AUP: Assignment - 10 [IPC]

Aditi Rajendra Medhane 111803177

17th November 2021

$\mathbf{Q}\mathbf{1}$

A pipe setup is given below that involves three processes. P is the parent process, and C1 and C2 are child processes, spawned from P. The pipes are named p1, p2, p3, and p4. Write a program that establishes the necessary pipe connections, setups, and carries out the reading/writing of the text in the indicated directions.

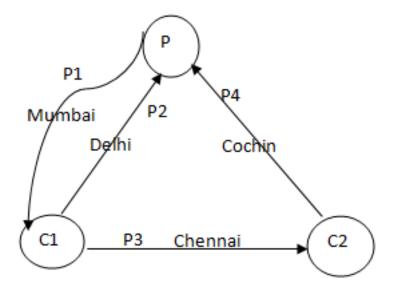


Figure 1: Pipe Setup

Code

```
#include <sys/types.h>
    #include <fcntl.h>
2
    #include <unistd.h>
    #include <errno.h>
    #include <stdio.h>
    #include <string.h>
    #define M1 "Mumbai"
    #define M2 "Delhi"
    #define M3 "Chennai"
10
    #define M4 "Cochin"
^{11}
12
    #define BUFLEN 10
13
14
    int main(void) {
15
16
             int pid, ppid;
17
18
             int pipes[5][2];
19
20
             int n;
21
             char buf[BUFLEN];
22
23
```

```
int i;
24
25
             /* open 4 pipes */
26
            for (i = 1; i <= 4; i++) {
27
                     if (pipe(pipes[i]) == -1) {
28
                              perror("pipe");
29
                              return errno;
30
                     }
31
            }
32
33
             if ((pid = fork()) == -1) {
34
                     perror("fork 1 failed");
35
                     return errno;
36
37
            else if (!pid) {
38
39
                     /* C1 */
40
                     /* 1 W */
41
                     close(pipes[1][1]);
42
43
                     /* 2 R */
44
                     close(pipes[2][0]);
45
46
                     /* 3 R */
47
                     close(pipes[3][0]);
48
49
                     /* 4 RW */
50
                     close(pipes[4][0]);
51
                     close(pipes[4][1]);
52
53
                     pid = getpid();
                     ppid = getppid();
55
56
                     printf("%d is child of %d\n", pid, ppid);
57
58
                     if ((n = read(pipes[1][0], buf, BUFLEN)) == -1) {
59
                              perror("read 1");
60
                              return errno;
61
62
                     printf("%d Read %s\n", pid, buf);
63
                     close(pipes[1][0]);
64
65
                     if (write(pipes[2][1], M2, strlen(M2) + 1) == -1) {
66
                              perror("write 2");
68
                              return errno;
                     }
69
                     printf("%d Wrote %s\n", pid, M2);
70
                     close(pipes[2][1]);
71
72
                     if (write(pipes[3][1], M3, strlen(M3) + 1) == -1) {
73
                              perror("write 3");
                              return errno;
75
76
                     printf("%d Wrote %s\n", pid, M3);
77
                     close(pipes[3][1]);
78
79
80
                     return 0;
            }
81
82
            if ((pid = fork()) == -1) {
83
                     perror("fork 2 failed");
84
85
                     return errno;
86
            else if (!pid) {
                     /* C2 */
88
89
                     /* 1 RW */
90
```

```
close(pipes[1][0]);
91
                      close(pipes[1][1]);
92
93
                      /* 2 RW */
                      close(pipes[2][0]);
95
                      close(pipes[2][1]);
96
97
                      /* 3 W */
98
                      close(pipes[3][1]);
99
100
                      /* 4 R */
101
                      close(pipes[4][0]);
102
103
                      pid = getpid();
104
                      ppid = getppid();
105
                      printf("%d is child of %d\n", pid, ppid);
106
107
                      if ((n = read(pipes[3][0], buf, BUFLEN)) == -1) {
108
                               perror("read 3");
109
                               return errno;
110
                      }
111
                      printf("%d Read %s\n", pid, buf);
112
                      close(pipes[3][0]);
113
114
                      if (write(pipes[4][1], M4, strlen(M4) + 1) == -1) {
115
                               perror("write 4");
116
                               return errno;
117
118
                      printf("%d Wrote %s\n", pid, M4);
119
                      close(pipes[4][1]);
120
121
                      return 0;
122
             }
123
124
             /* P */
125
126
              /* close read end of 1 */
127
             close(pipes[1][0]);
128
129
              /* close write end of 2 */
130
             close(pipes[2][1]);
131
132
133
              /* close write end of 4 */
             close(pipes[4][1]);
134
135
              /* close both ends of 3 */
136
             close(pipes[3][0]);
137
             close(pipes[3][1]);
138
139
140
             pid = getpid();
141
             printf("%d is parent\n", pid);
142
143
              if (write(pipes[1][1], M1, strlen(M1) + 1) == -1) {
144
                      perror("write 1");
145
146
                      return errno;
147
             printf("%d Wrote %s\n", pid, M1);
148
             close(pipes[1][1]);
149
150
             if ((n = read(pipes[2][0], buf, BUFLEN)) == -1) {
151
                      perror("read 2");
152
153
                      return errno;
             printf("%d Read %s\n", pid, buf);
155
             close(pipes[2][0]);
156
157
```

```
if ((n = read(pipes[4][0], buf, BUFLEN)) == -1) {
158
                      perror("read 4");
159
                      return errno;
160
             printf("%d Read %s\n", pid, buf);
162
             close(pipes[4][0]);
163
164
             return 0;
165
    }
166
167
```

Output

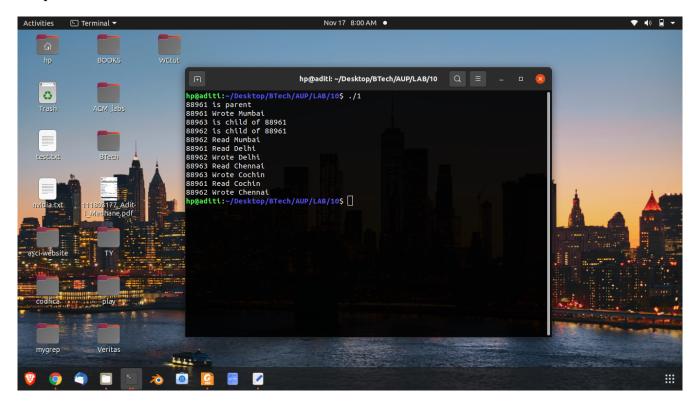


Figure 2: Messages read and written by processes

Let P1 and P2 be two processes alternatively writing numbers from 1 to 100 to a file. Let P1 write odd numbers and p2, even. Implement the synchronization between the processes using FIFO.

Code

```
#include <sys/types.h>
    #include <sys/stat.h>
2
    #include <unistd.h>
    #include <fcntl.h>
    #include <stdio.h>
    #include <errno.h>
    #include <string.h>
9
    #define FIF01 "/tmp/aup_fifo1"
10
    #define FIF02 "/tmp/aup_fifo2"
11
    #define FILENAME "/tmp/aup_file"
12
    #define BUFLEN 10
13
14
    int main(void) {
15
16
            int pid;
17
            int fr, fw, fp;
            int i;
19
            char buf [BUFLEN];
20
21
            if (mkfifo(FIFO1, S_IRUSR | S_IWUSR) == -1) {
22
                     perror("mkfifo 1");
23
24
                     return errno;
            }
25
26
             if (mkfifo(FIFO2, S_IRUSR | S_IWUSR) == -1) {
27
                     perror("mkfifo 2");
28
29
                     return errno;
            }
30
31
32
             if ((fp = open(FILENAME, O_WRONLY | O_CREAT,
                             S_{IRUSR} \mid S_{IWUSR}) == -1) \{
33
                     perror("file");
34
                     return errno;
35
            }
36
37
             if ((pid = fork()) == -1) {
38
39
                     perror("fork");
                     return errno;
40
41
            else if (pid) {
42
                     /* P1 */
43
44
                     if ((fw = open(FIFO1, O_WRONLY)) == -1) {
45
                              perror("write 1");
46
                              return errno;
47
48
49
                     if ((fr = open(FIFO2, O_RDONLY)) == -1) {
50
51
                              perror("read 2");
                              return errno;
52
                     }
53
54
                     i = 1;
55
                     while (i <= 100) {
56
                              sprintf(buf, "%d\n", i);
57
58
                              if (write(fp, buf, strlen(buf)) == -1) {
59
                                       perror("odd write");
60
```

```
return errno;
61
                               }
62
63
                               if (write(fw, "*", 1) == -1) {
                                        perror("sync write odd");
65
                                        return errno;
66
                               }
67
68
                               if (read(fr, buf, 1) == -1) {
69
                                        perror("sync read odd");
70
                                        return errno;
71
                               }
72
73
                               i += 2;
74
                      }
75
76
                       close(fp);
77
                       close(fw);
78
                       close(fr);
79
80
                      return 0;
81
             }
82
             else {
83
                       /* P1 */
84
85
                       if ((fr = open(FIF01, O_RDONLY)) == -1) {
86
                               perror("read 1");
87
                               return errno;
88
                      }
89
90
                       if ((fw = open(FIFO2, O_WRONLY)) == -1) {
91
                               perror("write 2");
92
                               return errno;
93
                      }
94
95
                      i = 2;
96
                      while (i <= 100) {
97
                               if (read(fr, buf, 1) == -1) {
98
                                        perror("sync read even");
99
                                        return errno;
100
                               }
101
102
                               sprintf(buf, "%d\n", i);
103
104
                               if (write(fp, buf, strlen(buf)) == -1) {
105
                                        perror("odd write");
106
                                        return errno;
107
                               }
108
109
                               if (write(fw, "*", 1) == -1) {
110
                                        perror("sync write even");
111
                                        return errno;
112
                               }
113
114
                               i += 2;
115
                      }
116
117
                       close(fp);
118
                       close(fw);
119
                       close(fr);
120
121
                      return 0;
122
             }
123
    }
124
```

Explanation

The program uses two FIFOs, /tmp/aup_fifo1 and /tmp/aup_fifo2. The file which is used for writing the numbers is /tmp/aup_file.

Output

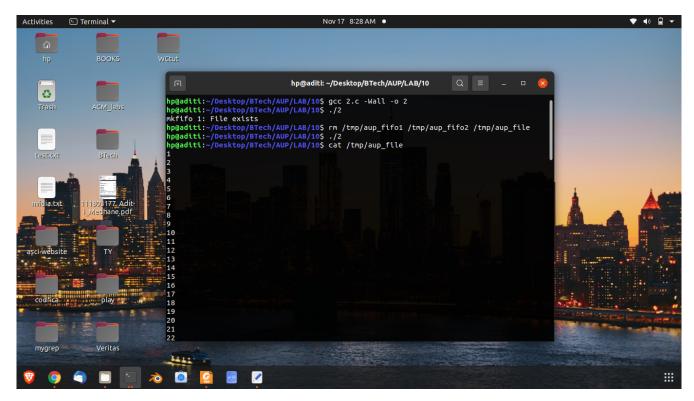


Figure 3: Synchronized writes to shared file

$\mathbf{Q3}$

Implement a producer-consumer setup using shared memory and semaphore. Ensure that data doesn't get over-written by the producer before the consumer reads and displays on the screen. Also ensure that the consumer doesn't read the same data twice.

Code

```
#include <sys/types.h>
    #include <unistd.h>
2
    #include <sys/mman.h>
3
    #include <sys/stat.h>
    #include <fcntl.h>
5
    #include <semaphore.h>
6
    #include <errno.h>
    #include <stdio.h>
    #define BUF_SIZE 5
10
    #define N_ITEMS 10
11
12
    int main(void) {
13
14
            int *buf;
15
            sem_t *sem_fill;
16
            sem_t *sem_empty;
             int pid;
18
             int i;
19
20
            printf("Maximum number of elements in buffer: %d\n", BUF_SIZE);
21
            printf("Number of items to be produced and consumed: %d\n", N_ITEMS);
22
23
             if ((buf = (int *)mmap(NULL,
25
                              BUF_SIZE * sizeof(int),
                              PROT_READ | PROT_WRITE,
26
                              MAP_SHARED | MAP_ANONYMOUS,
27
                              -1,
28
                              0)) == (void *)-1) {
29
                     perror("mmap 1");
                     return errno;
31
            }
32
33
             if ((sem_fill = (sem_t *)mmap(NULL,
34
                              sizeof(sem_t),
35
                              PROT_READ | PROT_WRITE,
36
                              MAP_SHARED | MAP_ANONYMOUS,
37
38
                              -1,
                              0)) == (void *)-1) {
39
                     perror("mmap fill");
40
41
                     return errno;
            }
42
43
             if (sem_init(sem_fill, 1, 0) == -1) {
44
                     perror("init fill");
45
                     return errno;
46
            }
47
48
             if ((sem_empty = (sem_t *)mmap(NULL,
49
50
                              sizeof(sem_t),
                              PROT_READ | PROT_WRITE,
51
                              MAP_SHARED | MAP_ANONYMOUS,
52
                              -1,
53
                              0)) == (void *)-1) {
54
                     perror("mmap 2");
55
56
                     return errno;
            }
57
58
             if (sem_init(sem_empty, 1, BUF_SIZE) == -1) {
59
```

```
perror("init empty");
60
                      return errno;
61
             }
62
63
             if ((pid = fork()) == -1) {
64
                      perror("fork");
65
                      return errno;
66
67
             else if (pid) {
68
                      /* parent, producer */
69
70
                      for (i = 0; i < N_ITEMS; i++) {</pre>
71
                               if (sem_wait(sem_empty) == -1) {
72
                                        perror("wait in producer");
73
                                        return errno;
74
                               }
75
76
                               buf[i % BUF_SIZE] = i;
                               printf("Writing %d into buffer\n", i);
78
79
                               if (sem_post(sem_fill) == -1) {
80
                                        perror("post in producer");
81
                                        return errno;
82
                               }
83
                      }
84
             }
85
             else {
86
                       /* child, consumer */
87
88
                      for (i = 0; i < N_ITEMS; i++) {</pre>
89
                               if (sem_wait(sem_fill) == -1) {
91
                                        perror("wait in consumer");
92
                                        return errno;
93
                               }
94
95
                               printf("Read %d from buffer\n", buf[i % BUF_SIZE]);
97
                               if (sem_post(sem_empty) == -1) {
98
                                        perror("post in consumer");
99
                                                 return errno;
100
                               }
101
                      }
102
             }
103
104
             return 0;
105
    }
106
```

Explanation

There is 1 producer and 1 consumer, 10 items are sent through the shared memory in total, capacity of the shared memory is 5 items. ### Output

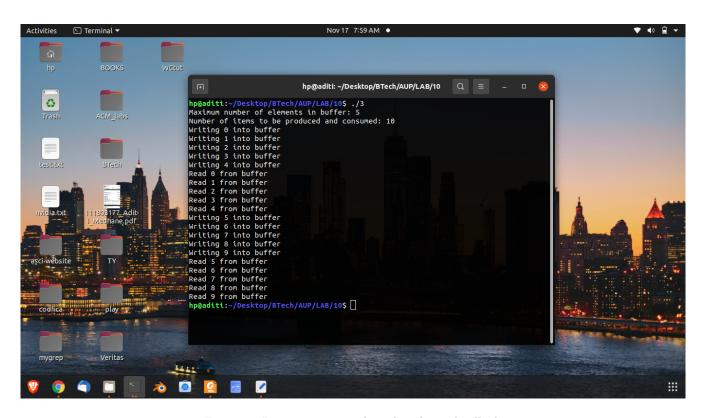


Figure 4: Items written and read without deadlock