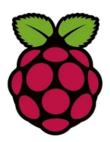
# Led Breathing Using Raspberry Pi





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# **Table of Contents**

- 1.0 Introduction
  - 1.1 Objective
  - 1.2 Requirement
  - 1.3 Principle
- 2.0 Hardware connections
- 3.0 Working
  - 3.1 Programming
  - 3.2 Debugging and exceution

### 1.0 Introduction

### 1.1 Objective

The main objective is to built the LED breathing circuit with Python programming using the Raspberry Pi 3 model B development board.

### 1.2 Requirement

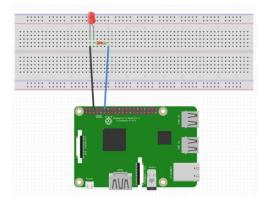
- √ 1 \* Breadboard
- ✓ Jumper wires
- √ 1 \* Raspberry Pi (I am using Raspberry Pi 3 Model B)
- ✓  $1 * 220\Omega$  Resistor
- √ 1 \* LED

### 1.3 Principle

The on-off pattern can simulate voltages in between full **on** (3.3 Volts) and **off** (0 Volts) by changing the portion of the time when the signal is on versus the time that the signal is off.

### 2.0 Hardware connections

Use the bread board and make connections as shown in visual representation below:



For calculating the resistor value, use ohms law:

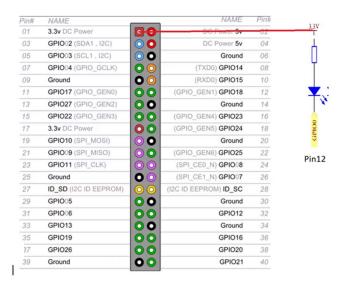
$$V_{in}=IR$$

' $V_{in}$ ' through GPIO is 3.3 V and current should not exceed the load of 16mA. Substituting values we get **R= 220** $\Omega$ .

# 3.0 Working

1. Once the wireless connection is established then open thonny Python IDE which mostly is pre installed in raspberry Pi's.





- 2. Make sure the Python library is uploaded and running .
- 3. Type in the program, and check for any errors.
- 4. Run the program.
- 5. Check for LED.



## 3.1 Programming

Enter the following program on Thonny Python IDE:

```
import RPi.GPIO as GPIO
import time
LedPin = 12
def setup():
         global
         GPIO.setmode (GPIO.BOARD)
                                         # Numbers GPIOs by physical location
         GPIO.setup(LedPin, GPIO.OUT)
                                         # Set LedPin's mode is output
         GPIO.output(LedPin, GPIO.LOW)
                                         # Set LedPin to low(OV) to switch on LED
         p = GPIO.PWM(LedPin, 1000)
                                         # set Frequece to 1KHz
                                         # Duty Cycle = 0%; DC(Length of Voltage Hi)
         p.start(0)
                                         # p.start(20)=20%
def loop():
         while True:
                  for dc in range(0, 101, 4):
                                                        # Increase duty cycle: 0~100 step=4
                           p.ChangeDutyCycle(dc)
                                                        # Change duty cycle
                            time.sleep(0.05)
                                                          time.sleep(sec)
                  time.sleep(1)
                  for dc in range (100, -1, -4):
                                                        # Decrease duty cycle: 100~0
                           p.ChangeDutyCycle(dc)
                            time.sleep(0.05)
                  time.sleep(1)
def destroy():
         p.stop()
         GPIO.output(LedPin, GPIO.HIGH)
                                            # turn off all leds
         GPIO.cleanup()
setup()
try:
except
         KeyboardInterrupt: # When 'Ctrl+C' is pressed, the child program destroy() will be executed.
         destroy()
```

### 3.1 Debugging and Execution

Connect the hardware and run the application to execute the program.

