

NITTE MEENAKSHI INSTITUTE OF TECHNOLOGY

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DEPARTMENT OF ARTIFICIAL INTELLIGENCE AND DATA SCIENCE

PRACTIAL RECORD BOOK

<u>DIGITAL IMAGE PROCESSING AND COMPUTER VISION</u> 21ADL66

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YEAR/SEM : $3^{RD}/6^{TH}$

SECTION : A

BRANCH : ARTIFICIAL INTELLIGENCE and DATA SCIENCE

DEPARTMENT OF ARTIFICIAL INTELLIGENCE AND DATA SCIENCE



CERTIFICATE

satisfactorily							
completed the course of experiments in <u>DIGITAL IMAGE PROCESSING AND COMPUTER VISION</u>							
Laboratory for the academic session 2023-2024 as prescribed by the Visvesvaraya							
Technological University.							
Register Number of the Candidate:							
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Sl. No	Program / Exercise
1.	Implementation of Relationships between Pixels Neighbor of 4,8 and Diagonal point
2.	a. Simulation and Display of an Image, Negative of an Image (Binary & Gray Scale)
	b. Display color Image, find its complement and convert to gray scale
3.	a. Implementation of Transformations of an Image (Scaling & Rotation)
	b. Display the color image and its Resized images by different methods
4.	Contrast stretching of a low contrast image, Histogram, and Histogram Equalization
5.	Display of bit planes of an Image
6.	Display of FTT (1D, 2D) of an image
7.	Computation of mean, Standard Deviation, Correlation coefficient of the given Image
8.	Implementation of Image Smoothening Filters (Mean and Median filtering of an image)
9.	Implementation of image sharpening filters and Edge Detection using Gradient Filters
9.	

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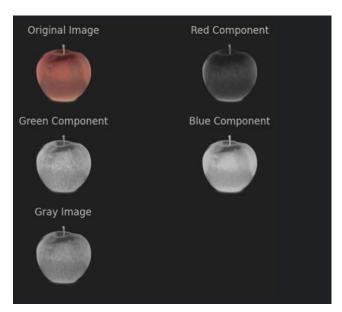
```
import numpy as np
PROGRAM 1
                                                              # Create the 5x5 array
                                                              a = np.array([
a = np.array([[17, 24, 1, 8, 15],
                                                                 [17, 24, 1, 8, 15],
         [23, 5, 7, 14, 16],
                                                                 [23, 5, 7, 14, 16],
         [4, 6, 13, 20, 22],
                                                                 [4, 6, 13, 20, 22],
         [10, 12, 19, 21, 3],
                                                                 [10, 12, 19, 21, 3],
                                                                 [11, 18, 25, 2, 9]
         [11, 18, 25, 2, 9]])
                                                              1)
print("a =")
print(a)
                                                              # Print the array
                                                              print("a =")
                                                              print(a)
b = int(input("Enter the row < size of the Matrix: "))
c = int(input("Enter the column < size of matrix: "))
                                                              # Get user input for row and column
print("Element:", a[b, c])
                                                              x = int(input("Enter the row (0 to 4): "))
                                                              y = int(input("Enter the column (0 to 4): "))
N4 = [a[b+1, c] \text{ if } b+1 < a.shape[0] \text{ else None,}
                                                              # Ensure the input is within bounds
   a[b-1, c] \text{ if } b-1 >= 0 \text{ else None,}
                                                              if 0 \le x \le 5 and 0 \le y \le 5:
   a[b, c+1] if c+1 < a.shape[1] else None,
                                                                 print("Element:", a[x, y])
   a[b, c-1] \text{ if } c-1 >= 0 \text{ else None}
                                                                 # Get 4-connected neighbors
print("N4 =")
                                                                 N4 = [
print(N4)
                                                                    a[x+1, y] if x+1 < 5 else None, # Down
                                                                    a[x-1, y] \text{ if } x-1 >= 0 \text{ else None}, # Up
N8 = [a[b+1, c] \text{ if } b+1 < a.shape[0] \text{ else None,}
                                                                    a[x, y+1] if y+1 < 5 else None, # Right
                                                                    a[x, y-1] if y-1 >= 0 else None # Left
   a[b-1, c] \text{ if } b-1 >= 0 \text{ else None,}
   a[b, c+1] if c+1 < a.shape[1] else None,
                                                                 print("N4 = ", N4)
   a[b, c-1] if c-1 \ge 0 else None, # Left
   a[b+1, c+1] if b+1 < a.shape[0] and c+1 < a.shape[1] else \cite{Magenta} 8-connected neighbors
   a[b+1, c-1] if b+1 < a.shape[0] and c-1 >= 0 else None,
                                                                 1 = 8M
                                                                    a[x+1, y] if x+1 < 5 else None, # Down
   a[b-1, c-1] if b-1 >= 0 and c-1 >= 0 else None,
                                                                    a[x-1, y] \text{ if } x-1 >= 0 \text{ else None}, # Up
   a[b-1, c+1] if b-1 >= 0 and c+1 < a.shape[1] else None] #
                                                                    a[x, y+1] if y+1 < 5 else None, # Right
print("N8 =")
                                                                    a[x, y-1] if y-1 >= 0 else None, # Left
print(N8)
                                                                    a[x+1, y+1] if x+1 < 5 and y+1 < 5 else None, #
                                                              Bottom-right
ND = [a[b+1, c+1] \text{ if } b+1 < a.shape[0] \text{ and } c+1 < a.shape[1] \text{ else Prone}, y-1] \text{ if } x+1 < 5 \text{ and } y-1 >= 0 \text{ else None}, #
   a[b+1, c-1] if b+1 < a.shape[0] and c-1 >= 0 else None,
                                                                    a[x-1, y-1] if x-1 >= 0 and y-1 >= 0 else None, #
   a[b-1, c-1] if b-1 >= 0 and c-1 >= 0 else None,
                                                              Top-left
                                                                    a[x-1, y+1] if x-1 >= 0 and y+1 < 5 else None #
   a[b-1, c+1] if b-1 >= 0 and c+1 < a.shape[1] else None]
                                                              Top-right
print("ND =")
print(ND)
                                                                 print("N8 = ", N8)
                                                                 # Get diagonal neighbors
                                                                 ND = [
  [[17 24 1 8 15]
                                                                    a[x+1, y+1] if x+1 < 5 and y+1 < 5 else None, #
   [23 5 7 14 16]
                                                              Bottom-right
   [ 4 6 13 20 22]
                                                                    a[x+1, y-1] if x+1 < 5 and y-1 >= 0 else None, #
   [10 12 19 21 3]
                                                              Bottom-left
   [11 18 25 2 9]]
                                                                    a[x-1, y-1] if x-1 >= 0 and y-1 >= 0 else None, #
  Element: 9
                                                              Top-left
  N4 =
                                                                    a[x-1, y+1] if x-1 >= 0 and y+1 < 5 else None #
                                                              Top-right
                                                                 print("ND = ", ND)
                                                                 print("Invalid row or column. Please enter values
```

within the range of the matrix.")

```
N8 =
[None, 3, None, 2, None, None, 21, None]
ND =
[None, None, 21, None]
```

plt.show()

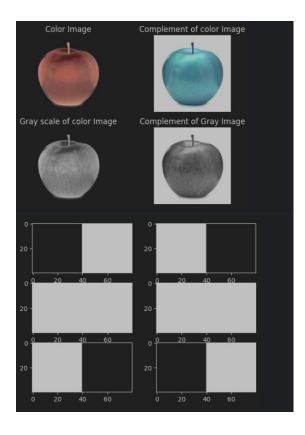
```
PROGRAM 2A
import cv2
import matplotlib.pyplot as plt
                                         import cv2 as cv
                                         import matplotlib.pyplot as plt
i = cv2.imread('apple.jpg')
                                         i = cv.imread("apple.jpg")
i = cv2.cvtColor(i, cv2.COLOR_BGR2RGB)
                                         plt.subplot(1,1,1)## row , colum , plot num
                                         i = cv.cvtColor(i,cv.COLOR_BGR2RGB)
plt.subplot(3, 2, 1)
                                         plt.imshow(i)
plt.imshow(i)
                                         plt.title("Original Image")
plt.title('Original Image')
plt.axis('off')
                                         r = image[:,:,0]
                                         plt.imshow(r,cmap = "gray")
r = i[:, :, 0]
                                         plt.title("Red Components")
plt.subplot(3, 2, 2)
                                         g = image[:,:,1]
plt.imshow(r, cmap='gray')
                                         plt.imshow(g,cmap = "gray")
plt.title('Red Component')
                                         plt.title("Green Components")
plt.axis('off')
                                         b = image[:,:,2]
g = i[:, :, 1]
                                         plt.imshow(b,cmap = "gray")
plt.subplot(3, 2, 3)
                                         plt.title("Blue Components")
plt.imshow(g, cmap='gray')
plt.title('Green Component')
                                         gray_image = cv.cvtColor(image,cv.COLOR_RGB2GRAY)
plt.axis('off')
                                         plt.imshow(gray_image,cmap = "gray")
                                         plt.title("Gray Image")
b = i[:, :, 2]
plt.subplot(3, 2, 4)
plt.imshow(b, cmap='gray')
plt.title('Blue Component')
plt.axis('off')
rg = cv2.cvtColor(i, cv2.COLOR_RGB2GRAY)
plt.subplot(3, 2, 5)
plt.imshow(rg, cmap='gray')
plt.title('Gray Image')
plt.axis('off')
plt.tight_layout()
```



Display color Image, find its complement and convert to gray scale

PROGRAM 2B import cv2	import matplotlib.pyplot as plt import numpy as np import cv2 as cv						
<pre>import numpy as np import matplotlib.pyplot as plt # Read the color image I = cv2.imread('apple.jpg')</pre>	<pre>def plot_img(img,title,cmap = None): plt.figure() plt.imshow(img,cmap = cmap) plt.title(title) plt.show()</pre>						
# Convert BGR to RGB (OpenCV reads images in BGR format)							
I_rgb = cv2.cvtColor(I, cv2.COLOR_BGR2RGB) # Plot original color image plt.subplot(2, 2, 1)) image = cv.imread("apple.jpg") image = cv.cvtColor(image,cv.COLOR_BGR2RGB) plot_img(image,"Color Image")						
plt.imshow(I_rgb) plt.title('Color Image')	c = cv.bitwise_not(image) plot_img(c,"Complement of Image")						
plt.axis('off') # Find complement of color image	gray = cv.cvtColor(image,cv.COLOR_RGB2GRAY) plot_img(gray,"gray scale",cmap = "gray"						
c = cv2.bitwise_not(I_rgb) plt.subplot(2, 2, 2)	gray_complement = cv.bitwise_not(gray) plot_img(gray_complement,"Gray Complement image", cmap = "gray")						
plt.imshow(c) plt.title('Complement of color Image') plt.axis('off') # Convert color image to grayscale	# Simulation of an Image (Arithmetic & Logic Operation) a = np.ones((40, 40), dtype=np.uint8) b = np.zeros((40, 40), dtype=np.uint8) c = np.hstack((a, b)) d = np.hstack((b, a))						
r = cv2.cvtColor(I_rgb, cv2.COLOR_RGB2GRAN) plt.subplot(2, 2, 3)	e = np.vstack((c, d)) YA = 10 * (c + d) M = c * d						
plt.imshow(r, cmap='gray') plt.title('Gray scale of color Image')	S = np.abs(c - d) $D = c / 4$						
plt.axis('off')	plot_img(c,"image",cmap = "gray")						
# Find complement of grayscale image	plot_img(d,"image",cmap = "gray")						
b = cv2.bitwise_not(r) plt.subplot(2, 2, 4)	plot_img(A,"image",cmap = "gray")						
plt.imshow(b, cmap='gray')	plot_img(M,"image",cmap = "gray")						
plt.title('Complement of Gray Image')	plot_img(S,"image",cmap = "gray")						
	plot_img(D,"image",cmap = "gray")						

```
plt.axis('off')
# Simulation of an Image (Arithmetic & Logic Operation)
a = np.ones((40, 40), dtype=np.uint8)
b = np.zeros((40, 40), dtype=np.uint8)
c = np.hstack((a, b))
d = np.hstack((b, a))
e = np.vstack((c, d))
A = 10 * (c + d)
M = c * d
S = np.abs(c - d)
D = c / 4
plt.figure()
plt.subplot(3, 2, 1)
plt.imshow(c, cmap='gray')
plt.subplot(3, 2, 2)
plt.imshow(d, cmap='gray')
plt.subplot(3, 2, 3)
plt.imshow(A, cmap='gray')
plt.subplot(3, 2, 4)
plt.imshow(M, cmap='gray')
plt.subplot(3, 2, 5)
plt.imshow(S, cmap='gray')
plt.subplot(3, 2, 6)
plt.imshow(D, cmap='gray')
plt.show()
```



Rotation)

import matplotlib.pyplot as plt import numpy as np import cv2 as cv

PROGRAM 3A

import cv2

import numpy as np

Load the image

image = cv2.imread('apple.jpg')

image = cv.imread("apple.jpg")

image = cv.cvtColor(image,cv.COLOR_BGR2RGB)

plt.imshow(image)
plt.title("Original Image")

 $scaled_img = cv.resize(image,None,fx = 0.5,fy = 0.5,interpolation = cv.INTER_LINEAR)$

plt.imshow(scaled_img)

from scipy import ndimage

rotated_image = ndimage.rotate(image,45)

plt.imshow(rotated_image)

Define scaling factor

scaling_factor = 0.5 # You can change this value

Perform scaling

scaled_image = cv2.resize(image, None, fx=scaling_factor, fy=scaling_factor, interpolation=cv2.INTER LINEAR)

Define rotation angle (in degrees)

rotation_angle = 45 # You can change this value

Perform rotation

height, width = scaled_image.shape[:2] rotation_matrix = cv2.getRotationMatrix2D((width/2, height/2), rotation_angle, 1) rotated_image = cv2.warpAffine(scaled_image, rotation_matrix, (width, height))

Display the original, scaled, and rotated images

cv2.imshow('Original Image', image)

cv2.imshow('Scaled Image', scaled_image)

cv2.imshow('Rotated Image', rotated_image)

cv2.waitKey(0)

cv2.destroyAllWindows()



Display the color image and its Resized images by different methods.

import matplotlib.pyplot as plt import numpy as np

 $scaling_factor = [0.5, 1.5, 2.0]$

interpolation = [cv.INTER_NEAREST,cv.INTER_LINEAR,cv.INTER_CUBIC]

import cv2

image = cv.imread("apple.jpg")

image = cv.cvtColor(image,cv.COLOR_BGR2RGB) import numpy as np

plt.imshow(image)

import cv2 as cv

Load the image

Define scaling factors

PROGRAM 3B

for i in scaling_factor: image = cv2.imread('apple.jpg') for j in interpolation:

scaled_img = cv.resize(image,None,fx = i,fy=i,interpolation=j)

cv.imshow(f"Resized(factor:{i}, Method = {method_name}",scaled_img)

method_name = "

scaling_factors = [0.5, 2.0] # You can add more scaling factors as needed

if j == cv.INTER NEAREST:

method_name = "Nearest Neighbor"

interpolation_methods = [cv2.INTER_NEAREST, cv2.INTER_LINEAR, cv2.INTER_CUBIC]

elif j== "cv.INTER_LINEAR": method_name = "Bilinear"

Display the original image

Define interpolation methods

cv2.imshow('Original Image', image)

else: # Perform resizing with different methods

for factor in scaling_factors:

method_name = "Bicubic"

for method in interpolation_methods:

Perform scaling

scaled_image = cv2.resize(image, None, fx=factor, fy=factor, interpolation=method)

cv.waitKey(0)

Display the resized image cv.destroyAllWindows()

method_name = ""

if method == cv2.INTER_NEAREST:

method_name = "Nearest Neighbor"

elif method == cv2.INTER_LINEAR:

method_name = "Bilinear"

elif method == cv2.INTER_CUBIC:

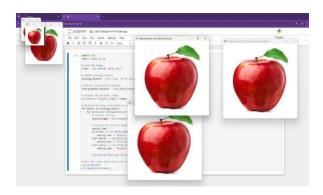
method name = "Bicubic"

cv2.imshow(f'Resized (Factor: {factor}, Method: {method_name})', scaled_image)

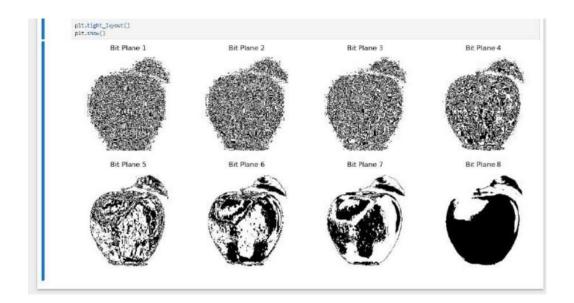
Wait for a key press and close all windows

cv2.waitKey(0)

cv2.destroyAllWindows()

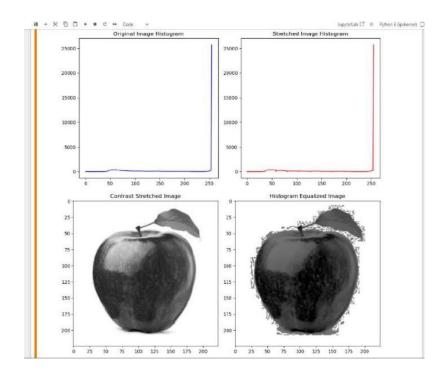


```
import cv2
                                               import numpy as np
                                               import matplotlib.pyplot as plt
PROGRAM 4
                                               # Helper function to plot images
import cv2
                                               def plot_image(image, title, cmap='gray'):
                                                 plt.figure()
import numpy as np
                                                 plt.imshow(image, cmap=cmap)
import matplotlib.pyplot as plt
                                                 plt.title(title)
                                                 plt.axis('off')
                                                 plt.show()
# Load the image
image = cv2.imread('input_image.jpg', cv2.IMREAD_GRAYSCALE)
                                               image = cv2.imread('apple.jpg', cv2.IMREAD_GRAYSCALE)
# Apply contrast stretching
                                               min_intensity = np.min(image)
                                               max_intensity = np.max(image)
min intensity = np.min(image)
                                               stretched_image = cv2.normalize(image, None, 0, 255,
max_intensity = np.max(image)
                                               norm_type=cv2.NORM_MINMAX)
stretched_image = cv2.normalize(image, None, 0, 255, norm_type=cv2.NORM_MINMAX)
                                               hist_original = cv2.calcHist([image], [0], None, [256], [0, 256])
# Calculate and plot histograms
                                               hist_stretched = cv2.calcHist([stretched_image], [0], None, [256], [0, 256])
hist_original = cv2.calcHist([image], [0], None, [256], [0, 256])
hist_stretched = cv2.calcHist([stretched_image], [0], None, [256], [0, 256])
                                               plt.figure(figsize=(10, 5))
plt.figure(figsize=(10, 5))
                                               plt.subplot(1, 2, 1)
                                               plt.plot(hist_original, color='b')
plt.subplot(1, 2, 1)
                                               plt.title('Original Image Histogram')
plt.plot(hist original, color='b')
                                               plt.subplot(1, 2, 2)
plt.title('Original Image Histogram')
                                               plt.plot(hist_stretched, color='r')
                                               plt.title('Stretched Image Histogram')
                                               plt.tight_layout()
plt.subplot(1, 2, 2)
                                               plt.show()
plt.plot(hist_stretched, color='r')
                                               # Apply histogram equalization
plt.title('Stretched Image Histogram')
                                               equalized_image = cv2.equalizeHist(image)
                                               # Calculate and plot histograms for equalized image
plt.tight_layout()
                                               hist_equalized = cv2.calcHist([equalized_image], [0], None, [256], [0, 256])
plt.show()
                                               # Plot images using the plot_image function
                                               plot_image(stretched_image, 'Contrast Stretched Image')
# Apply histogram equalization
                                               plot_image(equalized_image, 'Histogram Equalized Image')
equalized_image = cv2.equalizeHist(image)
# Calculate and plot histograms for equalized image
hist_equalized = cv2.calcHist([equalized_image], [0], None, [256], [0, 256])
plt.figure(figsize=(10, 5))
plt.subplot(1, 2, 1)
plt.imshow(stretched image, cmap='gray')
plt.title('Contrast Stretched Image')
plt.subplot(1, 2, 2)
plt.imshow(equalized_image, cmap='gray')
plt.title('Histogram Equalized Image')
plt.tight_layout()
plt.show()
```



plt.show()

```
import cv2
import numpy as np
import matplotlib.pyplot as plt
# Load the image in grayscale
image = cv2.imread('input_image.jpg', cv2.IMREAD_GRAYSCALE)
# Get the dimensions of the image
                                                        image = cv.imread("apple.jpg")
                                                        image = cv.cvtColor(image , cv.COLOR_BGR2GRAY)
height, width = image.shape
                                                        plt.imshow(image,cmap = "gray")
# Create an array to store the bit planes
                                                       image.shape
bit_planes = np.zeros((8, height, width), dtype=np.uint8)
                                                        bit_plane = np.zeros((8,height,width),dtype = np.uint8)
# Calculate the bit planes
for i in range(8):
  bit_planes[i] = (image >> i) & 1 # Extract ith bit plane
                                                       for i in range(8):
                                                          bit_plane[i] = (image >> i) &1
# Display the bit planes
                                                       for i in range(8):
plt.figure(figsize=(12, 6))
                                                          plt.subplot(2,4,i+1)
for i in range(8):
                                                          plt.imshow(bit_plane[i],cmap = "gray")
  plt.subplot(2, 4, i+1)
                                                        plt.show()
  plt.imshow(bit_planes[i], cmap='gray')
  plt.title(f'Bit Plane {i+1}')
  plt.axis('off')
plt.tight_layout()
```



import numpy as np import matplotlib.pyplot as plt from scipy.fftpack import fft2, fftshift

Read the image and convert to double precision array l = plt.imread('cancercell.jpg').astype(float)

```
# Perform 2-D FFT
f1 = np.fft.fft2(l)
```

Shift zero frequency component to the center f2 = np.fft.fftshift(f1)

Display magnitude of frequency spectrum plt.subplot(2, 2, 1) plt.imshow(np.abs(f1)) plt.title('Frequency Spectrum')

Display magnitude of centered spectrum plt.subplot(2, 2, 2) plt.imshow(np.abs(f2)) plt.title('Centered Spectrum')

Compute log(1 + abs(f2))f3 = np.log(1 + np.abs(f2))

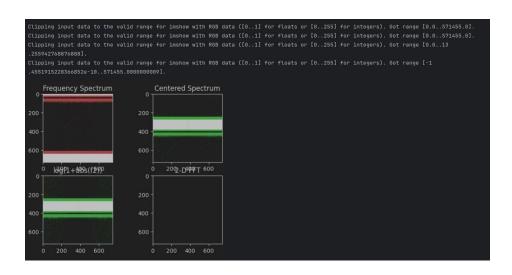
```
# Display log(1 + abs(f2))
plt.subplot(2, 2, 3)
plt.imshow(f3)
plt.title('log(1+abs(f2))')

# Perform 2-D FFT on f1
l_fft = fft2(f1)

# Take real part of the result
11 = np.real(l_fft)

# Display real part of 2-D FFT
plt.subplot(2, 2, 4)
plt.imshow(11)
plt.title('2-D FFT')
```

plt.show()



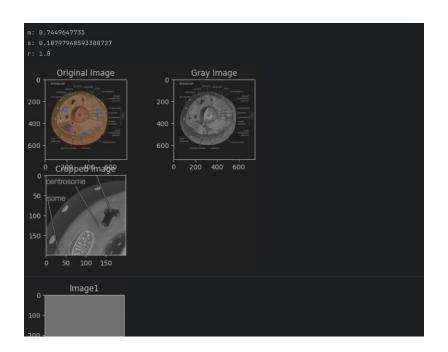
PROGRAM 7

import numpy as np import matplotlib.pyplot as plt from skimage import io, color from scipy.stats import pearsonr

Read the image i = io.imread('cancercell.jpg')

Display original image plt.subplot(2, 2, 1) plt.imshow(i) plt.title('Original Image')

```
# Convert to grayscale
g = color.rgb2gray(i)
# Display grayscale image
plt.subplot(2, 2, 2)
plt.imshow(g, cmap='gray')
plt.title('Gray Image')
# Crop the image
c = g[100:300, 100:300]
# Display cropped image
plt.subplot(2, 2, 3)
plt.imshow(c, cmap='gray')
plt.title('Cropped Image')
# Calculate mean and standard deviation of the cropped image
m = np.mean(c)
s = np.std(c)
print('m:', m)
print('s:', s)
# Generate checkerboard patterns
checkerboard = np.indices((400, 400)).sum(axis=0) % 2
# Create checkerboard images with different thresholds
k = checkerboard > 0.8
k1 = checkerboard > 0.5
# Display checkerboard images
plt.figure()
plt.subplot(2, 1, 1)
plt.imshow(k, cmap='gray')
plt.title('Image1')
plt.subplot(2, 1, 2)
plt.imshow(k1, cmap='gray')
plt.title('Image2')
# Calculate Pearson correlation coefficient between the two images
r, _ = pearsonr(k.flatten(), k1.flatten())
print('r:', r)
plt.show()
```



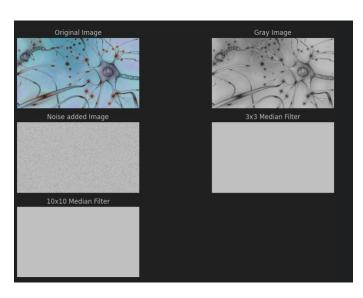
plt.subplot(3, 2, 2)

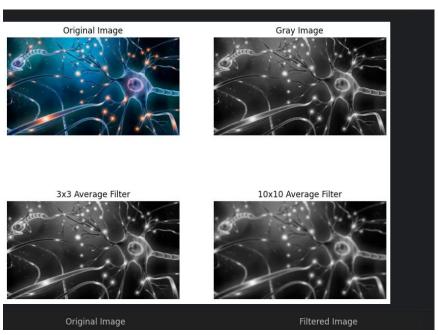
```
import cv2
import numpy as np
import matplotlib.pyplot as plt
from scipy.ndimage import convolve
from scipy.ndimage import median_filter
```

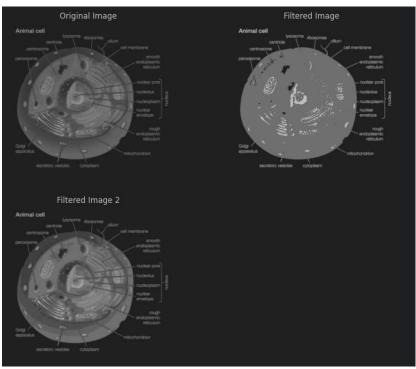
```
# Read the image
I = cv2.imread('C:/Users/anuam/OneDrive/Desktop/neuron.jpg')
K = cv2.cvtColor(I, cv2.COLOR_BGR2GRAY)
# Add salt and pepper noise
J = cv2.randu(K.copy(), 0, 255)
noise = np.random.choice([0, 255], K.shape, p=[0.95, 0.05])
J[noise == 255] = 255
J[noise == 0] = 0
# Apply median filters
f = median_filter(J, size=(3, 3))
f1 = median_filter(J, size=(10, 10))
# Display results
plt.figure(figsize=(12, 8))
plt.subplot(3, 2, 1)
plt.imshow(cv2.cvtColor(I, cv2.COLOR_BGR2RGB))
plt.title('Original Image')
plt.axis('off')
```

```
plt.imshow(K, cmap='gray')
plt.title('Gray Image')
plt.axis('off')
plt.subplot(3, 2, 3)
plt.imshow(J, cmap='gray')
plt.title('Noise added Image')
plt.axis('off')
plt.subplot(3, 2, 4)
plt.imshow(f, cmap='gray')
plt.title('3x3 Median Filter')
plt.axis('off')
plt.subplot(3, 2, 5)
plt.imshow(f1, cmap='gray')
plt.title('10x10 Median Filter')
plt.axis('off')
# Mean Filter and Average Filter
plt.figure(figsize=(10, 8))
i = cv2.imread('C:/Users/anuam/OneDrive/Desktop/neuron.jpg')
g = cv2.cvtColor(i, cv2.COLOR_BGR2GRAY)
# 3x3 Average filter
g1 = np.ones((3, 3)) / 9.0
b1 = convolve(g, g1)
plt.subplot(2, 2, 1)
plt.imshow(cv2.cvtColor(i, cv2.COLOR_BGR2RGB))
plt.title('Original Image')
plt.axis('off')
plt.subplot(2, 2, 2)
plt.imshow(g, cmap='gray')
plt.title('Gray Image')
plt.axis('off')
plt.subplot(2, 2, 3)
plt.imshow(b1, cmap='gray')
plt.title('3x3 Average Filter')
plt.axis('off')
# 10x10 Average filter
g2 = np.ones((10, 10)) / 100.0
b2 = convolve(g, g2)
```

```
plt.subplot(2, 2, 4)
plt.imshow(b2, cmap='gray')
plt.title('10x10 Average Filter')
plt.axis('off')
# Implementation of filter using Convolution
plt.figure(figsize=(10, 8))
I = cv2.imread('C:/Users/anuam/OneDrive/Desktop/earcell.jpg', cv2.IMREAD_GRAYSCALE)
plt.subplot(2, 2, 1)
plt.imshow(I, cmap='gray')
plt.title('Original Image')
plt.axis('off')
# Convolution with filter a
a = np.array([[0.001, 0.001, 0.001], [0.001, 0.001, 0.001], [0.001, 0.001, 0.001]))
R = convolve(I, a)
plt.subplot(2, 2, 2)
plt.imshow(R, cmap='gray')
plt.title('Filtered Image')
plt.axis('off')
# Convolution with filter b
b = np.array([[0.005, 0.005, 0.005], [0.005, 0.005, 0.005], [0.005, 0.005, 0.005]])
R1 = convolve(I, b)
plt.subplot(2, 2, 3)
plt.imshow(R1, cmap='gray')
plt.title('Filtered Image 2')
plt.axis('off')
plt.tight_layout()
plt.show()
```







```
import cv2
import numpy as np
import matplotlib.pyplot as plt
from scipy.ndimage import convolve
from scipy import ndimage
import os
# Define function to read image safely
def safe_imread(filename):
  if not os.path.exists(filename):
    raise FileNotFoundError(f"File '{filename}' not found.")
  return cv2.imread(filename)
# Define the Laplacian filter
def laplacian_filter(img, alpha=0.05):
  kernel = np.array([[0, 1, 0], [1, -4 + alpha, 1], [0, 1, 0]])
  return convolve(img, kernel)
# Main script
try:
  # Read the image
  i = safe_imread('C:/Users/anuam/OneDrive/Desktop/neuron.jpg')
  # Display the original image
  plt.subplot(4, 2, 1)
  plt.imshow(cv2.cvtColor(i, cv2.COLOR_BGR2RGB))
  plt.title('Original Image')
  plt.axis('off')
  # Convert to grayscale
  g = cv2.cvtColor(i, cv2.COLOR_BGR2GRAY)
  # Display the grayscale image
  plt.subplot(4, 2, 2)
  plt.imshow(g, cmap='gray')
  plt.title('Gray Image')
  plt.axis('off')
  # Apply Laplacian filter
  f = laplacian_filter(g, alpha=0.05)
  # Display the Laplacian filtered image
  plt.subplot(4, 2, 3)
  plt.imshow(f, cmap='gray')
  plt.title('Laplacian')
  plt.axis('off')
```

```
# Apply Sobel edge detection
s = cv2.Sobel(g, cv2.CV_64F, 1, 0, ksize=3) + cv2.Sobel(g, cv2.CV_64F, 0, 1, ksize=3)
# Display the Sobel edge detected image
plt.subplot(4, 2, 4)
plt.imshow(s, cmap='gray')
plt.title('Sobel')
plt.axis('off')
# Apply Prewitt edge detection
kernelx = np.array([[1, 0, -1], [1, 0, -1], [1, 0, -1]])
kernely = np.array([[1, 1, 1], [0, 0, 0], [-1, -1, -1]])
px = convolve(g, kernelx)
py = convolve(g, kernely)
p = np.sqrt(px*2 + py*2)
# Display the Prewitt edge detected image
plt.subplot(4, 2, 5)
plt.imshow(p, cmap='gray')
plt.title('Prewitt')
plt.axis('off')
# Apply Roberts edge detection
kernelx = np.array([[1, 0], [0, -1]])
kernely = np.array([[0, 1], [-1, 0]])
rx = convolve(g, kernelx)
ry = convolve(g, kernely)
r = np.sqrt(rx*2 + ry*2)
# Display the Roberts edge detected image
plt.subplot(4, 2, 6)
plt.imshow(r, cmap='gray')
plt.title('Roberts')
plt.axis('off')
# Apply Sobel edge detection (horizontal)
sobel_horizontal = cv2.Sobel(g, cv2.CV_64F, 1, 0, ksize=3)
# Display the Sobel horizontal edge detected image
plt.subplot(4, 2, 7)
plt.imshow(sobel_horizontal, cmap='gray')
plt.title('Sobel Horizontal')
plt.axis('off')
# Apply Sobel edge detection (vertical)
sobel_vertical = cv2.Sobel(g, cv2.CV_64F, 0, 1, ksize=3)
```

```
# Display the Sobel vertical edge detected image plt.subplot(4, 2, 8)
plt.imshow(sobel_vertical, cmap='gray')
plt.title('Sobel Vertical')
plt.axis('off')

plt.tight_layout()
plt.show()

except FileNotFoundError as e:
print(e)
```

