

Tutorial - 3

Q1 - Write linear search Pseudocode to search an element in a sorted array with minimum comparisons.

No. of comparisons can be reduced by copying the element to be searched (suppose n) to last location. So, that one last comparison when X is not present in $\text{arr}[]$ - saved

Pseudocode :-

```
search (arr, n, n)
if arr [n-1] == n // 1 comparison
    return "true"
backup = arr [n-1]
arr [n-1] = n ;
```

```
for i=0 ; i++ // No termination condition
if arr [i] == * ; // execute at most n
    times ; i.e., most n
    comparisons
```

```
    arr [n-1] = backup
    return (i < n-1) 1 / 1 comparison
    return found ;
else
    return not found ;
```

Q2 - Write Pseudocode for Iterative & Recursive Insertion sort why Insert sort is also called Online sort.

Q2 - Iterative Pseudocode :

/ sort an arr [] of size n
 Insertionsort (arr, n)
 Loop from i = 1 to n-1
 $a \rightarrow$ pick element arr (i) & Insert
 It into sorted sequence arr [0...i-1]

Recursive Pseudocode :

basecase - If ($n \leq 1$)

return ; // If arr 1 or smaller,
 return

sort first ($n-1$) elements

i.e., [arr, n-1]

last = arr [$n-1$] // Insert last element
 at correct position

$j = n-2$

Apply Insert algo

Print utility Pf arr of size n

- Insertion sort is called online sort because it does not need to know about what values it will sort & information is requested while algo runs
- whereas selection is offline sort

Q3 - Complexity of all sorting algorithms :-

selection sort - $\mathcal{O}(n^2)$

bubble sort - $\mathcal{O}(n)$

Insertion - $\mathcal{O}(n)$

heap - $\mathcal{O}(n \log(n))$

Quick - $\mathcal{O}(n \log(n))$

Merge - $\mathcal{O}(n \log(n))$

$$\text{Count} = O(n+k)$$

$$\text{Radix} = O(1/k)$$

Q4 - Divide all sorting algorithm into Inplace / stable / unstable.

Ans4 - Inplace : Bubble sort, Selection sort, Insertion & Heap sort

Stable : Merge sort, Count sort, Insertion sort & Bubble sort

Unstable : Quicksort, Heap & Selection sort

Q5 - Write recursive / iterative pseudocode for binary search. What's time & space complexity of linear & binary search.

Ans5 - $\text{low} = 0, \text{high} = n-1;$

while ($\text{low} \leq \text{high}$) // loop till search exhausts

}

int mid = ($\text{low} + \text{high}$) / 2 // find mid value in search space & compare

If ($\text{target} == \text{num}[mid]$)

pt with target

}

return mid;

use

If ($\text{target} < \text{num}[mid]$)

high = mid - 1;

}

else {

low = mid + 1 ;

}

return -1

// If target > middle
element discard all
element in left space

// If no element exists in array

Recursive Pseudocode

base condition:

 → If (low > high) {

 return -1 ;

}

 mid = (low + high) / 2 // find mid value

 If (target = num [mid])

 } return mid ;

}

 // If base condition not

 else If (target < num [mid])

 } return binary search (num, low, mid - 1, target)

}

else

"

 " (num, mid + 1, high, target)

Linear Search

Binary Search

Time (C)

$O(n)$

$O(\log n)$

Space (C)

$O(1)$

$O(1)$
Iteratively
↓ Recursively

Q6 - Recurrence relation for binary recursive search-

Ans6 - As mean element is selected as pivot array divides in branches of equal size. So that height of tree \rightarrow minimum.

In worst case, time complexity it will be $O(N^2)$ & will happen when array-sorted & smallest to largest elements is selected as pivot.

Recurrence relation of binary search

$$n = T(n) = T(n/2) + 1$$

Ans7 - Quick sort is best sorting algo in practical case as it follows locality of reference & also it's best case complexity is $O(\log(n))$

Q8 - Which sorting is best for practical uses. Explain.

Ans8 - Quicksort is fastest general-purpose sort. It's more effective for datasets that fit in memory. It's an in-place sort (doesn't require extra storage), so it's appropriate for arrays.

Q9 - What do you mean by number of inversions in an array?

Ans9 - Inversion count for an array indicates how far or close is the array from being sorted. If array already sorted inversion count is zero (0) but if array is sorted in reverse order inversion count - maximum.

Given array :

$$\text{arr}[] = \{7, 21, 31, 8, 10, 1, 20, 6, 4, 5\}$$

No. of inversions :- { (7, 1), (7, 6), (7, 4), (7, 5), (21, 20),
 (31, 8), (31, 10), (31, 1), (31, 20), (31, 6),
 (31, 4), (31, 5) (8, 1),
 (8, 6), (8, 5), (8, 4), (10, 1), (10, 6), (10, 4),
 (10, 5)}

Q10 - In which cases Quick sort will give best & worst case time complexity?

Ans 10 - Best case time complexity of quicksort is $O(N \log(N))$ & that will be when pivot is selected as mean element.

Q11 - Write recurrence relation of merge & quick sort in best & worst case. What are similarities & differences between the two?

Recurrence relation of merge sort in best case :-

$$T(n) = 2T\left(\frac{n}{2}\right) + O(n)$$

On solving, $T(n) = O(n \log(n))$

" " quick sort :-

$$T(n) = T(n-1) + O(n)$$

worst case : $O(n^2)$

Merge Sort

Quick Sort

→ Array partitioned into 2 halves

→ Worst + avg. case has same complexity $O(n \log(n))$

→ Array is partitioned into any ratio

→ Worst case $T(c) = O(n^2)$

requires lots of comparisons

- Can work well with any type dataset irrespective of size → Does not work well with large dataset
- Not In place, requires additional memory space to store auxiliary array → Quicksort Is In place as it doesn't require any additional storage
- Stable → Unstable
- Linked Lists → Arrays

Ques 12- Selection sort can be made stable if instead of swapping minimum element is placed in its position without swapping.

Eg:-

Word Sort (Put $a[]$, Put n)
for (Put $i=0$; $i < n-1$; $i++$) // Iteration

Put $min = i$; // find min element from arr $[i] \rightarrow arr[n-1]$

for (Put $j = i+1$; $j < n$; $j++$)
if ($a[min] > a[j]$)

$min = j$;

Put $key = a[min]$; // move min element at current i .

while ($min > i$)
}

$a[i] = key$

{

}

Q13 - Bubble sort scans whole array even when array is sorted.
 Can you modify bubble sort so that it doesn't scan whole array once sorted.

Ans13 - Bubble sort can be optimized if inner loop doesn't cause any swap.

```

Void bubble sort (int arr[], int n)
{
  int i, j;
  bool swapped;
  for (i=0; i<n-1; i++)
  {
    swapped = false;
    for (j=0; j<n-i-1; j++)
    {
      if (arr[j] > arr[j+1])
      {
        swap (arr[j], arr[j+1]);
        swapped = true;
      }
    }
    if (swapped = false)
      break;
  }
}
  
```

Q14 - Your computer has RAM = 2Gb & Array = 4Gb - sorting which algorithm will be used & why? Explain external + internal sorting.

Ans 14 - In such case, merge sort will be inefficient as it is an external sorting algorithm, i.e., data is divided into chunks & sorted using merge sort.

Internal Sorting

- All data is stored in memory at all times, while sorting - progress

- Shell sort applicable i.e., access whatever array elements you wish to & whenever

External Sorting

- Data stored outside memory & loaded to memory in small chunk

- Shell sort not applicable
∴ "arr" not entirely in memory, therefore, random access not possible