Project Food Sense

Problem Statement

> To use Nature Inspired Algorithms to determine the quality of food items using various gas sensors and camera

MFO

- > Fitness measure : distance of moth from corresponding flame
- Moth position updation: using logarithmic spiral
- Adaptive decrease of no of flames: for convergence
- Convergence

GSA

- Mass updation of agents : proportional to fitness
- Role of G Updation in convergence
- Convergence

GSA + MFO Hybrid

- Assign mass concept to Moths in MFO
- Communication between moths because of both MFO and GSA
- Increase the mass of the fitter moth GSA
- Moths spiral around fit flames MFO

Hybrid Algorithm (Contd.)

Moth motion is guided by not just by flames but by masses of other moths

Ideally, faster convergence

Pseudo Code

```
initialize moth_position, moth_velocity, moth_acceleration
calculate initial fitness for each moth
while(iteration < max iteration)
update flame_number
if (iteration == 1)
         F = sort(M)
         OF = sort(OM)
else
         F = sort(Mt-1, Mt)
         OF=sort(Mt-1, Mt);
end
for i=1: n
         for j=1:d
                  update r and t
                  D(i) = |F(i) - M(i)|
                  M(i) = D(i) \cdot ebt \cdot cos(2 \sqcap t) + F(j)
         end
end
```

Mass Fitness Relationship

- GSA Measure of Fitness is Mass
- MFO Measure of Fitness is distance to fittest moth
- GSA works on the premise that fitter agent attracts others towards itself

Mass Fitness Relationship

- > Hybrid algorithm, exploits this behaviour
- Hybrid Measure of Fitness is distance to fittest moth
- > Fittest moth has highest mass

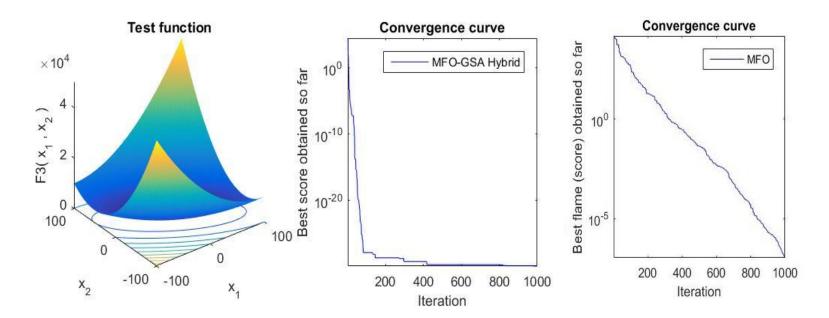
Problems Faced - G Updation

- > Stagnation of algorithm for values in the order of G0
- Reason for stagnation Slow decay of G
- \rightarrow 1/t vs 1/t² vs b^t where b<1 and t = iteration no
- Slow decay of G: results in deviation of Moths from optimum value
- Updated decay of G to facilitate faster convergence without stagnation
- > As iterations progress, decrease the GSA motion

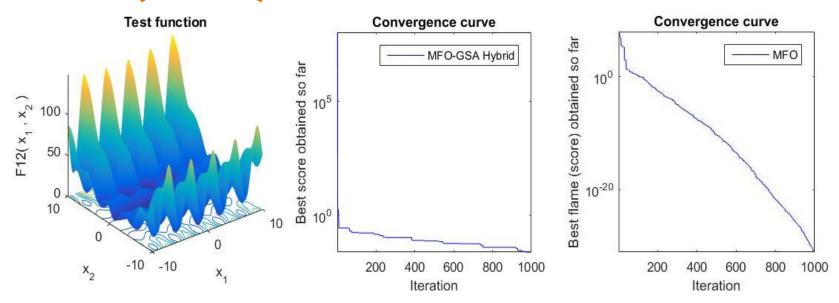
Problems Faced - Mass Updation

- Mass Updation according to previous mass
- Mass(i) = Mass(i) + Fitness(i) / Sum(Fitness(i))
- > Effective increase in mass of moth was negligible in this case
- Replaced with Mass(i) = 1 / fitness(i)

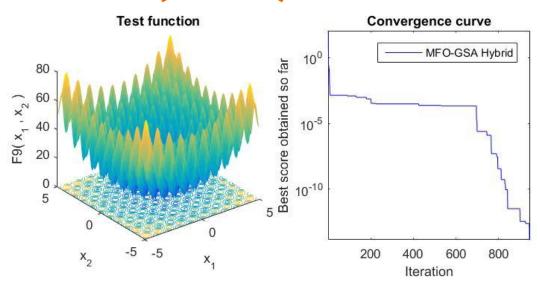
Results

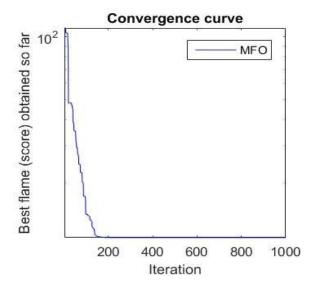


Results (Contd.)



Results (Contd.)





Optimized K-Means

```
initialize each particle to contain k randomly selected cluster centroids
for t = 1 to tmax do
          for particle i do
                     for each data vector d,
                                dist(d, m<sub>ii</sub>) to all cluster centroids C<sub>ii</sub>
                                assign d to cluster C<sub>ii</sub>: dist(d, m<sub>ii</sub>) = min {dist(d, m<sub>ii</sub>)}
                                F = [F \operatorname{dist}(d, m_{ii})]
                     endfor
                     C = best(F[])
          endfor
return Cii
endfunction
```

Results of Optimized K-Means

K-Means	Optimized K-Means
1.11	1.11
41.59	39.54
0.54	0.52
29.12	27.46
	1.11 41.59 0.54

Image Segmentation: K-Means

- Convert image to LAB color space
- Apply optimized K-Means on a and b







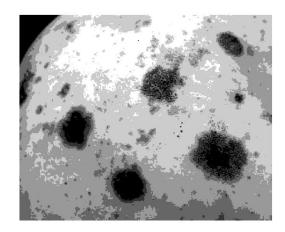


Image Segmentation: Multi-Level Thresholding

- Segment the image using thresholds
- Thresholding: manual process
- Brute force: Computationally expensive
- Optimization approach

Image Segmentation: Multi-Level Thresholding II

- Search for threshold values
- Fitness function: S_{inter_cluster} / S_{intra_cluster}



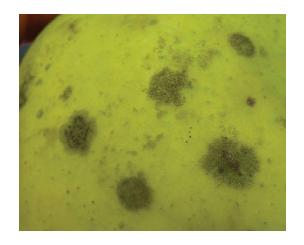


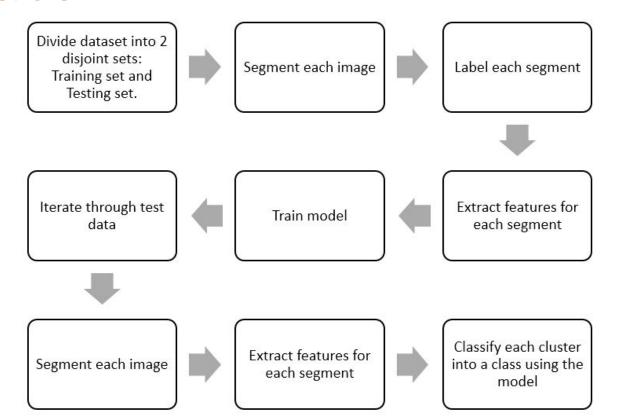
Image Segmentation: Multi-Level Thresholding III

```
Read Image
Add noise to the image
Generate image histogram
Initialize k moths with random positions and masses
for i = 1 to max iterations:
        while size(population) > size (new population):
                   MFO+GSA hybrid locomotion
                  F_i = S_{inter\_cluster} / S_{intra\_cluster}
                  sort(F[])
        endwhile
endfor
endfunction
```

Feature Extraction

- Local Binary Pattern
- Grey Level Co-occurrence Matrix
- Haralick Features

Classification



Future Work

- Collect gas sensor data
- Extend to other food items
- Explore other texture analysis for other food items