Title: Write a program using Arduino to control

LED (One or more ON/OFF).

Roll No:SAI&DC75 Batch: S9

Date of Performance: _ _ /_ _/_ _

Date of Assessment: __/__/___

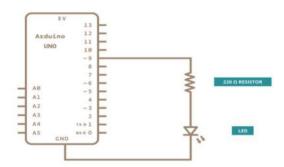
Particulars	Marks
Attendance (05)	
Journal (05)	
Performance (05)	
Understanding (05)	
Total (20)	
Signature of Staff Member	

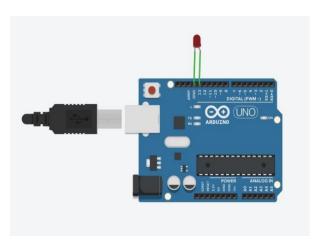
Program:-

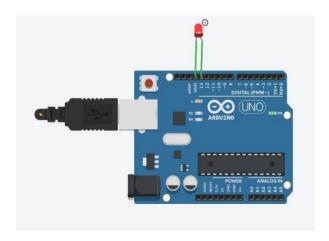
```
void setup()
{
  pinMode(13, OUTPUT);
}

void loop()
{
  digitalWrite(13, HIGH);
  delay(1000); // Wait for 1000 millisecond(s)
  digitalWrite(13, LOW);
  delay(1000); // Wait for 1000 millisecond(s)
}
```

Circuit Diagram:-







Title: Create a program that illuminates the green LED if the counter is less than 100, illuminates the yellow LED if the counter is between 101 and 200 and illuminates the red Roll Batch:

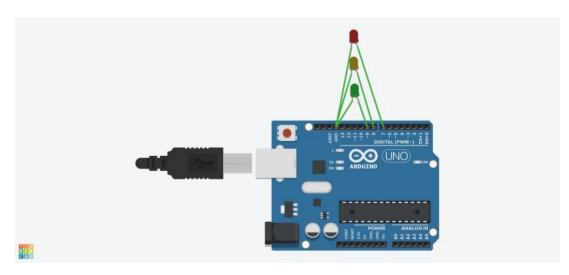
Date of Performance: _ _ /_ _/_ _

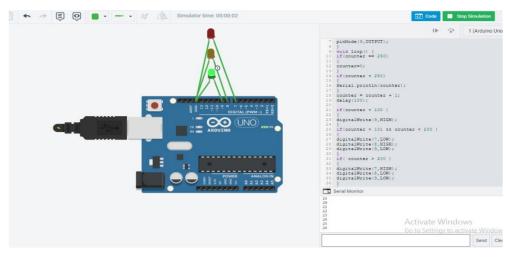
Particulars	Marks
Attendance (05)	
Journal (05)	
Performance (05)	
Understanding (05)	
Total (20)	
Signature of Staff Member	

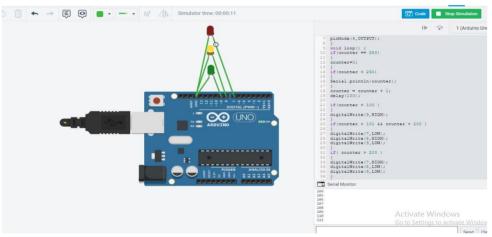
```
Program:-
int counter = 0;
void setup()
Serial.begin(9600);
pinMode(7,OUTPUT);
pinMode(8,OUTPUT);
pinMode(9,OUTPUT);
}
void loop() { if(counter
== 250)
{
counter=0;
}
if(counter < 250)
{
Serial.println(counter);
}
counter = counter + 1;
delay(100);
if(counter < 100)
digitalWrite(7,LOW);
digitalWrite(8,LOW);
digitalWrite(9,HIGH);
}
```

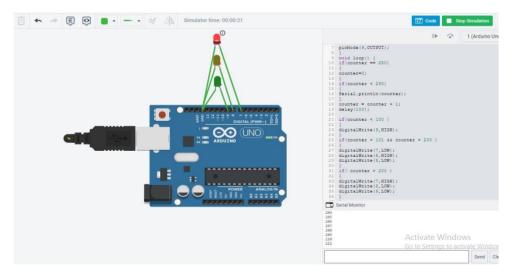
```
if(counter > 101 && counter < 200)
{
    digitalWrite(7,LOW);
    digitalWrite(8,HIGH);
    digitalWrite(9,LOW);
}

if( counter > 200 )
{
    digitalWrite(7,HIGH);
    digitalWrite(8,LOW);
    digitalWrite(9,LOW);
}
```









Title: Create a program so that when the user enters 'b' the blue light blinks, 'g' the green light is illuminated 'y' the yellow light is illuminated

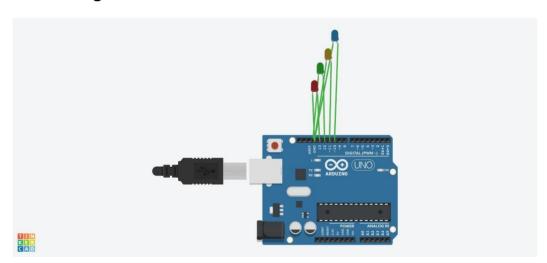
Roll Batch:

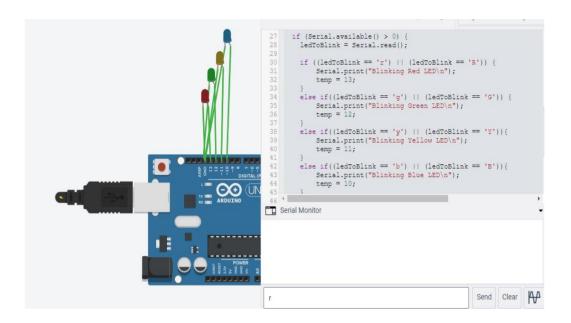
Date of Performance: _ _ /_ _/_ _

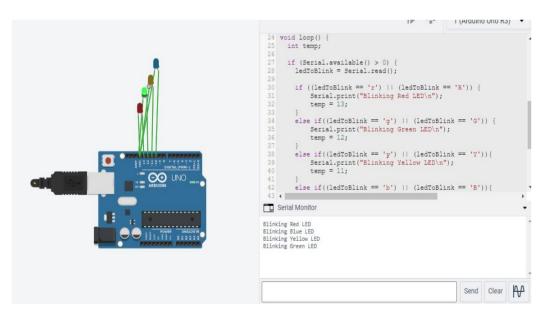
Particulars	Marks
Attendance (05)	
Journal (05)	
Performance (05)	
Understanding (05)	
Total (20)	
Signature of Staff Member	

```
Program:-
int RED = 13;
int GREEN = 12;
int YELLOW = 11;
int BLUE = 10;
char ledToBlink; void
setup() {
 pinMode(RED,OUTPUT);
 pinMode(YELLOW,OUTPUT);
 pinMode(BLUE,OUTPUT);
 pinMode(GREEN,OUTPUT);
 Serial.begin(9600);
}
void loop() { int
 temp;
 if (Serial.available() > 0) {
       ledToBlink = Serial.read();
  if ((ledToBlink == 'r') || (ledToBlink == 'R')) { Serial.print("Blinking
       Red LED\n");
       temp = 13;
  }
  else if((ledToBlink == 'g') || (ledToBlink == 'G')) {
       Serial.print("Blinking Green LED\n");
       temp = 12;
  }
  else if((ledToBlink == 'y') || (ledToBlink == 'Y')){
               Serial.print("Blinking Yellow LED\n");
```

```
temp = 11;
}
else if((ledToBlink == 'b') || (ledToBlink == 'B')){
    Serial.print("Blinking Blue LED\n");
    temp = 10;
}
else{
    Serial.print("\nInvalid Choice Try Again \n");
}
digitalWrite(temp, HIGH);
delay(1000);
digitalWrite(temp, LOW);
}
```







Experiment No.	. 10
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Title: Write a program read the temperature sensor and send the values to the serial monitor on the computer.

Roll No:SA&DC75 Batch: S9

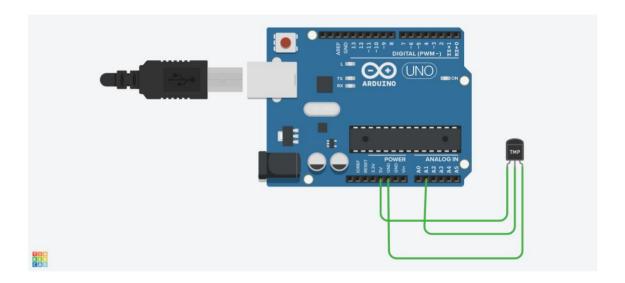
Date of Performance: _ _ /_ _/_ __

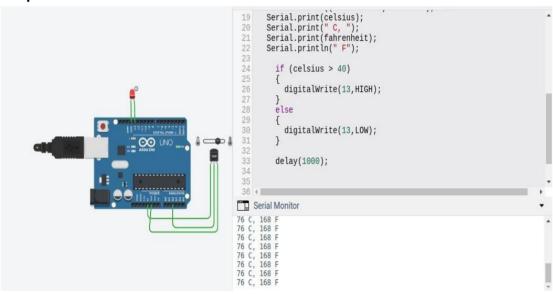
Date of Assessment: __/__/___

Particulars	Marks
Attendance (05)	
Journal (05)	
Performance (05)	
Understanding (05)	
Total (20)	
Signature of Staff Member	

```
Program:-
                  int
baselineTemp = 0; int
celsius = 0; int
fahrenheit = 0; void
setup()
{
 pinMode(A2, INPUT);
pinMode(13, OUTPUT);
 Serial.begin(9600);
  void
}
loop()
{
 celsius = map(((analogRead(A2) - 20) * 3.04), 0, 1023, -40, 125);
fahrenheit = ((celsius * 9) / 5 + 32);
 Serial.print(celsius);
 Serial.print(" C, ");
Serial.print(fahrenheit)
    Serial.println(" F");
if (celsius > 40)
  {
   digitalWrite(13,HIGH);
  }
  else
  {
   digitalWrite(13,LOW);
  }
```

```
delay(1000);
}
```





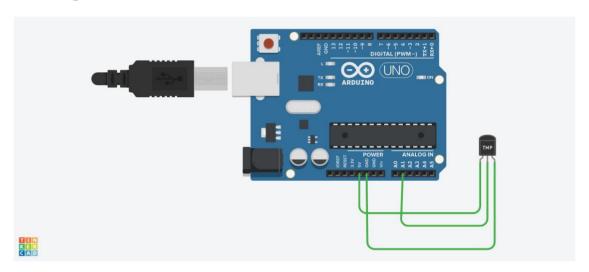
Title: Write a program so it displays the temperature

Roll	Batch:
Date of Performance:	//

Particulars	Marks
Attendance (05)	
Journal (05)	
Performance (05)	
Understanding (05)	
Total (20)	
Signature of Staff Member	

```
Program:-
int val;
int tempPin = 0;
float tfmax;
float tfmin = 100;
void setup()
{
Serial.begin(9600);
}
void loop()
{
val = analogRead(tempPin);
float mv = (val/1024.0)*500;
float cel = mv;
float farh = (cel*9)/5 + 32;
if (farh > tfmax)
tfmax = farh;
}
if (farh < tfmin)
{
tfmin = farh;
Serial.print("TEMPRATURE =
"); Serial.print(farh);
Serial.print("*F");
Serial.println();
```

```
Serial.print("Max Temp:");
Serial.print(tfmax);
Serial.println();
Serial.print("Min Temp:");
Serial.print(tfmin);
Serial.println();
Serial.println();
```



```
7 Serial.begin (9600);
8 }
9 void loop()
10 {
11 val = analogRead(tempPin);
12 float nv = ( val/1024.0)*500;
13 float cel = mv;
14 float fash = (cel*9)/5 + 32;
15 if (fash > tfmax)
16 if (fash > tfmax)
17 {
18 tfmax = fash;
20 if (fash < tfmin)
21 {
22 tfmin = fash;
23 serial.print("TEMPRATURE = ");
25 Serial.print("TEMPRATURE = ");
25 Serial.print("TEMPRATURE = ");
26 Serial.print("TEMPRATURE = ");
27 Serial.print("TEMPRATURE = ");
28 Serial.print("TEMPRATURE = ");
29 Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Serial.print("Seri
```

Title: Write a program to show the temperature

Roll No: Batch:

Date of Performance: _ _ /_ _/_ _

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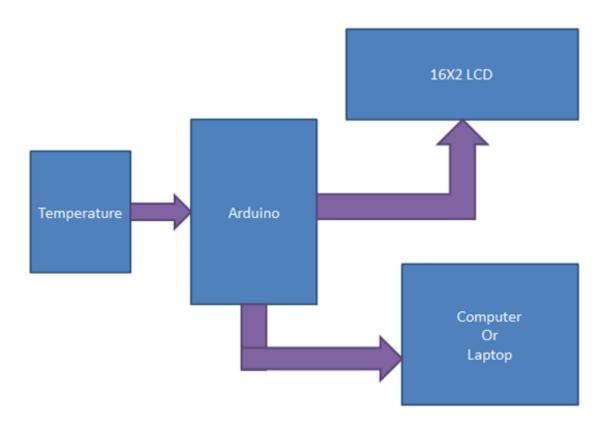
Particulars	Marks
Attendance (05)	
Journal (05)	
Performance (05)	
Understanding (05)	
Total (20)	
Signature of Staff Member	

Program:-

```
#include <SoftwareSerial.h>
SoftwareSerial bt(8, 9); // RX, TX
#include "dht.h"
#define dataPin A0
dht DHT:
int i = 0:
int temp;
int hum;
void setup() {
Serial.begin(9600);
bt.begin(9600);
Serial.println("Ready");
delay(2000);
pinMode(13, OUTPUT);
}
void loop(){
 int readData = DHT.read11(dataPin);
 hum = DHT.humidity; temp
 = DHT.temperature;
Serial.println();
Serial.println(hum);
 Serial.print("Humidity: ");
Serial.print(",");
Serial.print("Temp: ");
Serial.println(temp);
Serial.print("o"); //degree symbol
Serial.print("C ");
Serial.print(",");
bt.print(temp); //send distance to MIT App bt.print(";");
bt.print(hum); //send distance to MIT App
bt.println(";");
```

```
if(temp> 31)
{
    digitalWrite(13, HIGH);  // turn the LED on (HIGH is the voltage level) delay(1000);  // wait for a second
}
else
{
    digitalWrite(13, LOW);  // turn the LED on (HIGH is the voltage level) delay(1000);  // wait for a second
}
delay(1000);
}
```

Diagram:-



Title: Understanding the connectivity of Raspberry- Pi /Arduino circuit with IR sensor. Write an Application to detect obstacle and Roll Batch:

Date of Performance: _ _ /_ _/__

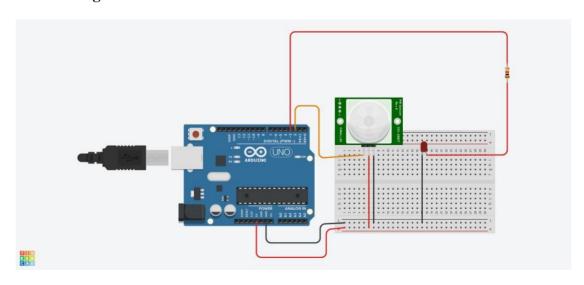
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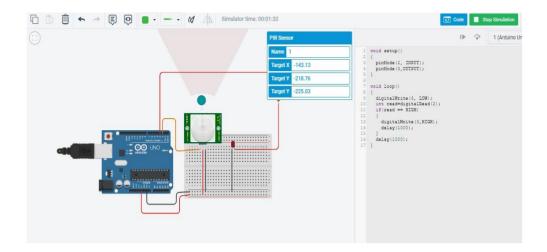
Particulars	Marks
Attendance (05)	
Journal (05)	
Performance (05)	
Understanding (05)	
Total (20)	
Signature of Staff Member	

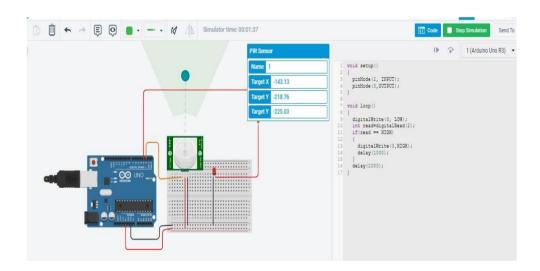
Program:-

```
void setup()
{
  pinMode(2, INPUT);
  pinMode(3,OUTPUT);
}
void loop()
{
  digitalWrite(3, LOW);
  int read=digitalRead(2);
  if(read == HIGH)
  {
    digitalWrite(3,HIGH);
    delay(1000);
  }
  delay(1000);
}
```

Circuit Diagram:-







Title: Study of ThingSpeak - an API and

Roll Batch:

Date of Performance: _ _ /_ _/__

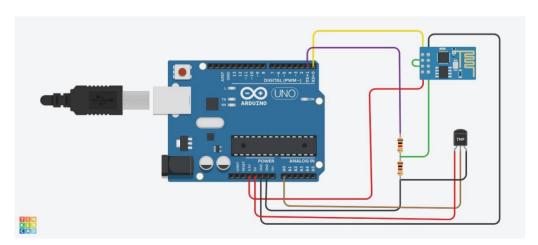
__ _

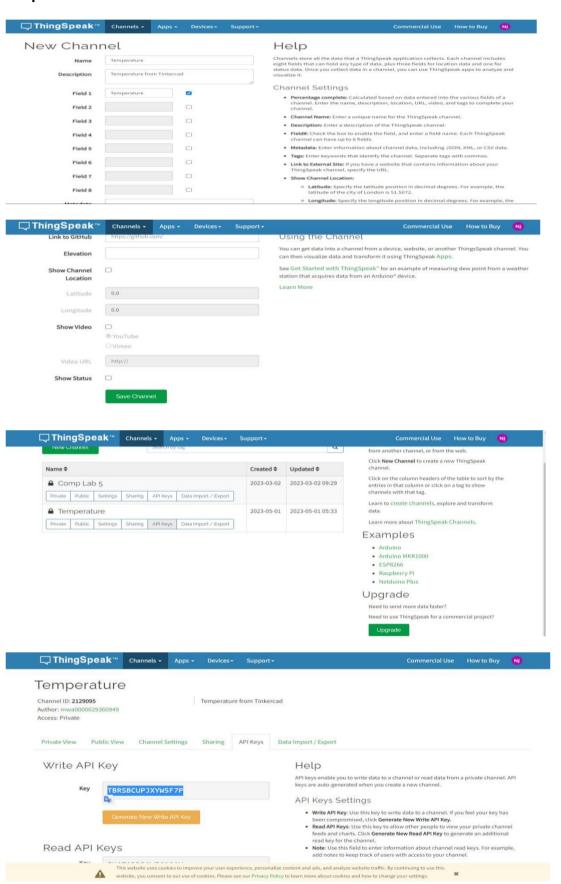
Particulars	Marks
Attendance (05)	
Journal (05)	
Performance (05)	
Understanding (05)	
Total (20)	
Signature of Staff Member	

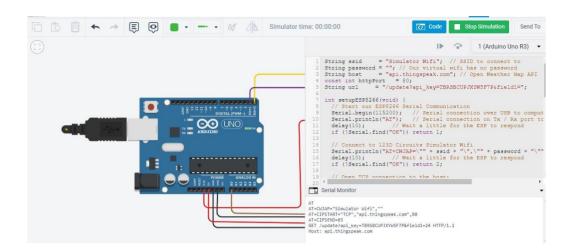
Program:-

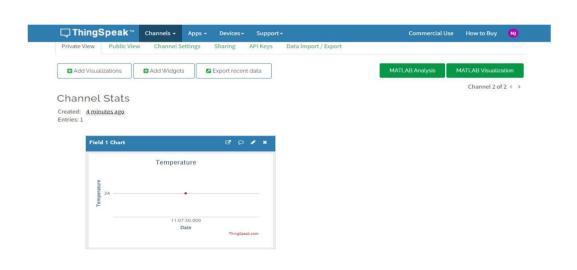
```
String ssid = "Simulator Wifi"; // SSID to connect to
String password = ""; // Our virtual wifi has no password
String host = "api.thingspeak.com"; // Open Weather Map API
const int httpPort = 80;
String url = "/update?api_key=TBRSBCUPJXYW5F7P&field1=";
int setupESP8266(void) {
 // Start our ESP8266 Serial Communication
 Serial.begin(115200); // Serial connection over USB to computer
 Serial.println("AT"); // Serial connection on Tx / Rx port to ESP8266
               // Wait a little for the ESP to respond
 delay(10);
 if (!Serial.find("OK")) return 1;
 // Connect to 123D Circuits Simulator Wifi
 Serial.println("AT+CWJAP=\"" + ssid + "\",\"" + password + "\"");
 delay(10);
               // Wait a little for the ESP to respond
 if (!Serial.find("OK")) return 2;
 // Open TCP connection to the host:
 Serial.println("AT+CIPSTART=\"TCP\",\"" + host + "\"," + httpPort);
 delay(50);
               // Wait a little for the ESP to respond
 if (!Serial.find("OK")) return 3; return
 0;
void anydata(void) {
 int temp = map(analogRead(A0),20,358,-40,125);
 // Construct our HTTP call
 String httpPacket = "GET" + url + String(temp) + "HTTP/1.1\r\nHost:" + host +
"\r\n\r\n";
```

```
int length = httpPacket.length();
 // Send our message length
 Serial.print("AT+CIPSEND=");
 Serial.println(length);
 delay(10); // Wait a little for the ESP to respond if (!Serial.find(">")) return -1;
 // Send our http request
 Serial.print(httpPacket);
 delay(10); // Wait a little for the ESP to respond
 if (!Serial.find("SEND OK\r\n")) return;
}
void setup() {
 setupESP8266()
}
void loop() {
anydata();
delay(10000);
}
```











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Title: Write an application to control the

Roll Batch:

Date of Performance: _ _ /_ _/__

Particulars	Marks
Attendance (05)	
Journal (05)	
Performance (05)	
Understanding (05)	
Total (20)	
Signature of Staff Member	

```
Program:-
```

```
void setup()
{
 pinMode(13, OUTPUT);
 pinMode(12, OUTPUT);
 pinMode(7, OUTPUT);
}
void loop()
{
 digitalWrite(13, HIGH);
 delay(1000); // Wait for 1000 millisecond(s)
 digitalWrite(13, LOW);
 delay(1000); // Wait for 1000 millisecond(s)
 digitalWrite(12, HIGH);
 delay(1000); // Wait for 1000 millisecond(s)
 digitalWrite(12, LOW);
 delay(1000); // Wait for 1000 millisecond(s) digitalWrite(7,
 HIGH);
 delay(2000); // Wait for 1000 millisecond(s) digitalWrite(7,
 LOW);
 delay(2000); // Wait for 1000 millisecond(s)
}
```

