Contents

***Abstract*—This manual is an introduction to control systems based on GATE problems.Links to sample Python codes are available in the text.**

Download python codes using

1 Stability

2 Routh Hurwitz Criterion

2.0.1. The characteristic equation of linear time invariant system is given by

$$\nabla(s) = s^4 + 3s^3 + 3s^2 + s + k = 0 \quad (2.0.1.1)$$

Find the condition for the system to be BIBO stable using the Routh Array.
Solution:

$$\nabla(s) = s^4 + 3s^3 + 3s^2 + s + k = 0 \quad (2.0.1.2)$$

The Routh hurwitz criterion:-

$$\begin{vmatrix} s^4 \\ s^3 \\ s^2 \\ s^1 \\ s^0 \end{vmatrix} \begin{vmatrix} 1 & 3 & k \\ 3 & 1 & 0 \\ \frac{8}{3} & k & 0 \\ \frac{\frac{8}{3}-3k}{\frac{8}{3}} & 0 & 0 \\ k & 0 & 0 \end{vmatrix} \quad (2.0.1.3)$$

Given system is stable if

$$k > 0, \frac{\frac{8}{3} - 3k}{\frac{8}{3}} > 0 \quad (2.0.1.4)$$

$$\frac{8}{3} - 3k > 0 \quad (2.0.1.5)$$

$$3k < \frac{8}{3} \quad (2.0.1.6)$$

$$(0 < k < \frac{8}{9}) \quad (2.0.1.7)$$

for example the zeros of polynomial $s^4 + 3s^3 + 3s^2 + s + 0.5 = 0$ are

$$s1 = -0.08373 + 0.45773i \quad (2.0.1.8)$$

$$s2 = -0.08373 - 0.45773i \quad (2.0.1.9)$$

$$s3 = -1.41627 + 0.55075i \quad (2.0.1.10)$$

$$s4 = -1.41627 - 0.55075i \quad (2.0.1.11)$$

2.0.2. Modify the Python code in Problem to verify your solution by choosing two different values of k.
Solution: The following code

```
codes/ee18btech11008/ee18btech11008.py
```

provides the necessary soution.

3 Compensators

4 Nyquist Plot