

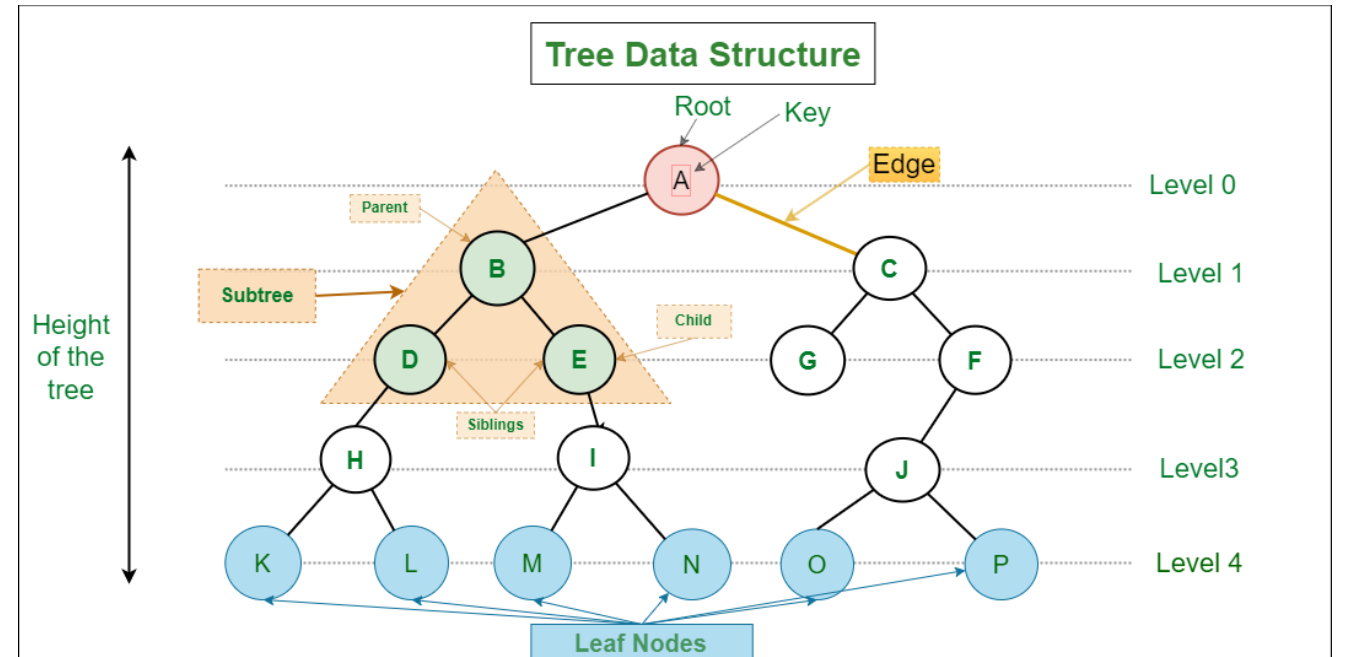
# Unit - II

## Trees

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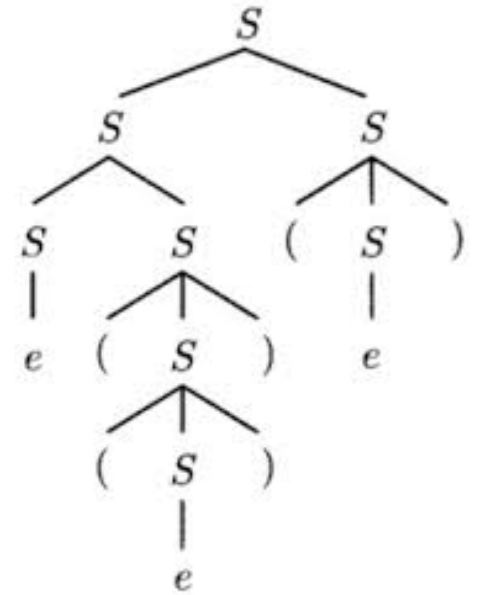
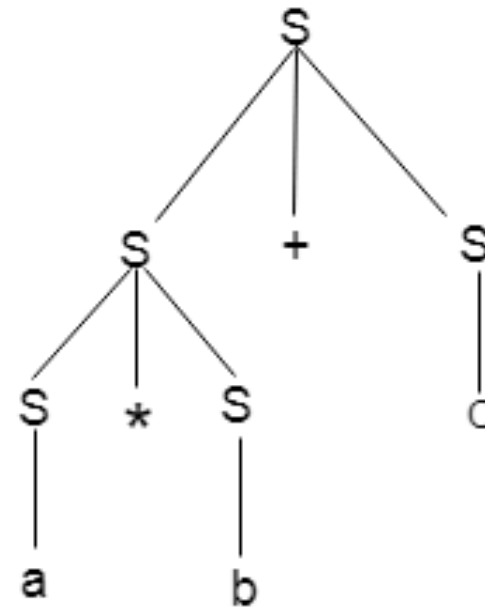
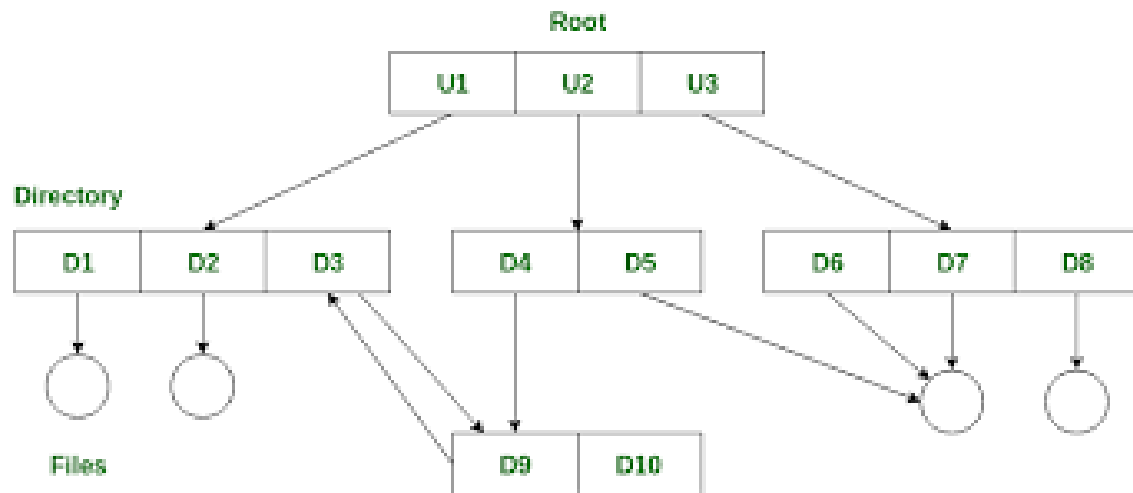
**COURSE CODE: 21AI33**

# Trees



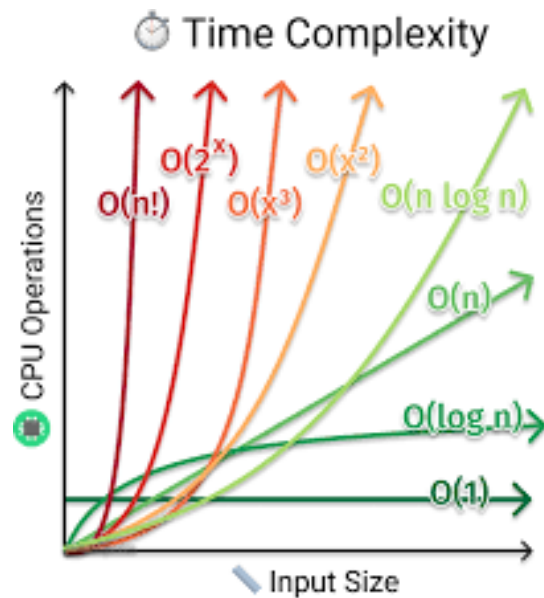
# Trees Concepts

- ❑ Represents information in hierarchical format
- ❑ Examples: File Directory, Parse Trees, Expression Trees



# Trees Concepts

## □ Logarithmic time complexity

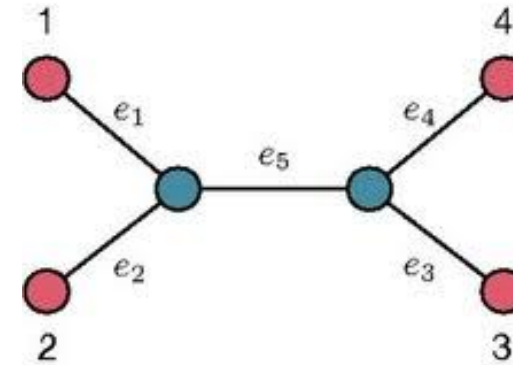
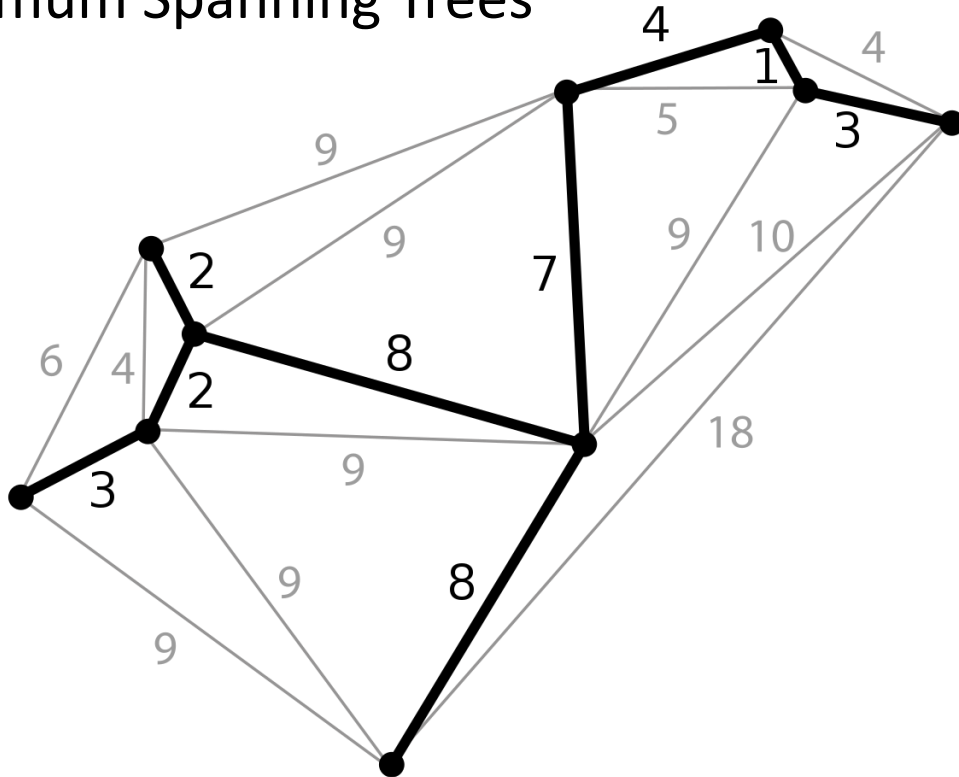


Algorithm	Best Time Complexity	Average Time Complexity	Worst Time Complexity	Worst Space Complexity
Linear Search	$O(1)$	$O(n)$	$O(n)$	$O(1)$
Binary Search	$O(1)$	$O(\log n)$	$O(\log n)$	$O(1)$
Bubble Sort	$O(n)$	$O(n^2)$	$O(n^2)$	$O(1)$
Selection Sort	$O(n^2)$	$O(n^2)$	$O(n^2)$	$O(1)$
Insertion Sort	$O(n)$	$O(n^2)$	$O(n^2)$	$O(1)$
Merge Sort	$O(n \log n)$	$O(n \log n)$	$O(n \log n)$	$O(n)$
Quick Sort	$O(n \log n)$	$O(n \log n)$	$O(n^2)$	$O(\log n)$
Heap Sort	$O(n \log n)$	$O(n \log n)$	$O(n \log n)$	$O(n)$
Bucket Sort	$O(n+k)$	$O(n+k)$	$O(n^2)$	$O(n)$
Radix Sort	$O(nk)$	$O(nk)$	$O(nk)$	$O(n+k)$
Tim Sort	$O(n)$	$O(n \log n)$	$O(n \log n)$	$O(n)$
Shell Sort	$O(n)$	$O((n \log(n))^2)$	$O((n \log(n))^2)$	$O(1)$

# Tree Types

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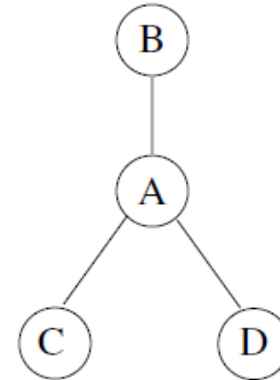
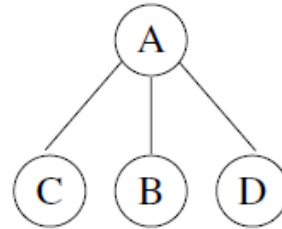
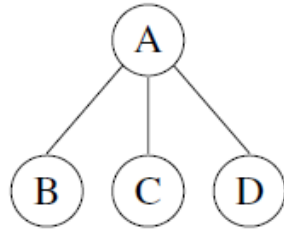
- Unrooted Tree
- Minimum Spanning Trees



# Tree Types

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- ❑ Rooted Tree
- ❑ Special Node called Root Node
- ❑ The remaining nodes are partitioned into  $n \geq 0$  disjoint sets  $T_1, \dots, T_n$ , where each of these sets is a tree.  $T_1, \dots, T_n$  are called the subtrees of the root.
- ❑ May be ordered or unordered based on the placement of subtrees



# K-ary Tree

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- ❑ A finite set of nodes that is either empty or consists of a root and the elements of  $k$  disjoint  $k$ -ary trees called the 1st, 2nd, ...,  $k$ th subtrees of the root.
- ❑ Example: Binary tree has  $K=2$  (left and right branches)
- ❑ Binary tree can have no nodes (Empty trees), but tree cannot



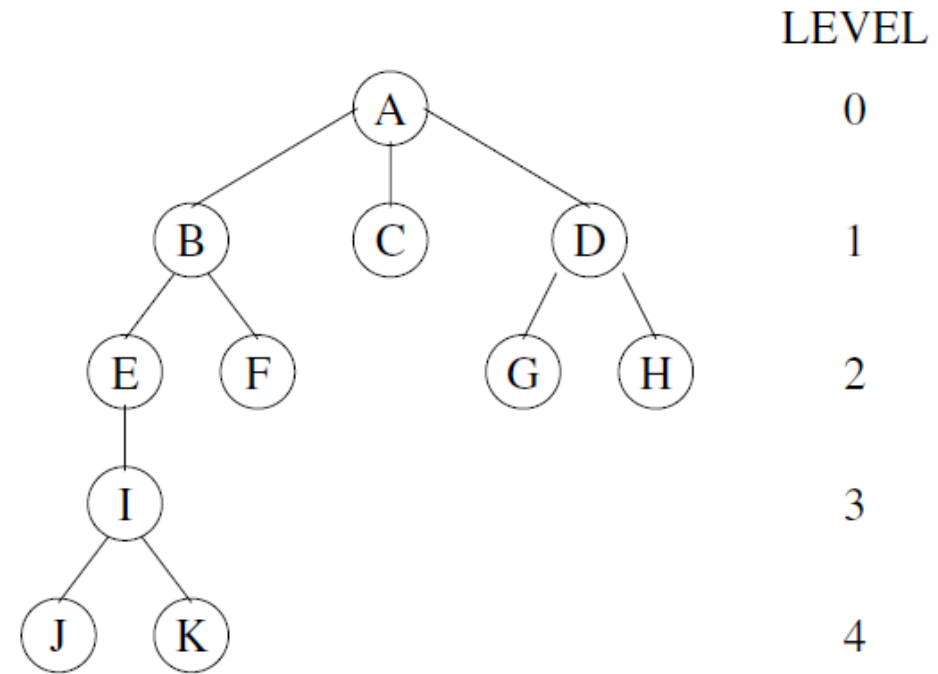
FIGURE 3.2: Different binary trees.

# Tree Representations

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## □ List Representation

(A (B (E (I (J, K)), F), C, D(G, H)))

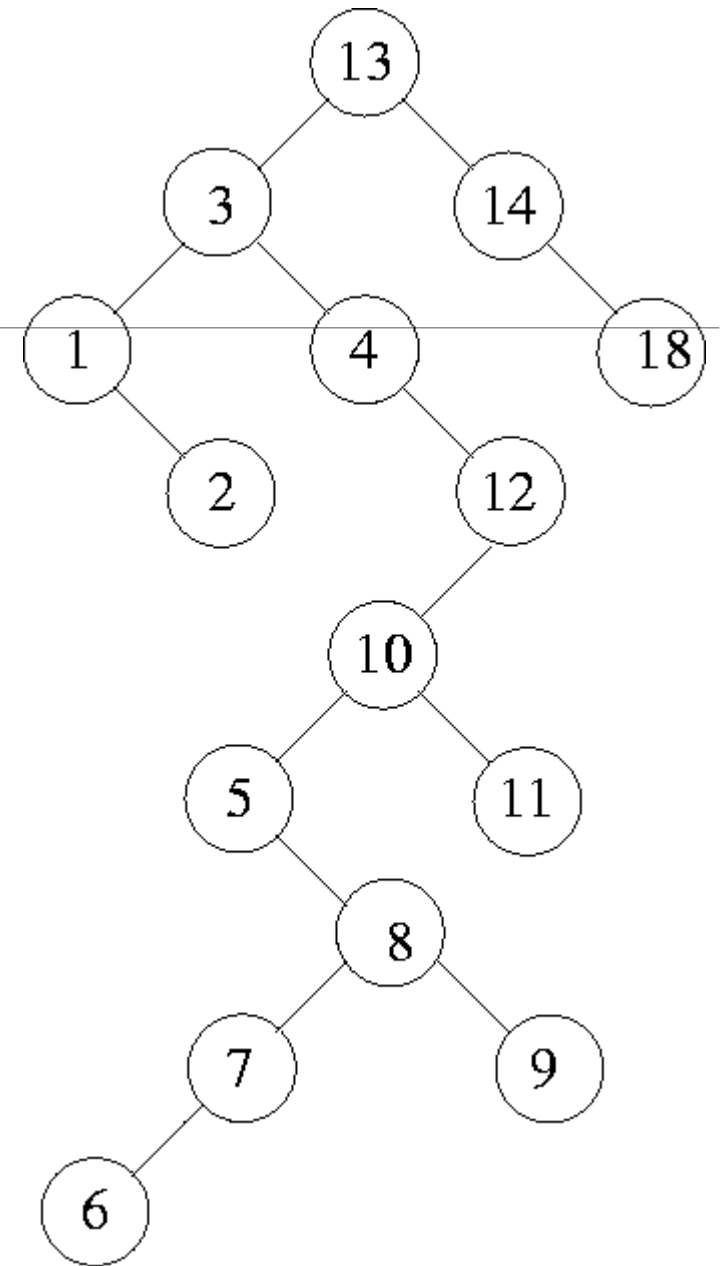




# Tree Representations

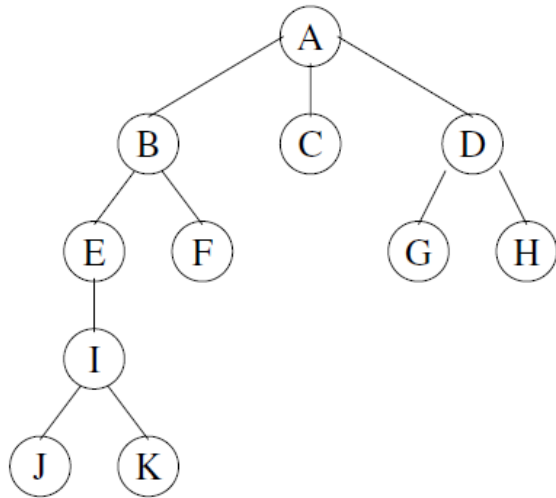
□ List Representation

ANS: ??



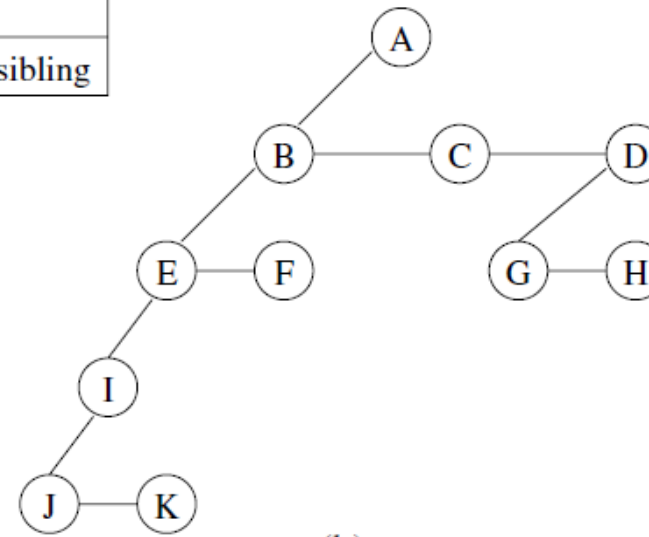
# Tree Representations

## Left-Child and Right-Sibling Representation & Binary Tree Representation

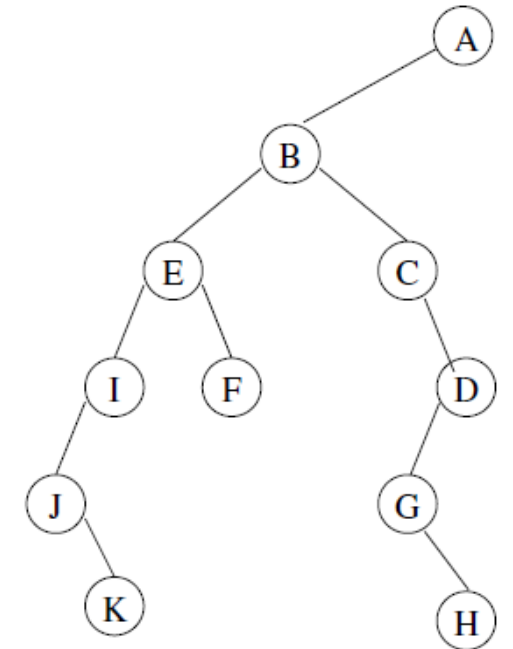


data	
left child	right sibling

(a)



(b)



(c)

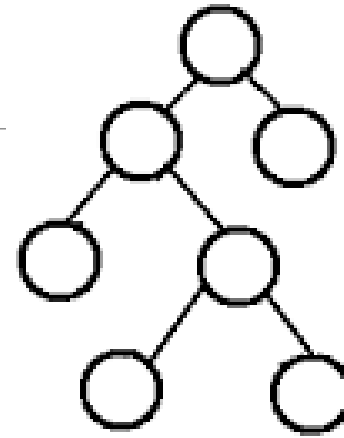
# Binary Trees Types

A full Binary tree is a special type of binary tree in which every parent node/internal node has either two or no children. It is also known as a proper binary tree.

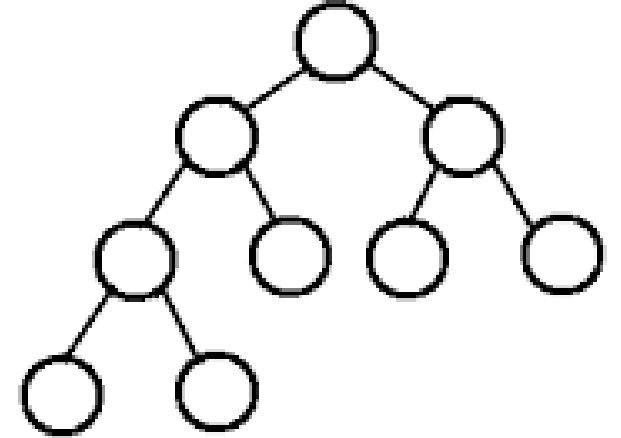
A complete binary tree is a binary tree in which every level, except possibly the last, is completely filled, and all nodes in the last level are as far left as possible.

A perfect Binary Tree is a binary tree in which each of the internal nodes has exactly two child nodes and all the leaf nodes are situated at the same level of the tree.

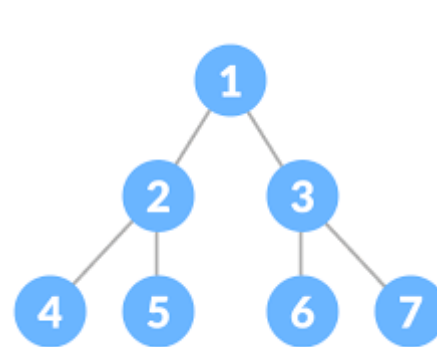
A balanced binary Tree where, **difference between the left and the right subtree for any node is not more than one.**



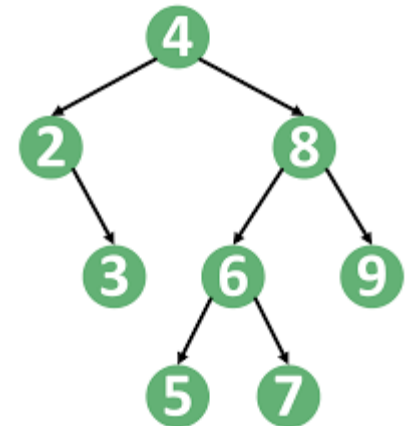
full tree



complete tree



## Perfect BT



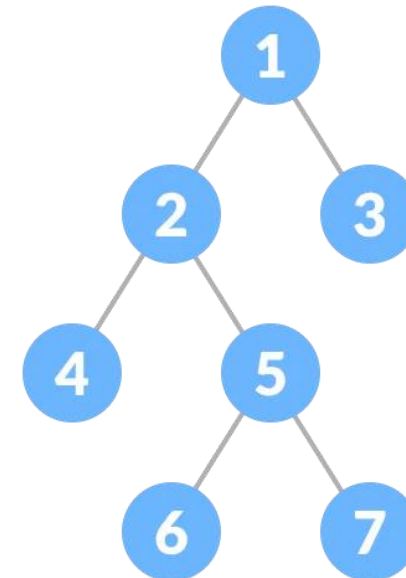
## Balanced BT

# Full BT Theorems

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1. The number of leaves is  $i + 1$ .
2. The total number of nodes is  $2i + 1$ .
3. The number of internal nodes is  $(n - 1) / 2$ .
4. The number of leaves is  $(n + 1) / 2$ .
5. The total number of nodes is  $2l - 1$ .
6. The number of internal nodes is  $l - 1$ .
7. The number of leaves is at most  $2^{\lambda} - 1$ .

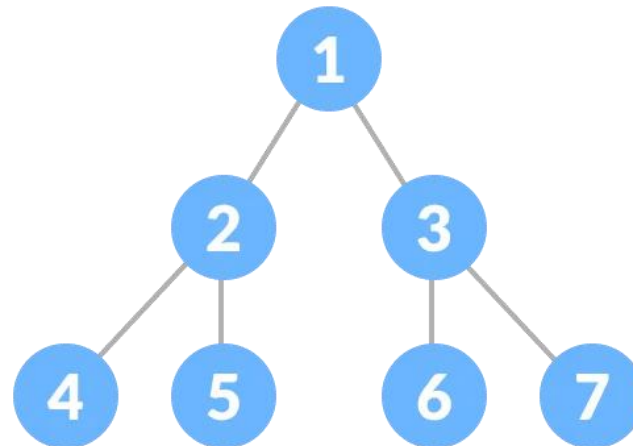
$i$  = the number of internal nodes  
 $n$  = be the total number of nodes  
 $l$  = number of leaves  
 $\lambda$  = number of levels



# Perfect BT Theorems

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1. A perfect binary tree of height  $h$  has  $2^{h+1} - 1$  nodes.
2. A perfect binary tree with  $n$  nodes has height  $\log(n + 1) - 1 = \Theta(\ln(n))$ .
3. A perfect binary tree of height  $h$  has  $2^h$  leaf nodes.
4. The average depth of a node in a perfect binary tree is  $\Theta(\ln(n))$ .



# BT Properties

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- Total number of nodes in a full binary tree = Number of non-leaf nodes + Number of leaf nodes
  - Number of leaf nodes = Number of non-leaf nodes + 1
  - Number of non-leaf nodes = Number of leaf nodes – 1
- *If number of leaf nodes in a full binary tree is  $x$ , how many nodes are present in that tree?*
- *If number of non-leaf nodes in a full binary tree is  $x$ , how many nodes are present in that tree?*

# BT Properties

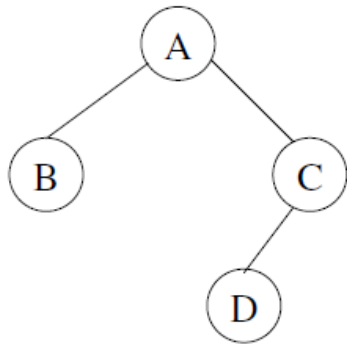
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- *How many binary tree can be formed with 3 nodes?*
- *How many ways you can allocate the data in 3 nodes Binary Tree?*
- *What is the maximum and minimum number of leaf nodes of a binary tree with  $n$  nodes?*
- *How many levels will there be in a completely binary tree if it has  $n$  number of nodes?*

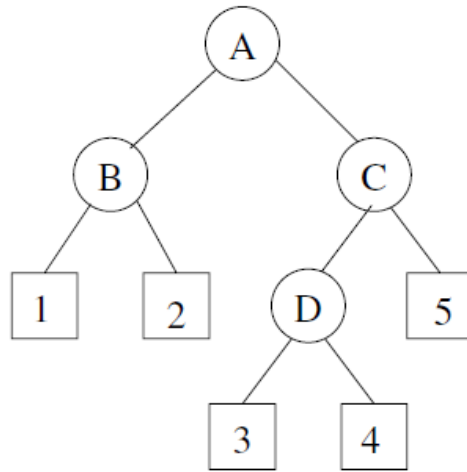
# Binary Trees and Properties

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A binary tree with  $n$  internal nodes has  $n + 1$  external nodes.



(a)



(b)

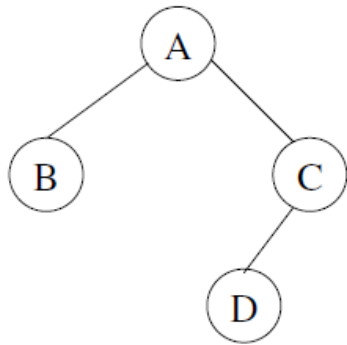
## Proof:

- Each internal node has maximum two children
- Total number of branches =  $2n$
- $n-1$  internal nodes have a single incoming branch
- $2n - (n-1) = n + 1$
- $n+1$  branches points to external node

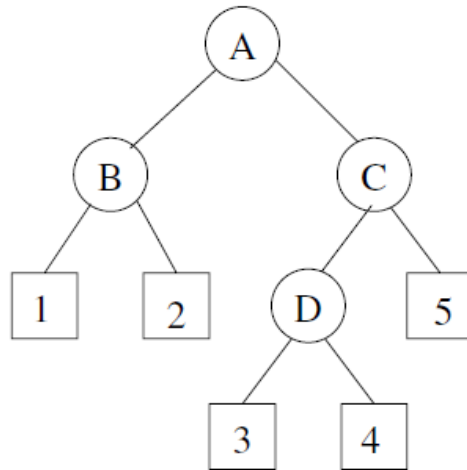


# Binary Trees and Properties

For any non-empty binary tree with  $n_0$  leaf nodes and  $n_2$  nodes of degree 2,  $n_0 = n_2 + 1$ .



(a)



(b)

## Proof:

- Let  $n_1$  be the number of nodes of degree 1
- Total number of nodes in the tree are  $n = n_0 + n_1 + n_2$  (Eq. 1)
- The number of branches in a binary tree is  $n-1$  since each non-root node has a branch leading into it.
- All branches are from nodes of degree 1 and 2. Thus, the number of branches is  $n_1 + 2n_2$ .
- Equating the two expressions for number of branches, we get  $n = n_1 + 2n_2 + 1$  (Eq. 2)

**From Eq.1 and Eq. 2 we get  $n_0 = n_2 + 1$**

# Binary Trees and Properties

*The height of a binary tree with  $n$  internal nodes is at least  $\log_2(n + 1)$  and at most  $n - 1$ .*

## Proof:

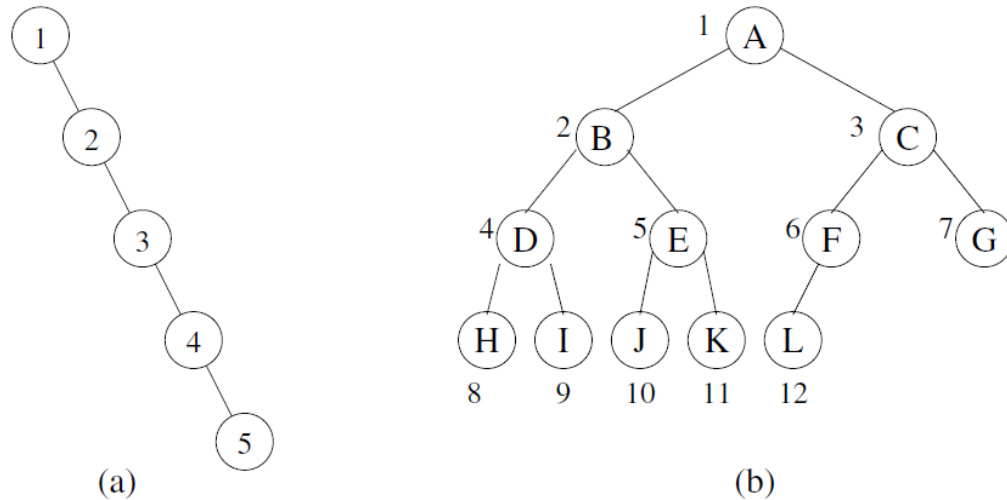


FIGURE 3.6: (a) Skewed and (b) complete binary trees.

- The worst case is a skewed tree
- The best case is a tree with  $2^i$  nodes at every level  $i$  except possibly the bottom level.
- If the height is  $h$ , then  $n + 1 \leq 2^h$ , where  $n + 1$  is the number of external nodes.

# Binary Trees Representations

## Nodes and Pointers

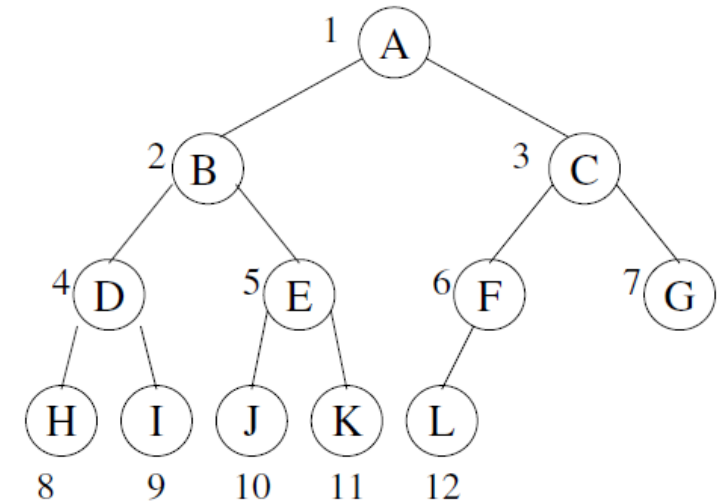
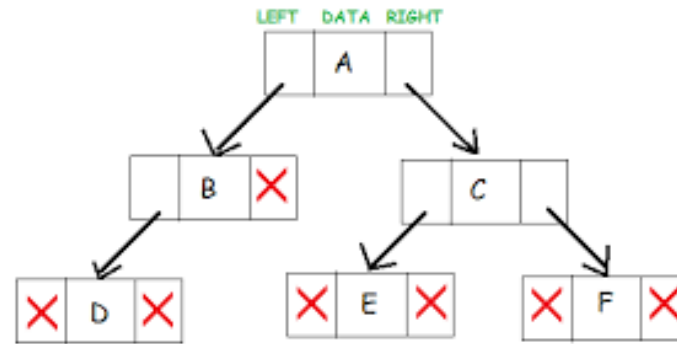
struct treenode

{

int data;

struct node \*lchild, \* rchild;

};



## Array Representation

1	2	3	4	5	6	7	8	9	10	11	12		
[	A	B	C	D	E	F	G	H	I	J	K	L	]

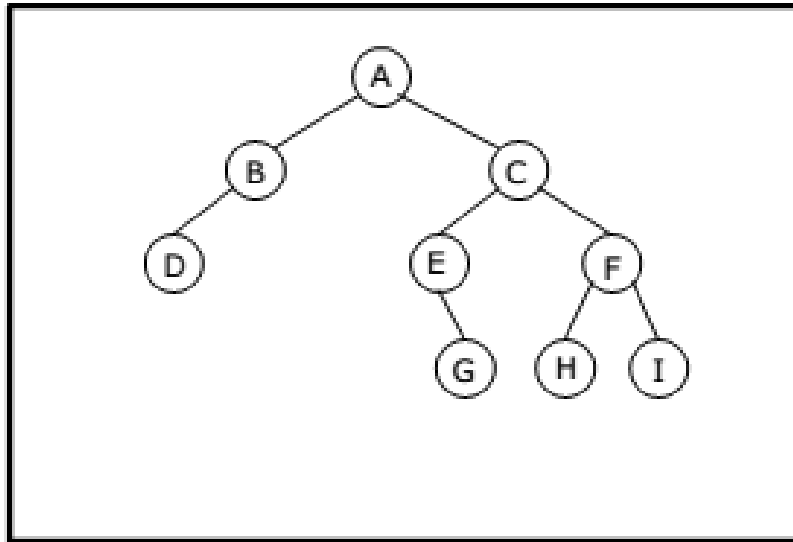
# Binary Tree Traversals

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- ❑ Processing every node in the tree systematically is the purpose of traversal
- ❑ Starting at a node, we can do one of three things:
  - visit the node ( $V$ ),
  - traverse the left subtree recursively ( $L$ ), and
  - traverse the right subtree recursively ( $R$ )
- ❑ inorder(LVR), preorder(VLR) and postorder(LRV)

# Binary Tree Traversals

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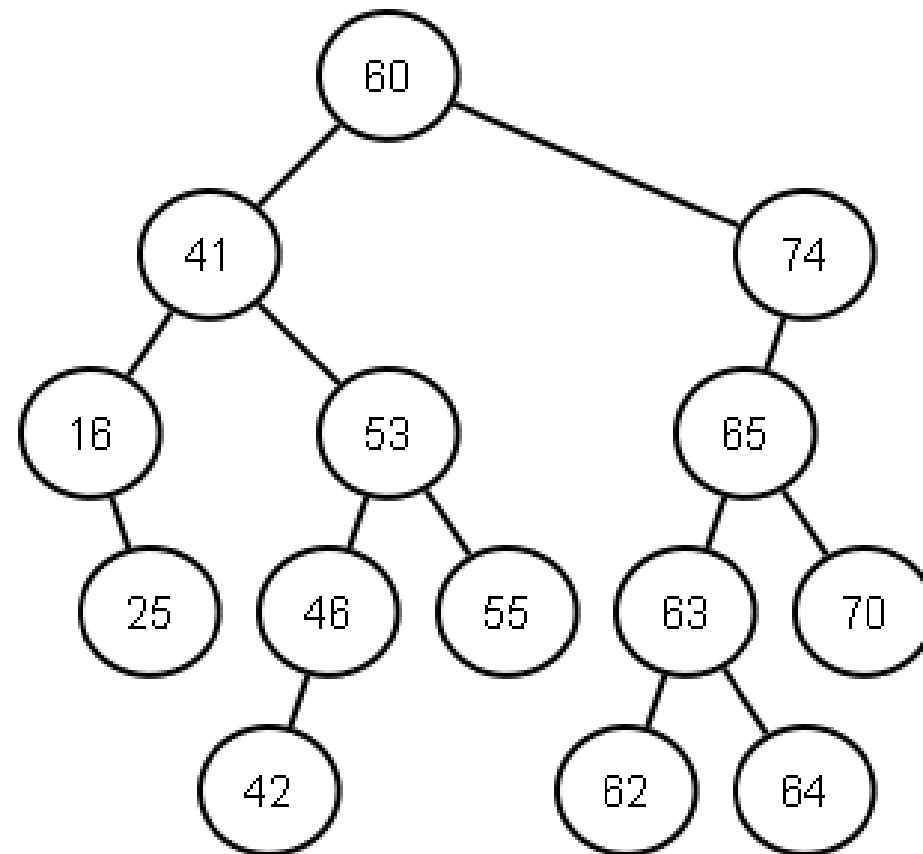
Binary Tree

- Preorder traversal yields:  
A, B, D, C, E, G, F, H, I
- Postorder traversal yields:  
D, B, G, E, H, I, F, C, A
- Inorder traversal yields:  
D, B, A, E, G, C, H, F, I
- Level order traversal yields:  
A, B, C, D, E, F, G, H, I

Pre, Post, Inorder and level order Traversing

# Binary Tree Traversals

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# inorder logic

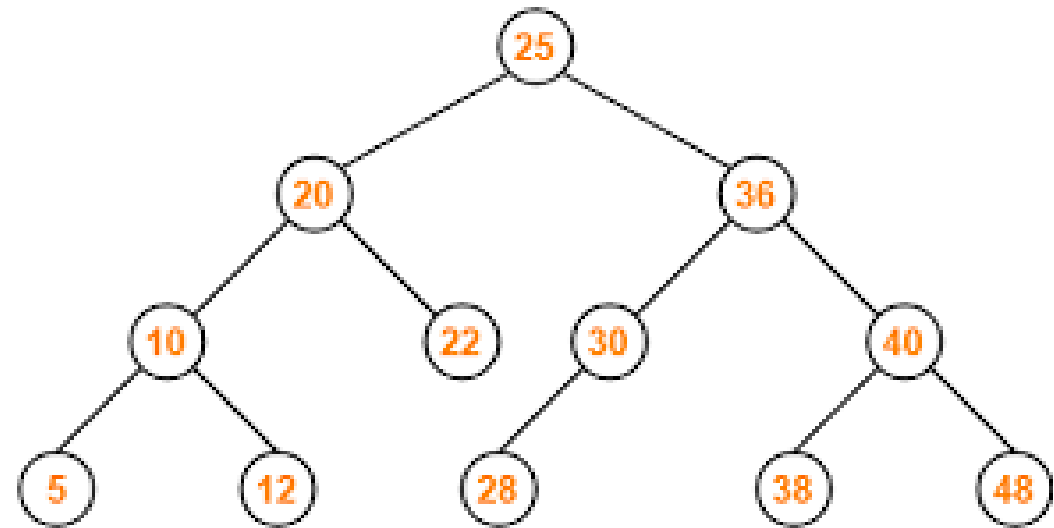
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```
inorder (struct node *currentnode)
{
    if (currentnode)
    {
        inorder(currentnode->lchild);
        print(currentnode->data); //process the node
        inorder(currentnode->rchild);
    }
}
```

# Binary Search Tree

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- ❑ Creation of Tree
- ❑ Traversals
- ❑ Deletion of node with a Key
- ❑ Searching of a node with a Key
- ❑ Etc.



Binary Search Tree



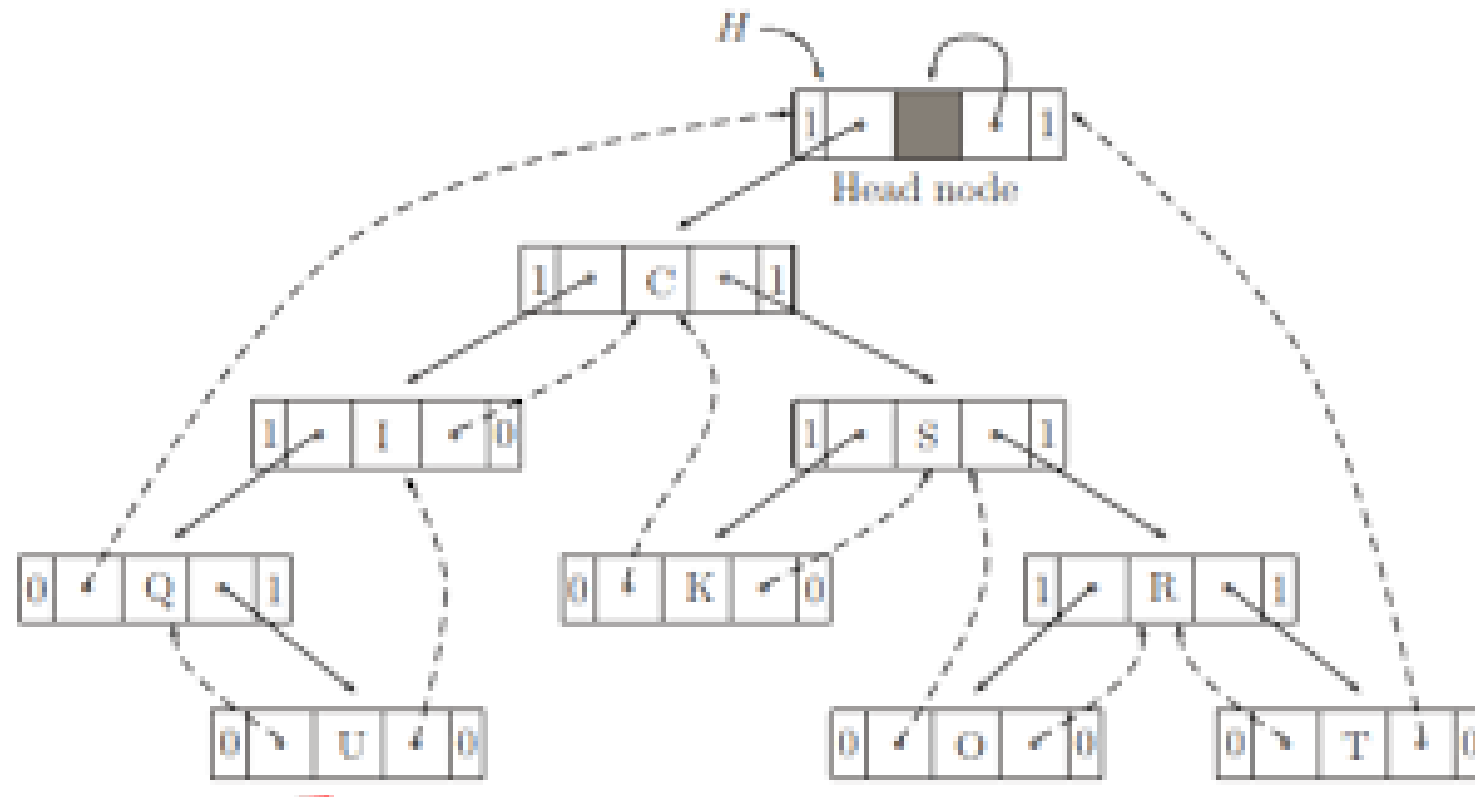
# Binā

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- *Minimum* and *Maximum* that respectively find the minimum and maximum elements in the binary search tree. The minimum element is found by starting at the root and following `LeftChild` pointers until a node with a 0 `LeftChild` pointer is encountered. That node contains the minimum element in the tree.
- Another operation is to find the  $k$ th smallest element in the binary search tree. For this, each node must contain a field with the number of nodes in its left subtree. Suppose that the root has  $m$  nodes in its left subtree. If  $k \leq m$ , we recursively search for the  $k$ th smallest element in the left subtree. If  $k = m + 1$ , then the root contains the  $k$ th smallest element. If  $k > m + 1$ , then we recursively search the right subtree for the  $k - m - 1$ st smallest element.
- The *Join* operation takes two binary search trees  $A$  and  $B$  as input such that all the elements in  $A$  are smaller than all the elements of  $B$ . The objective is to obtain a binary search tree  $C$  which contains all the elements originally in  $A$  and  $B$ . This is accomplished by deleting the node with the largest key in  $A$ . This node becomes the root of the new tree  $C$ . Its `LeftChild` pointer is set to  $A$  and its `RightChild` pointer is set to  $B$ .
- The *Split* operation takes a binary search tree  $C$  and a key value  $k$  as input. The binary search tree is to be split into two binary search trees  $A$  and  $B$  such that all keys in  $A$  are less than or equal to  $k$  and all keys in  $B$  are greater than  $k$ . This is achieved by searching for  $k$  in the binary search tree. The trees  $A$  and  $B$  are created as the search proceeds down the tree as shown in [Figure 3.11](#).
- An inorder traversal of a binary search tree produces the elements of the binary search tree in sorted order. Similarly, the inorder successor of a node with key  $k$  in the binary search tree yields the smallest key larger than  $k$  in the tree. (Note that we used this property in the *Delete* operation described in the previous section.)

# Threaded Binary Tree

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