EECS 489 Computer Networks

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Agenda

- Link-state routing
- Distance-vector routing

Recap: Least-cost path routing

- Given: router graph & link costs
- Goal: find least-cost path
 - > From each source router to each destination router

- Easy way to avoid loops
 - No reasonable cost metric is minimized by traversing a loop

Recap: Dijkstra's algorithm

- Network topology, link costs known to all nodes
 - All nodes have same info
- Each node ("src") computes least-cost paths to all other nodes
 - After k iterations, know least-cost path to k destinations

From routing algorithm to protocol

- Dijkstra's is a local computation!
 - Computed by a node given complete network graph
- Possibilities:
 - Option#1: a separate machine runs the algorithm
 - Option#2: every router runs the algorithm
- The Internet currently uses Option#2

Link-state routing

- Every router knows its local "link state"
 - Router u: "(u,v) with cost=2; (u,x) with cost=1"
- Each router floods its local link state to all other routers in the network
 - Does so periodically or when its link state changes
- Every router learns the entire network graph
 - Each runs Dijkstra's Shortest-Path First (SPF) algorithm locally to compute forwarding table

Flooding link state

Flooding

- A node sends its link-state info out all of its links
- The next node forwards the info on all of its links except the one the information arrived at
- When to initiate flooding?
 - Topology change (e.g., link/node failure/recovery)
 - Configuration change (e.g., link cost change)
 - Periodically
 - »To refresh link-state information (soft states)
 - »Typically (say) every 30 minutes

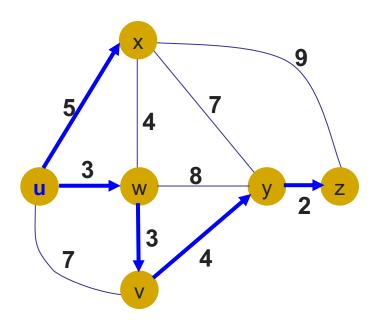
Convergence

- Why flood?
 - To get all the nodes in the network to converge to the new topology
- Upon convergence, all nodes will have consistent routing information and can compute consistent forwarding:
 - All nodes have the same link-state database
 - All nodes forward packets on shortest paths
 - The next router on the path forwards to the expected next hop

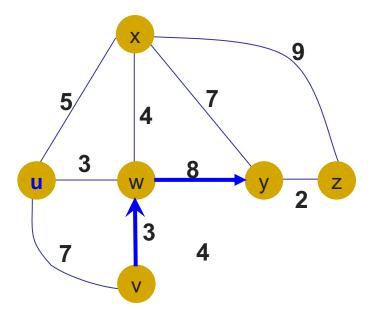
Convergence delay

- Time to achieve convergence
- Sources of convergence delay
 - Time to detect failure
 - Time to flood link-state information
 - Time to re-compute forwarding tables
- What happens if it takes too long to converge?

Loop from convergence delay



u and w think that the
path to y goes through v



v thinks that the path to y goes through w

Performance during convergence period

- Looping packets
- Lost packets due to black holes
- Out-of-order packets reaching the destination

Link-state routing

- Scalability?
 - > O(NE) messages
 - > O(N²) computation time
 - O(Network diameter) convergence delay
 - > O(N) entries in forwarding table

Link-state routing protocols

- OSPF: Open Shortest Path First
- IS-IS: Intermediate System to Intermediate System
 - Similar to OSPF

OSPF: Open Shortest-Path First

- Open: publicly available
- Uses link-state algorithm
 - Link-state packet dissemination
 - Topology map at each node
 - Route computation using Dijkstra's algorithm
- Router floods OSPF link-state advertisements to all other routers in entire AS
 - Carried in OSPF messages directly over IP (rather than TCP or UDP)
 - »Requires reliable transmission

Distance-vector protocol

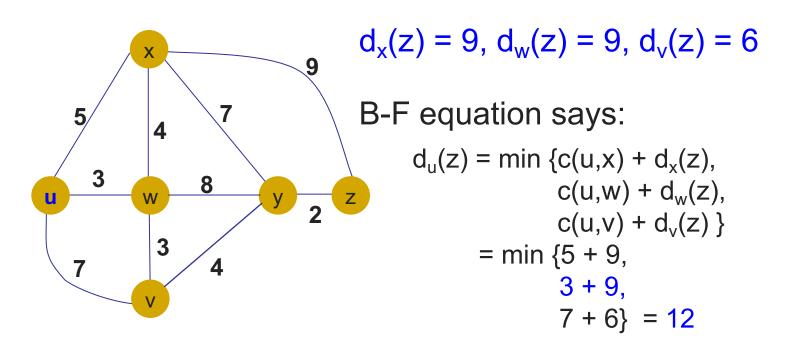
- Link-state routing protocol
 - Each node broadcasts its local information

- Distance-vector routing protocol
 - The opposite (sort of)
 - Each node tells its neighbors about its global view

Bellman-Ford equation

- Let
 - \rightarrow d_x(y) := cost of least-cost path from x to y
- Then
 - cost from neighbor v to destination y
 min taken over all neighbors v of x

Bellman-Ford example



Neighbor achieving the minimum (w) is next hop in shortest path, used in forwarding table

Distance vector algorithm

- D_x(y) is the estimate of least cost from x to y
 - > x maintains its own distance vector $\mathbf{D}_{\mathbf{x}} = [\mathbf{D}_{\mathbf{x}}(\mathbf{y}): \mathbf{y} \in \mathbf{N}]$
- Node x:
 - Knows cost to each neighbor v: c(x,v)
 - Maintains its neighbors' distance vectors
 - »For each neighbor v, x has $D_v = [D_v(y): y \in N]$

Distance vector algorithm

- From time-to-time, each node sends its own distance vector estimate to neighbors
- When x receives new DV estimate from neighbor, it updates its own DV using B-F equation
 - $D_x(y) \leftarrow \min_{v} \{c(x,v) + D_v(y)\}$ for each node $y \in N$
- Eventually, the estimate D_x(y) may converge to the actual least cost d_x(y)

Distance vector algorithm

Iterative, asynchronous

- Local iterations caused by
 - » Local link cost change
 - » DV update message from neighbor

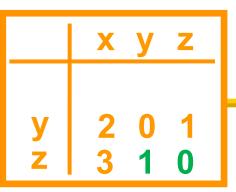
Distributed

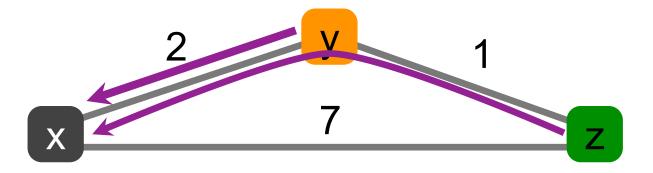
- Each node notifies neighbors only when its DV changes
 - » Neighbors then notify their neighbors if necessary

@each node:

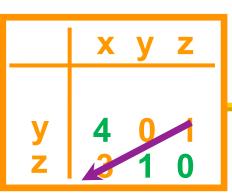
Wait for (change in local link cost OR msg from neighbor) Recompute estimates *Notify* neighbors if DV to any dest has changed

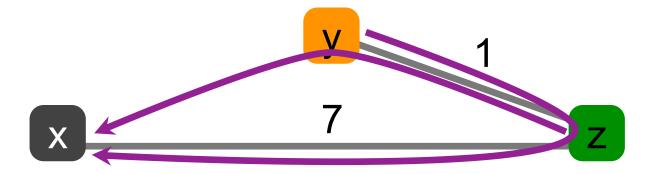
5-MINUTE BREAK!



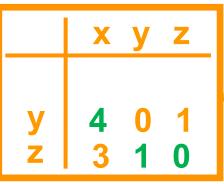


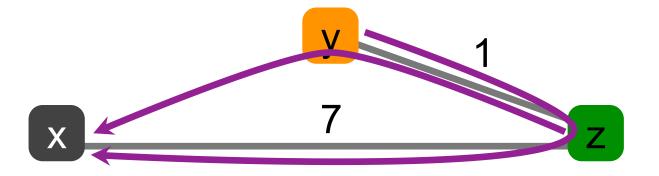
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y z	2 3	0	1 0

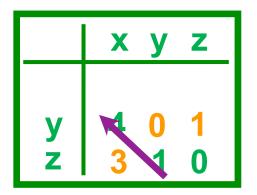


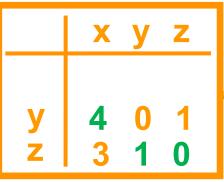


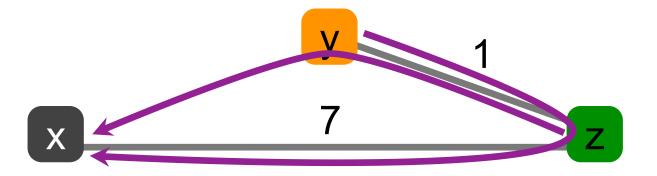
	X	У	Z
y z	2 3	0	1 0

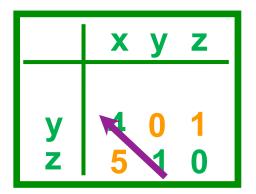


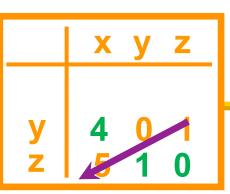


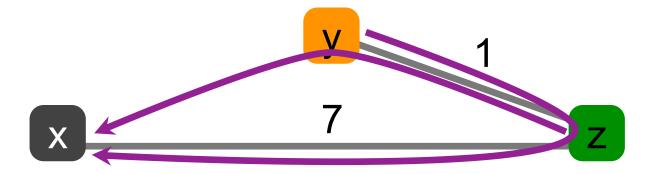




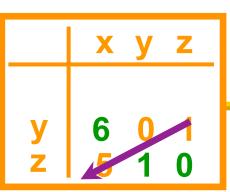


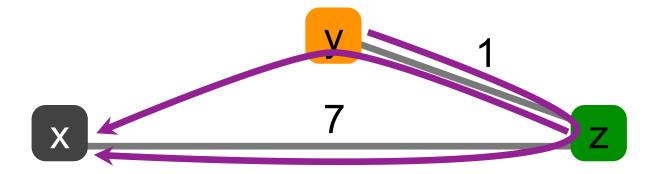




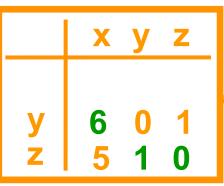


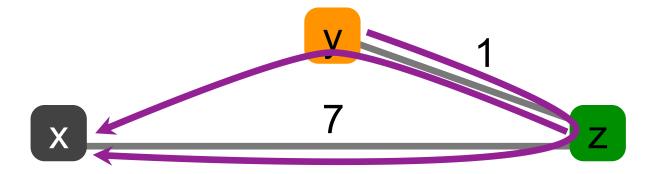
	X	у	Z
y	4 5	0	1

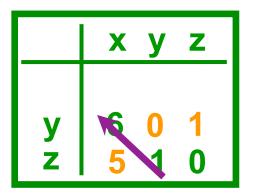


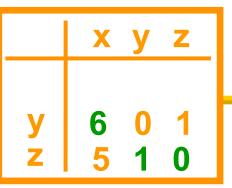


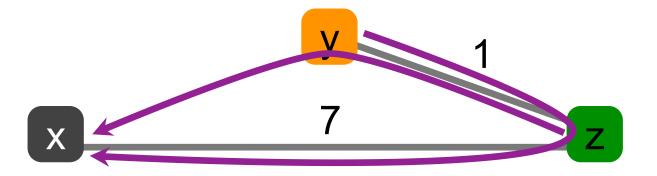
	X	у	Z
у	4	0	1
Z	5	1	0

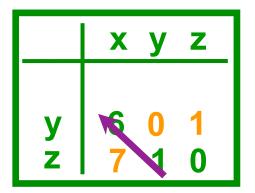


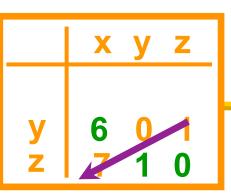


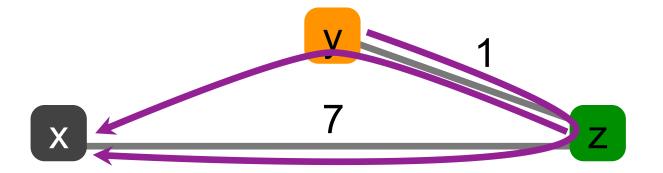




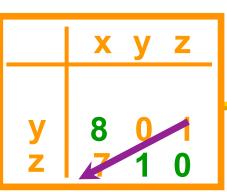


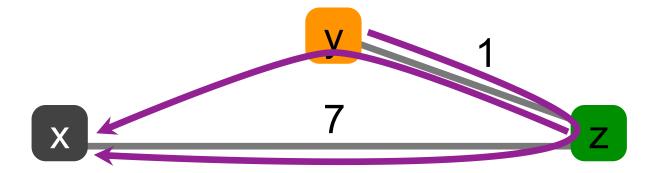




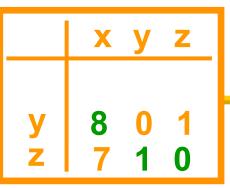


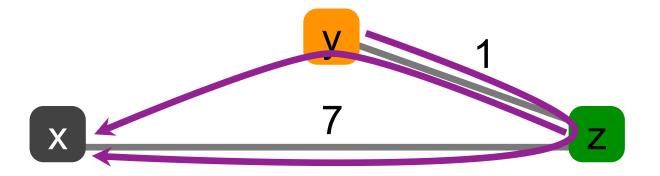
	Х	У	Z
y z	6 7	0	1 0

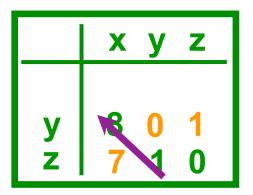


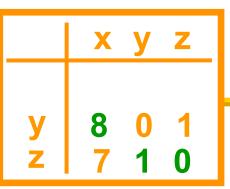


	Х	у	Z
y z	6 7	0	1 0

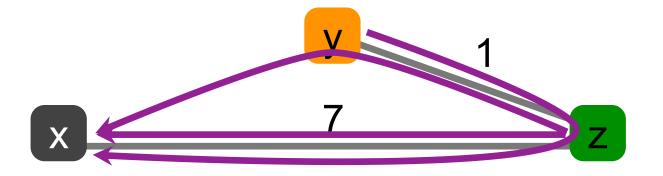








routing loop!



Count-to-infinity scenario

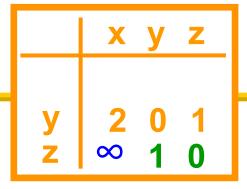
	X	у	Z
y	8 7	0	1 0

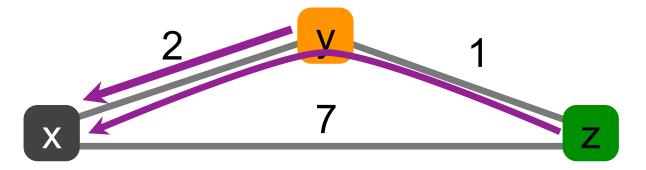
Problems with Bellman-Ford

- Routing loops
 - > z routes through y, y routes through x
 - y loses connectivity to x
 - y decides to route through z
- Can take a very long time to resolve
 - Count-to-infinity scenario

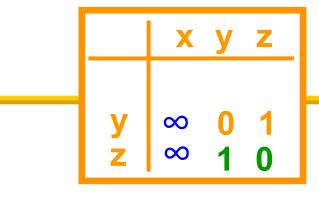
Poisoned reverse

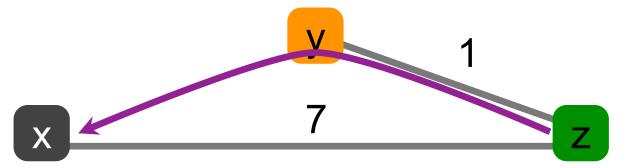
- One heuristic to avoid count-to-infinity
 - If z routes to x through y,»z advertises to y that its cost to x is infinite
 - > y never decides to route to x through z



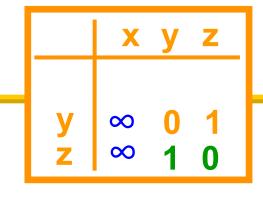


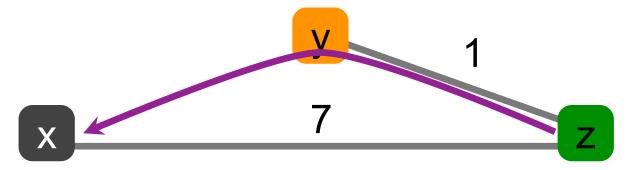
	X	у	Z
y z	2 3	0	1 0



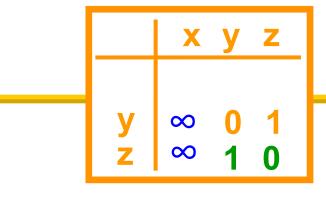


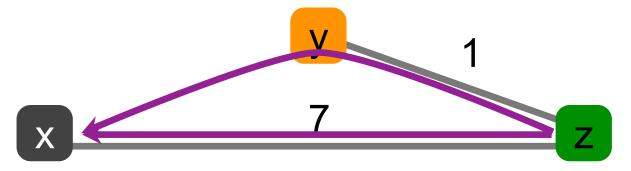
	Х	у	Z
y z	2 3	0	1 0



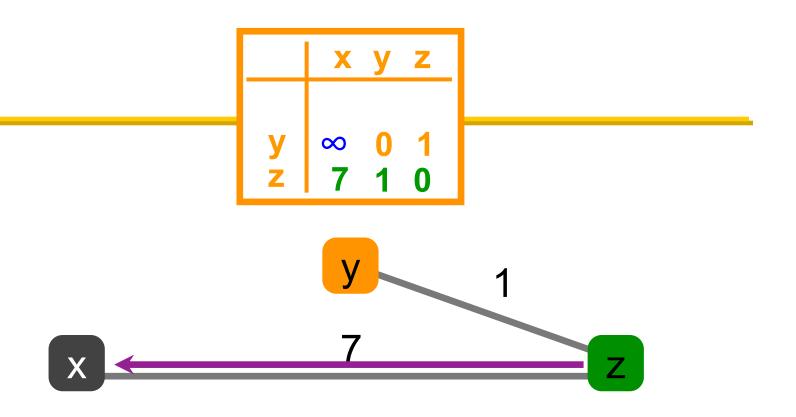


	X	У	Z
y z	∞ 3	0	1 0

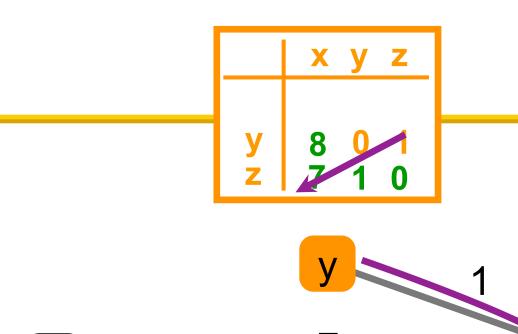


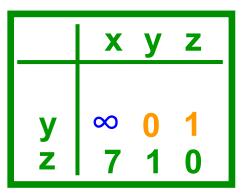


	Х	у	Z
у	&	0	1
Z	7	1	0



	X	У	Z
y	∞ 7	0	1 0





Poisoned reverse

- One heuristic to avoid count-to-infinity
 - If z routes to x through y,»z advertises to y that its cost to x is infinite
 - y never decides to route to x through z
- Not guaranteed
- Loop-free routing examples include
 - Path vector
 - Source tracing

Distance-vector routing

- Scalability?
 - Requires fewer messages than Link-State
 - O(N) update time on arrival of a new DV from neighbor
 - O(network diameter) convergence time
 - > O(N) entries in forwarding table
- RIP is a protocol that implements DV (IETF RFC 2080)

Comparison of LS and DV routing

Messaging complexity

- LS: with N nodes, E links, O(NE) messages sent
- DV: exchange between neighbors only

Speed of convergence

- LS: relatively fast
- DV: convergence time varies
 - Count-to-infinity problem

Robustness: what happens if router malfunctions?

- LS:
 - Node can advertise incorrect link cost
 - Each node computes its own table
- DV:
 - Node can advertise incorrect path cost
 - Each node's table used by others (error propagates)

Similarities between LS and DV routing

- Both are shortest-path based routing
 - Minimizing cost metric (link weights) a common optimization goal
 - »Routers share a common view as to what makes a path "good" and how to measure the "goodness" of a path
- Due to shared goal, commonly used inside an organization
 - RIP and OSPF are mostly used for intra-domain routing

Summary

- Intra-AS routing
 - Link-state routing
 - Distance-vector routing