THE SHAWARA TANDON DEARCH - It explores decision variable space (parameter space) of an objective function sequentially an a seemingly random lashion to find optimal point that optimize the objective function. - It is based on fenoling the minimum point wing random numbers. Strength Demple, easy to understand. 2) can be customized for specific 3) Con converge to global optimum solution if search space 9s compact. Weakness Practically for complex problems finding allohally optimum solution can take amount of three. Sundaram

PRIMITIVE RANDOM SEARCH (For multivous) Let f(x) be an objective function to be manifeled and x be the point under consideration consideration. - Pomittere algorithm lterates over follows Step 1: Choose a start point X as the current point. Step 2: Add a random vector de to the current point X au the devision Variable epace & evaluate the Objective function at the new popul Step3: If f(x+dx) < f(x), Set selvrent points $X = X + d_X$ Step 4: Stop if maxemum number of function évaluations le reached Otherwise of to back to step 2 to find a new point. FOR EDUCATIONAL USE

Phonettere approach es trulty a random method because search obtrecteons are purely gueded by a random number generator. WAYS TO IMPROVE ? Boused on following observations. Observation 1: If search an a direction resulte in a higher objective function, the opposite direction can often lead to a lower objective function. Observation 2 : Buccessive successful seasche
Pria Certain direction should bear
subsequent searching toward ture directly On the other hand, successive failures
on a certain direction should discourage
subsequent searching along this alived

	MODIFIED RAMDON1 SEARCH
	- Flast Observation leads to reverse step
	en me organal method.
	- Sewad Observation motivates the use
	of bras term.
	Algorithm:
	Step 1: choose a start point X a
	the current pornt! Set anikal
	the current pornt! Set anikal blad B equals to a xero vector
	,
	Step 2: Adal a bêae term B and a
	Trandom vector dx to the current
	poent X an the angut space \$
	evaluate the objective function at
,	the new point at X+B+dx
	Step 3: If f(X+B+dx) < f(x),
	Step 3 : If $f(x+i)+d_x) < f(x)$, Set current point of
	X = X + B + dx and
	Stept : rif B = \$ 0.213 +0.40x and
	goto step 6, otherwise go to next st
	. /

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crep4: If $f(X+B-d_X) \neq f(x)$, set current point as, X = X + B - dx and B = B - 0.4 dx goto step 6. otherwese , goto mext step. Step 5: Set the Beal g

B = 0.5B and goto step 6. Slep 6: Stop if the maximum no. of function evaluations pe reached. Otherwise goto step 2. to find a mew point.