# **Project Food Sense**

Mid-Semester Presentation

#### **Problem Statement**

> To use Nature Inspired Algorithms to determine the quality of food items using various gas sensors and camera

# Nature Inspired Optimized Algorithms - MFO

- Inspired from navigation method of Moths
- Concept of Moths and Flames
- Moths Candidate Solutions
- > Flames Best possible moths obtained so far
- Exploration v/s Exploitation

#### **MFO**

- > Fitness measure : distance of moth from corresponding flame
- Moth position updation: using logarithmic spiral
- Adaptive decrease of no of flames: for convergence
- Convergence

# **Nature Inspired Optimization Algorithms - GSA**

- Inspired from the Laws of Gravity
- Mass of Search Agent (M)
- Fitness of search agent (F)
- Randomization in Force calculation, position updation

#### **GSA**

- Mass updation of agents : proportional to fitness
- Role of G Updation in convergence
- Convergence

# **GSA + MFO Hybrid**

- Assign mass concept to Moths in MFO
- Communication between moths because of both MFO and GSA
- Increase the mass of the fitter moth GSA
- Moths spiral around fit flames MFO

# **Hybrid Algorithm (Contd.)**

Moth motion is guided by not just by flames but by masses of other moths

Ideally, faster convergence

# **Hybrid Algorithm Flow**

- > MFO locomotion
- Parameter updation
- GSA locomotion

### **Mass Fitness Relationship**

- GSA Measure of Fitness is Mass
- MFO Measure of Fitness is distance to fittest moth
- GSA works on the premise that fitter agent attracts others towards itself

# **Mass Fitness Relationship**

- > Hybrid algorithm, exploits this behaviour
- Hybrid Measure of Fitness is distance to fittest moth
- > Fittest moth has highest mass

### **Problems Faced - G Updation**

- > Stagnation of algorithm for values in the order of G0
- Reason for stagnation Slow decay of G
- $\rightarrow$  1/t vs 1/t<sup>2</sup> vs b<sup>t</sup> where b<1 and t = iteration no
- Slow decay of G: results in deviation of Moths from optimum value
- Updated decay of G to facilitate faster convergence without stagnation
- > As iterations progress, decrease the GSA motion

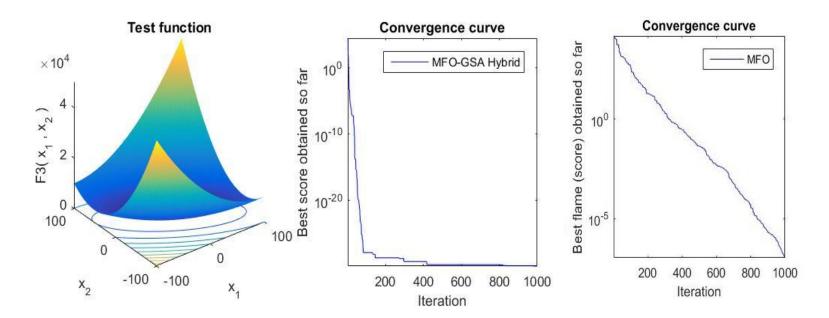
### **Problems Faced - Mass Updation**

- Mass Updation according to previous mass
- Mass(i) = Mass(i) + Fitness(i) / Sum(Fitness(i))
- Effective increase in mass of moth was negligible in this case
- Replaced with Mass(i) = 1 / fitness(i)

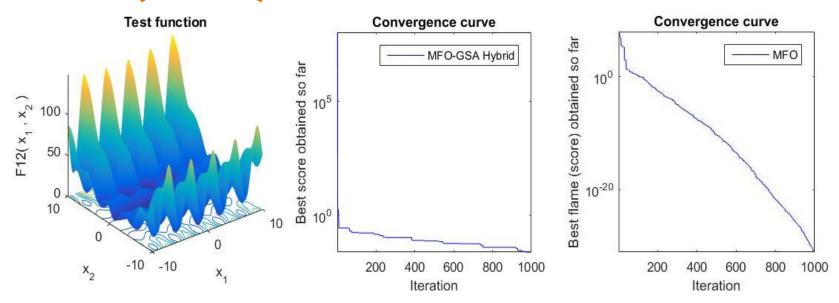
#### **Role of Randomization**

- Decreases effect of previous values on future values
- Significantly important contributor to performance
- Example

#### Results



# Results (Contd.)



# Results (Contd.)

