

nodeflux

Extending Vision Beyond Imagination

Week 3 – Surveillance Case

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Outline

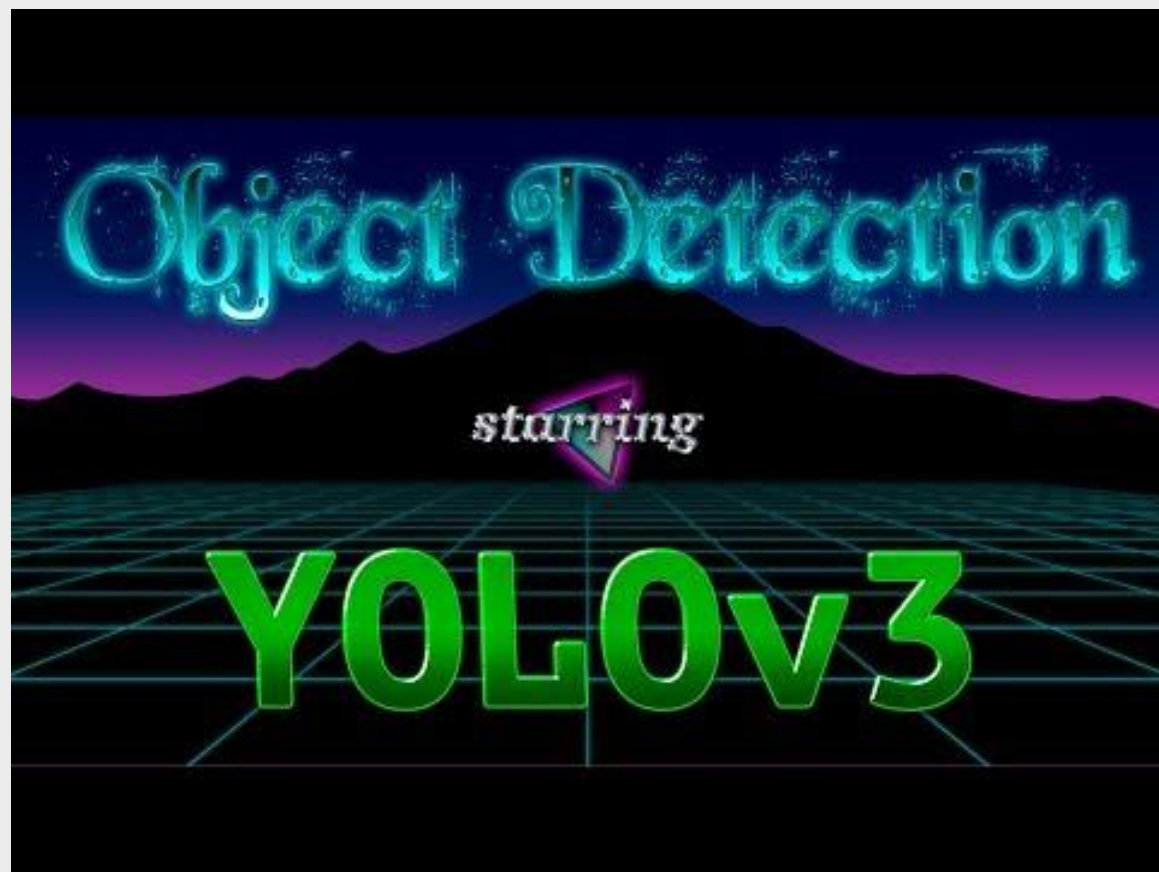
- Section 1 Introduction
- Section 2 Object Detection
- Section 3 Object Tracker
- Section 4 Simple Case





Section 1 - Introduction

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Object Detection
Expensive

Insight Data
More Expensive



Object Detection

Expensive

Insight Data

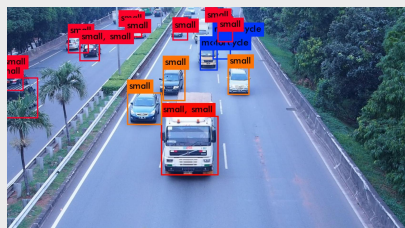
e



What's
Next?

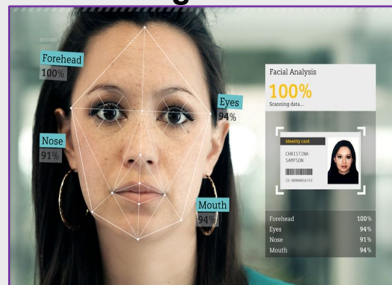


What's Next, After Object Detection ??

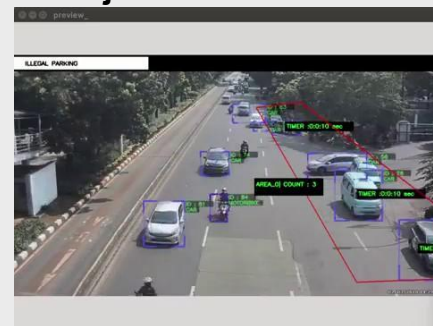


Alerting

Face recognition



Object Restriction



Data Analytics

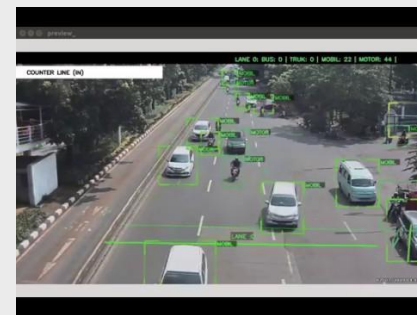
Dwelling Time



Dwell heatmap



Object Counter

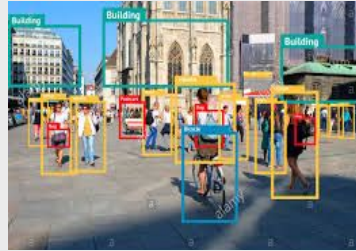


General Flow

Video Grabber



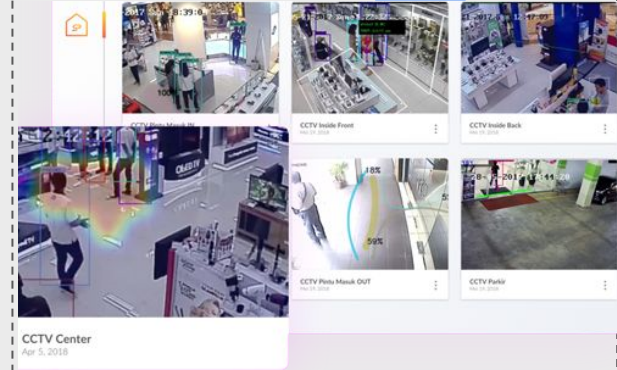
Object Detection



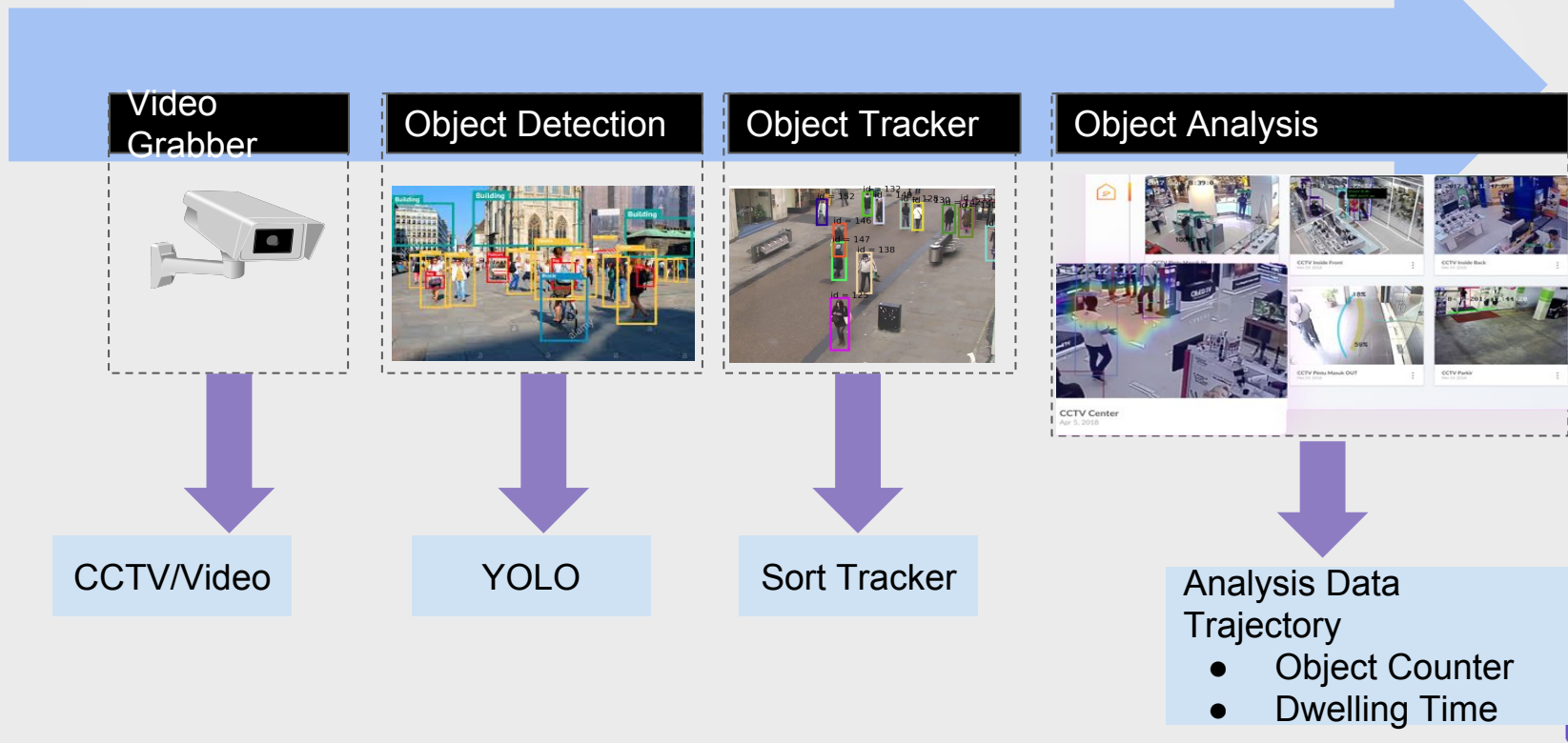
Object Tracker



Object Analytic

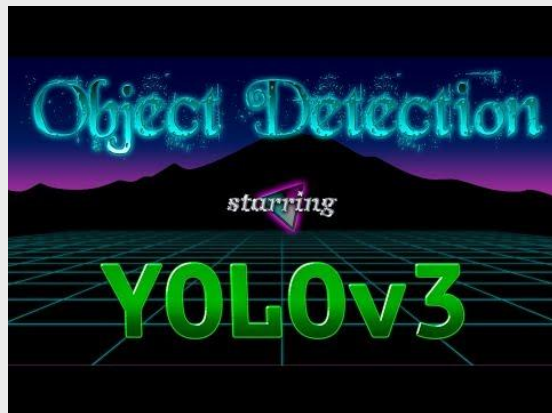
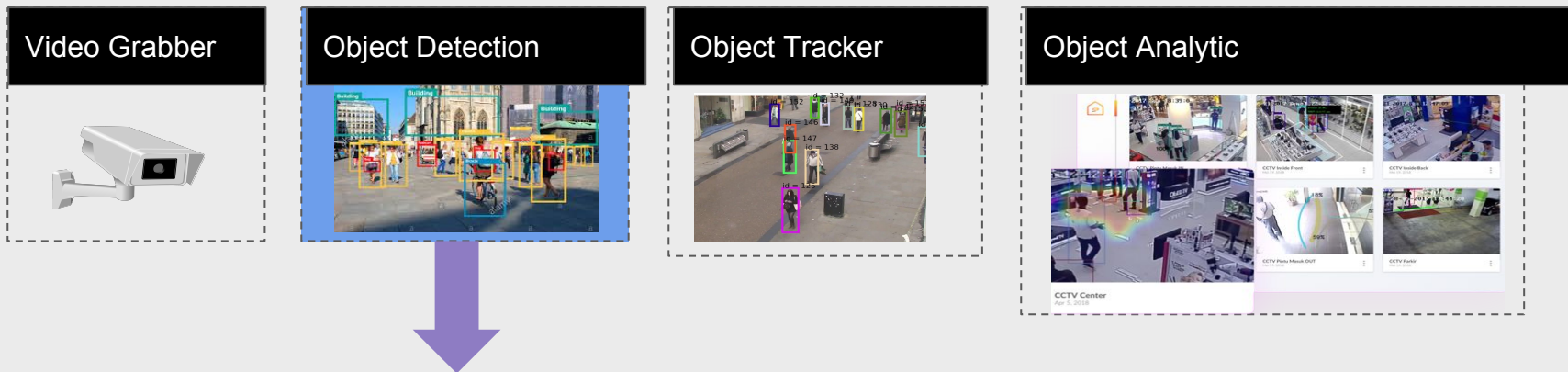


General Flow & Method proposed



Section 2 - Object Detection

Object Detection [YOLO]



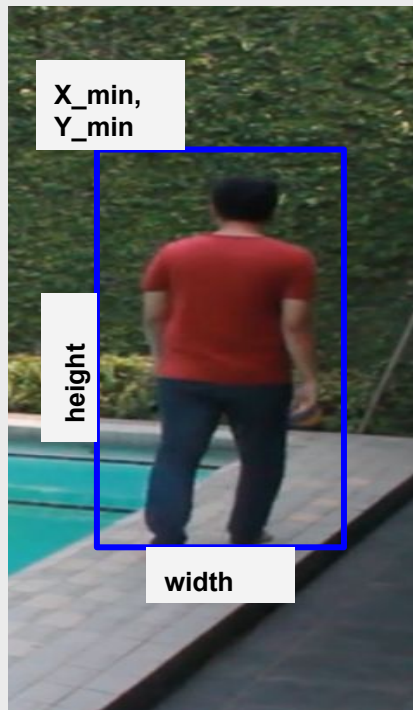
Object Detection

<https://drive.google.com/open?id=1rHNRe5evoRNsjiZl47svPYrAFmEGfDUGln9Qw-L5llu4>



Section 3 – Object Tracker

Object Detection [YOLO]



```
[  
  ('person',  
   0.7308904528617859,  
   (  
     345.1903076171875,  
     148.33767700195312,  
     42.11083984375,  
     182.61672973632812  
   )  
)  
]
```

Meta Data :

- Label
- Confidence level
- BBOX= x_min,y_min, width, height

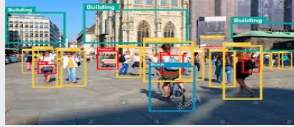


Object Tracker Concept

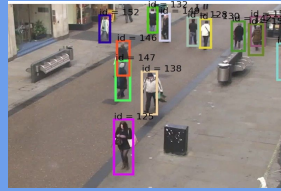
Video Grabber



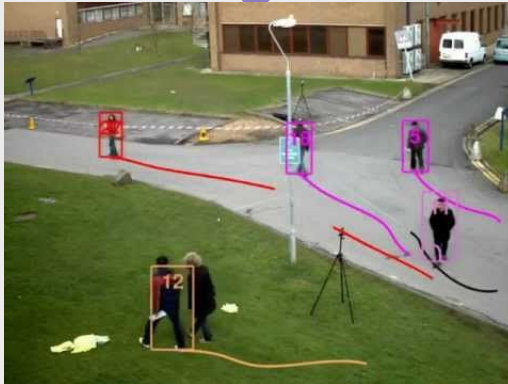
Object Detection



Object Tracker

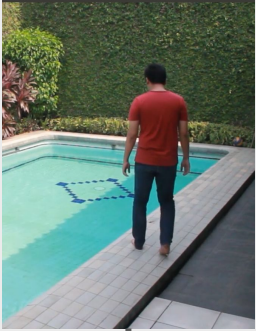


Object Analysis



Object Tracker Concept

Previous frame

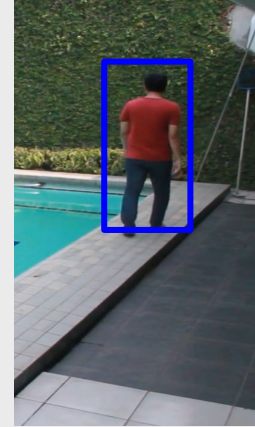


Current frame



Methods

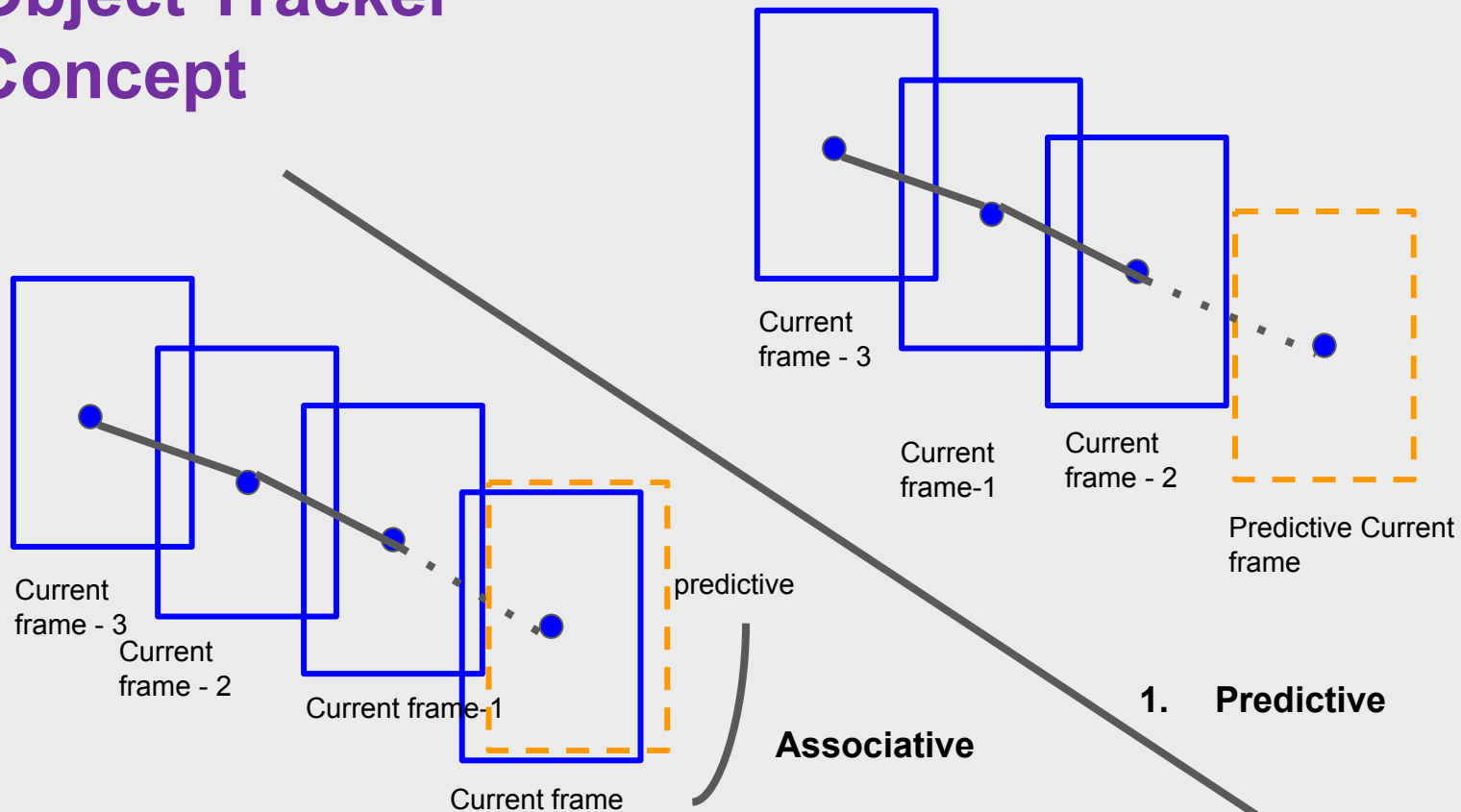
Current frame
tracking output



- Distance (Euclidean distance)
- Correlations (Regression, Kalman Filter)
- Feature similarity (NN, CNN)
- Combinations



Object Tracker Concept



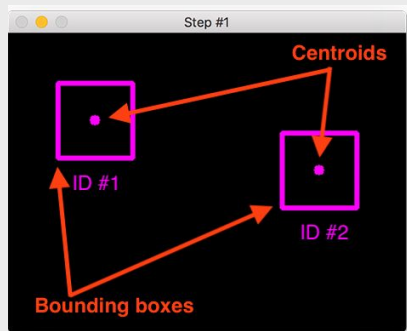
1. Predictive
2. Predictive, Correlative, Associative
 - Need object detector / bounding box



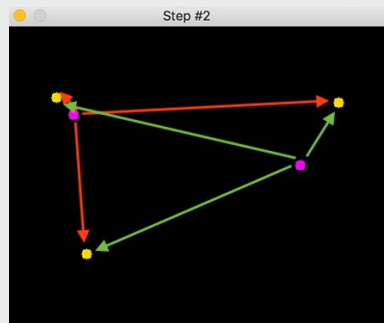
Object Tracker

[Distance similarity]

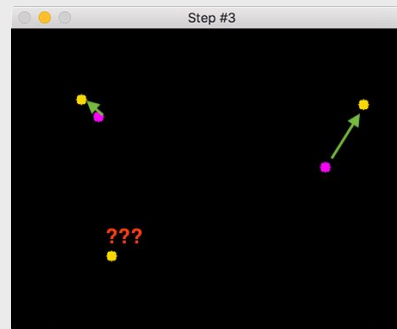
The centroid tracking algorithm



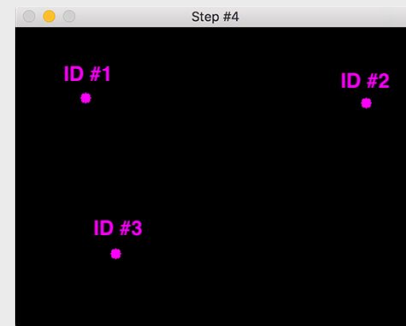
Step #1: Accept bounding box coordinates and compute centroids



Step #2: Compute Euclidean distance between new bounding boxes and existing objects



Step #3: Update (x, y)-coordinates of existing objects



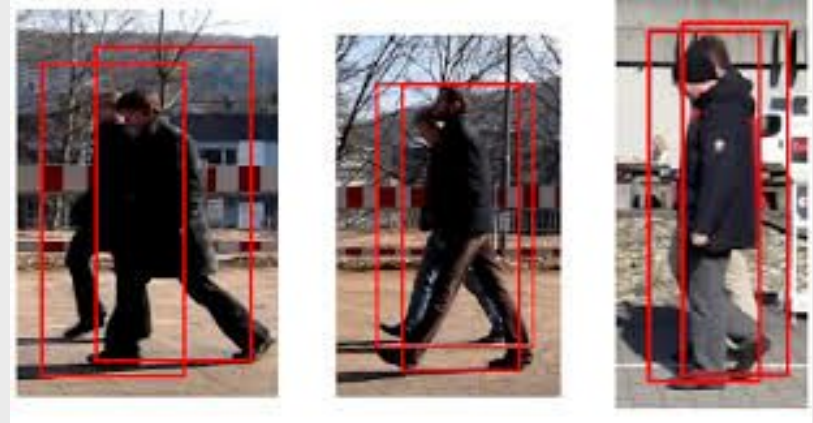
Step #4: Register new objects



Object Tracker

[CHALLENGES]

- What happens when an object overlaps/occluded with another one?
- What if, Object detector disappear on the frame.
- What if, being Frame skipping??



Object Tracker

[SORT Tracker]

Simple Online and Realtime Tracking

[Alex Bewley](#), [Zongyuan Ge](#), [Lionel Ott](#), [Fabio Ramos](#), [Ben Upcroft](#)

<https://github.com/abewley/sort>

The main focus is to associate objects efficiently for online and realtime applications

Combining Kalman Filter and Hungarian algorithm

Others Tracker

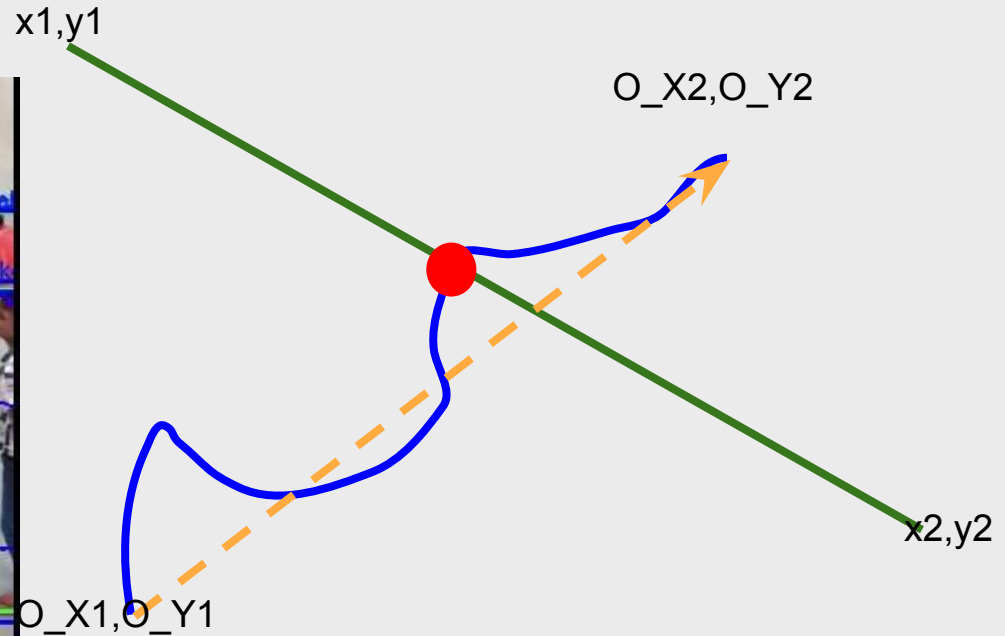
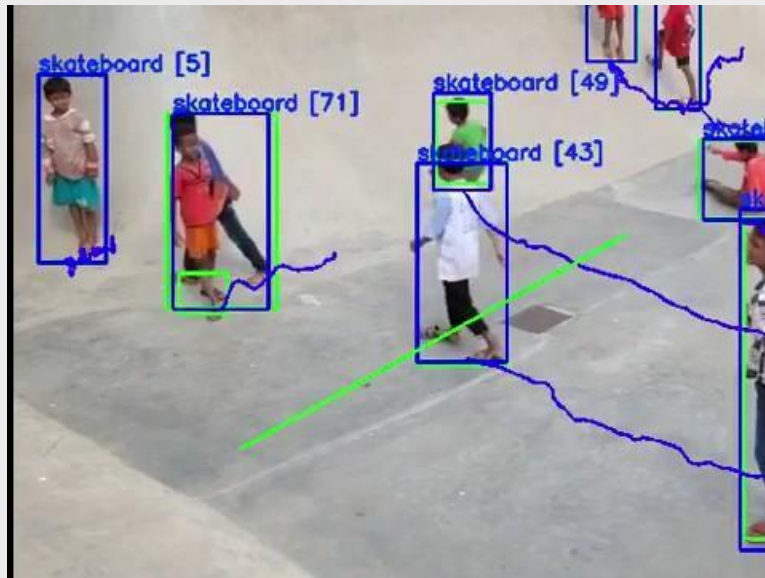
Tracker	OpenCV 3.0	OpenCV 3.1	OpenCV 3.2	OpenCV 3.3	OpenCV 3.4+
CSRT	N/A	Could not compile	No	No	Yes
KCF	N/A	Could not compile	Yes	Yes	Yes
Boosting	N/A	Could not compile	Yes	Yes	Yes
MIL	N/A	Could not compile	Yes	Yes	Yes
TLD	N/A	Could not compile	Yes	Yes	Yes
MedianFlow	N/A	Could not compile	Yes	Yes	Yes
MOSSE	N/A	Could not compile	No	No	Yes



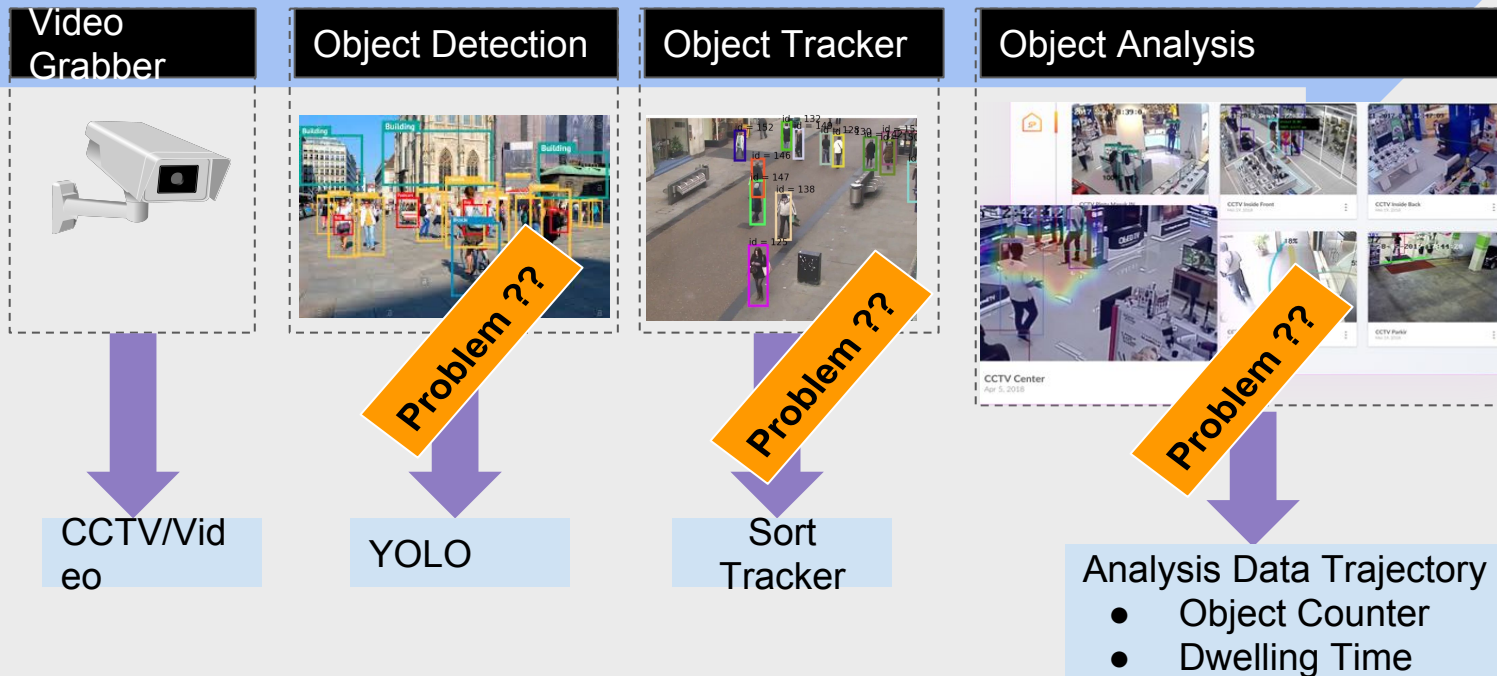
Section 4 - Simple case

Data Analytics

[Object line counter]



General flow & Method proposed



Thank you



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