CS 106B

Lecture 29: Esoteric Data

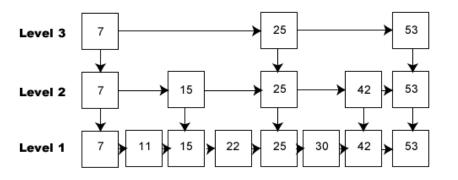
Structures: Skip Lists and

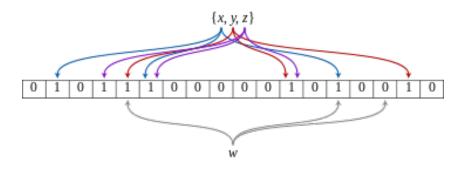
Bloom Filters

Wednesday, December 7, 2016

Programming Abstractions
Fall 2016
Stanford University
Computer Science Department

Lecturer: Chris Gregg







Today's Topics

- Logistics
- Final Exam Monday. See website for room assignments.
- •Final Review Session: Friday December 9, 3:30pm-5:00pm in Bishop Auditorium
- Esoteric Data Structures
- Skip Lists
- Bloom Filters



Esoteric Data Structures

- •In CS 106B, we have talked about many standard, famous, and commonly used data structures: Vectors, Linked Lists, Trees, Hash Tables, Graphs
- However, we only scratched the surface of available data structures, and data structure research is alive and well to this day.
- •Let's take a look at two interesting data structures that have interesting properties and you might not see covered in detail in a standard course: the **skip list** and the **bloom filter**.





Skip Lists

- A "skip list" is a balanced search structure that maintains an ordered, dynamic set for insertion, deletion and search
- What other efficient (log n or better) sorted search structures have we talked about?

Hash Tables (nope, not sorted)

Heaps (nope, not searchable)

Sorted Array (kind of, but, insert/delete is O(n))

Binary Trees (only if balanced, which we didn't really discuss)

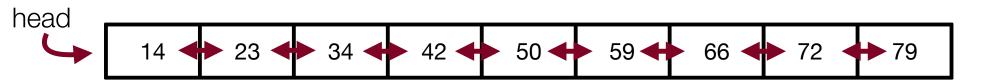


Skip Lists

- •A skip list is an easy-to-implement, simple, randomized search structure that will give us O(log N) in expectation for search, insert, and delete, but also with high probability.
- •Invented by William Pugh in 1989 -- fairly recent!



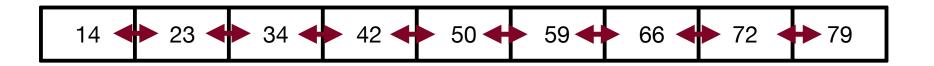
- Let's see what we can do with a linked list to make it better.
- •How long does it take to search a sorted, doubly-linked list for an element?



 $\frac{\log(N)}{\log(N)}$ nope! it is O(n) ... we *must* traverse the list!

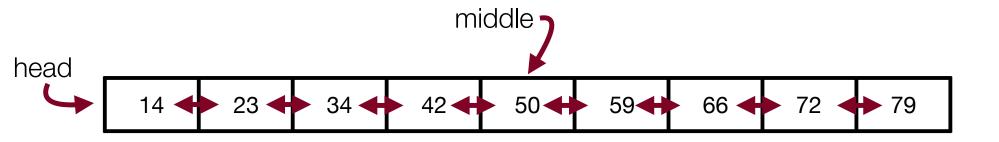


•How might we help this situation?





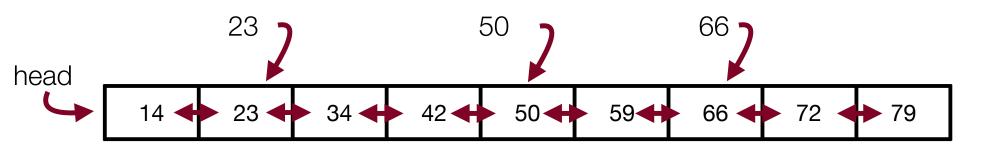
•What if we put another link into the middle?



•This would help a little...we could start searching from the middle, but we would still have to traverse



•Maybe we could add more pointers...



•This would help some more...

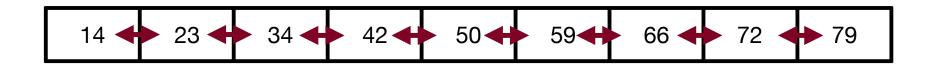


•Let's play a game. I've chosen the numbers for this list in a particular way. Does anyone recognize the sequence?





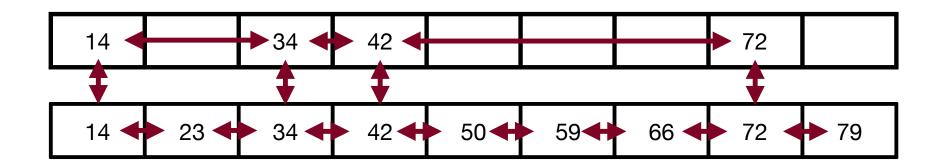
•Let's play a game. I've chosen the numbers for this list in a particular way. Does anyone recognize the sequence?



•These are the subway stops on the NYC 7th Avenue line:)



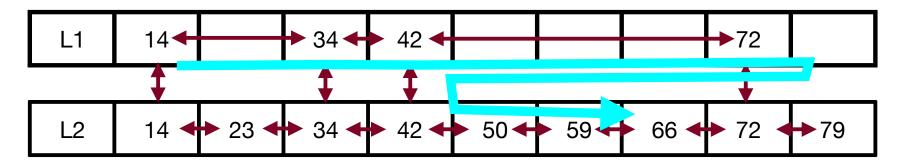
•A somewhat unique feature in the New York City subway system is that it has *express lines*:



•This models a skip list almost perfectly!

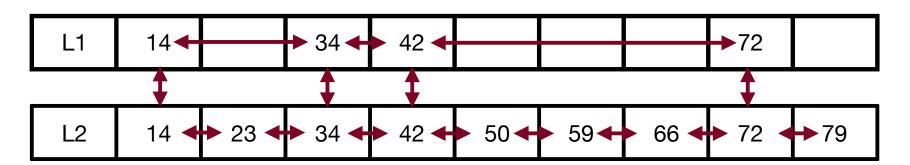


•To search the list (or ride the subway): Walk right in the top list (L1) and when you've gone too far, go back and then down to the bottom list (L2) (e.g., search for 59)



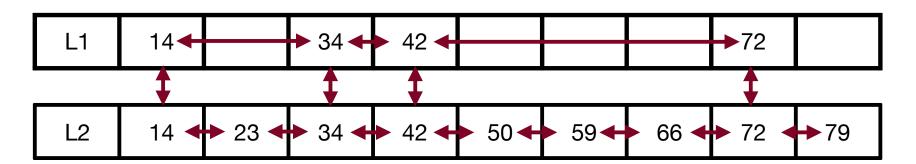


- •What is the best placement for the nodes in L1?
- •This placement might be good for subways, but we care about worst-case performance, which we want to minimize. How about equally spaced nodes?



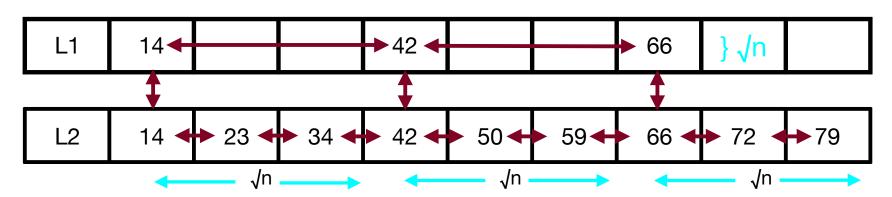


- •The "search cost" can be represented by |L1| + (|L2| / |L1|), or |L1| + (n / |L1|), where n is the number of nodes in L2 (L2 must have all stops)
- Let's do some calculus to minimize this amount...
- •The minimum will be when |L1| is equal to (n/|L1|), or when $|L1|=\sqrt{n}$





- •The minimum will be when |L1| is equal to (n/|L1|), or when $|L1|=\sqrt{n}$
- •So, the search cost with a minimum second list is $\sqrt{n} + n/\sqrt{n} = 2\sqrt{n}$
- •We want them equally spaced.



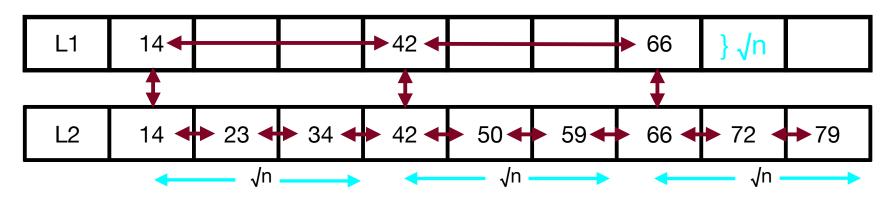


What if we had more linked lists??

2 sorted lists: 2√n

3 sorted lists: 3¾n

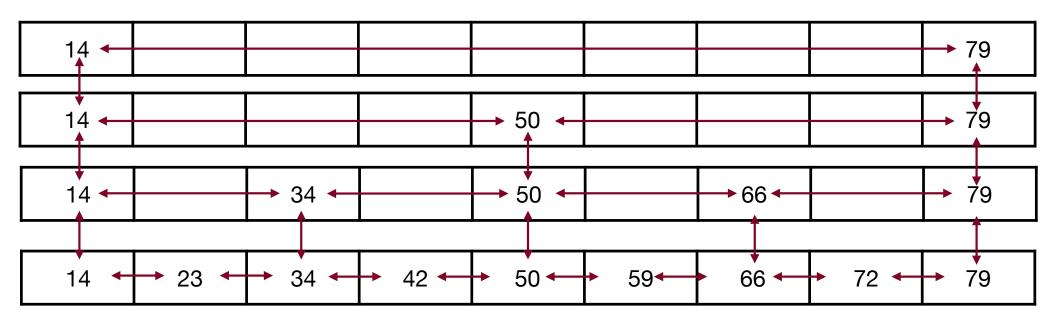
k sorted lists: k∜n





Skip Lists

log n linked lists look like a binary tree (and act like one!)





Building a Skip List

We just determined that the best option if we have n elements is to have log_2n lists.



Building a Skip List

To build a skip list, we could try to keep all the elements perfectly aligned — in the lowest list, we have n elements, and in the next list up we have n/2 elements, etc.



Building a Skip List

So...what we do instead is implement a probabilistic strategy — we flip a coin!



Building a Skip List Probabilistically

- 1. All elements must go into the bottom list (search to find the spot)
- 2. After inserting into the bottom list, flip a fair, two sided coin. If the coin comes up heads, add the element to the next list up, and flip again, repeating step 2.
- If the coin comes up tails, stop.
 (example on board you do have to have -∞ on each level)

Let's build one!



Skip Lists: Big(O) for Building, Searching, Deleting

To search a skip list, we "traverse" the list level-by-level, and there is a high probability that there are log n levels. Each level up has a good probability to have approximately half the number of elements. There is a high probability that searching is O(log n).

To insert, we first search O(log n), and then we must flip the coin to keep adding. Worst case? O(∞). But, there is a *very good probability* that we will have to do a small number of inserts up the list. So, this has a high probability of also being simply O(log n)

To delete? Find the first instance of your value, then delete from all the lists — also O(log n).



Our second esoteric data structure is called a *bloom filter*, named for its creator, Burton Howard Bloom, who invented the data structure in 1970.

A bloom filter is a space efficient, probabilistic data structure that is used to tell whether a member is in a set.



Bloom filters are a bit odd because they can *definitely* tell you whether an element is *not* in the set, but can only say whether the element is *possibly* in the set.



In other words: "false positives" are possible, but "false negatives" are not.

(A *false positive* would say that the element is in the set when it isn't, and a *false negative* would say that the element is not in the set when it is.



The idea is that we have a "bit array." We will model a bit array with a regular array, but you can compress a bit array by up to 32x because there are 8 bits in a byte, and there are 4 bytes to a 32-bit number (thus, 32x!) (although Bloom Filters themselves need more space per element than 1 bit).



a bit array:



Bloom Filters: start with an empty bit array (all zeros), and *k* hash functions.

$$k1 = (13 - (x \% 13))\% 7$$
, $k2 = (3 + 5x) \% 7$, etc.

0	1	2	3	4	5	6	7
0	0	0	0	0	0	0	0



Bloom Filters: start with an empty bit array (all zeros), and *k* hash functions.

The hash functions should be independent, and the optimal amount is calculable based on the number of items you are hashing, and the length of your table (see Wikipedia for details).

0	1	2	3	4	5	6	7
0	0	0	0	0	0	0	0



Values then get hashed by all k hashes, and the bit in the hashed position is set to 1 in each case.

0	1	2	3	4	5	6	7
0	0	0	0	0	0	0	0



Bloom Filter Example

Insert 129: x=129, k1=1, k2=4

k1 = (13 - (x % 13))% 7, k2 = (3 + 5x) % 7, etc.

0	1	2	3	4	5	6	7
0	1	0	0	1	0	0	0

k1 == 1, so we change bit 1 to a 1 k2 == 4, so we change bit 4 to a 1



Insert 479: x=479, k1=2, k2=4

k1 = (13 - (x % 13))% 7, k2 = (3 + 5x) % 7, etc.

0	1	2	3	4	5	6	7
0	1	1	0	1	0	0	0

k1 == 2, so we change bit 2 to a 1 k2 == 4, so we would change bit 3 to a 1, but it is already a 1.



To check if 129 is in the table, just hash again and check the bits.

k1=1, k2=4: probably in the table!

0	1	2	3	4	5	6	7
0	1	1	0	1	0	0	0

$$k1 = (13 - (x \% 13))\% 7$$
, $k2 = (3 + 5x) \% 7$, etc.



To check if 123 is in the table, hash and check the bits. k1=0, k2=2: *cannot* be in table because the 0 bit is still 0.

0	1	2	3	4	5	6	7
0	1	1	0	1	0	0	0

$$k1 = (13 - (x \% 13))\% 7$$
, $k2 = (3 + 5x) \% 7$, etc.



To check if 402 is in the table, hash and check the bits. k1=1, k2=4:

Probably in the table (but isn't! False positive!).

0	1	2	3	4	5	6	7
0	1	1	0	1	0	0	0

Online example: http://billmill.org/bloomfilter-tutorial/

$$k1 = (13 - (x \% 13))\% 7$$
, $k2 = (3 + 5x) \% 7$, etc.



What is the probability that we have a false positive?

If *m* is the number of bits in the array, then the probability that a bit is not set to 1 is

$$1-\frac{1}{m}$$



If k is the number of hash functions, the probability that the bit is not set to 1 by any hash function is

$$\left(1-\frac{1}{m}\right)^k$$



If we have inserted n elements, the probability that a certain bit is still 0 is

$$\left(1-\frac{1}{m}\right)^{kn}$$



To get the probability that a bit is 1 is just 1- the answer on the previous slide:

$$1 - \left(1 - \frac{1}{m}\right)^{kn}$$



Now test membership of an element that is not in the set. Each of the k array positions computed by the hash functions is 1 with a probability as above. The probability of all of them being 1, (false positive):

$$\left(1 - \left[1 - \frac{1}{m}\right]^{kn}\right)^k \approx \left(1 - e^{-kn/m}\right)^k$$



For our previous example, m=8, n=2, k=2, so:

$$\left(1 - \left[1 - \frac{1}{m}\right]^{kn}\right)^k = 0.17$$
, or 17% of the time we will get a false positive.



Bloom Filters: Why?

Why would we want a structure that can produce false positives?

Example: Google Chrome uses a local Bloom Filter to check for malicious URLs — if there is a hit, a stronger check is performed.



Bloom Filters: Why?

There is one more negative issue with a Bloom Filter: you can't delete! If you delete, you might delete another inserted value, as well! You could keep a second bloom filter of removals, but then you could get false positives in that filter...



Bloom Filters: Why?

You have to perform *k* hashing functions for an element, and then either flip bits, or read bits. Therefore, they perform in O(k) time, which is independent of the number of elements in the structure. Additionally, because the hashes are independent, they can be parallelized, which gives drastically better performance with multiple processors.



References and Advanced Reading

· References:

- •MIT Skip Lists lecture: http://ocw.mit.edu/courses/electrical-engineering-and-computer-science/6-046j-introduction-to-algorithms-sma-5503-fall-2005/video-lectures/lecture-12-skip-lists/
- •Online Bloom Filter example: http://billmill.org/bloomfilter-tutorial/
- •Wikipedia Bloom Filters: https://en.wikipedia.org/wiki/Bloom_filter



Extra Slides



Esoteric Data Structure: Ropes Normally, strings are kept in memory in contiguous chunks: "The_quick_fox_jumps_over_the_dog"

0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31
Т	h	е	_	q	U	i	С	k	_	f	0	X	_	j	u	m	р	S	_	0	V	е	r	_	t	h	е	_	d	0	g

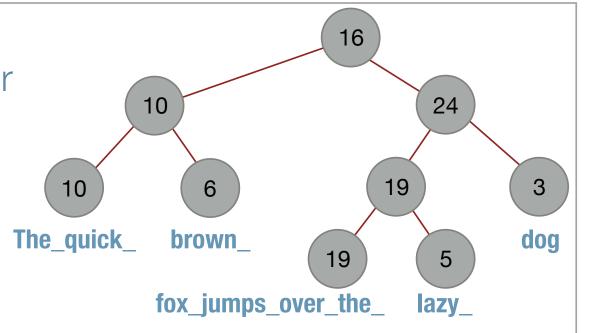
Ropes

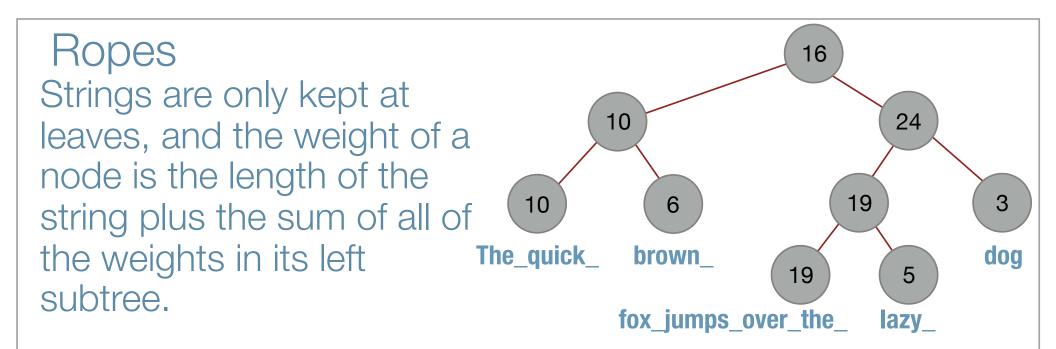
However, this doesn't make it easy to insert into a string: you have to break the whole string up each time, and re-create a new string.

0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31
Т	h	е	_	q	U	i	С	k	_	f	0	X	_	j	U	m	р	S	_	0	V	е	r	_	t	h	е	_	d	0	g

Ropes

A "rope" is a tree of smaller strings (eventually—it can start as a long string) that makes it efficient to store and manipulate the entire The_quick_string.

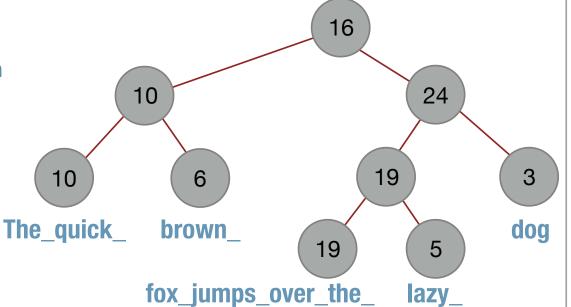




Ropes

Searching for a character at a position, do a recursive search from the root: to search for the "j" at character position 21:

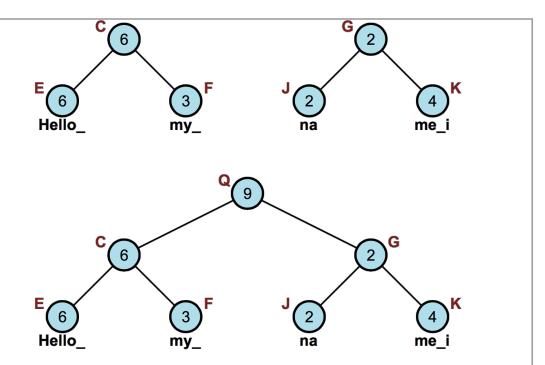
- The root is 16, which is less than 21. We subtract 21-16==5, and we go right.
- 24 > 5, no subtraction (only on right), go left
- 19 > 5, go left.
- 19 > 5, but no more left! The character at the index of the string at that node is "j"

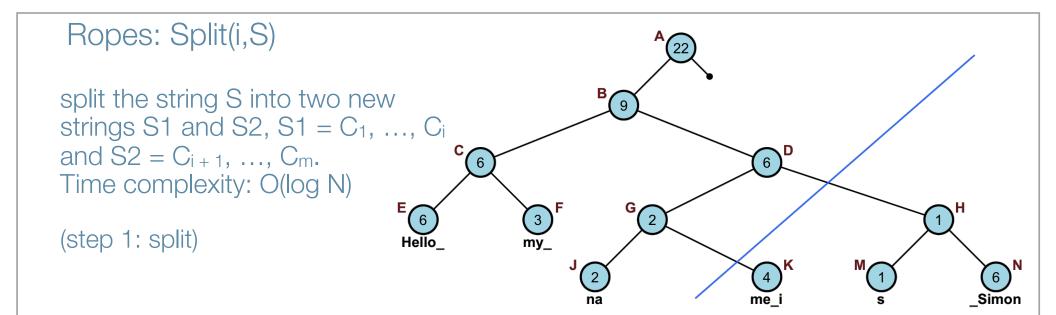


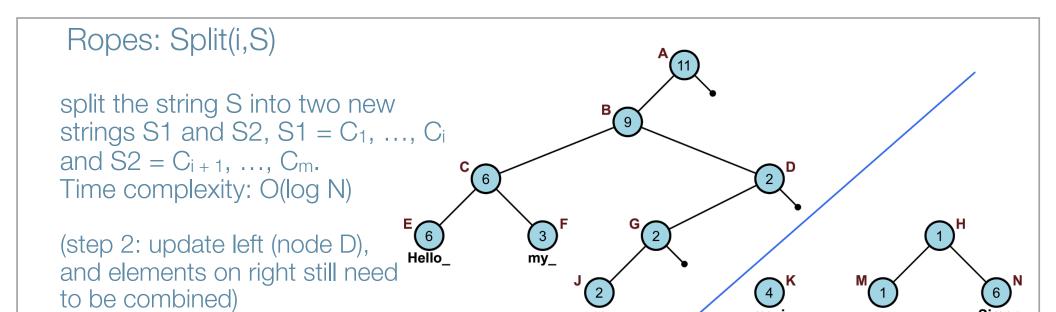
Ropes: Full search algorithm: O(log n) 16 // Note: Assumes 1-based indexing. 24 function index(RopeNode node, integer i) 10 if node.weight < i then</pre> return index(node.right, i - node.weight) else if exists(node.left) then 19 10 return index(node.left, i) else :_quick_ brown_ dog return node.string[i] 19 5 endif endif fox_jumps_over_the_

Ropes: Concatenate(S1,S2)
Time: O(1) (or O(log N) time to compute the root weight)

Simply create a new root node, with left=S1 and right=S2.



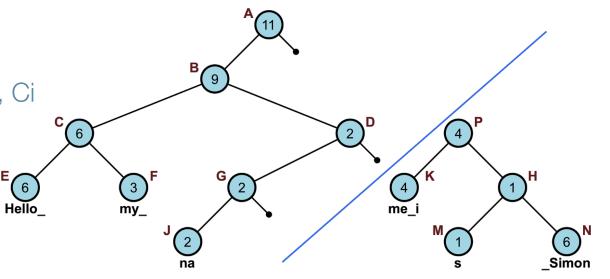




Ropes: Split(i,S)

split the string S into two new strings S1 and S2, S1 = C1, ..., Ci and S2 = C_{i+1} , ..., C_m . Time complexity: O(log N)

(step 3: combine with new root P for right side) (may need to balance)

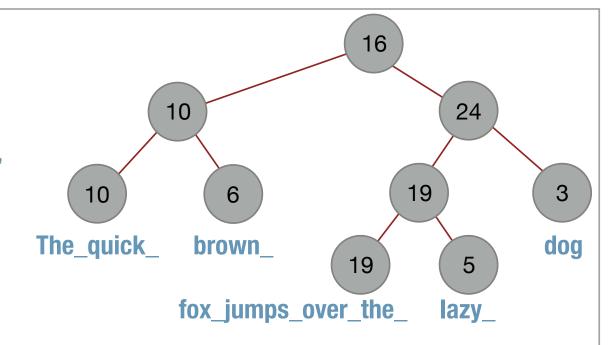


Ropes: Insert(i,S')

insert the string S' beginning at position i in the string s, to form a new string $C_1, \ldots, C_i, S', C_{i+1}, \ldots, C_m$.

Time complexity: O(log N).

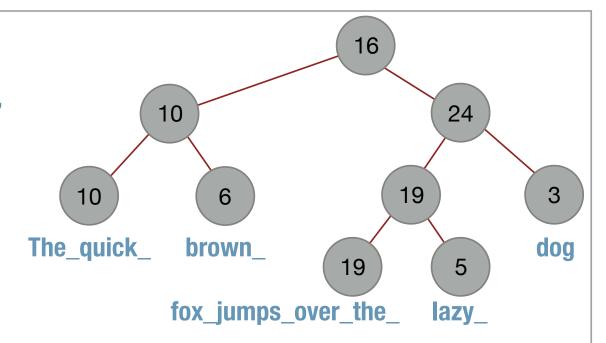
Can be done by a Split() and two Concat() operations



Ropes: Delete(i,j)

delete the substring C_i , ..., C_{i+j-1} , from s to form a new string C_1 , ..., C_{i-1} , C_{i+j} , ..., C_m . Time complexity: O(log N).

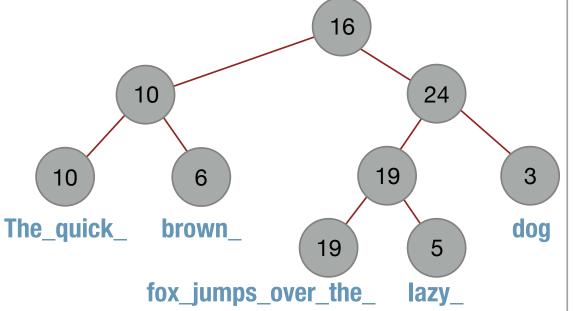
Can be done by two Split() operations and one Concat() operation



Ropes: Report(i,j)

output the string C_i , ..., C_{i+j-1} . Time complexity: O(j + log N)

To report the string C_i , ..., C_{i+j-1} , output C_i , ..., C_{i+j-1} by doing an inorder traversal of T starting at the node that has the i^{th} element.



Comparison: Ropes -vs- Strings (from Wikipedia) Rope Advantages:

- Ropes enable much faster insertion and deletion of text than monolithic string arrays, on which operations have time complexity O(n).
- Ropes don't require O(n) extra memory when operated upon (arrays need that for copying operations)
- Ropes don't require large contiguous memory spaces.
- If only nondestructive versions of operations are used, rope is a persistent data structure. For the text editing program example, this leads to an easy support for multiple undo levels.

Comparison: Ropes -vs- Strings (from Wikipedia) Rope Disadvantages:

- Greater overall space usage when not being operated on, mainly to store parent nodes. There is a trade-off between how much of the total memory is such overhead and how long pieces of data are being processed as strings; note that the strings in example figures above are unrealistically short for modern architectures. The overhead is always O(n), but the constant can be made arbitrarily small.
 - Increase in time to manage the extra storage
 - Increased complexity of source code; greater risk for bugs