

Instructions to use Path Planner:

- 1) Install redis server:
 `sudo apt-get install redis-server`
- 2) Build Path Planner
 - a) `cd Path_Planning`
 - b) `mkdir build && cd build`
 - c) `cmake ..`
 - d) `make`
- 3) Launch smallmap.py
 `python2 smallMap/zrf_version/smallmap.py`
- 4) Launch PathPlanner
 `./build/RF_PP/RFPP`
- 5) Visualize the map
 `python2 smallMap/zrf_version/gui.py`