1 we get that:

$$\sum_{i=1}^N (a_i^{opt})^2 \int_{\frac{i-1}{N}}^{\frac{i}{N}} (t - t_i)^2 dt = \sum_{i=1}^N (a_i^{opt})^2 \frac{|\Delta_i|^3}{2^{23}} \stackrel{(*)}{=} \frac{|\Delta|^3}{12} \sum_{i=1}^N (a_i^{opt})^2$$

(*): All the intervals are in the same size: $|\Delta_i| = |\Delta| = \frac{1}{N}$.

$$2 \sum_{i=1}^N a_i^{opt} c_i^{opt} \int_{\frac{i-1}{N}}^{\frac{i}{N}} (t - t_i) dt = 0$$

Using the expressions we got for optimal a_i, c_i we get:

$$\begin{aligned}
-2 \sum_{i=1}^N a_i^{opt} \int_{\frac{i-1}{N}}^{\frac{i}{N}} \phi(t) (t - t_i) dt &= -2 \sum_{i=1}^N (a_i^{opt})^2 \frac{|\Delta_i|^3}{12} = \\
&= -\frac{|\Delta|^3}{6} \sum_{i=1}^N (a_i^{opt})^2 \\
-2 \sum_{i=1}^N c_i^{opt} \int_{\frac{i-1}{N}}^{\frac{i}{N}} \phi(t) dt &= -2 \sum_{i=1}^N c_i^{opt} |\Delta_i| c_i^{opt} = -2 |\Delta| \sum_{i=1}^N (c_i^{opt})^2
\end{aligned}$$

And finally we get:

$$\begin{aligned}
(**) &= \int_0^1 (\phi(t))^2 dt - \frac{|\Delta|^3}{6} \sum_{i=1}^N (a_i^{opt})^2 - 2 |\Delta| \sum_{i=1}^N (c_i^{opt})^2 + \frac{|\Delta|^3}{12} \sum_{i=1}^N (a_i^{opt})^2 + |\Delta| \sum_{i=1}^N (c_i^{opt})^2 = \\
&= \int_0^1 (\phi(t))^2 dt - \frac{|\Delta|^3}{12} \sum_{i=1}^N (a_i^{opt})^2 - |\Delta| \sum_{i=1}^N (c_i^{opt})^2 =
\end{aligned}$$

$$|\Delta| = \frac{1}{N}$$

$$= \int_0^1 (\phi(t))^2 dt - \frac{1}{12N^3} \sum_{i=1}^N (a_i^{opt})^2 - \frac{1}{N} \sum_{i=1}^N (c_i^{opt})^2$$

4. As we saw in class the minimal MSE for picewise-constant approximation is:

$$MSE_{const} = \int_0^1 \phi^2(t) dt - \frac{1}{N} \sum_{i=1}^N (c_i^{opt})^2$$

If we calculate the difference $MSE_{lin} - MSE_{const}$ we get:

$$MSE_{lin} - MSE_{const} = -\frac{1}{12N^3} \sum_{i=1}^N (a_i^{opt})^2$$

And because $\forall i, (a_i)^2 \geq 0$ we get that: $-\frac{1}{12N^3} \sum_{i=1}^N (a_i^{opt})^2 \leq 0$

↓

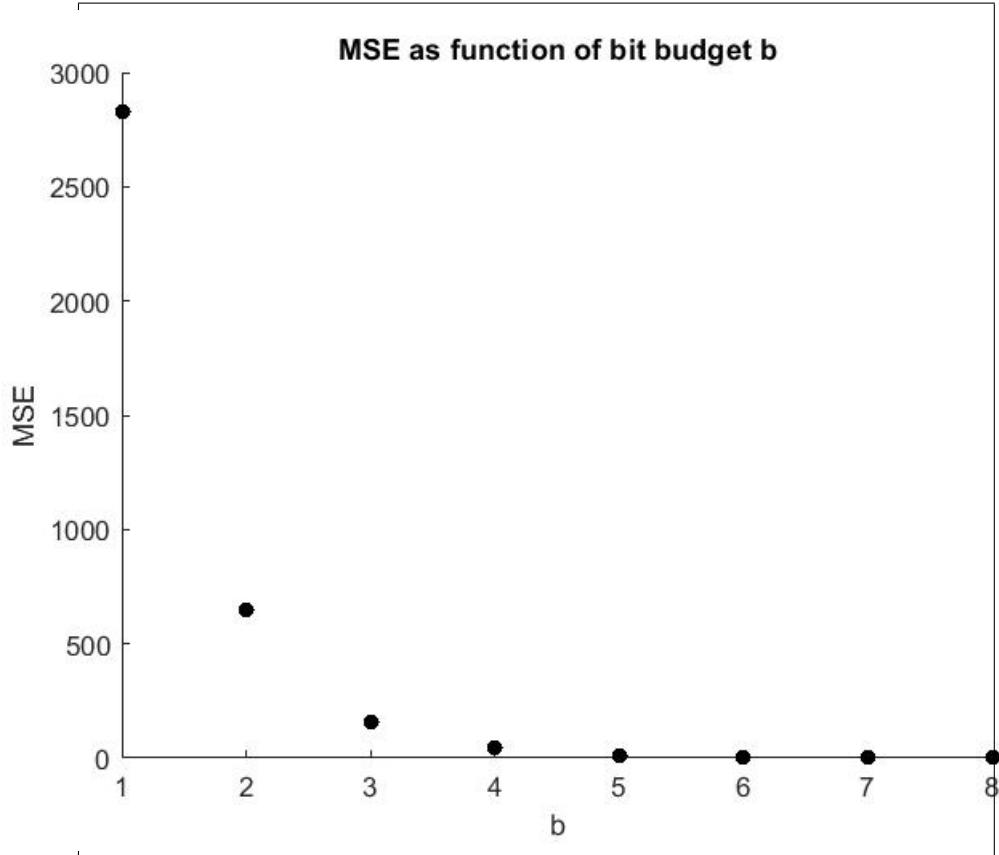
$$MSE_{lin} \leq MSE_{const}$$

Therefore the MSE using picewise linear approximation is lower(or equal) to the MSE achieved by using picewise-constant approximation.

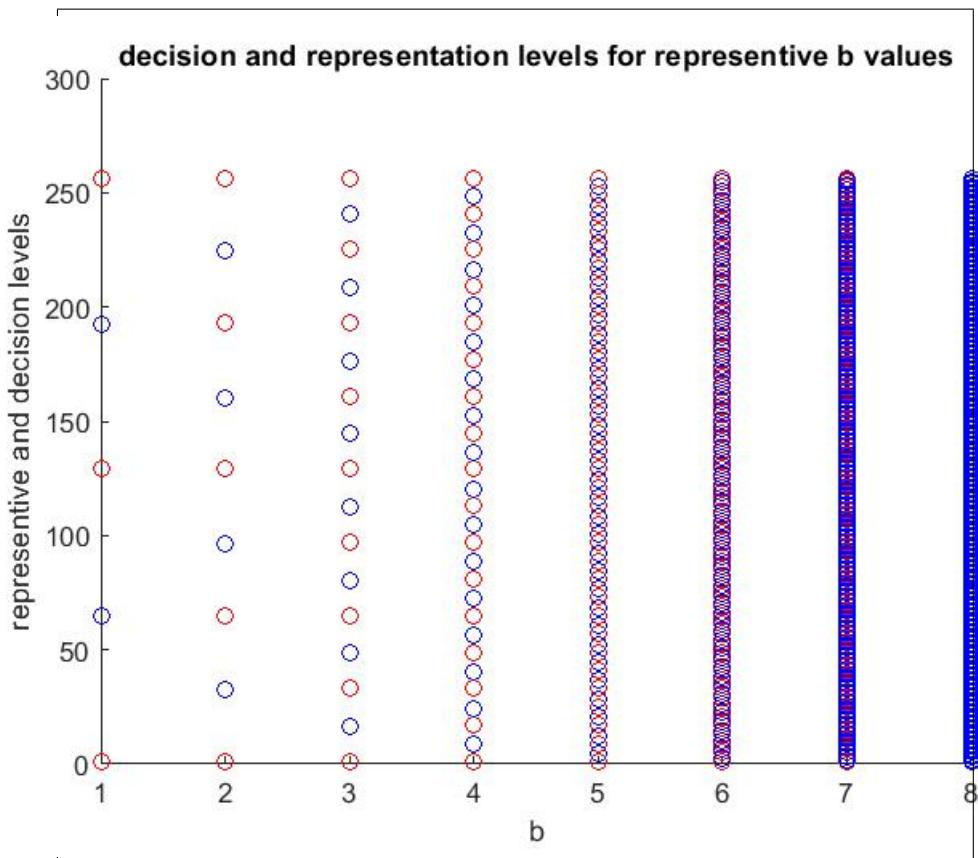
Part 2 - Matlab

Question 2 - uniform quantizer:

1. MSE as a function of the bit budget for $b=1,\dots,8$:



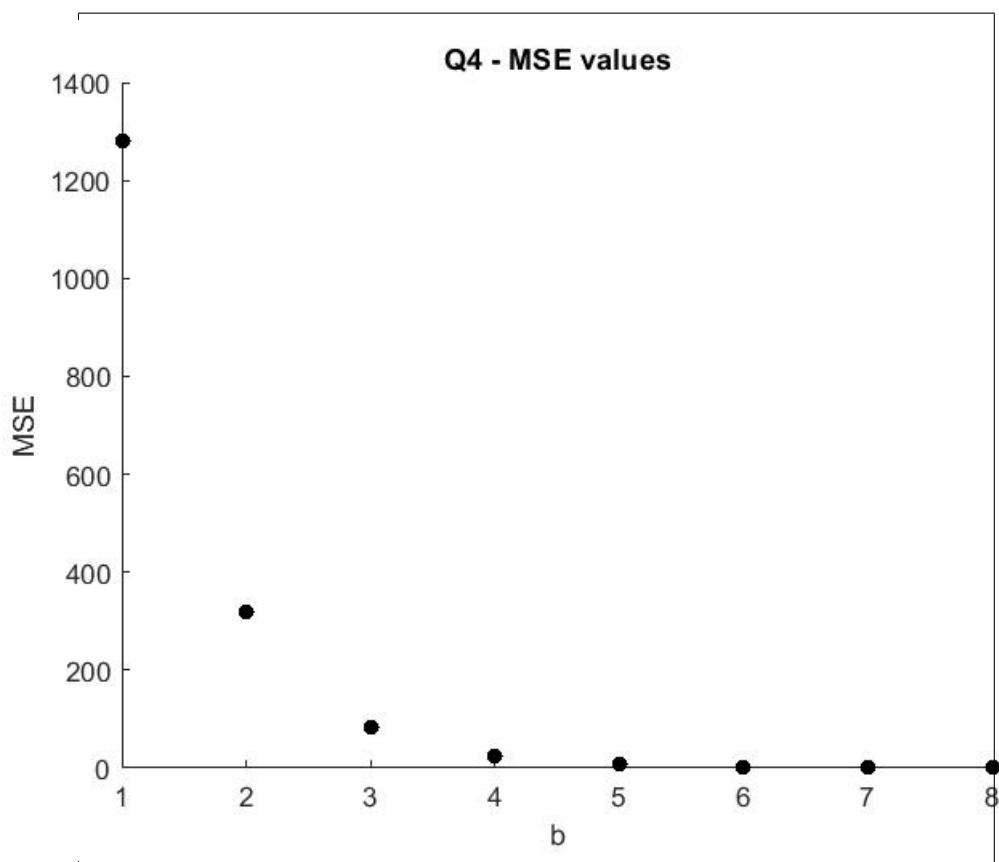
2. The decision and representation levels for representative b values:



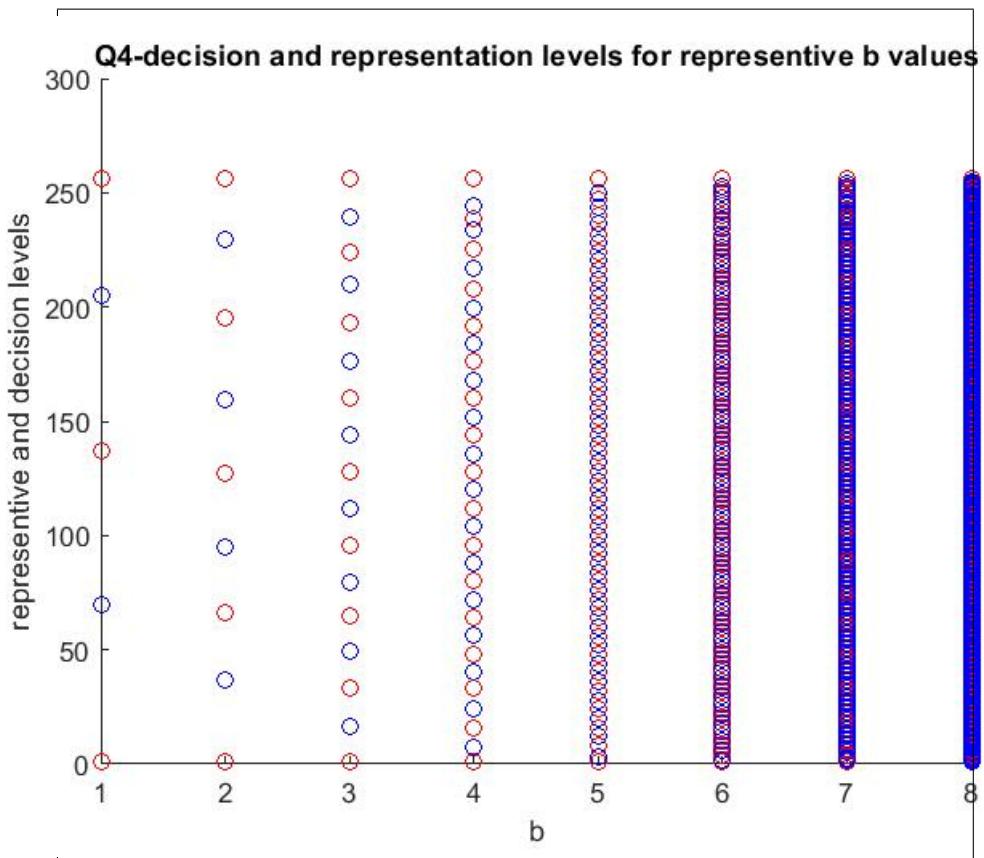
red-decision blue-representation 0.1: Figure

Question 4 - Max-Lloyd uniform quantization:

1. MSE as a function of the bit budget for $b=1,\dots,8$:



2. The decision and representation levels for representative b values:

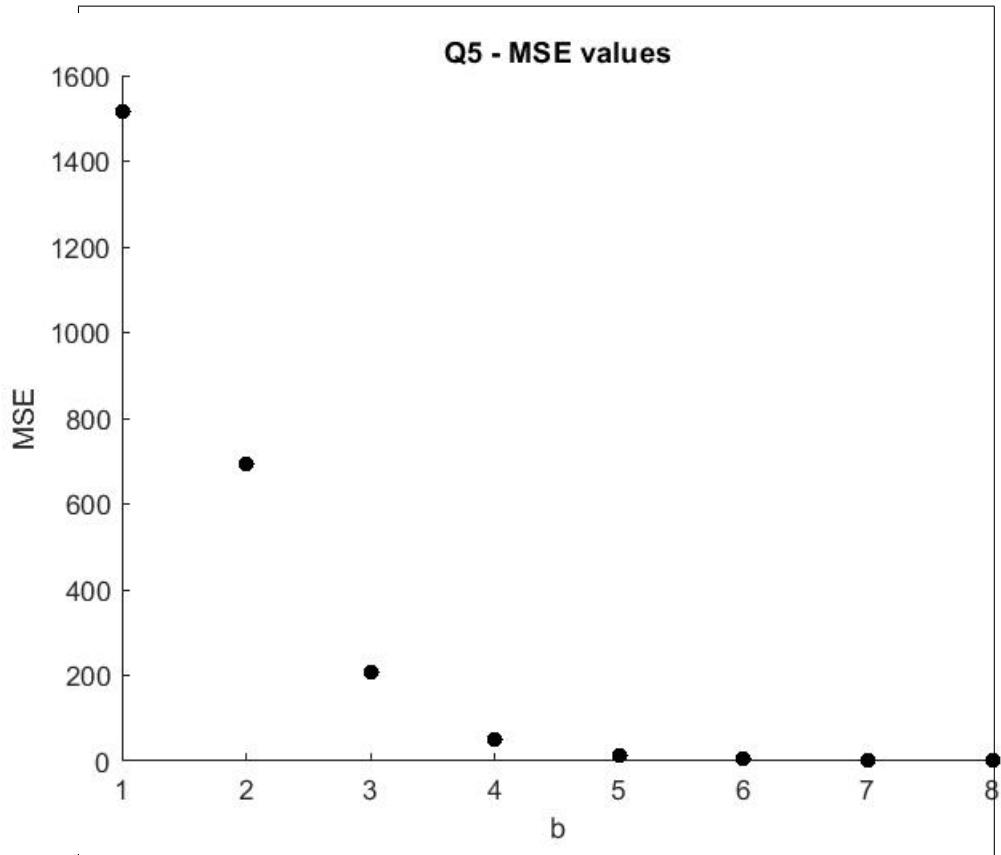


red-decision blue-representation 0.2: Figure

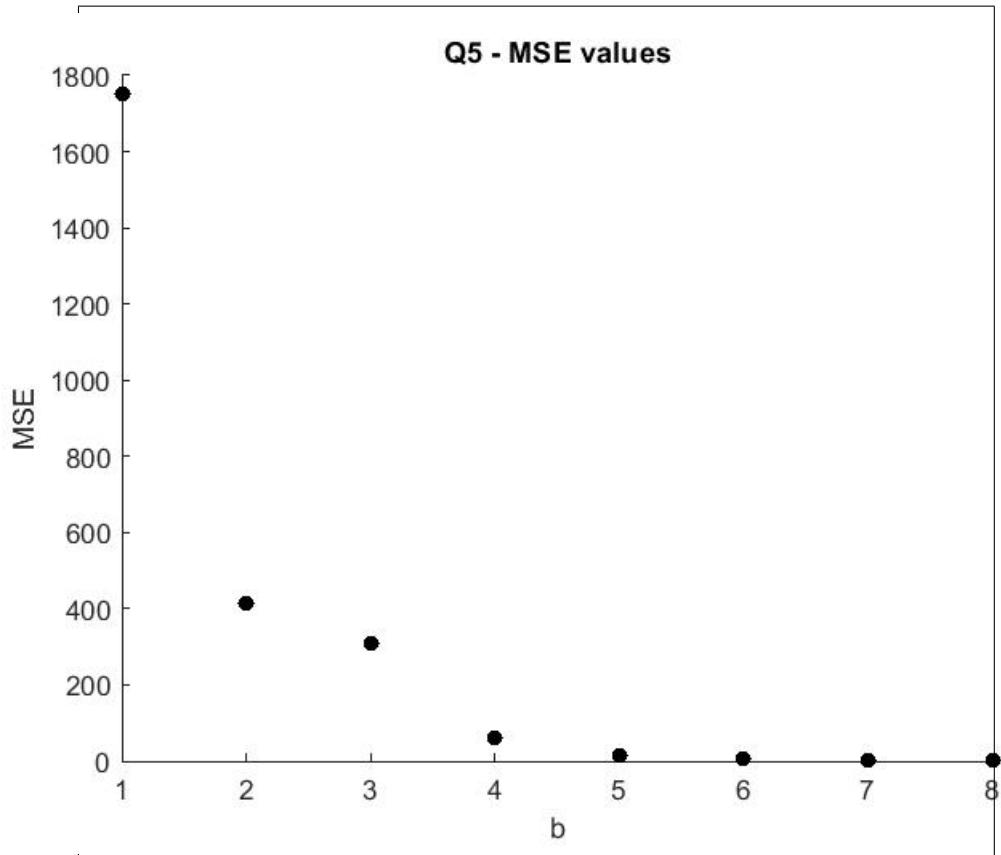
- As we could expected, the MSE values obtained using Max-Lloyd are lower than the MSE values obtained by the uniform quantization, as the Max-Lloyd algorithm should converge to the best representation and decision levels. And as we can see, the decision levels in the uniform quantization remain uniform, whereas in the Max-Lloyd algorithm they do not.

Question 5-Max-Lloyd random quantization:

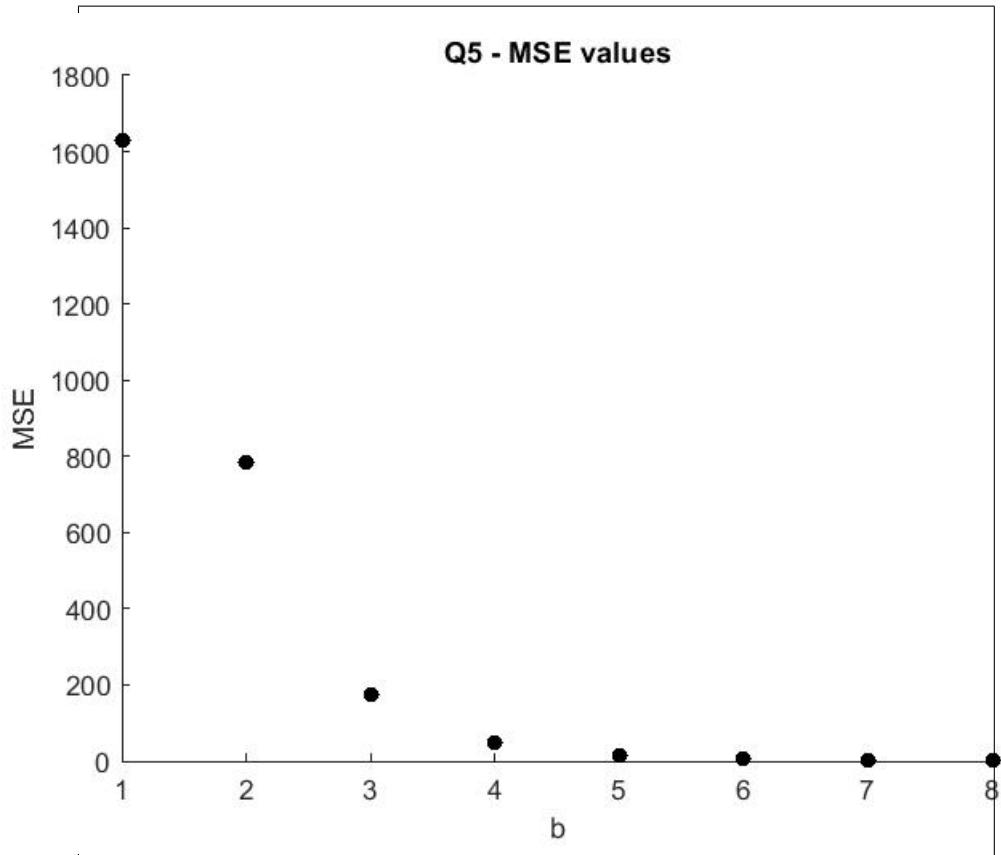
- MSE as a function of the bit budget for $b=1,\dots,8$ for 5 random quantizations:



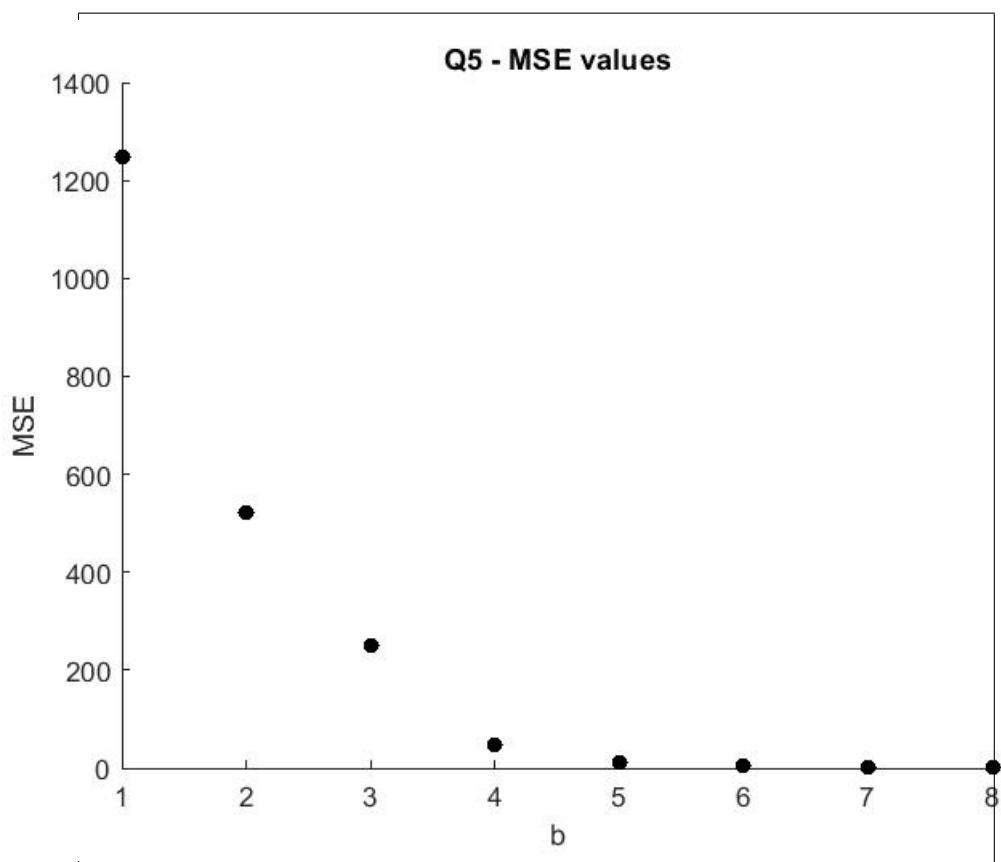
run no.1 0.3: Figure



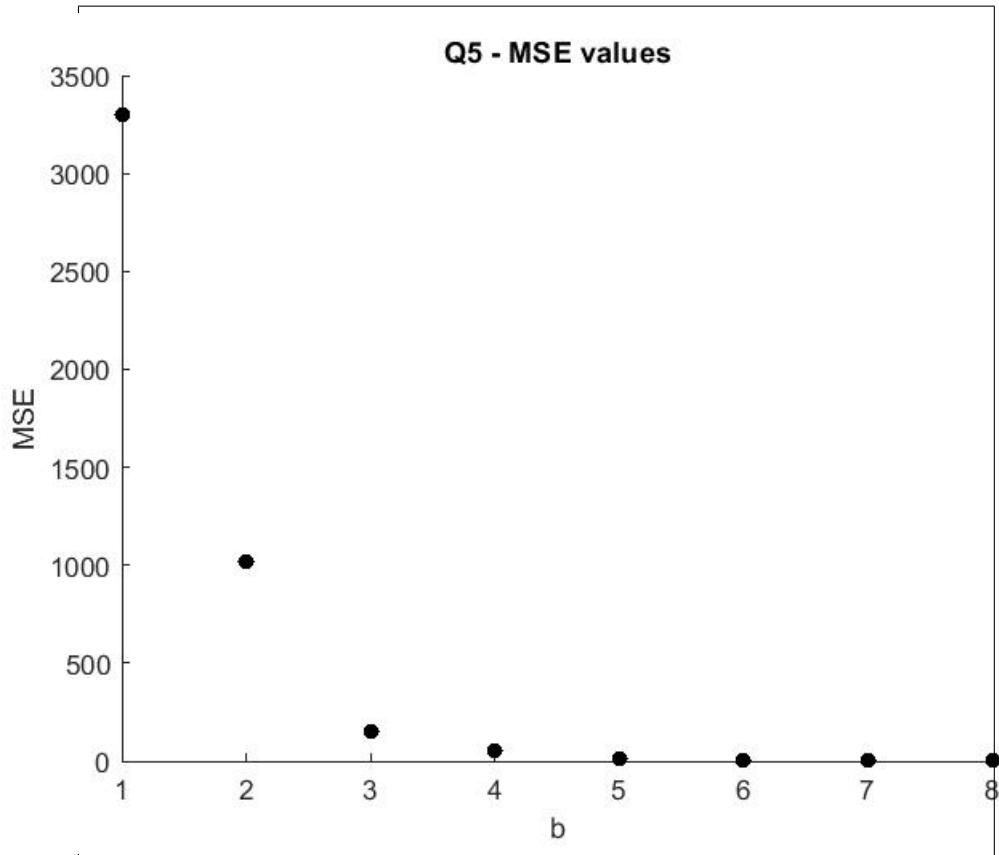
run no.2 0.4: Figure



run no.3 0.5: Figure

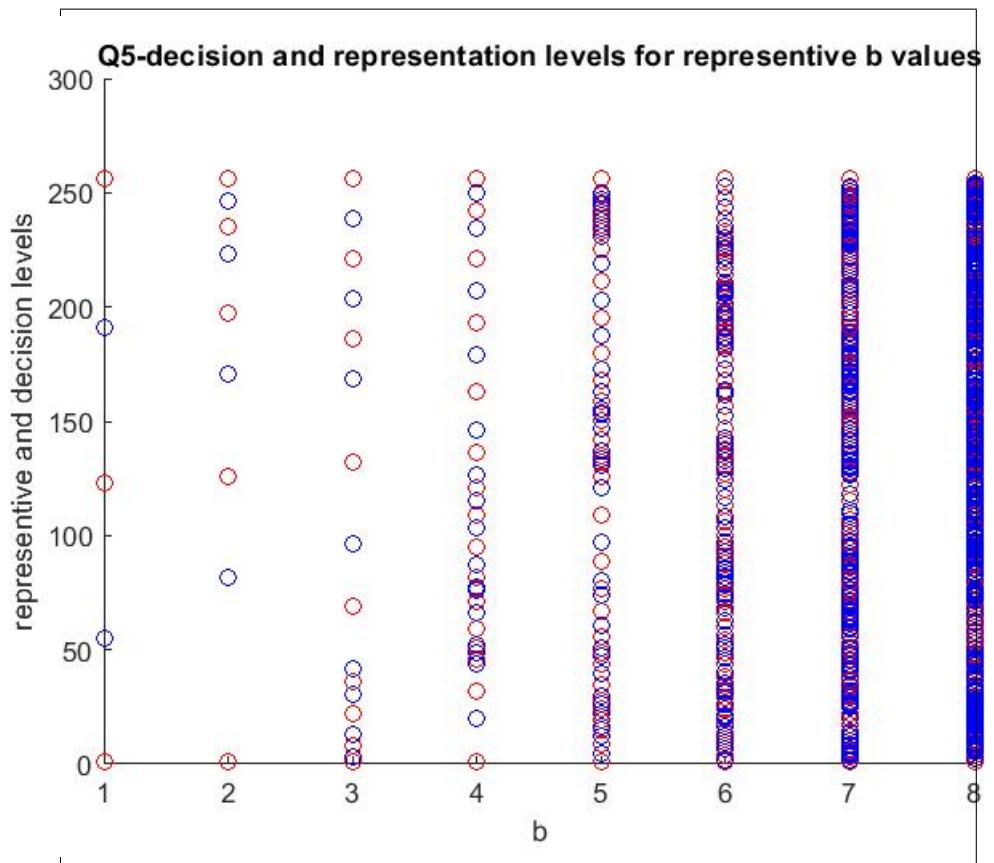


run no.4 0.6: Figure

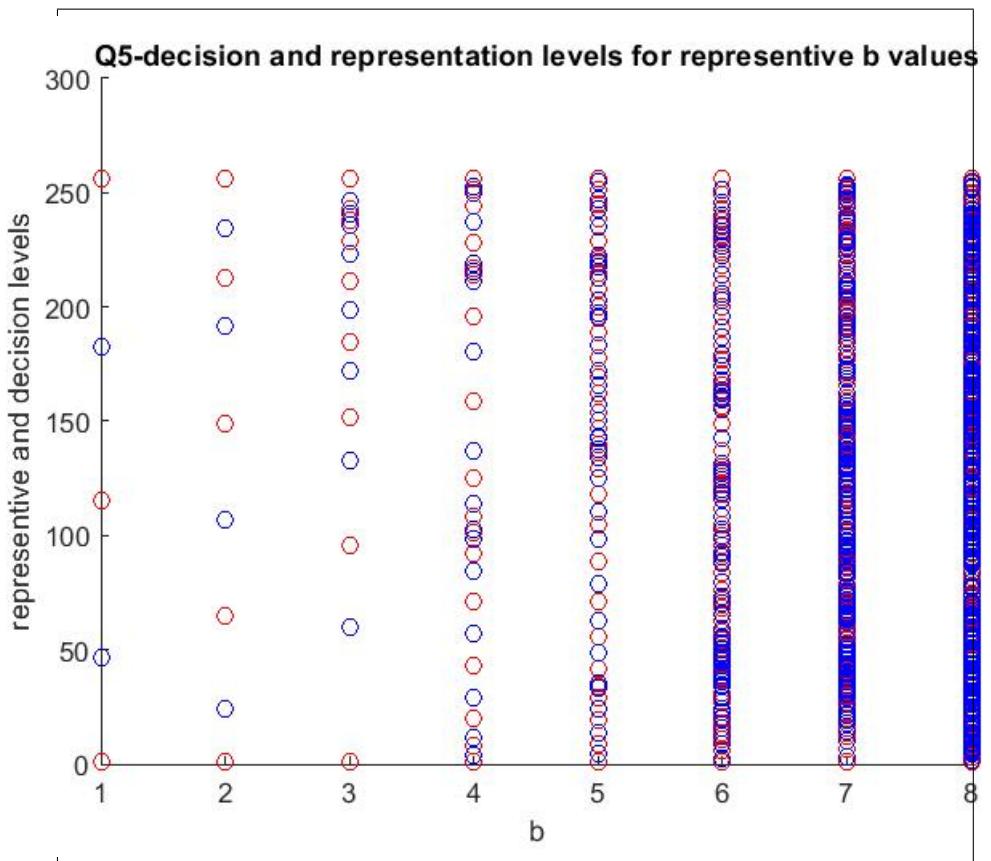


run no.5 0.7: Figure

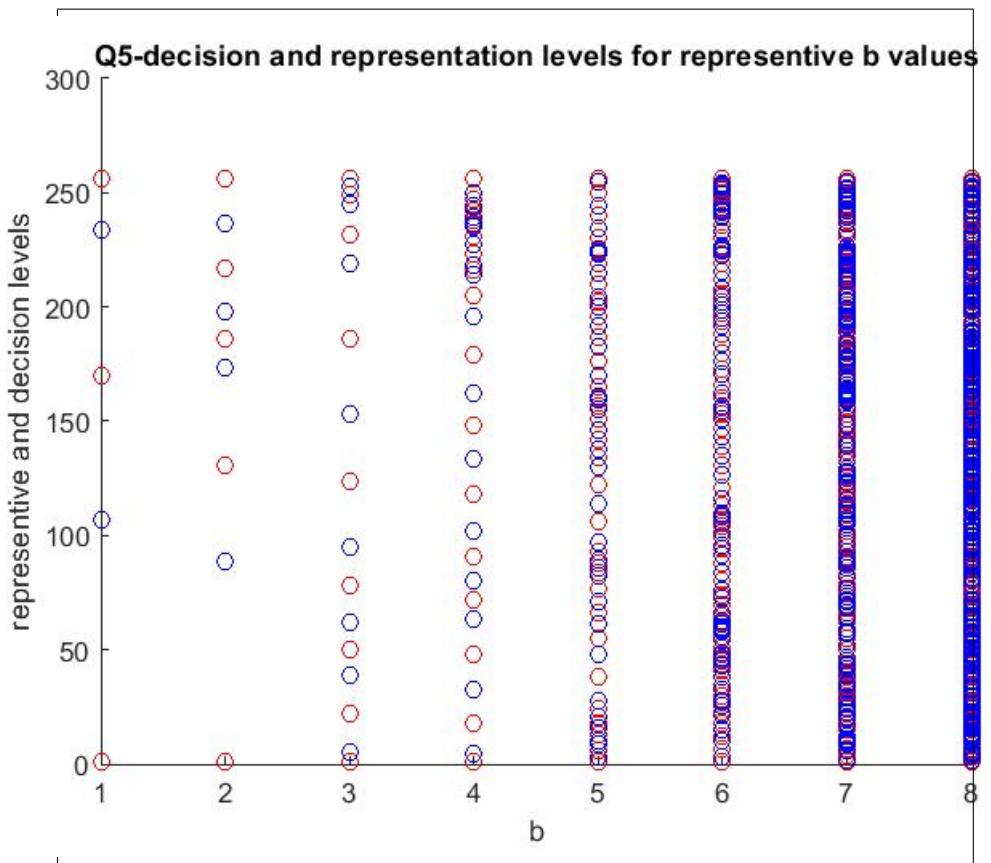
2. The decision and representation levels for representative b values, for 5 random quantizations:



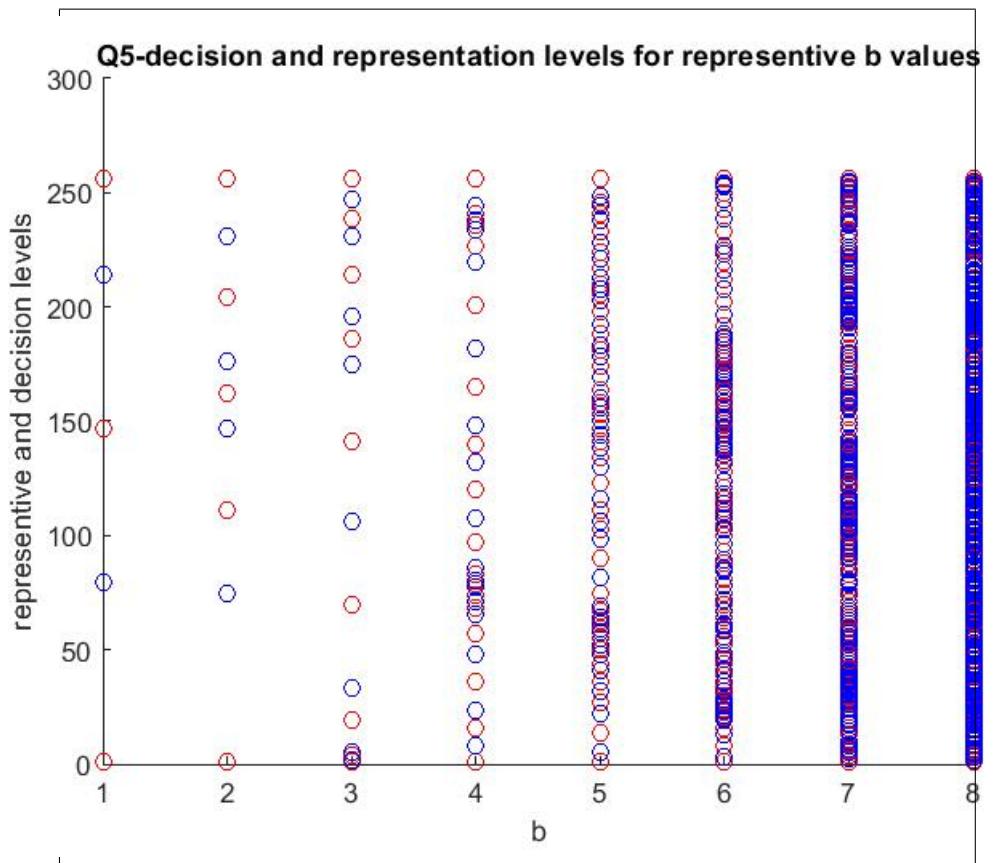
run no.1 0.8: Figure



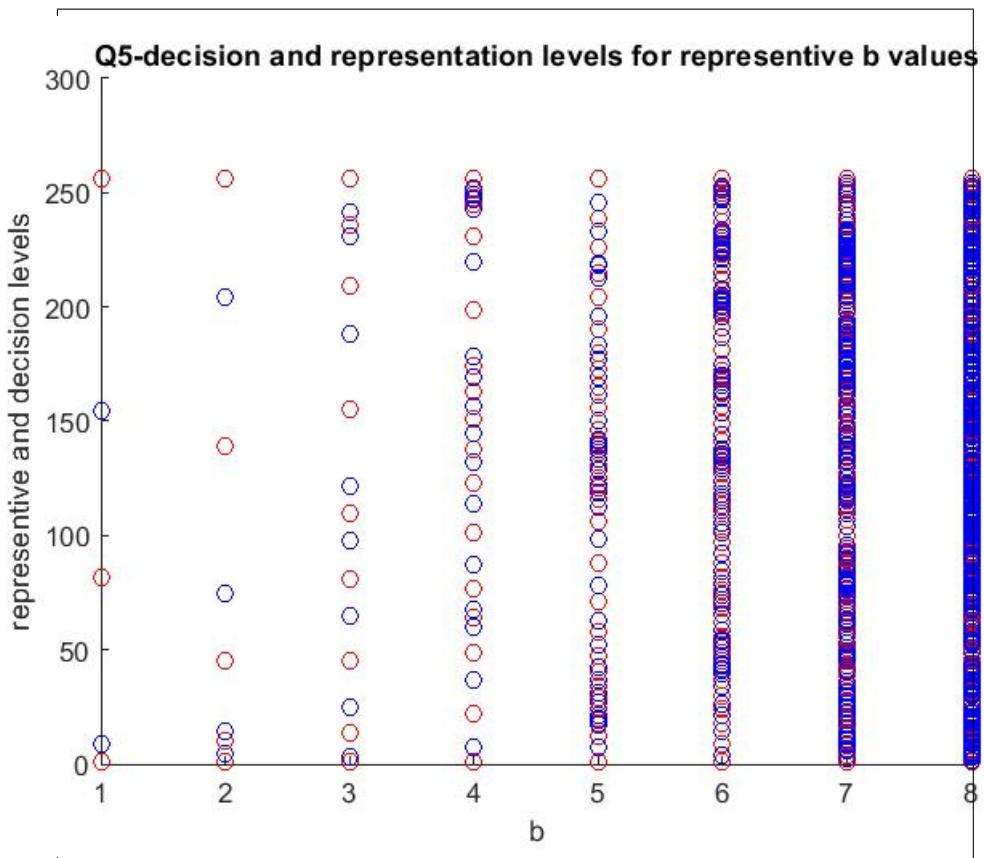
run no.2 0.9: Figure



run no.3 0.10: Figure



run no.4 0.11: Figure



run no.5 0.12: Figure

3. As we can see, the Max-Lloyd algorithm using uniform quantization obtained better results rather than starting with random quantization, as the MSE converged to zero in better performance.