

### Handbook of Physics

For courses:

Classical Physics for Engineers
Applied Physics for Engineers
Quantum Physics for Engineers
Condensed Matter Physics for Engineers



#### Compiled and Edited by

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**Fundamental Constants** 

### All the constants in this table are taken from *The NIST Reference on Constants*, *Units & Uncertainty* found in http://physics.nist.gov/constants.

Quantity	Symbol	Value	Unit
Speed of light in vacuum	c	299 792 458	$\mathrm{m}\mathrm{s}^{-1}$
Magnetic constant	$\mu_0$	$4\pi \times 10^{-7}$	$NA^{-2}$
Electric constant $1/\mu_0 c^2$	$\epsilon_0$	$8.854187817\times10^{-12}$	$\mathrm{F}\mathrm{m}^{-1}$
Newtonian constant of	G	$6.67384 \times 10^{-11}$	$m^3kg^{-1}s^{-2}$
gravitation		3.1	_
Planck constant	h	$6.62606957\times10^{-34}$	Js
$h/2\pi$	$\hbar$	$1.054571726 \times 10^{-34}$	Js
Elementary charge	e	$1.602176565\times10^{-19}$	C
Bohr magneton $e\hbar/2m_e$	$\mu_{ m B}$	$927.400968 \times 10^{-26}$	$ m JT^{-1}$
Nuclear magneton $e\hbar/2m_{\rm p}$	$\mu_{ m N}$	$5.05078353 \times 10^{-27}$	$ m JT^{-1}$
Fine-structure constant	α	$7.2973525698 \times 10^{-3}$	
$e^2/4\pi\epsilon_0\hbar c$			
Rydberg constant $\alpha^2 m_e c/2h$	$R_{\infty}$	10 973 731.568 539	$\mathrm{m}^{-1}$
Bohr radius	$a_0$	$0.52917721092\times10^{-10}$	m
$\alpha/4\pi R_{\infty} = 4\pi\epsilon_0 \hbar^2/m_{\rm e}e^2$			
Electron mass	$m_{ m e}$	$9.10938291 \times 10^{-31}$	kg
energy equivalent	$m_{\rm e}c^2$	0.510 998 928	MeV
Proton mass	$m_{ m p}$	$1.672621777 \times 10^{-27}$	kg
energy equivalent	$m_{ m p} c^2$	938.272 046	MeV
Neutron mass	$m_{ m n}$	$1.674927351 \times 10^{-27}$	kg
energy equivalent	$m_{ m n}c^2$	939.565 379	MeV
Avogadro constant	$N_{ m A}$	$6.02214129\times10^{23}$	$\mathrm{mol}^{-1}$
Atomic mass constant	$m_{ m u}$	$1.660538921 \times 10^{-27}$	kg
$m_{\rm u} = \frac{1}{12} m(^{12}{\rm C}) = 1{\rm u}$			
energy equivalent	$m_{ m u}c^2$	$1.492417954 \times 10^{-10}$	J
		931.494 061	MeV
Faraday constant $N_A e$	F	96 485.336 5	$C  \text{mol}^{-1}$
Universal gas constant	$R_u$	8.314 462 1	$\mathrm{J}\mathrm{mol}^{-1}\mathrm{K}^{-}$

Quantity	Symbol	Value	Unit
Boltzmann constant $R/N_A$	k	$1.3806488 \times 10^{-23}$	J K <sup>-1</sup>
Stefan-Boltzmann constant $(\pi^2/60)k^4/\hbar^3c^2$	σ	$5.670373 \times 10^{-8}$	$\mathrm{W}\mathrm{m}^{-2}\mathrm{K}^{-4}$
First radiation constant $2\pi hc^2$	$c_1$	$3.74177153\times10^{-16}$	$\mathrm{W}\mathrm{m}^2$
Second radiation constant $hc/k$	$c_2$	$1.4387770 \times 10^{-2}$	m K
Wien displacement law			
constant $b = \lambda_{\max} T$	<i>b</i>	$2.8977721 \times 10^{-3}$	m K
constant $b' = v_{\text{max}}/T$	b'	$5.8789254 \times 10^{10}$	$\mathrm{Hz}\mathrm{K}^{-1}$
Molar mass constant	$M_{ m u}$	$1 \times 10^{-3}$	$kg  mol^{-1}$
Molar mass of <sup>12</sup> C	$M(^{12}C)$	$12 \times 10^{-3}$	$kg  mol^{-1}$
Standard atmosphere		101.325	k Pa
Standard acceleration of gravity	g	9.806 65	${ m m~s^{-2}}$

### **Kinematics and Kinetics**

Quantity	Formula	Glossary
Velocity:	$v = \frac{ds}{dt}$	s = displacement t = time
Acceleration:	$a = \frac{d^2s}{dt^2}$	
Momentum:	p = mv	m = mass of the object
Newton's II law:	$F = \frac{dp}{dt} = ma$	F = force acting
Equations of motion with	v = u + at	v = final velocity
uniform acceleration:	$s = ut + \frac{1}{2}at^2$	u = initial velocity
	$v^2 - u^2 = 2as$	

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Uniform circular motion:		
a) Angular velocity:	$\omega = \frac{d\theta}{dt}$	$\theta = \text{angular}$ displacement
b) Relation between $v$ and $\omega$ :	$v = r\omega$	r = radius
c) Time period:	$T=2\pi/\omega$	
d) Angular acceleration:	$\alpha = \frac{d\omega}{dt} = \frac{d\omega}{d\theta}\omega$	
e) Linear acceleration:	$a = \alpha r$	
f) Equations of motion:	$\omega = \omega_0 + \alpha t$	$\omega_0$ = initial angular
2	$\theta = \omega_0 t + \frac{1}{2} \alpha t^2$	velocity
38/	$\omega^2 - \omega_0^2 = 2\alpha\theta$	1 = 1
g) Relations in terms of	$2\pi N$ $2\pi N$	\$
revolutions per minute (RPM) <i>N</i> :	$\omega = \frac{2\pi N}{60}, v = \omega r = \frac{2\pi N}{60}r$	
Superelevation:		
a) Centripetal force <i>or</i> centrifugal force:	$F = m\frac{v^2}{r}$	v = velocity, $m = $ mass $r = $ path radius
b) Frictional force:	F = fW	W = mg = weight
c) Condition for skidding on level road:	$v = \sqrt{fgr}$	f = coefficient of friction
d) Condition for over turning on level road:	$v = \sqrt{\frac{grB}{2h}}$	<ul><li>g = acceleration due to gravity</li><li>B = distance between</li></ul>
e) Condition for skidding on banked road:	$v = \sqrt{gr\left(\frac{f + \tan \theta}{1 - f \tan \theta}\right)}$	inner and outer wheels  h = height of center of gravity from ground
f) Condition for overturning on banked road:	$v = \sqrt{gr\left(\frac{B + 2h\tan\theta}{2h - B\tan\theta}\right)}$	$\theta$ = angle of superelevation

g) Reactions of a vehicle moving on a level circular path:	$R_A = \frac{W}{2} \left( 1 - \frac{v^2 h}{Bgr} \right)$ $R_B = \frac{W}{2} \left( 1 + \frac{v^2 h}{Bgr} \right)$	
h) Expression for superelevation, <i>e</i> :	$e = \frac{E}{B} = \tan \theta$ $e = \tan \theta = \frac{v^2}{qr}$	E = height from ground to elevated end of the road
i) Superelevation, <i>e</i> for rails:	$e = \frac{E}{G}$	G = gauge of rails
Projectile motion:	1/3	
a) Equation to the path of projectile:	$y = x \tan \alpha - \frac{gx^2}{2u^2 \cos^2 \alpha}$	$\alpha$ = angle of projection $u$ = velocity of
b) Horizontal range:	$R = \frac{u^2 \sin(2\alpha)}{g}, R_{\text{max}} = \frac{u^2}{g}$	projection
c) Time of flight:	$T = \frac{2u\sin\alpha}{g}$	
d) Maximum height:	$H = \frac{u^2 \sin^2 \alpha}{2g}$	

### **Oscillations**

Quantity	Formula	Glossary
Frequency:	$f = \frac{1}{T}$	T = time period
Angular frequency:	$\omega = \frac{2\pi}{T} = 2\pi f$	
Differential equation of a Simple Harmonic Motion (SHM):	$\frac{d^2y}{dt^2} + \omega^2 y = 0$	y = displacement

Equation of motion for a particle under linear SHM:	$y(t) = y_0 \sin(\omega t + \phi)$ or $y(t) = y_0 \cos(\omega t + \phi)$	$y_0 = \text{amplitude}$ $\phi = \text{phase}$
Velocity and acceleration for a particle under SHM:	$v = \omega \sqrt{y_0^2 - y^2}$ $a = -\omega^2 y$	
Time period of a spring-mass system undergoing SHM:	$T = \frac{\omega}{2\pi} = 2\pi \sqrt{\frac{m}{k}}$	m = mass attached $k = $ spring constant
Spring constant in stretching due to load mg	$k = \frac{mg}{L}$	L = stretching length $g = $ acceleration due to gravity
Effective spring constant for springs in series:	$\frac{1}{k_{\text{eff}}} = \frac{1}{k_1} + \frac{1}{k_2} + \frac{1}{k_3} + \cdots$	7.
Effective spring constant for springs in parallel:	$k_{\text{eff}} = k_1 + k_2 + k_3 + \cdots$	YU.S.
Damped harmonic oscillato	-	
a) Differential equation:	$\frac{d^2y}{dt^2} + 2b\frac{dy}{dt} + \omega^2 y = 0$	r = damping constant $2b = r/m$
b) General solution:	$y = A_1 e^{\left(-b + \sqrt{b^2 - \omega^2}\right)t} + A_2 e^{\left(-b - \sqrt{b^2 - \omega^2}\right)t}$	$\omega^2 = k/m$
c) Solution for critically damped case $(b^2 \approx \omega^2)$ :	$y = [(C+D)+ \beta t(C-D)]e^{-bt}$	$\beta = \sqrt{b^2 - \omega^2}$
d) Solution for low damping case $(b^2 < \omega^2)$ :	$y = Ae^{-bt}\sin(\beta't + \phi)$	$\beta' = \sqrt{\omega^2 - b^2}$
e) For this case the time period and the frequency is given by,	$T = \frac{2\pi}{\beta'} = \frac{2\pi}{\sqrt{\omega^2 - b^2}}$ $f = \frac{1}{T} = \frac{1}{2\pi} \sqrt{\frac{k}{m} - \frac{r^2}{4m^2}}$	

Forced Vibrations:		
a) Differential equation:	$\frac{d^2y}{dt^2} + 2b\frac{dy}{dt} + \omega^2 y$ $= f\sin(\omega_d t)$	$f = F_0/m$ $F_0 = \text{amplitude of the}$ external driving force
b) General solution:	$y = A\sin(\omega_d t - \phi)$	$\omega_d$ = angular frequency of the external force
c) Amplitude $A$ and phase $\phi$ :	$A = \frac{f}{\sqrt{\left(\omega^2 - \omega_d^2\right)^2 + 4b^2\omega_d^2}}$	R
	$\tan \phi = \frac{2b\omega_d}{\omega^2 - \omega_d^2}$	
d) Amplitude at resonance: $(\omega = \omega_d)$	$A_{\max} = \frac{f}{2b\omega_d}$	TEL

# Elasticity

Quantity	Formula	Glossary
Linear strain or Tensile	change in length $\Delta L$	
strain:	$=$ $\frac{1}{\text{original length}} = \frac{1}{L}$	
Volume strain or Bulk	_ change in volume _ $\Delta V$	
strain:	original volume V	
Shear strain:	$=\theta=\frac{\Delta x}{L}$	$\Delta x = deformation$
	L	F = applied force
Stress:	$Stress = \frac{F}{I}$	A = cross-sectional
	A	area
	stress ∝ strain	
Hooke's law:	stress _ modulus of	
	$\frac{1}{\text{strain}} = \text{elasticity}$	



	NT1 -t	
	$Y = \frac{\text{Normal stress}}{\text{Normal stress}}$	
Young's modulus ( <i>Y</i> ):	Longitudin al strain	
	$=\frac{FL}{A\Delta L}$	
	$-\frac{1}{A\Delta L}$	
	$K = \frac{\text{Normal stress}}{1 - 1}$	
Bulk modulus ( <i>K</i> ):	$K \equiv \frac{1}{\text{Volume strain}}$	
Buik modulus (K).	FV	
	$=\frac{FV}{A\Delta V}$	
	Tangential stress	
Rigidity modulus (η):	$\eta = \frac{1}{\text{Shearing strain}}$	(R)
ragiaity modulus (ij).	FL 30	
/ 8	$=\frac{FL}{A\Delta x}$	(A)
/ ¿S-	lateral strain	2
Daissan's Datis (-)	$\sigma = \frac{1}{\text{longitudinal strain}}$	D = original diameter
Poisson's Ratio ( $\sigma$ ):		$\Delta D$ = change in diameter
20	$=\frac{L}{\Delta L}\frac{\Delta D}{D}$	diameter
		$\alpha$ = elongation per unit
	$Y = \frac{1}{\alpha}$	length per unit stress
	$\alpha$	along the direction of
Relations between	$K = \frac{1}{3(\alpha - 2\beta)}$	the force
different modulus of	$3(\alpha-2\beta)$	$\beta$ = contraction per
elasticity	$\eta = \frac{1}{2(\alpha + \beta)}$	unit length per unit
	$2(\alpha + \beta)$	stress along the
	$\sigma = \frac{\beta}{-}$	direction ⊥ to the force
D 1 (* 1 )	α	
Relations between Young's modulus <i>Y</i> and	Y	
1	$K = \frac{Y}{3(1 - 2\sigma)}$	
bulk modulus K:  Relations between	3(1 20)	
Young's modulus Y and	Y	
rigidity modulus $\eta$ :	$\eta = \frac{Y}{2(1+\sigma)}$	
Relations between	/	
Young's modulus <i>Y</i> , bulk	0 ·- V	
modulus K and rigidity	$Y = \frac{9\eta K}{3K + n}$	
modulus $\eta$ :	$3K + \eta$	
modulus ij.		

Single cantilever:		
a) Bending moment for the beam bent to a radius of curvature of <i>R</i> :	$=\frac{Y}{R}I_g$	A = area of cross section of the beam
b) Geometrical moment of inertia:	$I_g = Ak^2$	k = radius of gyration about the neutral axis
c) Depression produced at a distance <i>x</i> from the fixed end:	$y = \frac{W}{YI_g} \left[ \frac{Lx^2}{2} - \frac{x^3}{6} \right]$	W = load L = length of the beam $\delta = \text{depression}$
d) Young's modulus of the material of the cantilever:	$Y = \frac{WL^3}{3\delta I_g}$	produced at loaded end
e) For beam with rectangular cross section	$I_g = \frac{bd^3}{12}$	b = breadth d = thickness
f) For beam with circular cross section	$I_g = rac{\pi r^4}{4}$	r = radius
Couple per unit twist of a cylindrical rod (or wire):	$C = \frac{\pi \eta R^4}{2L}$	R = cross-sectional radius of the cylinder
Time period of a torsional pendulum:	$T = 2\pi \sqrt{\frac{I}{C}}$	L = length of the wire I = moment of inertia
Rigidity modulus of the wire of a torsional pendulum:	$\eta = \frac{8\pi L}{R^4} \left(\frac{I}{T^2}\right)$	of the attached rigid body about the axis of rotation

### Thermodynamics

Quantity	Formula	Glossary
		T = temperature
		determined
Constant volume gas	P	P = gas pressure
thermometer:	$T = 273.16 \mathrm{K} \frac{1}{P_{\star}}$	measured
	11	$P_t = \text{gas pressure at}$
		triple point of water



Fahrenheit scale	$F = \frac{9}{5}C + 32$	C = Celsius scale
Pressure measured by a open U-tube mercury manometer:	$P = P_0 + \rho gz$ $= \rho gz_0 + \rho gz$ $= \rho g(z_0 + z)$	$P_0$ = atmospheric pressure $\rho$ = density of mercury g = acceleration due to gravity z = difference in height of mercury in the two limbs $z_0$ = barometer reading
Heat energy required to raise the temperature of a liquid or a solid by $\Delta T$ :	$\Delta Q = mC\Delta T$	m = mass of the substance $C = $ specific heat
First law of thermodynamics:	$Q = \Delta U + W$	Q = heat transferred to the system $\Delta U$ = change in internal energy of the system W = work done by the system
Ideal gas equation of state:	$PV = nR_uT$ $PV = mRT$ $m = nM$ $R = R_u/M$	$P = \text{pressure}$ $V = \text{volume}$ $n = \text{number of moles}$ $R_u = \text{universal gas}$ $\text{constant}$ $T = \text{temperature}$ $M = \text{molecular weight}$ $m = \text{mass of the gas}$ $R = \text{gas constant}$
Work done by gas expansion:	$W = \int_{V_i}^{V_f} P dV$	$V_i$ = initial volume $V_f$ = final volume
Work done in a isobaric process:	$W = P(V_f - V_i) = P\Delta V$	

Work done in a isothermal process:	$W = mRT \ln \left( \frac{V_f}{V_i} \right)$	
Adiabatic equation of state:	$PV^{\gamma} = \text{constant}$	$\gamma = C_P/C_V$ $C_P = \text{specific heat at}$ constant pressure $C_V = \text{specific heat at}$ constant volume $C_P - C_V = R$
Work done in adiabatic expansion of gases:	$W = \frac{1}{\gamma - 1} (P_i V_i - P_f V_f)$	$P_i$ , $V_i$ , $P_f$ , $V_f$ are initial and final pressures and volumes respectively.

### Fluid Mechanics I

Quantity	Formula	Glossary
Specific volume:	$V_{\rho} = \frac{V_m}{m} = \frac{1}{\rho}$	$V_m$ = volume of the fluid $m$ = mass of the fluid $\rho$ = density of the fluid
Specific gravity:	$SG = \frac{\rho}{\rho_{\rm w}}$	$\rho_{\rm w}$ = 1000 kg/m <sup>3</sup> is the density of water at 4°C.
Newton's law of viscosity for one-dimensional shear flow of Newtonian fluids:	$\tau = \mu \frac{du}{dy}$	$\tau = \text{shear stress}$ $\mu = \text{absolute viscosity}$ $du/dy = \text{velocity gradient}$
The force <i>F</i> required to move the upper plate at a constant speed of <i>V</i> while the lower plate remains stationary:	$F = \mu A \frac{V}{l}$	A = contact area between the plate and the fluid l = distance between the two parallel plates
Kinematic viscosity:	$v = \frac{\mu}{\rho}$	



Torque required in concentric cylinders rotational viscometer:  Bulk modulus of elasticity for fluids: (in Pa)	$T = \mu \frac{4\pi^2 R^3 \dot{n} L}{l}$ $\kappa = -V_\rho \left(\frac{\partial P}{\partial V_\rho}\right)_T = \rho \left(\frac{\partial P}{\partial \rho}\right)_T$	$L$ = length of the cylinder $\dot{n}$ = number of revolutions per unit time $R$ = radius of the inner cylinder $l$ = fluid layer thickness
Isothermal compressibility: (in Pa <sup>-1</sup> )	$\alpha = \frac{1}{\kappa} = -\frac{1}{V_{\rho}} \left( \frac{\partial V_{\rho}}{\partial P} \right)_{T}$ $= \frac{1}{\rho} \left( \frac{\partial \rho}{\partial P} \right)_{T}$	within a small gap between two concentric cylinders P = pressure on the fluid $\rho = \text{density of the liquid}$ c = velocity of the sound
Adiabatic compressibility: (ultrasonic interferometer)	$ \alpha_{\text{ad}} = \frac{1}{\kappa} = \frac{\gamma}{\rho c^2} = \frac{1}{\rho c^2} $ $ c = \lambda f $	waves through the liquid $\gamma = c_p/c_v$ is the specific heat ratio of the fluid $\gamma = 1$ for liquids
Surface tension $\sigma_s$ :		
a) Force balance for a U-shaped wire frame with a movable side:	$F = 2b\sigma_s$	b = breadth of the movable side of the frame
b) Work done to stretch the wire frame by area $\Delta A = 2b \Delta x$ :	$W = F \Delta x = \sigma_s \Delta A$	$\Delta x = \text{distance moved}$
c) Excess pressure inside a droplet or air bubble of radius <i>R</i> :	$\Delta P_{\text{droplet}} = P_i - P_o = \frac{2\sigma_s}{R}$	$P_i$ and $P_o$ are the pressures inside and outside the
d) Excess pressure inside a soap bubble of radius <i>R</i> :	$\Delta P_{\text{bubble}} = P_i - P_o = \frac{4\sigma_s}{R}$	droplet or bubble.
e) Surface energy increase in the droplet:	$\delta W_{\text{surface}} = \sigma_s dA$ $= \sigma_s d(4\pi R^2) = 8\pi R \sigma_s dR$	

Capillary rise in a circular tube of constant radius <i>R</i> :	$h = \frac{2\sigma_s}{\rho gR}\cos\phi$	$\rho$ = density of the liquid $g$ = acceleration due to gravity $\phi$ = contact (or wetting) angle
Reynolds number for internal flow in a circular pipe:	$Re = \frac{Inertial forces}{Viscous forces}$ $= \frac{V_{avg}D}{\nu} = \frac{\rho V_{avg}D}{\mu}$	$V_{\text{avg}}$ = average flow velocity $D$ = diameter of the pipe
Streamline equation:	$\frac{dr}{V} = \frac{dx}{u} = \frac{dy}{v} = \frac{dz}{w}$	$d\vec{r} = dx\hat{i} + dy\hat{j} + dz\hat{k}$ = infinitesimal arc length
Pathline: (location at time <i>t</i> )	$\vec{x} = \vec{x}_{\text{start}} + \int_{t_{\text{start}}}^{t} \vec{V} dt$	$\vec{V} = u\hat{i} + v\hat{j} + w\hat{k}$ = velocity vector
Integral form of the continuity equation:	$ \int_{\substack{\text{control} \\ \text{volume}}} \frac{\partial \rho}{\partial t} dV_m \\ + \oint_{\substack{\text{control} \\ \text{surface}}} \rho \vec{V} . \hat{n} dA = 0 $	$\rho$ = density of the fluid at each point in the control volume $\vec{V}$ = velocity of the fluid at each point on the control surface $\hat{n}$ = unit vector outward normal to the control surface $dV_m$ = infinitesimal volume element $dA$ = infinitesimal area element
Continuity equation for a steady flow of an ideal fluid through a tube with varying cross section:	$A_1V_1 = A_2V_2$	$V_1$ and $V_2$ are average speeds of the fluid at entrance and exit of the tube. $A_1$ and $A_2$ are cross-sectional areas at the entrance end and the exit end.

### Fluid Mechanics II

Quantity	Formula	Glossary
Buoyant force:	$F_B = \rho g V$	$\rho$ = density of the fluid
Poiseuille's formula for the volume of liquid flowing per second through a cylindrical tube of circular cross section:	$\eta = \frac{\pi a^4}{8l} \left(\frac{P}{V}\right)$ with $P = \rho g h$ , $\eta = \frac{\pi \rho g a^4}{8l} \left(\frac{h}{V}\right)$	<ul> <li>g = acceleration due to gravity</li> <li>V = volume of the object</li> <li>P = fluid pressure</li> <li>a = capillary tube radius</li> <li>l = length of capillary tube</li> <li>V = volume of liquid</li> </ul>
Poiseuille's equation in corrected version:	$\eta = \frac{\rho g h \pi a^4}{8V(l+1.64a)} - \frac{V \rho}{8\pi (l+1.64a)}$	passing through the tube  h = height of liquid in  capillary tube
Empirical relation between viscosity and temperature:	$\log \eta = a + \frac{b}{T}$	a and $b$ are constants. $T = absolute temperature$
Variation of viscosity with temperature according to kinetic theory of gases:	$\eta = \alpha \eta_0 T^{1/2}$	$\alpha$ is a constant $\eta_0 = \text{viscosity at } 0^{\circ} \text{ C}$
Sutherland's modified formula for viscosity:	$\eta = \eta_0 \frac{\alpha T^{1/2}}{1 + S/T}$	S = Sutherland's constant
Bernoulli's theorem:	$\frac{P_1}{\rho} + gh_1 + \frac{1}{2}v_1^2$ $= \frac{P_2}{\rho} + gh_2 + \frac{1}{2}v_2^2 = \text{const.}$ $\frac{P}{\rho} + gh + \frac{1}{2}v^2 = \text{const.}$	$P_1$ and $P_2$ are fluid pressures at points 1 and 2. $h_1$ and $h_2$ are the heights of the tube from the ground at points 1 and 2. $v_1$ and $v_2$ are velocities of the fluid at points 1 and 2.

Venturi meter:	$\frac{P_1}{\rho g} + h_1 + \frac{v_1^2}{2g}$ $= \frac{P_2}{\rho g} + h_2 + \frac{v_2^2}{2g}$ When the tube is horizontal $h_1 = h_2$ $\frac{P_1}{\rho} + \frac{v_1^2}{2} = \frac{P_2}{\rho} + \frac{v_2^2}{2}$	
Rate of flow using Venturi meter:	$Q = a_1 v_1 = a_2 v_2$ $= a_1 a_2 \sqrt{\frac{2(P_1 - P_2)}{(a_1^2 - a_2^2)}}$ $= a_1 a_2 \sqrt{\frac{2\rho gH}{(a_1^2 - a_2^2)}}$	$a_1$ and $a_2$ are areas of cross-section of the tube at points 1 and 2. $H = \text{rise in fluid level}$ between capillaries attached at points 1 and 2.

### Quantum Mechanics

Quantity	Formula	Glossary
Planck's formula for the blackbody radiation: Power radiated per unit area per unit solid angle per unit frequency by a black body at temperature <i>T</i> :	$U(\nu, T) = \frac{8\pi h \nu^3 / c^3}{\left[\exp\left(\frac{h\nu}{kT}\right) - 1\right]}$	h = Planck constant $c = speed of light in$ $vacuum$ $k = Boltzmann constant$ $v = frequency of the$ $v = electromagnetic radiation$
Einstein's fundamental equation for photoelectric effect:	$E_K = h\nu - \Phi$	$E_K$ = kinetic energy of the ejected electron $\nu$ = frequency of photon $\Phi$ = work function of the metal



Energy of the discrete emission or absorption of radiation by atoms:	$h\nu = \left  E_i - E_f \right $	$E_i$ = initial state energy $E_f$ = final state energy
Energy of the emitted photon:	$E = hv = \frac{hc}{\lambda}$	$\lambda$ = wavelength of the emitted photon
Compton formula:	$\lambda' - \lambda = \frac{h}{m_e c} (1 - \cos \theta)$	$\lambda$ = wavelength of the incident photon $\lambda'$ = wavelength after scattering $m_e$ = electron rest mass $c$ = speed of light $\theta$ = scattering angle
Compton wavelength of the electron:	$\lambda_e = \frac{h}{m_e c}$ $= 2.43 \times 10^{-12} \text{ m}$	
Compton formula in terms of the energies:	$E_{\gamma'} = \frac{E_{\gamma}}{1 + \frac{E_{\gamma}}{m_e c^2} (1 - \cos \theta)}$	$E_{\gamma} = hc/\lambda = \text{incident}$ energy $E_{\gamma'} = \text{scattered photon}$ energy
de Broglie wavelength:	$\lambda = \frac{h}{p}$ $\lambda = \frac{h}{\sqrt{2mqV}}$	p = momentum of the particle $m =$ mass of the particle $q =$ charge of the particle $V =$ potential with which the particle is accelerated
Phase velocity:	$v_p = \frac{\omega}{k} = \nu \lambda$	$\omega$ = angular frequency $k = 2\pi/\lambda$ = wave number $\nu$ = frequency
Group velocity:	$v_g = rac{d\omega}{dk}$	
Relation between group velocity and phase velocity:	$v_g = v_p - \frac{2\pi}{k} \left( \frac{dv_p}{d\lambda} \right)$	

Heisenberg uncertainty relationships:	$\Delta x \Delta p_x \ge \frac{h}{4\pi}$ $\Delta E \Delta t \ge \frac{h}{4\pi}$ $\Delta J \Delta \theta \ge \frac{h}{4\pi}$	$\Delta x$ , $\Delta p_x$ , $\Delta E$ , $\Delta t$ , $\Delta J$ and $\Delta \theta$ are the uncertainties in the measurement of the position, momentum, energy, time, angular momentum and angular position respectively.
Time independent Schrödinger wave equation in one dimension:	$\frac{d^2\psi}{dx^2} + \frac{8\pi^2 m}{h^2} (E - V)\psi = 0$	$\psi \equiv \psi(x)$ = wave function E = total energy V = potential energy
Probability density:	$P(x,t) = \Psi^*\Psi =  \Psi(x,t) ^2$	5.
Normalization condition:	$\int_{X}  \Psi(x,t) ^2  dx = 1$	7
Schrödinger equation in operator form:	$\hat{H}\psi = E\psi$	$\hat{H}= ext{Hamiltonian operator}$
Particle in one-dimensional of infinite depth:	l potential well	
a) Differential equation:	$\frac{d^2\psi}{dx^2} + k^2\psi = 0$ $k^2 = \frac{8m\pi^2 E}{h^2}$	
b) Solution:	$\psi = A\cos(kx) + B\sin(kx)$	
c) Energy eigen values:	$E = \frac{n^2 h^2}{8ma^2}$ $n = 1, 2, 3 \dots$	a = width of the well
d) Normalized wave function:	$\psi_n = \sqrt{\frac{2}{a}} \sin\left(\frac{n\pi}{a}x\right)$	

### **Principles of Quantum Computation**

Quantity	Formula	Glossary
Inner product of two wave functions $\psi(x)$ and $\phi(x)$ :	$\langle \psi   \phi \rangle = \int \psi^* \phi  dx$ $\langle \phi   \psi \rangle = \int \phi^* \psi  dx = \langle \psi   \phi \rangle^*$	
Wave function as linear combination of basis vectors:	$ \psi\rangle = a_1 \phi_1\rangle + a_2 \phi_2\rangle + \cdots$ $ \psi\rangle = \sum_{n=1}^{\infty} a_n \phi_n\rangle$	$ \phi_1\rangle,  \phi_2\rangle, \dots$ are basis vectors. $a_1, a_2, a_3, \dots$ are complex coefficients.
Inner product of $ \psi\rangle$ with itself:	$\langle \psi   \psi \rangle = \sum_{n=1}^{\infty}  a_n ^2$	2.
Normalization condition:	$\frac{\overline{n=1}}{\langle \psi   \psi \rangle} = 1$	Su
Orthogonality condition:	$\langle \psi_1   \psi_2 \rangle = \langle \psi_2   \psi_1 \rangle = 0$	
Condition for orthnormality of basis vectors:	$\langle \phi_1   \phi_2 \rangle = \langle \phi_2   \phi_1 \rangle = 0$ $\langle \phi_1   \phi_1 \rangle = 1 \text{ and }$ $\langle \phi_2   \phi_2 \rangle = 1$ In general $\langle \phi_m   \phi_n \rangle = \delta_{mn}$	$\delta_{mn} = \begin{cases} 0 & \text{for } m \neq n \\ 1 & \text{for } m = n \end{cases}$
Hermitian matrix M:	$\mathbf{M}^{\dagger} = \mathbf{M}$	M <sup>†</sup> is the conjugate transpose of M
Unitary matrix U:	$\mathbf{U}^{\dagger}\mathbf{U} = \mathbf{U}\mathbf{U}^{\dagger} = \mathbf{I}$	
Pauli's spin matrices:	$\sigma_x = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix},  \sigma_y = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix},$ $\sigma_z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$	$ 0\rangle = \begin{pmatrix} 1\\0 \end{pmatrix}$ and $ 1\rangle = \begin{pmatrix} 0\\1 \end{pmatrix}$ $\alpha$ and $\beta$ are complex
A qubit:	$ \psi\rangle = \alpha  0\rangle + \beta  1\rangle$	numbers, called the amplitude of the states.
Bloch sphere representation:	$ \psi\rangle = \cos\frac{\theta}{2} 0\rangle + e^{i\phi}\sin\frac{\theta}{2} 1\rangle$	$\theta$ = polar angle $\phi$ = azimuth angle

## **Electrical Conductivity in Solids and Band Theory of Solids**

Quantity	Formula	Glossary
Ohm's Law:	V = IR	V = voltage applied
Resistivity:	$\rho = \frac{RA}{L}$	<ul><li>I = current flowing</li><li>R = resistance</li><li>A = area of</li></ul>
Conductivity:	$\sigma = \frac{1}{\rho} = \frac{L}{RA}$	cross-section $L = \text{length of the}$
Electric field:	$E = \frac{V}{L}$	material $n = \text{carrier}$
Current density:	$J = \frac{I}{A} = \sigma E$	concentration  e = electronic charge
Electric current in a conductor:	$I = nev_d A$	$v_d$ = drift velocity m = mass of the
Drift velocity:	$v_d = \frac{eE}{m}\tau$	electron $ au$ =mean collision time
Electrical conductivity of a conductor:	$\sigma = \frac{ne^2\tau}{m}$	
Mobility of electrons:	$\mu = \frac{v_d}{E} = \frac{e\tau}{m}$	
Fermi factor:	$f(E) = \frac{1}{1 + \exp\left(\frac{E - E_F}{kT}\right)}$	E = energy level $E_F$ = Fermi level k = Boltzmann
Density of states in a material in the energy range $E \& E + dE$ :	$g(E)dE = \frac{4\pi}{h^3} (2m)^{3/2} E^{1/2} dE$	constant $T = \text{temperature of the }$ material
Number of free electrons per unit volume in the energy range $E \& E + dE$ :	N(E) dE = g(E)f(E) dE	- Marchar
Total number of free electrons per unit volume in metals:	$n = \frac{8\pi}{3h^3} (2m)^{3/2} E_F^{3/2}$	m = mass of the electron



Fermi energy at 0 K:	$E_F = \frac{h^2}{8m} \left(\frac{3n}{\pi}\right)^{2/3}$	
Carrier concentration in in	trinsic semiconductor:	
a) for electrons:	$n = N_C e^{-(E_C - E_F)/kT}$ $N_C = 2 \left[ \frac{2\pi m_e^* kT}{h^2} \right]^{3/2}$	$N_C$ and $N_V$ are effective density of states in the conduction
b) for holes:	$p = N_V e^{-(E_F - E_V)/kT}$ $N_V = 2 \left[ \frac{2\pi m_h^* kT}{h^2} \right]^{3/2}$	and valence band. $m_{\rm h}^* = \text{effective mass of}$ electron in the material $m_{\rm h}^* = \text{effective mass of}$
Fermi level in intrinsic semiconductor:	$E_F = \left(\frac{E_C + E_V}{2}\right) + \frac{3}{4}kT\ln\left(\frac{m_{\rm h}^*}{m_{\rm e}^*}\right)$	hole in the material $E_C$ = lowest energy level in the conduction band $E_V$ = is the highest
a) For small <i>kT</i> :	$E_F = \frac{E_C + E_V}{2}$	energy level in the valence band
b) With $E_C - E_V = E_g$ :	$E_F = \frac{E_g}{2} + E_V$	$E_g$ = is the energy gap
Intrinsic charge carrier concentration:	$n_i = \sqrt{np} = 2 \left(\frac{2\pi k}{h^2}\right)^{3/2}$ $(m_e^* m_h^*)^{3/4} T^{3/2} e^{-E_g/2kT}$	
Conductivity of an intrinsic semiconductor:	$\sigma_i = e n_i (\mu_e + \mu_h)$	$\mu_{\rm e} = { m mobility} \ { m of}$ electrons $\mu_{ m h} = { m mobility} \ { m of} \ { m holes}$
Fermi energy for extrinsic semiconductors:		
a) n-type	$E_{F_n} = \frac{E_C + E_D}{2} - \frac{kT}{2} \ln \frac{N_C}{N_d}$	$N_d$ = donor concentration
b) p-type	$E_{F_p} = \frac{E_V + E_A}{2} + \frac{kT}{2} \ln \frac{N_V}{N_a}$	$N_a$ = acceptor concentration
Law of Mass Action:	$np = n_i^2 = \text{constant}$	

Hall voltage:	$V_H = R_H \frac{BI}{t}$	$R_H$ = Hall coefficient $B$ = applied magnetic
Hall coefficient:		field
a) For metals and <i>n</i> -type	_1	I = current flowing
semiconductors:	$R_H = \frac{-1}{-1}$	t = thickness of the
semiconductors.	ne ne	material
b) For <i>p</i> -type	1	
semiconductors:	$R_H = \frac{1}{pe}$	

### Semiconductor Devices

Quantity	Formula	Glossary
Internal Potential barrier:	$V_0 = \frac{kT}{e} \ln \left( \frac{N_D N_A}{n_i^2} \right)$	$k = \text{Boltzmann}$ $\text{constant}$ $T = \text{temperature}$ $e = \text{electronic charge}$ $N_D = \text{donors}$ $\text{concentration}$ $N_A = \text{acceptors}$ $\text{concentration}$
The diode equation:	$I = I_0 \left[ \exp\left(\frac{eV}{kT}\right) - 1 \right]$	$n_i$ = intrinsic carrier concentration
Wavelength of light emitted by LED:	$\lambda = rac{hv}{E_g}$	V = voltage across the diode
Relation between currents in a transistor:	$I_E = I_B + I_C$	$I = $ current through the diode $I_0 = $ reverse saturation
Common base current gain factor:	$\alpha_{dc} = \frac{I_C}{I_E}$	current $E_q = \text{energy gap}$
Common emitter dc current gain:	$\beta_{dc} = \frac{I_C}{I_B}$	$I_E$ = emitter current $I_B$ = base current
Voltage gain of an amplifier:	$Gain = \frac{Output\ Voltage}{Input\ Voltage}$	$I_C$ = collector current



### **Dielectrics and Transducers**

Quantity	Formula	Glossary
Dipole moment of two	$\mu = (2a)q$	2a distance between
charges $-q$ and $+q$ :	$\mu = (2a)q$	the charges
Induced dipole moment:	$\mu = \alpha E$	$\alpha$ = polarizability
Torque on the dipole in	$\tau = qE2a\sin\theta = \mu E\sin\theta$	E = applied electric
an electric field:		field
Polarization (total dipole	$\mu_{ ext{total}}$	V = volume of the
moment / unit volume):	$P = \frac{\mu_{\text{total}}}{V}$	dielectric
	3	$\epsilon_0$ = permittivity of free
Electric displacement:	$D = \epsilon_0 \epsilon_r E$	space
Liectric displacement.	$D = \epsilon_0 \epsilon_r L$	$\epsilon_r$ = relative
14		permittivity
Relation for dielectric		151
susceptibility, $\chi$ , for	$P = \chi \epsilon_o E$	S
linear dielectrics:		
Relation between $\epsilon_r$ and	$\epsilon_r = 1 + \gamma$	
χ:	- γ - · χ	/ /
Electronic or Atomic	$P_e = N\alpha_e E$	N = number of atoms
Polarization:		per unit volume
Electronic polarizability:	$\alpha_e = \frac{\epsilon_0(\epsilon_r - 1)}{N}$	$\alpha_e$ = electronic
		polarizability
Ionic Polarization:	$P_i = N\alpha_i E$	$\alpha_i$ = ionic polarizability
		k = Boltzmann
Orientation or dipole	$P_o = \frac{N\mu^2 E}{3kT}$	constant
Polarization:	$P_o = \frac{1}{3kT}$	T = temperature
		$\mu$ = dipole moment
Orientation	$\alpha_o = \frac{\mu^2}{3kT}$	
polarizability:	$\alpha_o = \frac{1}{3kT}$	
Internal field in a solid		d = thickness of the
for one dimensional	$E_i = E + \frac{1.2\mu}{\pi\epsilon_0 d^3}$	dielectric slab
infinite array of dipoles:	$\pi \epsilon_0 d^3$	uiciectiic siab
Clausius Mosotti	$\epsilon_r - 1 N\alpha_e$	
equation:	$\frac{\epsilon_r - 1}{\epsilon_r + 2} = \frac{N\alpha_e}{3\epsilon_0}$	
	27 . 2 220	



Piezoelectric transducer formula:		F = applied force
The charge generated $Q$ is given by,		d = piezoelectric
a) For longitudinal	Q = Fd	coefficient of the
arrangement:	$Q = \Gamma u$	crystal ( $d_{quartz} =$
b) For transverse	O = Ed(h/a)	$2.3 \times 10^{-12} \text{C/N}$
arrangement:	Q = Fd(b/a)	b/a = thickness/width

Quantity	Formula	Glossary
Boltzmann factor:	$\frac{N_2}{N_1} = e^{-h\nu/kT}$	h = Planck constant $k = $ Boltzmann
Einstein's coefficients:	$\frac{A_{21}}{B_{21}} = \frac{8\pi h v^3}{c^3}$ $B_{12} = B_{21}$	constant $T = \text{temperature}$ $v = \text{frequency of the}$
Energy density at thermal equilibrium:	$U(v,T) = \frac{A}{B} \frac{1}{\exp\left(\frac{hv}{kT}\right) - 1}$	electromagnetic radiation $A = A_{21}$ $B = B_{21}$
Length of the resonator cavity:	$L=n\frac{\lambda}{2},  n=1,2,3,\ldots$	$\lambda = \text{Wavelength}$

### **Optical Fibers**

Quantity	Formula	Glossary
Snell's law:	$n_1\sin\theta_1=n_2\sin\theta_2$	$n_1$ and $n_2$ are the refractive indices. $\theta_1$ and $\theta_2$ are angle of incidence & refraction.
Absolute refractive index:	$n = \frac{c}{v}$	c and v are velocities of light in vacuum and the medium.

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Numerical aperture:	NA = $\sin \theta_0 = \frac{\sqrt{n_1^2 - n_2^2}}{n_0}$	$\theta_0$ = acceptance angle $n_0$ , $n_1$ and $n_2$ are the refractive indices of
Fraction Index Change:	$\Delta = \frac{n_1 - n_2}{n_1}$	surrounding medium, core and cladding.
Relation between NA and Δ:	$NA = n_1 \sqrt{2\Delta}$	
V-number if surrounding medium is air:	$V = \frac{\pi d}{\lambda} \text{NA}$	d = core diameter $\lambda = \text{wavelength of light}$
Number of modes for step index fiber:	$pprox rac{V^2}{2}$	
Number of modes for graded index fiber:	$pprox rac{V^2}{4}$	
Attenuation co-efficient (loss per unit length):	$\alpha = -\frac{10}{L} \log \left( \frac{P_{\text{out}}}{P_{\text{in}}} \right)$	$P_{\text{out}}$ = output power $P_{\text{in}}$ = input power L = length of the optical fiber

### Superconductivity

Quantity	Formula	Glossary
Critical current required		R = radius of the wire
to destroy the	$I_c = 2\pi R H_c$	$H_c$ = critical magnetic
superconductivity:		field
		$H_0 = \min \max$
Minimum magnetic field		magnetic field required
required to destroy	$T^2$	at 0 K to destroy
superconductivity at	$H_c = H_0 \left[ 1 - \frac{T^2}{T_c^2} \right]$	superconductivity
temperature $T$ :		$T_c$ = transition
		temperature

Frequency of electromagnetic radiation emitted by a Josephson junction:  $v = \frac{qV}{h} = \frac{2eV}{h}$  h = Planck's constant V = voltage applied q = total charge of the pair e = electronic charge

### **Material Characterization**

Quantity	Formula	Glossary
Ultimate tensile strength: (N/mm²)	$T_{u} = \frac{\text{Ultimate Load}}{\left( \text{Original area of cross-section} \right)}$ $= \frac{P_{u}}{A_{0}}$	$P_u$ = maximum load where necking down occurs $A_0$ = initial cross sectional area of specimen
Elastic limit: (N/mm²)	$T_e = \frac{P_e}{A_0}$	$P_e={ m elastic\ load\ limit}$ (in N)
Proportional limit: (N/mm²)	$T_p = \frac{P_p}{A_0}$	$P_p$ = Proportional load limit (in N)
Yield point: (N/mm²)	$T_s = \frac{P_s}{A_0}$	$P_s$ = load at the yield point
Stiffness: or the modulus of elasticity:	$E = \frac{T}{\epsilon} = \frac{P_p L}{\epsilon A_0}$	L = gauge length
Rupture: Breaking strength	$=rac{P_f}{A_0}$	$P_f$ = load at failure
The Brinell Hardness Number (BHN):	$= \frac{BHN = \frac{P}{A}}{\pi D(D - \sqrt{D^2 - d^2})}$	P = load (in N)  A = area of contact  between the ball and the indentation  D = diameter of the ball  d = diameter of the impression



Complex reflectance ratio measured in ellipsometry:	$\rho = \frac{R_p}{R_s} = \tan \Psi  e^{i\Delta}$	$R_S$ and $R_P$ are the amplitudes of the $s$ and $p$ components of the polarized light $\tan \Psi = \text{modulus of}$ amplitude reflection ratio $\Delta = \text{phase difference}$ between $s$ and $p$ polarized reflected light
Solar cell <i>I-V</i> characteristics curve: Equation for current:	$I = I_0 \left[ \exp\left(\frac{qV}{nkT}\right) - 1 \right] - I_L$	$I_0$ = dark saturation current q = electronic charge V = applied voltage across the terminals of
Bragg's equation for x-ray diffraction:	$n\lambda = 2d\sin\theta$	d = interplanar distance in the crystal $\theta =$ incident angle $\lambda =$ wavelength of x-ray beam $n = 1, 2, 3, \dots$ specifies the order of reflection
Scherrer equation: Crystallite size,	$D = \frac{K\lambda}{\beta \cos \theta}$	$\beta$ = full width at half maximum of peaks measured in radian located at any $2\theta$ in the pattern $K$ = shape factor and is usually taken as about 0.89.

The kinetic energy $E_K$ of the photoelectron ejected in XPS method:	$E_K = h\nu - E_B - \phi$	h = Plank's constant v = frequency of the x-rays incident $E_B$ = binding energy of electron $\phi$ = work function
Limit of resolution of a Scanning Electron Microscope (SEM):	$\Delta x = \frac{\lambda}{2\mu \sin \theta}$ $\lambda = \frac{h}{\sqrt{2meV}}$	$2\mu \sin \theta = \text{numerical}$ aperture of the objective $1/\Delta x = \text{resolving}$ power of the microscope $\lambda = \text{de Broglie}$ wavelength of electrons $m = \text{mass of the}$ electron $e = \text{electronic charge}$ $V = \text{voltage with which}$ the electron is accelerated

### Formulae used in lab

Quantity	Formula	Glossary
Volume resonator:	$f_x = \sqrt{\frac{\left(f^2 V\right)_{\text{avg}}}{V_x}}$	f = frequency of the
		tuning fork
		V = volume of the
		resonating air
Young's modulus of the material of the cantilever:	$q=rac{4mgL^3}{bd^3\delta_{ m mean}}$	$\delta_{\mathrm{mean}} = \mathrm{depression} \ \mathrm{for}$
		mass m
		L, b, d = length, breadth
		and thickness of the
		cantilever

R = radiusL =length of the wire Rigidity modulus of the I =moment of inertia  $\eta = \frac{8\pi L}{R^4} \left( \frac{I}{T^2} \right)$ wire of a torsional of the attached rigid pendulum: body about the axis of rotation Moment of Inertia: (with rotation axis passing through their centers)  $I_1 = MR^2/2$ a) For circular disc with axis ⊥ to disc plane radius R and mass M:  $I_2 = MR^2/4$ axis along diameter  $I_3 = M(L^2 + B^2)/12$ b) For rectangular plate axis ⊥ to plate plane with length L, breadth B $I_4 = ML^2/12$ axis ⊥ to plate length and mass M:  $I_5 = MB^2/12$ axis ⊥ to plate breadth  $\lambda$  = wavelength of the Thickness of the paper light by interference at an air L = air wedge lengthwedge:  $\beta$  = fringe width C = grating constantn =order of diffraction  $\lambda = \frac{C \sin \theta_n}{}$  $x_n$  = distance between Laser diffraction: central and nth maxima  $\theta_n = \tan^{-1}\left(\frac{x_n}{d}\right)$ d = distance betweengrating and screen  $\sin \theta_0 = \frac{W}{\sqrt{(4L^2 + W^2)}}$ Numerical Aperture L =distance from the (NA): optical fiber to screen Capacitance and  $\tau$  = time constant  $C = \frac{\tau}{R}$  and  $\epsilon_r = \frac{Cd}{\epsilon_0 A}$ dielectric constant: R = resistance in series $R = \frac{V}{I}$ f =frequency of the  $L = \frac{V}{2\pi f I}$ Black box: applied AC source  $C = \frac{I}{2\pi f V}$ 

 $X_L = 2\pi f_0 L$  $X_C = \frac{1}{2\pi f_0 C}$ L = inductanceC = capacitanceSeries LCR:  $L = \frac{1}{4\pi^2 f_0^2 C}$  $f_0$  = resonance frequency  $Q = f_0/\Delta f$ e = electronic chargeV = voltage acrossThe diode equation: (at  $I = I_0 \left[ \exp\left(\frac{eV}{kT}\right) - 1 \right]$ diode, I = currenttemperature T) through the diode.  $I_0$  = reverse saturation current  $V_K$  = knee voltage of  $\lambda = \frac{hc}{eV_K}$ Wavelength of LED: the LED  $I_C$  = collector current  $\beta = \left[ \frac{I_{C_2} - I_{C_1}}{I_{B_2} - I_{B_1}} \right]_{V_{CE}}$  $I_B$  = base current Transistor parameters:  $V_{CE}$  = voltage across collector & emitter  $\rho = \text{density of copper.}$ A and l are area of cross-section and  $E_F = 1.36 \times 10^{-15}$ Fermi energy of copper: length of the wire. m = slope of theresistance versus temperature graph.  $m = \frac{n \sum xy - \sum x \sum y}{n \sum x^2 - (\sum x)^2}$ n = number of dataLinear Least Square Fit points formulas: m = slope $c = \frac{\sum y \sum x^2 - \sum x \sum xy}{n \sum x^2 - (\sum x)^2}$ c = y-intercept k = Boltzmann constant $E_g = \frac{4.606 \, km}{1.6 \times 10^{-19}}$ Band gap of a thermister:  $m = \text{slope of the } \log R$ (in eV) versus 1/T graph