



PENGOLAHAN SINYAL DIGITAL

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IMPORTANT PROPERTIES OF THE Z-TRANSFORM

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THE IMPORTANT PROPERTIES OF THE Z-TRANSFORM

- Linearity

$$Z[a_1x_1(n) + a_2x_2(n)] = a_1X_1(z) + a_2X_2(z); \quad \text{ROC: } \text{ROC}_{x_1} \cap \text{ROC}_{x_2}$$

- Sample shifting

$$Z[x(n - n_o)] = z^{-n_o} X(z); \quad \text{ROC: } \text{ROC}_x$$

- Frequency shifting

$$Z[a^n x(n)] = X\left(\frac{z}{a}\right); \quad \text{ROC: } \text{ROC}_x \text{ scaled by } |a|$$

THE IMPORTANT PROPERTIES OF THE Z-TRANSFORM

- Folding

$$Z[x(-n)] = X(1/z); \quad \text{ROC: Inverted ROC}_x$$

- Complex conjugation

$$Z[x^*(n)] = X^*(z^*); \quad \text{ROC: ROC}_x$$

- Differentiation in the z-domain (multiplication-by-a-ramp property)

$$Z[nx(n)] = -z \frac{dX(z)}{dz}; \quad \text{ROC: ROC}_x$$

THE IMPORTANT PROPERTIES OF THE Z-TRANSFORM

- Multiplication

$$Z[x_1(n)x_2(n)] = \frac{1}{2\pi j} \oint_C X_1(v) X_2\left(\frac{z}{v}\right) v^{-1} dv;$$

$$\text{ROC: } \text{ROC}_{x_1} \cap \text{Inverted ROC}_{x_2}$$

- C is a closed contour that encloses the origin and lies in the common ROC

- Convolution

$$Z[x_1(n) * x_2(n)] = X_1(z) X_2(z); \quad \text{ROC: } \text{ROC}_{x_1} \cap \text{ROC}_{x_2}$$

EXAMPLE

- Let $X_1(z) = 2 + 3z^{-1} + 4z^{-2}$ and $X_2(z) = 3 + 4z^{-1} + 5z^{-2} + 6z^{-3}$.
 - Determine $X_3(z) = X_1(z) X_2(z)$.

EXAMPLE

- From definition

$$X(z) \triangleq Z[x(n)] = \sum_{n=-\infty}^{\infty} x(n) z^{-n}$$

- $X_1(z) = 2 + 3z^{-1} + 4z^{-2}$ and $X_2(z) = 3 + 4z^{-1} + 5z^{-2} + 6z^{-3}$
 - So

$$x_1(n) = \{2, 3, 4\} \qquad x_2(n) = \{3, 4, 5, 6\}$$

EXAMPLE

- $X_3(z) = X_1(z) X_2(z) \rightarrow$ Convolution

$$Z[x_1(n) * x_2(n)] = X_1(z) X_2(z)$$

- the convolution of these two sequences will give the coefficients of the required polynomial product

```
>> x1 = [2,3,4]; x2 = [3,4,5,6];
```

```
>> x3 = conv(x1,x2)
```

```
>> x3 = 6 17 34 43 38 24
```

- Hence

$$X_3(z) = 6 + 17z^{-1} + 34z^{-2} + 43z^{-3} + 38z^{-4} + 24z^{-5}$$

EXAMPLE

- Let $X_1(z) = z + 2 + 3z^{-1}$ and $X_2(z) = 2z^2 + 4z + 3 + 5z^{-1}$.
 - Determine $X_3(z) = X_1(z) X_2(z)$.

EXAMPLE

```
function [y,ny] = conv_m(x,nx,h,nh)
% Modified convolution routine for signal processing
% -----
% [y,ny] = conv_m(x,nx,h,nh)
% [y,ny] = convolution result
% [x,nx] = first signal
% [h,nh] = second signal
%
nyb = nx(1)+nh(1); nye = nx(length(x)) + nh(length(h));
ny = [nyb:nye]; y = conv(x,h);
```

EXAMPLE

- $X_1(z) = z + 2 + 3z^{-1}$ and $X_2(z) = 2z^2 + 4z + 3 + 5z^{-1}$

$$x_1(n) = \{1, \underset{\uparrow}{2}, 3\} \quad x_2(n) = \{2, 4, \underset{\uparrow}{3}, 5\}$$

```
>> x1 = [1,2,3];    n1 = [-1:1];
>> x2 = [2,4,3,5]; n2 = [-2:1];
>> [x3,n3] = conv_m(x1,n1,x2,n2)
x3 = 2 8 17 23 19 15
n3 = -3 -2 -1 0 1 2
```

- Hence

$$X_3(z) = 2z^3 + 8z^2 + 17z + 23 + 19z^{-1} + 15z^{-2}$$

COMMON Z-TRANSFORM PAIRS

<i>Sequence</i>	<i>Transform</i>	<i>ROC</i>
$\delta(n)$	1	$\forall z$
$u(n)$	$\frac{1}{1 - z^{-1}}$	$ z > 1$
$-u(-n - 1)$	$\frac{1}{1 - z^{-1}}$	$ z < 1$
$a^n u(n)$	$\frac{1}{1 - az^{-1}}$	$ z > a $
$-b^n u(-n - 1)$	$\frac{1}{1 - bz^{-1}}$	$ z < b $
$[a^n \sin \omega_0 n] u(n)$	$\frac{(a \sin \omega_0) z^{-1}}{1 - (2a \cos \omega_0) z^{-1} + a^2 z^{-2}}$	$ z > a $
$[a^n \cos \omega_0 n] u(n)$	$\frac{1 - (a \cos \omega_0) z^{-1}}{1 - (2a \cos \omega_0) z^{-1} + a^2 z^{-2}}$	$ z > a $
$na^n u(n)$	$\frac{az^{-1}}{(1 - az^{-1})^2}$	$ z > a $
$-nb^n u(-n - 1)$	$\frac{bz^{-1}}{(1 - bz^{-1})^2}$	$ z < b $

EXAMPLE

- Using z-transform properties and the z-transform table, determine the z-transform of

$$x_1(n) = (n-2)(0,5)^{(n-2)} \cos\left[\frac{\pi}{3}(n-2)\right] u(n-2)$$

EXAMPLE

$$x_1(n) = (n-2)(0,5)^{(n-2)} \cos\left[\frac{\pi}{3}(n-2)\right] u(n-2)$$

- Applying the sample-shift property

$$Z[x(n-n_o)] = z^{-n_o} X(z)$$



$$X(z) = Z[x(n)] = z^{-2} Z\left[n(0,5)^n \cos\left(\frac{\pi n}{3}\right) u(n)\right]$$

EXAMPLE

$$X(z) = Z[x(n)] = z^{-2} Z \left[n(0,5)^n \cos\left(\frac{\pi n}{3}\right) u(n) \right]$$

- Applying the multiplication by a ramp property

$$Z[nx(n)] = -z \frac{dX(z)}{dz}$$



$$X(z) = z^{-2} \left\{ -z \frac{dZ \left[(0,5)^n \cos\left(\frac{\pi n}{3}\right) u(n) \right]}{dz} \right\}$$

EXAMPLE

$$X(z) = z^{-2} \left\{ -z \frac{dZ \left[(0,5)^n \cos\left(\frac{\pi n}{3}\right) u(n) \right]}{dz} \right\}$$

- From table

$$\begin{aligned} Z \left[(0,5)^n \cos\left(\frac{\pi n}{3}\right) u(n) \right] &= \frac{1 - \left(0,5 \cos \frac{\pi}{3}\right) z^{-1}}{1 - 2 \left(0,5 \cos \frac{\pi}{3}\right) z^{-1} + 0,25 z^{-1}}; \quad |z| > 0,5 \\ &= \frac{1 - 0,25 z^{-1}}{1 - 0,5 z^{-1} + 0,25 z^{-2}}; \quad |z| > 0,5 \end{aligned}$$

EXAMPLE

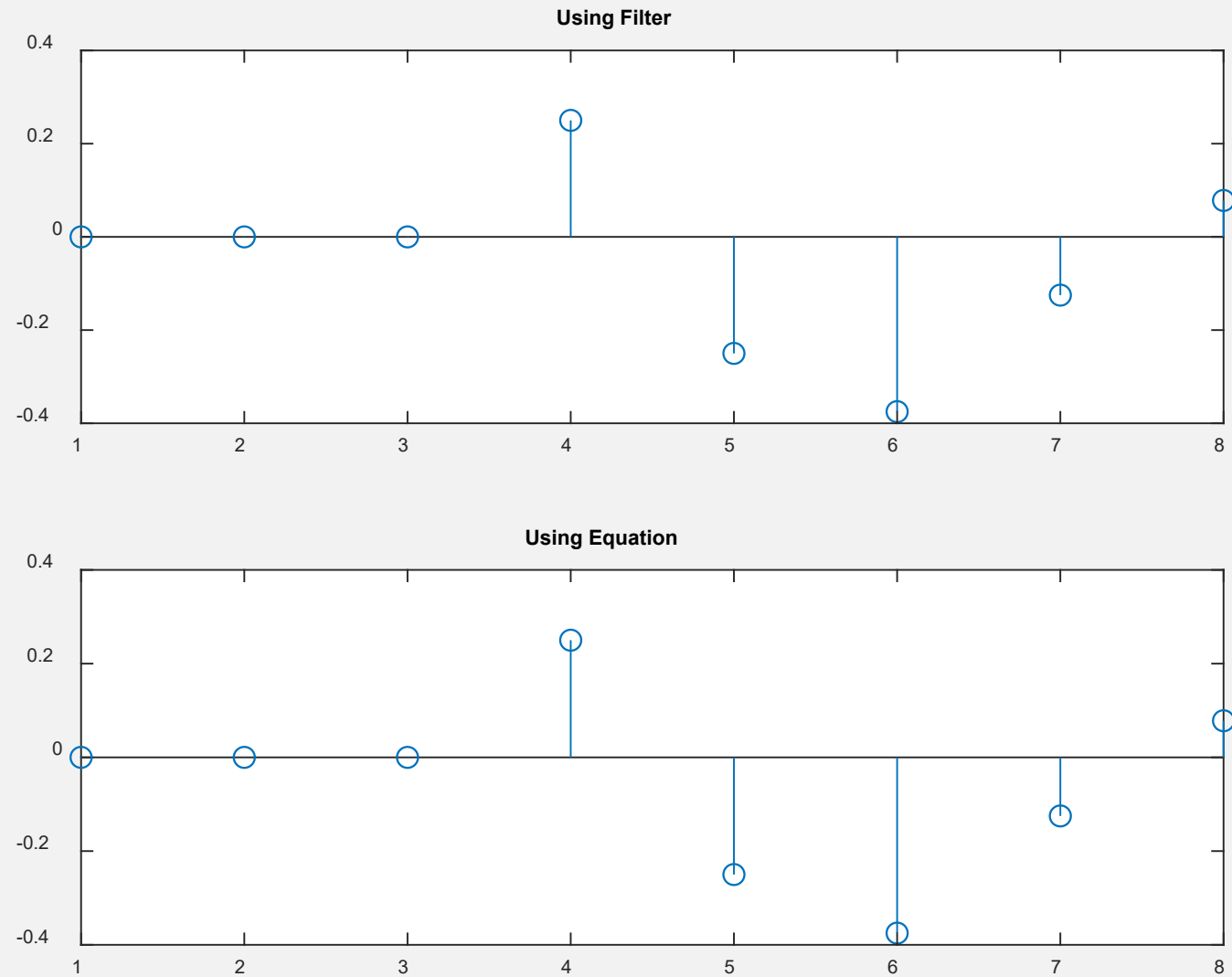
- Hence

$$\begin{aligned}
 X(z) &= -z^{-1} \frac{d}{dz} \left\{ \frac{1 - 0,25z^{-1}}{1 - 0,5z^{-1} + 0,25z^{-2}} \right\}; \quad |z| > 0,5 \\
 &= -z^{-1} \left\{ \frac{-0,25z^{-2} + 0,5z^{-3} - 0,0625z^{-4}}{1 - z^{-1} + 0,75z^{-2} - 0,25z^{-3} + 0,0625z^{-4}} \right\}, \\
 &= \frac{0,25z^{-3} - 0,5z^{-4} + 0,0625z^{-5}}{1 - z^{-1} + 0,75z^{-2} - 0,25z^{-3} + 0,0625z^{-4}}, \quad |z| > 0,5
 \end{aligned}$$

EXAMPLE: MATLAB VERIFICATION

```
>> b = [0,0,0,0.25,-0.5,0.0625]; a = [1,-1,0.75,-0.25,0.0625];  
>> [delta,n]=impseq(0,0,7)  
>> x = filter(b,a,delta) % check sequence  
>> x = [(n-2).*(1/2).^(n-2).*cos(pi*(n-2)/3)].*stepseq(2,0,7)
```

EXAMPLE: MATLAB VERIFICATION



THE INVERSION OF Z-TRANSFORM

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THE INVERSE Z-TRANSFORM

- The inverse z-transform of a complex function $X(z)$ is given by

$$x(n) \triangleq Z^{-1}[X(z)] = \frac{1}{2\pi j} \oint_C X(z) z^{n-1} dz$$

- The inverse z-transform computation requires an evaluation of a complex contour integral
 - a complicated procedure
 - use the partial fraction expansion method

THE INVERSE Z-TRANSFORM IDEA

- $X(z)$ is a rational function of z^{-1}
 - can be expressed as a sum of simple factors using the partial fraction expansion
- The individual sequences corresponding to these factors can be written down using the z-transform table.

THE INVERSE Z-TRANSFORM PROCEDURE

- Given

$$X(z) = \frac{b_o + b_1 z^{-1} + \dots + b_M z^{-M}}{1 + a_1 z^{-1} + \dots + a_N z^{-N}}, \quad R_{x-} < |z| < R_{z+}$$

- express it as

$$X(z) = \underbrace{\frac{\tilde{b}_o + \tilde{b}_1 z^{-1} + \dots + \tilde{b}_{N-1} z^{-(N-1)}}{1 + a_1 z^{-1} + \dots + a_N z^{-N}}}_{\text{Proper rational part}} + \underbrace{\sum_{k=0}^{M-N} C_k z^{-k}}_{\text{polynomial part if } M \geq N}$$

- Can be obtained by performing polynomial division if $M \geq N$ using the `deconv` function.

THE INVERSE Z-TRANSFORM PROCEDURE

- Perform a partial fraction expansion on the proper rational part of $X(z)$ to obtain

$$X(z) = \sum_{k=1}^N \frac{R_k}{1 - p_k z^{-1}} + \sum_{k=0}^{M-N} C_k z^{-k}$$

- p_k is the k th pole of $X(z)$ and R_k is the residue at p_k
- The poles are distinct for which the residues are given by

$$R_k = \frac{\tilde{b}_0 + \tilde{b}_1 z^{-1} + \dots + \tilde{b}_{N-1} z^{-(N-1)}}{1 + a_1 z^{-1} + \dots + a_N z^{-N}} \left(1 - p_k z^{-1} \right) \Big|_{z=p_k}$$

THE INVERSE Z-TRANSFORM PROCEDURE

- If a pole p_k has multiplicity r , then its expansion is given by

$$\sum_{\ell=1}^r \frac{R_{k,\ell} z^{-(\ell-1)}}{(1-p_k z^{-1})} = \frac{R_{k,1}}{1-p_k z^{-1}} + \frac{R_{k,2} z^{-1}}{(1-p_k z^{-1})^2} + \dots + \frac{R_{k,r} z^{-(r-1)}}{(1-p_k z^{-1})^r}$$

- the residues $R_{k'}$ are computed using a more general formula

THE INVERSE Z-TRANSFORM PROCEDURE

- write $x(n)$ as

$$x(n) = \sum_{k=1}^N R_k Z^{-1} \left[\frac{1}{1 - p_k z^{-1}} \right] + \sum_{k=0}^{M-N} C_k \delta(n - k)$$

- finally, use the relation from Table to complete $x(n)$

$$Z^{-1} \left[\frac{z}{z - p_k} \right] = \begin{cases} p_k^n u(n) & |z_k| \leq R_{x-} \\ -p_k^n u(-n-1) & |z_k| \geq R_{x+} \end{cases}$$

EXAMPLE

- Find the inverse z-transform of

$$x(z) = \frac{z}{3z^2 - 4z + 1}$$

EXAMPLE

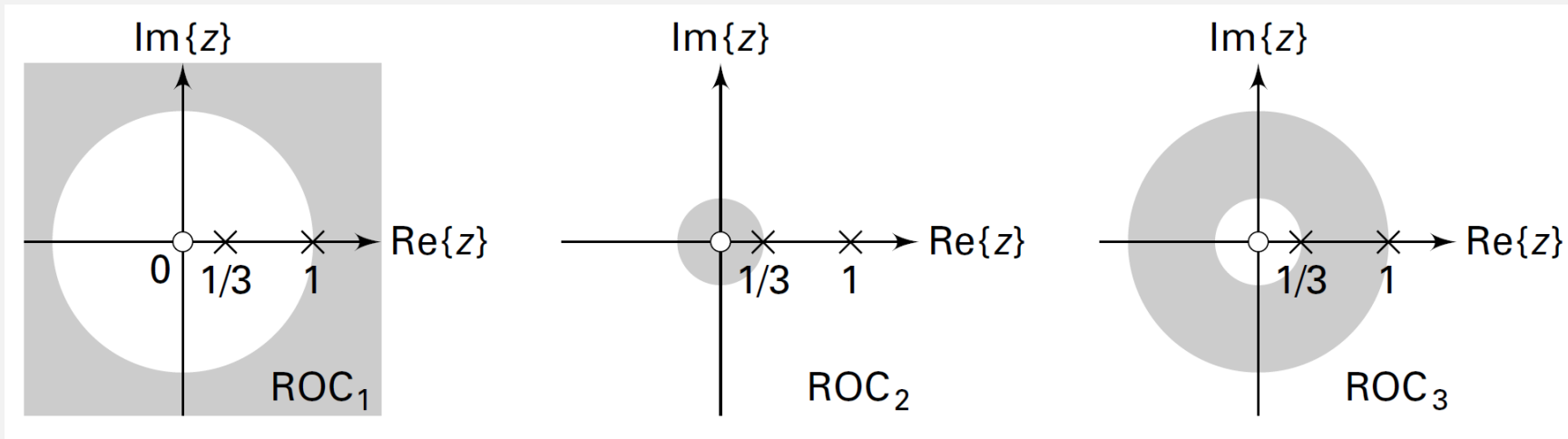
$$x(z) = \frac{z}{3z^2 - 4z + 1}$$

- Write

$$\begin{aligned} X(z) &= \frac{z}{3\left(z^2 - \frac{4}{3}z + \frac{1}{3}\right)} = \frac{\frac{1}{3}z^{-1}}{1 - \frac{4}{3}z^{-1} + \frac{1}{3}z^{-2}} \\ &= \frac{\frac{1}{3}z^{-1}}{\left(1 - z^{-1}\right)\left(1 - \frac{1}{3}z^{-1}\right)} = \frac{\frac{1}{2}}{1 - z^{-1}} - \frac{\frac{1}{2}}{1 - \frac{1}{3}z^{-1}} \\ &= \frac{1}{2} \left(\frac{1}{1 - z^{-1}} \right) - \frac{1}{2} \left(\frac{1}{1 - \frac{1}{3}z^{-1}} \right) \end{aligned}$$

EXAMPLE

- $X(z)$ has two poles: $z_1 = 1$ and $z_2 = 1/3$
- there are *three* possible ROCs



EXAMPLE

1. $\text{ROC}_1: 1 < |z| < \infty$.

Both poles are on the interior side of the ROC_1

$$|z_1| \leq R_{x-} = 1 \text{ and } |z_2| \leq 1$$

a right-sided sequence.

$$x_1(n) = \frac{1}{2}u(n) - \frac{1}{2}\left(\frac{1}{3}\right)^n u(n)$$

EXAMPLE

2. $\text{ROC}_2: 0 < |z| < 1/3$.

both poles are on the exterior side of the ROC_2

$|z_1| \geq R_{x+} = 1/3$ and $|z_2| \geq 1/3$

$$\begin{aligned} x_2(n) &= \frac{1}{2} \left\{ -u(-n-1) \right\} - \frac{1}{2} \left\{ -\left(\frac{1}{3}\right)^n u(-n-1) \right\} \\ &= \frac{1}{2} \left(\frac{1}{3}\right)^n u(-n-1) - \frac{1}{2} u(-n-1) \end{aligned}$$

a left-sided sequence.

EXAMPLE

3. $\text{ROC}_3: \frac{1}{3} < |z| < 1$.

pole z_1 is on the exterior side of the $\text{ROC}_3: |z_1| \geq R_{x+} = 1$

pole z_2 is on the interior side of the $\text{ROC}_3: |z_2| \leq \frac{1}{3}$

$$x_3(n) = -\frac{1}{2}u(-n-1) - \frac{1}{2}\left(\frac{1}{3}\right)^n u(n)$$

a two-sided sequence.

MATLAB IMPLEMENTATION

- A MATLAB function `residuez` is available to compute the residue part and the direct (or polynomial) terms of a rational function in z^{-1} .
- A rational function in which the numerator and the denominator polynomials are in *ascending* powers of z^{-1}

$$\begin{aligned}
 X(z) &= \frac{b_o + b_1 z^{-1} + \dots + b_M z^{-M}}{a_o + a_1 z^{-1} + \dots + a_N z^{-N}} = \frac{B(z)}{A(z)} \\
 &= \sum_{k=1}^N \frac{R_k}{1 - p_k z^{-1}} + \sum_{k=0}^{M-N} C_k z^{-k}
 \end{aligned}$$

MATLAB IMPLEMENTATION

$$[R,p,C]=\text{residuez}(b,a)$$

- Computes the residues, poles, and direct terms of $X(z)$ in which two polynomials $B(z)$ and $A(z)$ are given in two vectors b and a
 - column vector R contains the residues
 - column vector p contains the pole locations
 - row vector C contains the direct terms

MATLAB IMPLEMENTATION

- If $p(k) = \dots = p(k+r-1)$ is a pole of multiplicity r , then the expansion includes the term of the form

$$\frac{R_k}{1 - p_k z^{-1}} + \frac{R_{k+1}}{(1 - p_k z^{-1})^2} + \dots + \frac{R_{k+r-1}}{(1 - p_k z^{-1})^r}$$

MATLAB IMPLEMENTATION

`[b,a]=residuez(R,p,C)`

- Three input arguments and two output arguments
- Converts the partial fraction expansion back to polynomials with coefficients in row vectors b and a.

EXAMPLE - RESIDUE CALCULATIONS

- Consider the rational function

$$X(z) = \frac{z}{3z^2 - 4z + 1}$$

EXAMPLE - RESIDUE CALCULATIONS

- Consider the rational function

$$X(z) = \frac{z}{3z^2 - 4z + 1}$$

- Rearrange $X(z)$ so that it is a function in ascending powers of z^{-1} .

$$X(z) = \frac{z^{-1}}{3 - 4z^{-1} + z^{-2}} = \frac{0 + z^{-1}}{3 - 4z^{-1} + z^{-2}}$$

EXAMPLE - RESIDUE CALCULATIONS

- using the MATLAB script

$$X(z) = \frac{z^{-1}}{3 - 4z^{-1} + z^{-2}} = \frac{0 + z^{-1}}{3 - 4z^{-1} + z^{-2}}$$

```
>> b = [0,1]; a = [3,-4,1]; [R,p,C] = residuez(b,a)
```

```
R =
```

```
0.5000
```

```
-0.5000
```

```
p =
```

```
1.0000
```

```
0.3333
```

```
c =
```

```
[]
```

$$X(z) = \frac{\frac{1}{2}}{1 - z^{-1}} - \frac{\frac{1}{2}}{1 - \frac{1}{3}z^{-1}}$$

EXAMPLE - RESIDUE CALCULATIONS

- convert back to the rational function form

$$X(z) = \frac{\frac{1}{2}}{1 - z^{-1}} - \frac{\frac{1}{2}}{1 - \frac{1}{3}z^{-1}}$$

```
>> [b,a] = residuez(R,p,C)
```

```
b =
```

```
0.0000
```

```
0.3333
```

```
a =
```

```
1.0000
```

```
-1.3333
```

```
0.3333
```

$$X(z) = \frac{0 + \frac{1}{3}z^{-1}}{1 - \frac{4}{3}z^{-1} + \frac{1}{3}z^{-2}} = \frac{z^{-1}}{3 - 4z^{-1} + z^{-2}} = \frac{z}{3z^2 - 4z + 1}$$

EXAMPLE

- Compute the inverse z-transform of

$$X(z) = \frac{1}{(1 - 0,9z^{-1})^2 (1 + 0,9z^{-1})}, \quad |z| > 0,9$$

EXAMPLE

- Evaluate the denominator polynomial as well as the residues using the MATLAB script

$$X(z) = \frac{1}{(1 - 0,9z^{-1})^2 (1 + 0,9z^{-1})}, \quad |z| > 0,9$$

```
>> b = 1; a = poly([0.9, 0.9, -0.9])
a = 1.0000 -0.9000 -0.8100 0.7290
>> [R,p,C]=residuez(b,a)
R = 0.2500 0.5000 0.2500
p = 0.9000 0.9000 -0.9000
c = []
```

EXAMPLE

- From the residue calculations and using the order of residues

$$\begin{aligned}
 X(z) &= \frac{0,25}{1-0,9z^{-1}} + \frac{0,5}{(1-0,9z^{-1})^2} + \frac{0,25}{1+0,9z^{-1}}, \quad |z| > 0,9 \\
 &= \frac{0,25}{1-0,9z^{-1}} + \frac{0,5}{0,9} z \frac{0,9z^{-1}}{(1-0,9z^{-1})^2} + \frac{0,25}{1+0,9z^{-1}}, \quad |z| > 0,9
 \end{aligned}$$

- Using table and the z-transform property of time-shift

$$\begin{aligned}
 x(n) &= 0,25(0,9)^n u(n) + \frac{5}{9}(n+1)(0,9)^{n+1} u(n+1) + 0,25(-0,9)^n u(n) \\
 &= 0,75(0,9)^n u(n) + 0,5n(0,9)^n u(n) + 0,25(-0,9)^n u(n)
 \end{aligned}$$

EXAMPLE

- MATLAB verification

```
>> [delta,n] = impseq(0,0,7); x = filter(b,a,delta) % check sequence
x =
Columns 1 through 4
1.000000000000000 0.900000000000000 1.620000000000000 1.458000000000000
Columns 5 through 8
1.968300000000000 1.771470000000000 2.125764000000000 1.913187600000000
>> x = (0.75)*(0.9).^n + (0.5)*n.*(0.9).^n + (0.25)*(-0.9).^n % answer sequence
x =
Columns 1 through 4
1.000000000000000 0.900000000000000 1.620000000000000 1.458000000000000
Columns 5 through 8
1.968300000000000 1.771470000000000 2.125764000000000 1.913187600000000
```

EXAMPLE

- Determine the inverse z-transform of

$$X(z) = \frac{1 + 0,4\sqrt{2}z^{-1}}{1 - 0,8\sqrt{2}z^{-1} + 0,64z^{-2}}$$

- so that the resulting sequence is causal and contains no complex numbers

EXAMPLE

- have to find the poles of $X(z)$ in the polar form to determine the ROC of the causal sequence

```
>> b = [1,0.4*sqrt(2)]; a=[1,-0.8*sqrt(2),0.64];
>> [R,p,C] = residuez(b,a)
R =
0.5000 - 1.0000i
0.5000 + 1.0000i
p =
0.5657 + 0.5657i
0.5657 - 0.5657i
C = []
>> Mp=(abs(p))' % pole magnitudes
Mp = 0.8000 0.8000
>> Ap=(angle(p))/pi % pole angles in pi units
Ap = 0.2500 -0.2500
```

$$X(z) = \frac{1 + 0,4\sqrt{2}z^{-1}}{1 - 0,8\sqrt{2}z^{-1} + 0,64z^{-2}}$$

EXAMPLE

- From these calculations

$$X(z) = \frac{1 + 0,4\sqrt{2}z^{-1}}{1 - 0,8\sqrt{2}z^{-1} + 0,64z^{-2}}$$

- Using table

$$X(z) = \frac{0,5 - j}{1 - 0,8e^{+j\frac{\pi}{4}}z^{-1}} + \frac{0,5 + j}{1 - 0,8e^{+j\frac{\pi}{4}}z^{-1}}, \quad |z| > 0,8$$

$$\begin{aligned} x(n) &= (0,5 - j)0,8^n e^{+j\frac{\pi}{4}n} u(n) + (0,5 + j)0,8^n e^{-j\frac{\pi}{4}n} u(n) \\ &= 0,8^n \left[0,5 \left\{ e^{+j\frac{\pi}{4}n} + e^{-j\frac{\pi}{4}n} \right\} - j \left\{ e^{+j\frac{\pi}{4}n} - e^{-j\frac{\pi}{4}n} \right\} \right] u(n) \\ &= 0,8^n \left[\cos\left(\frac{\pi n}{4}\right) + 2 \sin\left(\frac{\pi n}{4}\right) \right] u(n) \end{aligned}$$

EXAMPLE

- MATLAB verification

$$X(z) = \frac{1 + 0,4\sqrt{2}z^{-1}}{1 - 0,8\sqrt{2}z^{-1} + 0,64z^{-2}}$$

```
>> [delta, n] = impseq(0,0,6);  
>> x = filter(b,a,delta) % check sequence  
>> x = ((0.8).^n).*(cos(pi*n/4)+2*sin(pi*n/4))
```



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